Potential Power of the Pyramidal Structure II

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ABSTRACT

Research on "pyramid power" began in the late 1930s. To date, many documents on "pyramid power" have been published. We have been conducting scientific research on the unexplained "power" of a pyramidal structure (PS) since October 2007. The research focuses on the detection of a non-contact effect of the unexplained "power" of the PS on biosensors (i.e., edible cucumber sections of Cucumis sativus "white spine type") placed at the top of the PS. In this paper, in particular, we compared the non-contact effect of upper and lower biosensors placed in two layers on the PS apex, and we analyzed the difference of the non-contact effect due to the difference in the layers. The magnitude of the non-contact effect was represented by the calibrated psi index $\Psi_{(B-CAL)}$ calculated from gas concentrations emitted from the biosensors. A method to determine the presence or absence of the non-contact effect by analyzing the gas concentrations was developed by the International Research Institute (IRI). $\Psi_{(E-CAL)}$, which represents the magnitude of the non-contact effect, was the average value of the respective non-contact effect of the upper and lower biosensors stacked in two layers on the PS apex. We conducted the analysis on the assumption that the non-contact effect on the upper and lower biosensors might be different. Therefore, we considered that upper and lower biosensor calibration was required for $\Psi_{(E-CAL)}$, and we introduced a new calibrated psi index $\Psi_{(E-CAL)Layer}$. Scientifically rigorous experiments to date have detected $\Psi_{(E-CAL)}$ with statistical significance and have demonstrated potential power of the PS ($p = 6.0 \times 10^{-3}$; Welch's t-test, two-tails, the following p values are also the Welch's t-test values). Based on data demonstrating the potential power of the PS, we analyzed the non-contact effects on the upper and lower biosensors of the PS apex. We obtained a surprising result that the non-contact effect on the upper biosensors (farther from the PS) was larger than that on the lower biosensors (closer to the PS) ($p = 4.0 \times 10^{-7}$). This suggested that the characteristic of the potential power of the PS, which is considered to exist near the PS apex, is distinctive. We also found that the non-contact effect due to the potential power of the PS varies with the season, and is large in summer and small in winter. In our discussion, we proposed a model that could theoretically explain the experimental results that the non-contact effect on the upper biosensors at the PS apex is larger than the lower biosensors. In proposing this model, we assumed that there were two different types of potential power at the PS apex and that the biosensors had two different gas-generating reactions. In a simulation using the model, the experimental results were well approximated in which the non-contact effect on the biosensors differs depending on the difference between the upper and lower layers. The results of this paper are the world's first to prove aspects of the "pyramid power" through scientifically rigorous experiments and analysis. These results will become a new field of science in the future, and their broad applications are expected.

1. INTRODUCTION

In the late 1930s, the Frenchman Antoine Bovis found a naturally mummified small animal in the Great Pyramid of Giza. This was the beginning of research on a so-called "pyramid power". To date, many documents on the "pyramid power" have been published [1-18]. Among them, some made a scale model of the large pyramid of Giza and conducted experiments [1-4, 8, 12, 18], one book tried to elucidate unexplained functions of the pyramid using mathematical formulas [17], and another acquired patent information [15]. However, scientific research papers published in academic journals are rare [19, 20]. On the other hand, it is true that there are documents that deny the existence of the "pyramid power" as pseudo-science [21-24]. The grounds for denying the "pyramid power" are that experiments did not provide sufficiently statistical significance, and that there was no scientific theory to understand the phenomenon.

We have been studying unexplained "power" of a pyramidal structure (PS) using a biosensor (edible cucumber sections: *Cucumis sativus* "white spine type") since October 2007. Scientifically rigorous experiments and analyzes demonstrated the existence of an unexplained "power" of the PS (an unexplained function of the PS) with statistically very high significance. The results of our research on the PS have been published as seven original papers [25-31], two research summaries [32, 33], and one chapter in a book [34].

In experiments using the PS, we performed two types of experiments with different conditions as follows.

Experiment 1: An experiment conducted in a state where the PS and a human (a test subject) were related.

Experiment 2: An experiment conducted in a state where the PS and a human (a test subject) were not related.

Experiment 1 is the experiment that was conducted from several hours before meditating to 20 days after meditation when the test subject meditated (Hemi-Sync[®] [35]) within the PS. Experiment 1 suggested the existence of two unexplained energies of human origin (force types I and II) [31, 33]. From Experiment 1, the following two results were obtained.

