

Study on Wave Field Characteristics and Imaging of Collapse Column in Three-Dimensional Detection with Love Channel Wave Reflected outside the Working Face

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Abstract

The safety accidents caused by collapse column water diversion occur frequently, which has great hidden danger to the safety production of coal mine. Limited by the space of underground, the detection of collapse column on the outside of working face has been a difficult problem. Based on this, numerical simulation and imaging research were carried out in this paper. The results indicate that when a seismic source near the roadway is excited, a part of seismic wave propagates along the roadway direction, namely direct P-wave, direct S-wave and direct Love channel wave. When the body waves and Love channel wave propagating to the outside of working face meet the interface of collapse column, the reflected Love channel wave and reflected body waves are generated. Reflection body waves and direct waves are mixed in time domain, which is difficult to identify in seismic records, while reflected Love channel wave whose amplitude is relatively strong. The reflected Love channel wave which has a large interval from other wave trains in the time domain is easily recognizable in seismic record, which makes it suitable for advanced detection of collapse column. The signal-to-noise ratio of X component is higher than that of Y component and Z component. According to the seismic records, polarization filtering was carried out to enhance the effective wave, which removed the interference waves, and the signal was migrated to get the position parameters of collapse column interface, which was basically consistent with the model position.

Keywords

Reflected Love Channel Wave, 3D Numerical Simulation, Collapse Column, Wave Field Characteristics, Migration Imaging

1. Introduction

Collapse column is a typical geological structure in coal mining in North and South China. Its formation is mainly related to tectonic fissure zone, fracture, groundwater activity, and karst [1]. Due to the frequent occurrence of safety accidents caused by collapse column conducting water, there exist huge hidden dangers to the safety production of coal mine [2]. Therefore, the detection of collapse column has been a hot topic. With the increase of coal mining depth, the accuracy of three-dimensional seismic exploration on the ground has been limited [3]. Seismic detection in coal mining is not affected by ground conditions and has the advantages of being close to the geological structure, less attenuation of the energy of seismic waves and high-frequency components and interference of seismic wave propagation path [4], and is then applied in structure detection of coal mine [5]. At the same time, there is a special geological body of coal seam in the coal mine. Therefore, channel wave detection is the preferred method of seismic detection [6].

Transmission channel wave method is the most typical method of collapse column detection [7]. When the source is excited in the coal seam, the presence of the collapse column will destroy the continuity of the coal seam, and the non-development of the channel wave is one of the signs of the existence of the collapse column [8]. In 2015, Wang Ji used transmission channel wave detection for in-face collapse column detection. Based on the channel wave energy attenuation coefficient for imaging research, the boundary position of the collapse column was circled and was relatively consistent with the actual results [9]. Li Guangyi *et al.* used channel wave seismic transmission method to detect the collapse column in field and circled the range of the collapse column, which effectively guided the actual production [10]. In 2019, Ma Xin *et al.* studied the collapse column of the coal mining work face detected by the transmission channel wave through numerical simulation [11].

Mason *et al.* conducted an experimental study on the detection of faults in working face using reflected channel wave in the Pye Hill coal mine. Buchanan proposed dynamic trace gathering (DTG) [12]. Buchanan then proposed dynamic gather stacking and adaptive delayed summation method [13]. Elsen and Schott conducted reflected channel wave experiments at several coal mines in Germany, including Patberg and Stein, and used polarization filtering and envelope superposition for imaging [14]. Hu *et al.* introduced reverse-time pre-stack elastic migration technology into the study of reflected channel wave, and formed the image of reflected wave by means of model data [15]. However,

relatively less research has been done on the detection of collapse column outside the working face.

Based on the above problems, this paper uses numerical simulation to study the detection of collapse column by using reflected Love channel wave outside the working face. The purpose of this study is to reveal the three-dimensional wave field characteristics of collapse column detection, and use feature waves for inverse imaging research, which provides theoretical guidance for the detection of collapse column in underground coal seam.

