

# On the Regularization Method for Solving Ill-Posed Problems with Unbounded Operators

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## Abstract

Let  $A: D(A) \subset X \to Y$  be a linear, closed, and densely defined unbounded operator, where X and Y are Hilbert spaces. Assume that A is not boundedly invertible. Suppose the equation Au = f is solvable, and instead of knowing exactly f only know its approximation  $f_{\delta}$  satisfies the condition:

 $||f_{\delta} - f|| \le \delta, 0 < \delta \to 0$ . In this paper, we are interested a regularization method to solve the approximation solution of this equation. This approximation is a unique global minimizer  $u_{\alpha,\delta}$  of the functional  $F_{\delta}(u) := ||Au - f_{\delta}||^2 + \alpha ||u||^2$ , for any  $f_{\delta} \in Y$ , defined as follows:  $u_{\alpha,\delta} = A^* (AA^* + \alpha I_x)^{-1} f_{\delta}$ . We also study the stability of this method when the regularization parameter is selected a priori and a posteriori. At the same time, we give an application of this method to the weak derivative operator equation in Hilbert space  $H = L^2[0,1]$ .

# **Keywords**

Ill-Posed Problem, Regularization Method, Unbounded Linear Operator

# **1. Introduction**

Let  $A: D(A) \subset X \to Y$  be a linear, closed, densely defined unbounded operator, where *X* and *Y* are Hilbert spaces. Consider the equation

$$Au = f \tag{1}$$

Problem-solving solution of Equation (1) is called ill-posed [1] if A is not boundedly invertible. This may happen if the null space  $N(A) = \{u : Au = 0\}$  is not trivial, *i.e.* A is not injective, or if A is injective but  $A^{-1}$  is unbounded, *i.e.* the range of A, R(A) is not closed [2].

If  $||A|| < \infty$ , problem-solving stable solution of Equation (1) has been extensively studied in the literature in detail ([2] [3] [4] [5] [6] and references therein).

If  $f_{\delta}$ , the noisy data, are given

$$\|f_{\delta} - f\| \le \delta \tag{2}$$

is a stable approximation to the unique minimal norn solution to Equation (1) was constructed by several methods (variational regularization, quasi solution, iterative regularization, ... [2] [3] [4] [5] [6] and references therein).

If *A* is a linear, closed, densely defined unbounded operator, problem (1) has been some recent research [2] [7] [8] [9] [10] [11], however, there are still many open problems such as parameter choice rules of regularization method with the linear closed, densely defined unbounded operator  $A: D(A) \subset X \to Y$ .

Our aim is to study problem-solving stable approximation solution of Equation (1) when operator A is a linear, closed, and densely defined from space Hilbert X into space Hilbert Y. We shall present the regularization method for solving the problem (1), we shall present a priori and a posteriori parameter choice rules of regularization; at the same time give an application to the weak derivative operator equation.

The paper structure consists of 3 sections: Section 1 the introduction briefly summarizes the recent research results and come up with the problem that needs to be studied; Section 2 presents some main results; Section 3 presents an application of this method.

#### 2. Some Main Results

**Lemma 1.** [2] Let  $A: D(A) \subset X \to Y$  be a linear, closed, densely defined operator, where X and Y are Hilbert spaces, then

1) the operators  $T = A^*A$  and  $Q = AA^*$  are densely defined, self-adjoint;

2)  $A^*$  is closed, densely defined and  $A^{**} = A$ ;

3) the operators  $\tilde{A} := (I_X + A^*A)^{-1} : X \to Y$ ,  $A\tilde{A} : X \to Y$  are both defined on all of X and are bounded,  $\sigma(\tilde{A}) \subseteq [0,1]$ . Also,  $\tilde{A}$  is self-adjoint;

4) the operator  $\hat{A} := (I_Y + AA^*)^{-1} : Y \to X$  is bounded and self-adjoint and  $A^*\hat{A} : Y \to X$  is bounded.

**Lemma 2.** Let  $A: D(A) \subset X \to Y$  be a linear, closed, densely defined operator, where X and Y are Hilbert spaces. If f = Ay,  $y \perp N(A)$  then y is unique.