1) When the PS and a human unconsciousness (force type I) were related.

A change in the non-contact effect, which seems to correspond to an unconscious change, was detected during the transition from a sleep state to an awake state of a human (the test subject) 6 km or more away (1% significance) [30, 33].

2) When the PS and the effect of a human (the test subject) meditating in the PS (force type II) were related.

The non-contact effect with delay was detected over a dozen days after meditation ($p = 3.5 \times 10^{-6}$; Welch's t-test, two-tails, the following *p* values are also the Welch's t-test values) [26, 27, 32, 33]. The characteristics of the non-contact effect with delay could be very well approximated by theoretical curves calculated from a model of transient response phenomena in control theory [26, 32, 33].

As a result of Experiment 2, the non-contact effect on the biosensors placed at the PS apex was detected with statistical significance ($p = 6.0 \times 10^{-3}$), demonstrating the existence of the potential power of the PS [31]. It was also found that the non-contact effect due to the potential power of the PS varies with the season, and is large in summer and small in winter.

Until now, the non-contact effect on the biosensors has been expressed as the calibrated psi index $\Psi_{(E-CAL)}$ [31, 34]. $\Psi_{(E-CAL)}$ is the average value of the non-contact effect values $\Psi_{1(E-CAL)}$ and $\Psi_{2(E-CAL)}$ of the upper and lower biosensors placed on the PS apex in two layers. In this paper, based on the experimental data obtained in Experiment 2, the non-contact effect of each of the upper and lower biosensors placed at the PS apex was compared. Therefore, we considered that upper and lower sensor calibration is required for $\Psi_{(E-CAL)}$, and we introduced a new calibrated psi index $\Psi_{(E-CAL)Layer}$. The reason that the introduction of $\Psi_{(E-CAL)Laver}$ became possible was that sufficient experimental data were obtained (n = 468), and analysis that separated the upper and lower layers became possible. A surprising result was obtained that the non-contact effect on the upper biosensors (farther from the PS) was larger than that of the lower biosensors (closer to the PS) ($p = 4.0 \times 10^{-7}$). In other words, it became clear that the potential power of the PS has different effects on the upper and lower biosensors. In order to understand this phenomenon quantitatively, we improved the model proposed in our previous paper [31] and proposed a new model considering the distribution characteristics of potential power of the PS. In a simulation using this new model, we were able to approximate the experimental results in which the non-contact effect differs between the upper and lower layers. The discovery of the potential power of the PS obtained through scientifically rigorous experiments and analysis is the world's first research to demonstrate the "pyramid power". This result will become a new field of science in the future, and broad applications are expected.

2. EXPERIMENT

2.1. Pyramidal Structure (PS)

Figure 1(a) showed the PS used in the present experiment. The PS was a square pyramid with a height of 107 cm, a ridgeline length of 170 cm and a base length of 188 cm. The angle (tilt angle) between the bottom and the side of the PS was 49.1°. The base of the PS was raised by four tripods to a height of 73 cm from the floor. The frame of the PS was made of four aluminum pipes (2 cm diameter, 0.36 cm thick pipe wall). Each side had a Sierpinski triangle pattern and it consisted of aluminum plates (0.3 mm thick). At the top of the PS, a Faraday cage for electrostatic shielding of the biosensors was placed. A calibration control point was set up 8 m away from the PS [25, 34]. The PS is a simple and static structure which does not have any mechanically movable parts nor does it have a supply of known energy.

2.2. Detection of Unexplained "Power" (Non-Contact Effect) of the PS

To demonstrate the "pyramid power" of the PS, we examined the presence or absence of the noncontact effect on the biosensors (cucumber fruit sections). To detect the non-contact effect, the gas concentration generated by the gas production reaction of the cucumber sections was measured. Samples were prepared according to a simultaneous calibration technique (SCAT) [36] to prepare homogeneous biosensors (Figure 1(b)). The detection method the non-contact effect by analyzing the gas concentrations released from the biosensors was researched and developed by the International Research Institute (IRI), and we used it previously to successfully detect a healer's non-contact effect and a wave like bio-field around the healer [37-39].