2. Principle of Channel Wave Detection and Imaging

2.1. Principle of Sidewall Reflected Channel Wave

The direct P-wave and S-wave are first received in seismic records, subsequently, the direct channel wave also propagates to the receivers and is received. This three direct wave groups are the most obvious. When there is structural development in the working face (there is a wave impedance interface), which generated reflected channel wave [16], and the detection diagram is shown in **Figure** 1. Therefore, the development and distribution of the internal structure of the working face are detected by reflected channel wave.

2.2. Principle of Polarization Migration Imaging

In a certain time window, the covariance matrix is formed according to the amplitude value set of spatial data points, and the eigenvalues and corresponding eigenvectors of the covariance matrix are solved. The eigenvector corresponding to the maximum eigenvalue must be in the maximum polarization direction. According to the particle polarization and the relationship between the principal polarization direction and the propagation path direction, the filtering parameters



Figure 1. Schematic diagram of reflected channel wave detection.

are set to separate the effective wave from the interference wave [17].

1) The constitution of covariance matrix

For three-component data acquisition, assume that there are m sampling points in the time window (t_1, t_2) , and the three-components on each receiving point correspond to X_i, Y_i, Z_i (representing the amplitude value of the sampling point, respectively), and their average values in the time window (t_1, t_2) are as follows:

$$N_x = \frac{1}{M} \sum_{i=M_1}^{M_2} X_i , \quad N_y = \frac{1}{M} \sum_{i=M_1}^{M_2} Y_i , \quad N_z = \frac{1}{M} \sum_{i=M_1}^{M_2} Z_i$$
(1)

where $(M_2 - M_1) \cdot \Delta t = t_2 - t_1$, $M = M_2 - M_1 + 1$, Δt is the sampling interval, and the above formula can be sorted into covariance matrix:

$$\frac{1}{M} \begin{bmatrix} \sum_{i=M_{1}}^{M_{2}} (X_{i} - N_{x}) (X_{i} - N_{x}), \sum_{i=M_{1}}^{M_{2}} (X_{i} - N_{x}) (Y_{i} - N_{y}), \sum_{i=M_{1}}^{M_{2}} (X_{i} - N_{x}) (Z_{i} - N_{z}), \\ \sum_{i=M_{1}}^{M_{2}} (Y_{i} - N_{y}) (X_{i} - N_{x}), \sum_{i=M_{1}}^{M_{2}} (Y_{i} - N_{y}) (Y_{i} - N_{y}), \sum_{i=M_{1}}^{M_{2}} (Y_{i} - N_{y}) (Z_{i} - N_{z}), \\ \sum_{i=M_{1}}^{M_{2}} (Z_{i} - N_{z}) (X_{i} - N_{x}), \sum_{i=M_{1}}^{M_{2}} (Z_{i} - N_{z}) (Y_{i} - N_{y}), \sum_{i=M_{1}}^{M_{2}} (Z_{i} - N_{z}) (Z_{i} - N_{z}), \end{bmatrix}$$
(2)

According to the covariance matrix, three eigenvalues, λ_1 , λ_2 and λ_3 can be obtained. Through these three eigenvalues, the axis of the ellipsoid composed of the particle vibration track can be determined. The principal eigenvector V_1 corresponding to the maximum eigenvalue λ_1 is the long axis direction of the ellipsoid, which is called the principal polarization direction.

2) Parameter setting and selection of polarization filter

According to the eigenvalues λ_1 , λ_2 and λ_3 obtained from the covariance matrix and the angle θ between the principal polarization direction and the propagation path direction, the polarization coefficient factor τ and the principal polarization direction factor φ are defined.