**Proof.** Suppose  $y_1$ , and  $y_2$  satisfy  $f = Ay_1$ ,  $y_1 \perp N(A)$ , and  $f = Ay_2$ ,  $y_2 \perp N(A)$  then  $A(y_1 - y_2) = 0$ . Thus  $y_1 - y_2 \in N(A)$ . There exits  $u \in N(A)$  such that  $y_1 - y_2 = u$  imply  $\langle y_1 - y_2, u \rangle = \langle y_1, u \rangle - \langle y_2, u \rangle = 0 = \langle u, u \rangle$ . Thus u = 0, it follows that  $y_1 = y_2$ .

**Theorem 1.** For any  $f \in Y$ , the problem

$$F(u) = ||Au - f||^2 + \alpha ||u||^2 \rightarrow \min, \alpha = \operatorname{const} > 0,$$
(3)

has a unique solution  $u_{\alpha} = A^* (AA^* + \alpha I_Y)^{-1} f$ , where  $I_Y$  is the identity operator on *Y*.

Proof. Consider the equation

$$AA^* + \alpha I_{\gamma} w_{\alpha} = f, \alpha = \text{const} > 0$$
<sup>(4)</sup>

which is uniquely solvable  $w_{\alpha} = (AA^* + \alpha I_Y)^{-1} f$  (Lemma 1). Let  $u_{\alpha} = A^* w_{\alpha}$  then

$$Au_{\alpha} = AA^{*} \left(AA^{*} + \alpha I_{Y}\right)^{-1} f$$
  
=  $\left(AA^{*} + \alpha I_{Y}\right) \left(AA^{*} + \alpha I_{Y}\right)^{-1} f - \alpha I_{Y} \left(AA^{*} + \alpha I_{Y}\right)^{-1} f$   
=  $f - \alpha w_{\alpha}$ ,

or

 $Au_{\alpha}-f=-\alpha w_{\alpha}.$ 

We have

$$F(u+v) = \|Au - f\|^{2} + \alpha \|u\|^{2} + \|Av\|^{2} + \alpha \|v\|^{2} + 2\operatorname{Re}\left[(Au - f, Av) + \alpha(u, v)\right], (5)$$

for any  $v \in D(A)$ . If  $u = u_{\alpha}$ , then

$$(Au_{\alpha} - f, Av) + \alpha(u_{\alpha}, v) = -\alpha(w_{\alpha}, Av) + \alpha(u_{\alpha}, v)$$
  
=  $-\alpha(A^*w_{\alpha}, v) + \alpha(u_{\alpha}, v) = 0.$  (6)

Thus Equation (6) implies

$$F\left(u_{\alpha}+v\right) = F\left(u_{\alpha}\right) + \left\|Av\right\|^{2} + \alpha \left\|v\right\|^{2} \ge F\left(u_{\alpha}\right)$$

$$\tag{7}$$

and  $F(u_{\alpha} + v) = F(u_{\alpha})$  if and only if v = 0, so  $u_{\alpha}$  is the unique minimier of F(u).

Theorem 1 is proved.

**Theorem 2.** If f = Ay,  $y \perp N(A)$  then

$$\lim_{\alpha \to 0} \|u_{\alpha} - y\| = 0, u_{\alpha} = A^* \left( A A^* + \alpha I \right)^{-1} f.$$
(8)

**Proof.** It follows from Lemma 2, y is unique. Write Equation (4) as  $A(A^*w_{\alpha} - y) = -\alpha w_{\alpha}$ . Apply  $A^*$ , which is possible because  $w_{\alpha} \in D(A^*)$ , we obtain

$$A^*A(u_\alpha - y) = -\alpha u_\alpha. \tag{9}$$

Multiply Equation (9) by  $u_{\alpha} - y$ , we obtain

$$(A^*A(u_{\alpha}-y),u_{\alpha}-y) = -\alpha(u_{\alpha},u_{\alpha}-y)$$

or

$$\|A(u_{\alpha} - y)\|^{2} = -\alpha (\|u_{\alpha}\|^{2} - (u_{\alpha}, y)).$$
(10)

Since  $\alpha > 0$  this implies

$$\left\|\boldsymbol{u}_{\alpha}\right\|^{2} \leq (\boldsymbol{u}_{\alpha}, \boldsymbol{y}),$$

so

$$\|u_{\alpha}\| \leq \|y\|, \forall \alpha > 0.$$

Therefore one may assume (taking a subsequence) that  $u_{\alpha}$  weakly converges to an element z,  $u_n \coloneqq u_{\alpha_n} \dagger z$ , as  $\alpha_n \to 0$ .