Figure 1. Pyramidal structure used in the experiment, biosensors and its installation status. (a) shows the pyramidal structure (PS) used in the experiment. (b) Left, biosensors prepared according to SCAT; right, placement of samples on the PS apex and calibration control point for the PS. (c) Left, placement of samples at the PS apex; right, placement of samples at the PS apex and calibration control point (pattern diagram).

 G_{E1} and G_{E2} , the experimental samples of Pair 1 and Pair 2 in Figure 1(b), were placed in covered Petri dishes at the PS apex in two layers. And G_{C1} and G_{C2} , the control samples of Pair 1 and Pair 2, and G_{E3} , G_{E4} , G_{C3} and G_{C4} , the control samples of Pair 3 and Pair 4 were similarly placed at the calibration control point 8 m away from the PS, also in two layers. For G_E and G_O the larger subscript number was the upper layer (Figure 1(c)). The biosensors were kept in place for 30 minutes. G_E and G_C were the same cut section, but the direction of the cutting was different. G_E was cut in the same direction as the cucumber growth axis, while G_c was cut in the opposite direction. Previous experiments demonstrated that the gas concentration varies depending on the direction of the cut section, and $G_E < G_C$ [29]. The center point of the bottom of the Petri dish of G_{E} placed at the PS apex coincided with the extension of the center of the four aluminum pipes near the PS apex (Figure 1(c)). After setting the covered Petri dish there for 30 minutes, the Petri dish was removed from the PS and its lid was taken off. Each Petri dish was then placed in a closed container with a volume of 2.2 liters and the containers were placed in a temperature-controlled room to be stored side by side on shelves for each pair. Storage time was 24 h - 48 h. After storage, the gas concentrations released from the cucumber sections were measured. Gas detection tubes (Ethyl acetate detector tube 141 L: Gastech, Japan) and a gas sampling pump (GV-100: Gastech, Japan) were used to measure the gas concentrations.

2.3. Non-Contact Effect Magnitude Psi Index Ψ

To examine the non-contact effect on the biosensors, we introduced a psi index Ψ that quantifies the magnitude of the non-contact effect [31, 34]. Ψ was calculated by Equation (1) using the measured gas concentrations. We considered that the unexplained "power" of the PS has a very small effect on changes in gas concentrations. Then, the non-contact effect may be buried in noise, making its detection difficult. The reason was that the gas generation reaction of the biosensors was considered to react sensitively due to factors such as differences between individual cucumbers and environmental conditions. Therefore, in order to minimize the noise displacement, a paired sample method (Figure 1(b)) was used in which G_E and G_C were compared as a pair. Ψ is 100 times the natural logarithm of the ratio calculated for the gas concentrations of each pair. The relationship between the *J* value we used previously and Ψ was $\Psi = 100 J$ [40].

$$\begin{split} \Psi_{1} &= 100 \ln \left(G_{E1} / G_{C1} \right), \\ \Psi_{2} &= 100 \ln \left(G_{E2} / G_{C2} \right), \\ \Psi_{3} &= 100 \ln \left(G_{E3} / G_{C3} \right), \\ \Psi_{4} &= 100 \ln \left(G_{E4} / G_{C4} \right). \end{split}$$
(1)

In Equation (1), $G_{E1} - G_{E4}$ and $G_{C1} - G_{C4}$ were gas concentrations (ppm) measured from the biosensors shown in **Figure 1(b)**. $\Psi_1 - \Psi_4$ were the psi index values before calibration. G_{E3} , G_{C3} , G_{E4} , and G_{C4} were biosensors placed at the calibration control point, and G_E and G_C differed only in the direction of the cut section. Therefore, it was considered that the influence of the difference in the direction of the cut section of cucumber was detected from Ψ_3 and Ψ_4 . From Ψ_1 and Ψ_2 , it was considered that two effects were detected, the effect of the difference in the cutting direction and the effect of the difference in the placement (the PS apex and the calibration control point). The results of subtracting the average values of Ψ_3 and Ψ_4 from Ψ_1 and Ψ_2 are $\Psi_{1(E-CAL)}$ and $\Psi_{2(E-CAL)}$. $\Psi_{1(E-CAL)}$ and $\Psi_{2(E-CAL)}$ calibrated against environmental factors such as temperature, humidity, atmospheric pressure, geomagnetism, etc., and also calibrated against the cutting direction. Therefore, the calibrated psi indices, $\Psi_{1(E-CAL)}$ and $\Psi_{2(E-CAL)}$, were considered to be the results (non-contact effect by the PS) reflecting only the effect of the unexplained "power" of the PS.