Polarization coefficient factor τ :

$$\tau = \frac{\left(1 - \frac{\lambda_2}{\lambda_1}\right)^2 + \left(1 - \frac{\lambda_3}{\lambda_1}\right)^2 + \left(\frac{\lambda_2}{\lambda_1} - \frac{\lambda_3}{\lambda_1}\right)^2}{2\left(1 + \frac{\lambda_2}{\lambda_1} + \frac{\lambda_3}{\lambda_1}\right)^2}$$
(3)

principal polarization direction factor φ :

$$\varphi = \begin{cases} \cos\theta, & \text{P-wave} \\ \sin\theta, & \text{S-wave} \end{cases}$$
(4)

The filtering function is set as follows:

$$F(t) = \tau^{p}(t)\varphi^{q}(t)$$
(5)

where, the indexes P and Q are the weighted coefficients.

The original seismic record is the arrival time information about the spatial position and reflection phase of the excitation receiver. Generally, the reflection

path information in these original records cannot directly represent the actual location of the underground geological body, so the subsequent migration and homing processing is needed [18].

If the S-coordinate of the source's point is (x_s, y_s, z_s) , the R-coordinate of the receiver's point is (x_R, y_R, z_R) , and the G-coordinate of the reflection point is (x_G, y_G, z_G) , then the ellipsoid equation formed by the source-receiver and the travel path of the reflected signal is as follows:

$$\frac{x_G^2}{L_G^2 - 4z_S^2} + \frac{y_G^2}{L_G^2 - 4z_S^2} + \frac{z_G^2}{L_G^2} = \frac{1}{4}$$
(6)

According to the principle of pre-stack diffraction migration, each source-receiver can form an ellipsoid according to the travel length of seismic ray. Due to the multiple coverage technology in the actual detection, there are many pairs of source and check relations. At this time, each pair of source and check relations can construct the ellipsoid equation, and all the ellipsoid equations are combined to obtain the common section, which is the position where the reflection signal is generated.

3. Numerical Modeling and Analysis

3.1. Numerical Modeling

According to the result of the three-dimensional seismic exploration showed that there may be a large collapse column about 90 m in diameter at the distance of 60m from the outside of a working face in actual engineering project. However, the surface terrain is complex and the fluctuations are large, which caused large restriction and low reliability of the three-dimensional seismic detection. In order to ensure the safety of the working face, detection work must be carried out in the coal mine. As the collapse column is located outside the boundary of the working face, there is only one roadway around it. Limited by the construction conditions, the working face transmission detection cannot be done, therefore, only the reflected channel wave detection is a suitable choice.

Taking into account the field conditions, a three-dimensional simulation was conducted based on high-order staggered-grid finite difference method [19], and a three-dimensional model of the collapse column containing the roadway was designed, as is shown in **Figure 2**, and the elastic parameters of the collapse column model are shown in **Table 1**. The physical parameters of this model meet the excitation conditions of Love channel wave [20]. A three-dimensional spatial coordinate system was established, X direction is vertical to the survey line, that is, the direction of coal seam side; Y direction is parallel to the survey line, that is, the direction pointing to the fault; Z direction is vertical downward, that is, the direction pointing to the floor. The size of the model in the X, Y and Z directions is 200 m, 400 m, 200 m, respectively. The width of air roadway is 4m, and the height is 5 m. The central position was located at the coordinate point 0 m, 2.5 m and 97.5 m in X, Y, and Z direction. The length is 400 m and the coal thickness is 2.5 m. The collapse column model boundary is located in



Figure 2. Numerical model. (a) 3D-model diagram; (b) top view; (c) left view; (d) front view.

Table 1. Model parameters.

Medium	$V_p/(\mathrm{m}\cdot\mathrm{s}^{-1})$	$V_{s'}/({ m m}\cdot{ m s}^{-1})$	$ ho/(\mathrm{kg}\cdot\mathrm{m}^{-3})$
Surrounding rock	4100	2369	2365
Coal seam	1800	1050	1300
Air roadway	340	0	1.29
Collapse column	2700	1560	2200

the X direction 302 m to 390 m, Y direction 67 m to 187 m, Z direction 85 m to 140 m. The size of the model grid is $\Delta x = \Delta y = \Delta z = 0.2$ m.