It follows from Equation (10) that

$$\lim_{n \to \infty} \|A(u_n - y)\| = 0, i.e. \lim_{n \to \infty} \|Au_n - f\| = 0.$$

We shall prove that z = y.

Let  $\gamma$  run through the set such that  $\{A^*A\gamma\}$  is dense in  $N^{\perp}$ , where N := N(A). Note that N(T) = N(A), where  $T = A^*A$ . Because of the formulas  $X = \overline{R(T)} \oplus N(T)$  the  $\{\gamma\} = D(T)$  is dense in X, and the set  $\{T\gamma\}$  is dense in  $N^{\perp}$ .

Multiply the equation  $T(u_{\alpha} - y) = -\alpha u_{\alpha}$  by  $\gamma$  and pass to the limit  $\alpha \to 0$ . We obtain

$$(z-y,T\gamma)=0.$$

We have assume  $y \perp N$ . If  $z \perp N$ , then  $z - y \perp N$  and  $z - y \perp N^{\perp}$ , so z - y = 0.

One may always assume that  $z \perp N$  because  $Tu_{\alpha} = Tu_{\alpha}$ , where  $u_{\alpha}$  is the orthogonal projection of  $u_{\alpha}$  onto  $N^{\perp}$ .

Thus, we have  $u_n := u_{\alpha_n} \dagger z$ ,  $||u_n|| \le ||y||$ . Thus implies  $\lim_{n \to \infty} ||u_n - y|| = 0$ . For convenience for the reader we prove this claim. Since  $u_n := u_{\alpha_n} \dagger z$ , one

gets  $||y|| \le \lim_{n \to \infty} ||u_n||$ . The inequality  $||u_n|| \le ||y||$  implies  $\lim_{n \to \infty} ||u_n|| \le ||y||$ . Therefore  $\lim_{n \to \infty} ||u_n|| = ||y||$ . This and the weakly converge  $u_n \coloneqq u_{\alpha_n} \ddagger z$  imply strong convergence

$$||u_n - y||^2 = ||u_n||^2 + ||y||^2 - 2\operatorname{Re}(u_n - y) \to 0$$
, as  $n \to \infty$ .

Theorem 2 is proved.

**Theorem 3.** If 
$$||f_{\delta} - f|| \le \delta$$
,  $f = Ay$ ,  $y \perp N(A)$  and  
 $F_{\delta}(u) = ||Au - f_{\delta}||^{2} + \alpha ||u||^{2} = \min,$ 
(11)

then there exists a unique global minimier  $u_{\alpha,\delta}$  to (11) and  $\lim_{\delta \to 0} ||u_{\delta} - y|| = 0$ , where  $u_{\delta} := u_{\alpha(\delta),\delta}$  and  $\alpha(\delta)$  is properly chosen, in particular  $\lim_{\delta \to 0} \alpha(\delta) = 0$ .

**Proof.** It follows from Lemma 2, y is unique. The existence and uniqueness of the minimizer  $u_{\alpha,\delta}$  of  $F_{\delta}(u)$  follows from Theorem 1 and  $u_{\alpha,\delta} = A^* (Q + \alpha I_Y)^{-1} f_{\delta}$ . We have

$$\left\|u_{\alpha,\delta} - y\right\| \le \left\|u_{\alpha,\delta} - u_{\alpha}\right\| + \left\|u_{\alpha} - f\right\|.$$

By Theorem 2,  $||u_{\alpha} - f|| \coloneqq \eta(\alpha) \to 0$ , as  $\alpha \to 0$ . Let us estimate

$$\left|u_{\alpha,\delta}-u_{\alpha}\right|=\left\|A^{*}\left(Q+\alpha I_{Y}\right)^{-1}\left(f_{\delta}-f\right)\right\|\leq\delta\left\|A^{*}\left(Q+\alpha I_{Y}\right)^{-1}\right\|.$$