$$\begin{split} \Psi_{1(E-CAL)} &= \Psi_1 - (\Psi_3 + \Psi_4)/2, \\ \Psi_{2(E-CAL)} &= \Psi_2 - (\Psi_3 + \Psi_4)/2, \\ \Psi_{3(C-CAL)} &= \Psi_3 - (\Psi_3 + \Psi_4)/2, \\ \Psi_{4(C-CAL)} &= \Psi_4 - (\Psi_3 + \Psi_4)/2. \end{split}$$
(2)

Finally, the calibrated psi index $\Psi_{(E-CAL)}$, the non-contact effect on the biosensors, was obtained from the average of the lower and upper calibrated psi indices $\Psi_{1(E-CAL)}$ and $\Psi_{2(E-CAL)}$.

$$\Psi_{(\text{E-CAL})} = \left(\Psi_{1(\text{E-CAL})} + \Psi_{2(\text{E-CAL})}\right) / 2.$$
(3)

The purpose of this paper was to analyze the difference of the non-contact effect on the upper and lower biosensors placed in two layers. Therefore, $\Psi_{(E-CAL)Layer}$ was introduced, which allows calibration of the two stacked upper and lower layers.

$$\Psi_{1(E-CAL)Layer1} = \Psi_{1(E-CAL)} - \Psi_{3(C-CAL)} = \Psi_{1} - \Psi_{3},$$

$$\Psi_{2(E-CAL)Layer2} = \Psi_{2(E-CAL)} - \Psi_{4(C-CAL)} = \Psi_{2} - \Psi_{4}.$$
(4)

Here, $\Psi_{(E-CAL)LayerAve}$, which is the average value of $\Psi_{1(E-CAL)Layer1}$ and $\Psi_{2(E-CAL)Layer2}$, coincided with $\Psi_{(E-CAL)}$.

$$\Psi_{(\text{E-CAL})\text{LayerAve}} = \left(\Psi_{1(\text{E-CAL})\text{Layer1}} + \Psi_{2(\text{E-CAL})\text{Layer2}}\right) / 2$$

$$= \left(\Psi_{1(\text{E-CAL})} + \Psi_{2(\text{E-CAL})}\right) / 2 = \Psi_{(\text{E-CAL})}.$$
(5)

3. EXPERIMENTAL AND ANALYTICAL RESULTS

In this paper, in order to verify the potential power of the PS, the data obtained in Experiment 2 described in "1. Introduction" were analyzed (n = 468). Experiment 2 was not only an "experiment performed without the test subject in the PS", but also an experiment that met two conditions (Conditions 1 and 2). The reason why these conditions were added is described below. If Conditions 1 and 2 were not satisfied, we had found that the effect of the PS on the biosensors was not the effect of the potential power of the PS but the effect of "the state in which the PS and the test subject were related" [26, 27, 30, 32, 33].

Figure 2 shows the average gas concentration released from the biosensors (n = 468). In the figure, we observed no significant difference between the average gas concentrations of all the biosensors $G_{E1} - G_{E4}$ and $G_{C1} - G_{C4}$ (p = 0.088). However, the following possibilities 1) - 4) were considered. 1) At the PS apex, the gas concentration of the biosensors placed in the upper layer (G_{E2}) was higher than that in the lower layer (G_{E1}). 2) Conversely, at the calibration control point, the gas concentrations of the biosensors placed in the upper layer (G_{E4} , G_{C2} , G_{C4}) were lower than those in the lower layer (G_{E3} , G_{C1} , G_{C3}). 3) When the experimental sample $G_{E1} - G_{E4}$ and the control sample $G_{C1} - G_{C4}$ were compared, the difference in gas concentration due to the layer was larger in $G_{E1} - G_{E4}$ than in $G_{C1} - G_{C4}$. 4) In the experimental samples, the



Figure 2. Average gas concentration emitted from the biosensors. The red circles indicate the average gas concentrations of the biosensors G_{E1} and G_{E2} placed at the PS apex. The blue circles indicate the average gas concentrations of the biosensors G_{E3} , G_{E4} and $G_{C1} - G_{C4}$ placed at the calibration control point. The results of the two stacked biosensors are connected by dotted lines. All error bars show the 99% confidence interval.

difference in gas concentration due to the difference in layer was reversed between G_{E1} and G_{E2} at the PS apex and G_{E3} and G_{E4} at the calibration control point. 5) In the control samples, G_{C1} , G_{C2} , G_{C3} and G_{C4} at the calibration control point showed almost equal changes in gas concentration due to the difference in the layer. From 1) - 5), it was considered that the biosensors G_{E1} and G_{E2} at the PS apex showed an abnormal reaction as compared with the biosensors at the calibration control point.