The observation system was arranged with 25 three-component receivers and the offset was 10 m. The receivers are arranged in a straight line in the direction of the collapse column. The position of NO1 receiver was located at the coordinate point 5 m, 5 m and 98 m in X, Y, and Z direction. There are 3 sources totally, and the position of source S1 was located at the coordinate point 390 m, 5 m and 98 m in X, Y, and Z direction of source S2 was located at the coordinate point 350 m, 5 m and 98 m in X, Y, and Z direction. The position of source S3 was located at the coordinate point 300 m, 5 m and 98 m in X, Y, and Z direction. The position of source S3 was located at the coordinate point 300 m, 5 m and 98 m in X, Y, and Z direction. The numerical simulation is carried out using X-direction concentration source with a source frequency of 120 Hz and a sampling frequency of 10 kHz. The model boundary uses PML absorption boundary [21], and the free interface of roadway is processed by HA method to reduce the interference of artificial boundary [22].

3.2. Seismic Record

Figures 3(a)-(c) respectively show the X component seismic records of S1 source, S2 source and S3 source. As is shown, Event 1, Event 2, Event 3 stand for



Figure 3. Seismic record of X component, (a) S1 source seismic record, (b) S2 source seismic record, and (c) S3 source seismic record.

direct P-wave, direct S-wave, and direct channel wave. When the seismic wave propagates in the impedance interface of collapse column, it reflects back. Hence, Event 4, Event 5, and Event 6 stand for the reflected P-wave, reflected S-wave, and reflected channel wave. The seismic records of Y and Z components are shown in **Figure 4**.

Through comparison, it shows that the signal-to-noise ratio of the X component is higher than that of the Z component and Z component. Love channel wave is formed by SH wave interference [23], and SH wave is relatively developed in X component, so the energy of Love channel wave in X component is relatively stronger. At the same time, the reflected wave of S2 source is distinguished obviously, and the hyperbola is obvious. The signal-to-noise ratio is relatively higher.

3.3. Analysis of Three Dimensional Snapshots of Wave Field

According to the seismic records, the signal-to-noise ratio of X component is higher than that of Y component and Z component. Therefore, the wave field snapshot of X component of S2 source is selected to analyze the characteristics of seismic waves. Figure 5 shows the wave field snapshots of X component at 30 ms, 60 ms and 70 ms. At 30 ms, wave front 1, wave front 2 and wave front 3 are direct P-wave, direct S-wave and direct Love channel wave. when the seismic waves propagate to 60 ms, seismic waves meet the wave impedance interface of collapse column, and part of seismic waves propagate into the collapse column, wave front 4 is transmission P-wave, wave front 5 is transmission S-wave, and part of seismic wave generates reflected waves, wave front 6 is reflected P-wave propagating in the direction of roadway, and wave front 7 is reflected S-wave. At 70 ms, when the Love channel wave propagates to the impedance interface of the collapse column, a part of the Love channel wave propagates into the collapse column. Because there is no coal seam in the collapse column, the Love channel wave is converted into SH wave [24], and continues to propagate along the collapse column. As shown in wave front 8, wave front 9 is the reflected Love channel wave.

Figure 6 shows the wave field snapshots of X component at 90 ms, 100 ms



Figure 4. Seismic records, (a) shows the Y-component seismic record of S1 source, (b) shows the Y-component seismic record of S2 source, (c) shows the Y-component seismic record of S3 source; (d) shows the z-component seismic record of S1 source, (e) shows the z-component seismic record of S2 source, (f) shows the z-component seismic record of S3 source.



Figure 5. 3D wave field snapshot, (a) 30 ms wave field snapshot, (b) 60 ms wave field snapshot, (c) 70 ms wave field snapshot.



Figure 6. 3D wave field snapshot, (a) 90 ms time wave field snapshot, (b) 100 ms time wave field snapshot, (c) 120 ms wave field snapshot.

and 120 ms. When the seismic waves propagate to 90 ms, the reflected body waves and the direct waves are mixed, reflected S-wave and reflected Love channel wave, as shown in wavefront 8 and wavefront 9. The wave field snapshots at 100 ms and 120 ms are similar to that at 90 ms, but with the increase of propagation distance, reflected S-wave is mixed with direct Love channel wave.