By the polar decomposition theorem [12], one has  $A^* = UQ^{1/2}$ , where U is a partial isometry, so  $||U|| \le 1$ . One has,

$$\begin{split} \left| A^* \left( Q + \alpha I_Y \right)^{-1} \right\| &= \left\| U Q^{1/2} \left( Q + \alpha I_Y \right)^{-1} \right\| \le \left\| Q^{1/2} \left( Q + \alpha I_Y \right)^{-1} \right\| \\ &= \max_{\lambda \ge 0c} \frac{\lambda^{1/2}}{\lambda + \alpha} = \frac{1}{2\sqrt{\alpha}}, \end{split}$$

where the spectral representation for Q was used.

Thus

$$\left\| u_{\alpha,\delta} - y \right\| \le \frac{\delta}{2\sqrt{\alpha}} + \eta\left(\alpha\right). \tag{12}$$

For a fixed small  $\delta > 0$ , choose  $\alpha = \alpha(\delta)$  which minimizes the right side of

Equation (12). Then  $\lim_{\delta \to 0} \alpha(\delta) = 0$  and  $\lim_{\delta \to 0} \left( \frac{\delta}{2\sqrt{\alpha(\delta)}} + \eta(\alpha(\delta)) \right) = 0.$ 

Theorem 3 is proved.

**Remark 1.** We can also choose  $\alpha(\delta) = c\delta^k$ , with any k < 2 and c = const > 0. The constant *c* can be arbitrary.

We can also choose  $\alpha(\delta)$  by a descrepancy principle. For example, consider the equation for finding  $\alpha(\delta)$ :

$$\|Au_{\alpha,\delta} - f_{\delta}\| = c\delta, c = \text{const} > 1.$$

We assume that  $||f_{\delta}|| > c\delta$ .

That is the content of the following theorem.

Theorem 4. The equation

$$\left|Au_{\alpha,\delta} - f_{\delta}\right| = c\delta, c = \text{const} > 1, \left\|f_{\delta}\right\| > c\delta,$$
(13)

has a unique solution  $\alpha = \alpha(\delta) > 0$ ,  $\lim_{\delta \to 0} \alpha(\delta) = 0$ , and if  $u_{\delta} := u_{\alpha(\delta),\delta}$ , then  $\lim_{\delta \to 0} ||u_{\delta} - y|| = 0$ .

**Proof.** Let us prove that Equation (13) has a unique root  $\alpha(\delta) > 0$ ,  $\lim_{\delta \to 0} \alpha(\delta) = 0$ . Indeed, using the spectial theorem [12], one gets

$$\begin{split} \left\|Au_{\alpha,\delta} - f_{\delta}\right\|^{2} &= \left\|\left[AA^{*}\left(Q + \alpha I\right)\right]^{-1} f_{\delta}\right\|^{2} = \int_{0}^{\infty} \left|\frac{s}{s + \alpha} - 1\right|^{2} d\left(E_{s}, f_{\delta}, f_{\delta}\right) \\ &= \alpha^{2} \int_{0}^{\infty} \frac{d\left(E_{s}, f_{\delta}, f_{\delta}\right)}{\left(s + \alpha\right)^{2}} \coloneqq g\left(\alpha, \delta\right), \end{split}$$

where  $E_s$  is the resolution of the identity of Q.

One has  $g(\infty, \delta) = ||f_{\delta}||^2 > c^2 \delta^{\delta}$ , and  $g(+0, \delta) = ||P_{N^*} f_{\delta}||^2$ , where  $P_{N^*}$  is the orthoprojector onto the subspace  $N^* = N(Q) = N(A^*) = R(A)^{\perp}$ .