Figure 3 shows a scatter plot (n = 468) to determine whether there was a correlation between the gas concentrations emitted from the biosensors stacked in two layers, upper and lower. It was concluded that the correlation coefficient of gas concentration between the two layered biosensors was about 0.7 at both the PS apex and the calibration control point, indicating a positive correlation.

Figure 4(a) shows the sum of the gas concentrations of the upper and lower biosensors in two layers.



Figure 3. The scatter plot of gas concentration of the biosensors placed in two layers, upper and lower. The vertical axis shows the results of the upper layer biosensors and the horizontal axis shows the results of the lower layer biosensors. (a) shows the results of the biosensors placed at the PS apex. (b)-(d) show the results of the biosensors placed at the calibration control point. The numerical value at the upper left of each graph is the correlation coefficient. The lower-right part of each graph shows the first-order approximation fitting line and the coefficient of determination R^2 .



Figure 4. Sum and ratio of the gas concentrations. (a) The sum and (b) the ratio of the gas concentrations of the upper and lower biosensors in a two-layered biosensor. All error bars show the 99% confidence interval.

From an analysis of variance (ANOVA), p = 0.45 and no significant difference was observed. However, different gas concentrations ($G_E < G_C$) were obtained depending on the direction of the axis of the cut section of the cucumbers [29]. The experimental samples $(G_{E1} + G_{E2})$ and $(G_{E3} + G_{E4})$ were almost the same, but the control samples tended to be in the order $(G_{C1} + G_{C2}) < (G_{C3} + G_{C4})$. The following was considered as the reason for this order despite being placed at the calibration control point and having the same axial direction for cutting. In other words, we considered that the effect of the PS apex did not appear directly on the biosensors G_{E1} and G_{E2} placed at the PS apex, rather it appeared on the biosensor pair G_{C1} and G_{C2} . A similar phenomenon has been seen in other experimental reports [39, 41]. Figure 4(b) shows the gas concentration ratio calculated by dividing the upper gas concentration by the lower one, taking the logarithm and multiplying by 100. This expression was similar to the psi index of Equation (1). For ANOVA, p = 5.2 × 10⁻⁶, and a significant difference was recognized. Tukey's test showed that $100\ln(G_{E2}/G_{E1})$ was abnormally large compared to the others. Figure 4 revealed the following findings. No significant difference was found in the sum of the gas concentrations of the biosensors placed on the upper and lower layers, but the ratio of the gas concentrations indicated that $100\ln(G_{E2}/G_{E1})$ was abnormally large. Therefore, it was considered that one or both G_{E1} and G_{E2} placed at the PS apex exhibited an abnormal change different from that when placed at the calibration control point.

Figure 5 shows the scatter diagram (n = 468) to determine whether or not there is a correlation between the gas concentrations of the biosensors of the pair shown in Figure 1(b). Figure 5(a) and Figure 5(b) include the results of G_{E1} or G_{E2} placed at the PS apex. Figure 5(c) and Figure 5(d) include the results of the biosensors placed at the calibration control point. All the correlation coefficients showed a positive correlation of about 0.8. Therefore, it was found that the correlation coefficient between the paired biosensors was larger than the correlation coefficient between the two layered biosensors in Figure 3.