To sum up, the source is excited near the roadway, the direct P-wave, S-wave and slot wave propagate along the roadway and are received by the receivers. When P-wave, S-wave and Love channel wave propagate to the collapse column interface, which generate reflected P-wave, reflected S-wave, and Love channel wave. But some reflected P-wave and reflected S-wave are easily mixed with direct channel wave, so it is difficult to distinguish them from the seismic record. Therefore, the reflection trough is reflected in the time domain. The wave is the characteristic wave of collapse column.

4. Research on Inversion Imaging

The Y-component signal with the highest signal-to-noise ratio is used for migration imaging. Firstly, the original signal is preprocessed. After polarization filtering, the interference waves are removed and the effective wave is enhanced. The processing result is shown in **Figure 7**. The reflected Love channel wave is shown as event 1, and the reflected Love channel wave signal is enhanced.

The velocity of Love channel wave is 1.1 km/s, and the result of migration imaging is shown in **Figure 8**, which is basically consistent with the forward model. Due to the limitation of the space of the roadway, only part of the collapse column boundary can be detected. The experimental results provide theoretical guidance for the next field test.

5. Discussions

5.1. Comparison between Seismic Detection Method of Channel Wave and Body Waves



In seismic detection of working face by using the reflected body waves and the





Figure 8. Migration imaging.

reflected channel wave, when the source is excited in the coal seam, most of the energy will be confined in the coal seam [25], so the body waves energy is relatively weak, and the channel wave energy is relatively strong. At the same time, in the conventional reflection detection, the reflected body waves are easy to mix with the channel wave, which reduces the signal-to-noise ratio of seismic records. Relatively speaking, the energy of channel wave is strong and the wave train is wide, which is distinguished from other wave trains in time domain. Meanwhile, the high frequency signal of the channel wave is rich. Compared with the body waves, the imaging resolution of the channel wave is higher.

5.2. Comparison with Detection Method of Rayleigh Channel Wave and Love Channel Wave

Channel waves can be divided into two types: Love channel waves and Rayleigh channel waves. The development condition of Love channel wave is relatively simple, but the formation condition of a Rayleigh channel wave is quite strict [26]. When the parameters of surrounding rock and coal seam do not meet the excitation conditions of Rayleigh channel wave, effective signals cannot be collected. The generation condition of Love channel wave (perpendicular to coal wall) is simple and more universal. From the perspective of actual construction, it is easier to operate the exciting and receiving in the left and right sides of the coal roadway than in the roof and floor.

6. Conclusions

The following conclusions are obtained through numerical simulation:

1) The three-dimensional numerical simulation of the collapse column model on the outside of the working face shows that the reflected Love channel wave's amplitude is relatively strong. The Love wave which has a large interval from other wave trains in the time domain is easily recognizable in seismic record. The signal-to-noise ratio of X component is higher than that of Y component and Z component. 2) When a seismic source near the roadway is excited, a part of seismic wave propagates along the roadway direction, namely direct P-wave, direct S-wave and direct Love channel wave. When the body waves and Love channel wave propagating to the outside of working face meet the interface of collapse column, the reflected Love channel wave and reflected body waves are generated. Reflection body waves and direct waves are mixed in time domain, which is difficult to identify in seismic records, but the reflected Love channel wave is easy to identify on seismic records due to the large interval other wave trains in time domain. The reflected Love channel wave is a characteristic wave existing at the interface of collapse column.

3) According to the seismic records, polarization filtering is carried out to enhance the effective wave, remove the interference waves, which removes the interference wave, and the signal is migrated to get the position parameters of collapse column interface, which is basically consistent with the model position. The research results provide theoretical guidance for the next step of field test.

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Conflicts of Interest

The authors declare no conflicts of interest regarding the publication of this paper.

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