Since  $f \in R(A)$  and  $||f_{\delta} - f|| \le \delta$ , it follows that  $||P_{N^*}f_{\delta}|| \le \delta$ , so  $g(+0,\delta) \le \delta^2$ . The function  $g(\alpha,\delta)$  for a fixed  $\delta > 0$  is a continuous strictly in-

 $g(+0,\delta) \le \delta^2$ . The function  $g(\alpha,\delta)$  for a fixed  $\delta > 0$  is a continuous strictly increasing function of  $\alpha$  on  $[0,\infty)$ . Therefore there exists a unique  $\alpha = \alpha(\delta) > 0$ which solves Equation (13) if  $||f_{\delta}|| > c\delta$  and c > 1. Clearly  $\lim_{\delta \to 0} \alpha(\delta) = 0$ , because  $\lim_{\delta \to 0} c\alpha(\delta) = 0$  and the relation  $\lim_{\delta \to 0} \alpha^2(\delta) \int_0^\infty \frac{d(E_s, f_{\delta}, f_{\delta})}{(s + \alpha(\delta))^2} = 0$  implies

 $\lim_{\delta \to 0} \alpha(\delta) = 0$ . The function  $\alpha = \alpha(\delta)$  is a monotonically growing function of

 $\delta$  with  $\alpha(+0) = 0$ .

Let us prove that  $\lim_{\delta \to 0} ||u_{\delta} - y|| = 0$ , where  $u_{\delta} \coloneqq u_{\alpha(\delta),\delta}$ , and  $\alpha(\delta)$  solves Equation (13). By the definition of  $u_{\delta}$ , we get

$$\|Au_{\alpha}-f_{\delta}\|^{2}+\alpha(\delta)\|u_{\delta}\|^{2} \leq \|Ay-f_{\delta}\|^{2}+\alpha(\delta)\|y\|^{2}=\delta^{2}+\alpha(\delta)\|y\|^{2}.$$

Since  $||Au_{\alpha} - f_{\delta}||^2 = c^2 \delta^2 > \delta^2$ , it follows that  $||u_{\delta}|| \le ||y||$ . Thus  $u_{\delta} \dagger z$ , and, as in the proof of Theorem 2, we obtain z = y and  $\lim_{\delta \to 0} ||u_{\delta} - y|| = 0$ .

Theorem 4 is proved.

**Remark 2.** Theorems 1 - 4 are well known in the case of a bounded operator *A*.

If *A* is bounded, then a necessary condition for the minimum of the functional  $f(u) = ||Au - f||^2 + \alpha ||u||^2$  is the equation

$$A^*Au + \alpha u = A^*f. \tag{14}$$

Hence in this case conditions are required  $f \in D(A^*)$ .

If *A* is unbounded, then *f* does not necessarily belong to  $D(A^*)$ , so Equation (14) may have no sence. Therefore, some changes in the usual theory are necessary. The changes are given in this paper. We prove, among other things, that for any  $f \in Y$ , in particular for  $f \notin D(A^*)$ , the element  $u_{\alpha} = A^* (AA^* + \alpha I_Y)^{-1} f$  is well defined for any  $\alpha = \text{const} > 0$ , provided that *A* is a closed, linear, densely defined operator in Hilbert space (Theorem 1).

#### **3. Applications**

As a simple concrete example of this type of approximation, consider differentiation in  $H = L^2[0,1]$ .

We define the operator  $A: D(A) \subset H \to H$  as follows

$$Af = \frac{\mathrm{d}f}{\mathrm{d}x}, \, f \in D(A)$$

with  $D(A) = \{ f \in H : f \text{ is absolutely continuous on } [0,1] \text{ and } f'(x) \in H \}$ .

Then D(A) is dense in *H* since it contains the complete orthonormal set  $\{\sin n\pi x\}_{n=1}^{\infty}$ .

Clearly, A is a linear operator.

We show that A is a closed operator in Hilbert space H. Indeed, for suppose  $\{f_n\} \subset D(A)$  and  $f_n \to f$  and  $f'_n \to g$ , in each case the convergence being in the  $L^2[0,1]$  norm. Since

$$f_n(x) = f_n(0) + \int_0^x f_n'(t) \mathrm{d}t,$$

we see that the sequence of constant functions  $\{f_n(0)\}$  converges in  $L^2[0,1]$  and hence the numerical sequence  $\{f_n(0)\}$  converges to some real number *C*.