Figure 6(a) shows the average (n = 468) of the sum of the gas concentrations emitted from the



Figure 5. The scatter plot of gas concentration of the biosensors between pairs. The vertical axis indicates results of the experimental samples (G_E) , and the horizontal axis indicates results of the control samples (G_C) . (a) and (b) show the results including G_{E1} and G_{E2} placed at the PS apex. (c) and (d) show the results of the biosensors on the calibration control point. The numerical value at the upper left of each graph is the correlation coefficient. The lower-right part of each graph shows the first-order approximation fitting line and the coefficient of determination R^2 .

biosensors of the pair. For ANOVA, p = 0.57, and no significant difference was observed. Although there was no significant difference, when $(G_{E3} + G_{C3})$ and $(G_{E4} + G_{C4})$ placed at the calibration control point were compared, there was a tendency that $(G_{E3} + G_{C3}) > (G_{E4} + G_{C4})$. The difference between $(G_{E3} + G_{C3})$ and $(G_{E4} + G_{C4})$ was only the difference between the respective upper and lower layers. Therefore, at the calibration reference point, it was suggested that the gas concentration of the lower biosensors was higher than that of the upper biosensors. Atmospheric pressure was considered as one of the causes. On the other hand, when $(G_{E1} + G_{C1})$ and $(G_{E2} + G_{C2})$ including the biosensors G_{E1} and G_{E2} placed at the PS apex were compared, the opposite tendency was shown. Similar to the results of Figure 2 and Figure 4(b), the following was found from the results of Figure 6(a). G_{E1} and G_{E2} placed at the PS apex were abnormal compared to G_{E3} , G_{E4} and $G_{C1} - G_{C4}$ at the calibration control point. However, it was not possible to determine



Figure 6. Sum of gas concentration of paired biosensors and psi index $\Psi_1 - \Psi_4$. (a) shows the average of the sum of the gas concentrations of the biosensors in the pair shown in Figure 1(b). (b) shows the psi index $\Psi_1 - \Psi_4$ calculated by Equation (1). All error bars show the 99% confidence interval.

whether the abnormality was with G_{E1} or G_{E2} , or both. Therefore, we tried to identify them separately by calculating the psi index $\Psi_1 - \Psi_4$ (Figure 6(b); the vertical axis is the magnitude of the psi index, and the horizontal axis is the psi index $\Psi_1 - \Psi_4$ before the calibration calculation by Equation (1)). For ANOVA, a significant difference was obtained for $\Psi_1 - \Psi_4$ ($p = 9.3 \times 10^{-6}$). Among $\Psi_1 - \Psi_4$ values, only Ψ_2 was positive and the others were negative. There was no significant difference between Ψ_1 , Ψ_3 and Ψ_4 . Therefore, Ψ_2 was considered to indicate an abnormal value. Since G_{E2} was included in the formula of Ψ_2 , we concluded that G_{E2} placed at the PS apex showed an abnormal value different from other biosensors. However, there was no significant difference between Ψ_1 , Ψ_3 and Ψ_4 , but it seemed that there was a difference between Ψ_3 and Ψ_4 . The cause was thought to be the result of the difference due to the layer between the pairs, as pointed out in the explanation of Figure 6(a).

Figure 7(a) and **Figure 7(b)** show the moving average (window size is 180 days) of psi index $\Psi_1 - \Psi_4$. The horizontal axis indicates the dates which are values from 1 to 366 obtained by starting at 1 and counting from January 1 of each year in which the experiment was conducted. The dates analyzed in this paper were obtained from experiments between July 2010 and September 2017. Using the same experimental data, we have already published one paper demonstrating the potential power of the PS [31]. In addition, papers on the unexplained functions of the PS [26, 27, 30] and papers on the characteristics of the biosensors [28, 29] were presented from the results of experiments conducted during the same period. From the results of the moving averages of Ψ_1 and Ψ_2 (Figure 7(a)), we found that $\Psi_1 < \Psi_2$ throughout the year, with the psi index increasing in summer and decreasing in winter. Summer was the period when the daytime was more than 12 hours and therefore from the day of the spring equinox to the day of the autumn equinox. When not a leap year, the former was March 20, and the value on the horizontal axis, 81. Similarly,



Figure 7. Moving average of psi index $\Psi_1 - \Psi_4$. (a) and (b) are moving averages of the psi index $\Psi_1 - \Psi_4$ (window size is 180 days). The horizontal axis is the date (1-366). The solid line is the psi index calculated from the lower layer pair, and the dotted line is the psi index calculated from the upper layer pair.

the latter was September 23, and the value on the horizontal axis, 267. Winter was the period when the daytime was less than 12 hours. The numbers of summer data were n = 252 and for winter data, n = 216. In **Figure 7(b)**, the moving averages of Ψ_3 and Ψ_4 were both negative values, which could be understood from the result of $G_E < G_C$ [29]. The moving averages of Ψ_3 and Ψ_4 were considered to be almost constant throughout the year. In **Figure 7(a)**, $\Psi_1 < \Psi_2$ for the lower layer Ψ_1 and the upper layer Ψ_2 , whereas in **Figure 7(b)**, $\Psi_3 > \Psi_4$ for the lower layer Ψ_3 and the upper layer Ψ_4 . In other words, we found that the magnitude of the psi index showed the opposite tendency between **Figure 7(a)** and **Figure 7(b)**. Similar to the previous results, the results in **Figure 7** also showed that the PS apex is a space that gives a unique effect (non-contact effect) to the biosensors compared to the calibration control point. Based on the results of the calibration control point, we found that Ψ_1 tended to decrease in winter and Ψ_2 tended to increase in summer.

Figure 8(a) shows the scatter plot for Ψ_1 and Ψ_2 , and **Figure 8(b)** shows the scatter plot for Ψ_3 and Ψ_4 . It was found that both **Figure 8(a)** and **Figure 8(b)** had a positive correlation. As seen in **Figure 5**, the correlation between the gas concentrations of the pairs was about 0.8 in all cases, and the distribution was similar. In contrast, the following was found from the scatter plot of Ψ calculated from the ratio of the gas concentrations of the pair. The distributions of Ψ_1 and Ψ_2 that included the gas concentration at the PS apex and the distributions of Ψ_3 and Ψ_4 that included the gas concentration at the calibration control point were significantly different. The results in **Figure 8** also revealed that the PS apex was a space that showed an abnormal response to the biosensors compared to the calibration control point.

Figure 9 shows the difference in the non-contact effect due to the difference in layers for the biosensors



Figure 8. The scatter plot of psi index. (a) is a scatter plot of Ψ_1 and Ψ_2 . (b) is a scatter plot of Ψ_3 and Ψ_4 . The numerical value at the upper left of each graph is the correlation coefficient. The lower part of the graph shows the linear approximation fitting line and the coefficient of determination R².

placed at the PS apex (n = 468). Above, **Figure 6(b)** and **Figure 7(a)** suggested that the magnitude of the non-contact effect on the biosensors placed at the PS apex differs between the upper and lower layers. **Figure 9** shows in two ways the non-contact effect on the upper and lower biosensors located at the PS apex; that is, $\Psi_{(E-CAL)}$ and $\Psi_{(E-CAL)Layer}$ which can calibrate the difference between layers. The black circles show the average value of $\Psi_{1(E-CAL)Layer}$ and $\Psi_{2(E-CAL)}$ in Equation (2) ($p = 2.5 \times 10^{-5}$). The red squares show the average value of psi index which was calibrated for the difference in the layers in Equation (4)., $\Psi_{1(E-CAL)Layer1} = \Psi_1 - \Psi_3$ and $\Psi_{2(E-CAL)Layer2} = \Psi_2 - \Psi_4$ ($p = 4.0 \times 10^{-7}$). It was found that the $\Psi_{(E-CAL)Layer}$, which calibrated the layer difference, had a smaller p-value than $\Psi_{(E-CAL)}$. From these results, we concluded that it was necessary to use the $\Psi_{(E-CAL)Layer}$ that calibrated the difference between layers when analyzing the difference between the upper and lower layers of the non-contact effect on the biosensors placed at the PS apex.

Figure 10(a) shows the moving average (window size is 180 days) of $\Psi_{1(E-CAL)Layer1}$, $\Psi_{2(E-CAL)Layer2}$ and their average $\Psi_{(E-CAL)LayerAve}$. According to Figure 9, for the average value, $\Psi_{1(E-CAL)Layer1} < \Psi_{2(E-CAL)Layer2}$. And from Figure 10(a), the tendency of $\Psi_{1(E-CAL)Layer1} < \Psi_{2(E-CAL)Layer2}$ was seen throughout the year. At the PS apex, the non-contact effect on the upper biosensors was larger than on the lower biosensors. The $\Psi_{1(E-CAL)Layer1}$ and $\Psi_{2(E-CAL)Layer2}$ tended to increase in summer and decrease in winter. Figure 10(b) shows the scatter diagram of $\Psi_{1(E-CAL)Layer1}$ versus $\Psi_{2(E-CAL)Layer2}$. The correlation coefficient was 0.87, indicating a strong correlation.