Now define  $h \in D(A)$  by  $h(x) = C + \int_0^x g(t) dt$ . Then, for any  $x \in [0,1]$ , we have by of the Cauchy-Schwarz inequality

$$|f_n(x) - h(x)| = |f_n(0) - C + \int_0^x (f'_n(t) - g(t)) dt|$$
  

$$\leq |f_n(0) - C| + \int_0^x |f'_n(t) - g(t)| dt$$
  

$$\leq |f_n(0) - C| + ||f'_n - g||$$

and hence  $f_n \to h$  uniformly. Therefore,  $f = h \in D(A)$  and Af = f' = h' = g, verifying that the operator A is closed, linear, densely defined in  $L^2[0,1]$ . Let

$$D^* = \{g \in D(A) : g(0) = g(1) = 0\}.$$

Then for  $f \in D(A)$  and  $g \in D^*$ , we have

$$\left\langle Af,g\right\rangle = \int_{0}^{1} f'(t)g(t)dt = f(t)g(t)\Big|_{0}^{1} - \int_{0}^{1} f(t)g'(t)dt = \left\langle f,-g'\right\rangle$$

Therefore  $D^* \subset D(A^*)$  and  $A^*g = -g'$ , for  $g \in D^*$ . On the other hand, if  $g \in D(A^*)$ , let  $g^* = A^*g$ . Then

$$\langle Af,g \rangle = \langle f,g^* \rangle$$

for all  $f \in D(A)$ . In particular, for  $f \equiv 1$ , we find that  $\int_0^1 g^*(t) dt = 0$ . Now let

$$h(t) = -\int_0^t g^*(s) \mathrm{d}s.$$

Then  $h \in D^*$  and  $A^*h = g^* = A^*g$  and hence  $h - g \in N(A^*)$ . Therefore,  $\langle Af, h - g \rangle = 0$ , for all  $f \in D(A)$ . But R(A) contains all continuous function and hence  $g = h \in D^*$ .

We conclude that

$$D(A^*) = D^*$$
, and  $A^*g = -g'$ .

According to Theorem 1, for any  $f \in Y = L^2[0,1]$ , the problem

$$F(u) = ||Au - f||^2 + \alpha ||u||^2 \to \min, \alpha = \text{const} > 0,$$

has a unique solution  $u_{\alpha} = A^* (AA^* + \alpha I)^{-1} f$ , where *I* is the identity operator on  $Y = L^2[0,1]$ .  $f \in Y = L^2[0,1]$  does not necessarily belong to  $D(A^*)$ .

It follows from Theorem 2, that if f = Ay,  $y \perp N(A)$  then

$$\lim_{\alpha \to 0} \|u_{\alpha} - y\| = 0, u_{\alpha} = A^* (AA^* + \alpha I)^{-1} f.$$

It follows from Theorem 3, that if  $||f_{\delta} - f|| \le \delta$ , f = Ay, and

$$F_{\delta}(u) = \|Au - f_{\delta}\|^{2} + \alpha \|u\|^{2} = \min,$$
(15)

then there exists a unique global minimier  $u_{\alpha,\delta}$  to Equation (15) and  $\lim_{\delta \to 0} ||u_{\delta} - y|| = 0$ , where  $u_{\delta} \coloneqq u_{\alpha(\delta),\delta}$  and  $\alpha(\delta)$  is properly chosen, in particular  $\lim_{\delta \to 0} \alpha(\delta) = 0$ .

It follows from Theorem 4, that the equation  $\vec{I}$ 

$$\left|Au_{\alpha,\delta} - f_{\delta}\right| = c\delta, c = \text{const} > 1, \left\|f_{\delta}\right\| > c\delta,$$

has a unique solution  $\alpha = \alpha(\delta) > 0$ ,  $\lim_{\delta \to 0} \alpha(\delta) = 0$ , and if  $u_{\delta} := u_{\alpha(\delta),\delta}$ , then  $\lim_{\delta \to 0} ||u_{\delta} - y|| = 0$ .

## **Conflicts of Interest**

The author declares no conflicts of interest regarding the publication of this paper.

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