Figure 11 shows the summer and winter data for $\Psi_1 - \Psi_4$ and $\Psi_{1(E-CAL)Layer1}$, $\Psi_{2(E-CAL)Layer2}$. Earlier, **Figure 6(b)** showed the annual average of $\Psi_1 - \Psi_4$, while **Figure 11(a)** shows the average of summer and winter values of $\Psi_1 - \Psi_4$. The number of data was n = 252 in summer (orange squares) and n = 216 in winter (black squares). Compared to the difference between summer and winter of Ψ_3 and Ψ_4 calculated only with the biosensors placed at the calibration control point, it was found that the difference between summer and winter of Ψ_1 and Ψ_2 including G_{E1} and G_{E2} placed at the PS apex was larger. This result was expected



Figure 9. The non-contact effect on the biosensors placed at the PS apex in two layers. The black circles are the average value of the calibrated psi indices $\Psi_{1(E-CAL)}$ and $\Psi_{2(E-CAL)}$ in Equation (2). The red squares are the average values of the psi index $\Psi_{1(E-CAL)Layer1} = \Psi_1 - \Psi_3$ and $\Psi_{2(E-CAL)Layer2} = \Psi_2 - \Psi_4$, which was calibrated for the difference in the layers in Equation (4). All error bars show the 99% confidence interval.

from Figure 7(a) and Figure 7(b). Although the reason is not clear, there was a tendency that $\Psi_3 > \Psi_4$ at the calibration control point. Figure 11(b) shows the summer and winter data of $\Psi_{1(E-CAL)Layer1}$ and $\Psi_{2(E-CAL)Layer2}$ with respect to the results of Figure 9. It turned out that summer and winter behaviors were the consequence of almost parallel movement.

4. DISCUSSION

4.1. Moving Average of the $\Psi_{(E-CAL)}$ and Proposal of "Model 1"

In our previous paper [31], we conducted the demonstration of the potential power of the PS under the condition that "the PS and a human (the test subject) were not related". As a result, the average value of the $\Psi_{(E-CAL)}$, which indicates the magnitude of the non-contact effect, became a positive value in summer, demonstrating the potential power of the PS (1% significance). It was also found that the moving average of the $\Psi_{(E-CAL)}$ changed seasonally. We introduced one theoretical model that can explain the seasonal change of the moving average of the $\Psi_{(E-CAL)}$ ("Model 1") [31]. The introduction process of "Model 1" is shown in 1) to 3) below.

1) Data analysis revealed that the moving average of $\Psi_{\mbox{\tiny (E-CAL)}}$ was large in summer and small in winter.

2) "Model 1" was introduced to explain the seasonal change of the moving average of the $\Psi_{(E-CAL)}$ (Figure 12). The characteristics and assumptions of "Model 1" were as follows (i)-(iv).

- (i) There are two types of potential powers (potential power 1 (P_1) and potential power 2 (P_2)) near the PS apex.
- (ii) The biosensors G_{E1} and G_{E2} at the PS apex are affected by the potential powers P_1 and P_2 .



Figure 10. The moving average of $\Psi_{1(E-CAL)Layer1}$, $\Psi_{2(E-CAL)Layer2}$ and their average, and the scatter plot of $\Psi_{1(E-CAL)Layer1}$ and $\Psi_{2(E-CAL)Layer2}$. (a) shows the moving average (window size is 180 days) of the psi index $\Psi_{1(E-CAL)Layer1}$ (red solid line), $\Psi_{2(E-CAL)Layer2}$ (red dotted line) and their average $\Psi_{(E-CAL)LayerAve}$ (green solid line). (b) is a scatter diagram of $\Psi_{1(E-CAL)Layer1}$ on the horizontal axis and $\Psi_{2(E-CAL)Layer2}$ on the vertical axis.

- (iii) There are at least two types of biosensor gas generation reactions (*a* reaction and β reaction).
- (iv) In "Model 1", a_E and β_E are the average gas concentrations generated from the experimental sample (G_E) by a and β reactions. The a_C and β_C are the average gas concentrations generated from the control sample (G_C) by a and β reactions. Further, $a_E < a_C$ and $\beta_E < \beta_C$ are satisfied. The reason is that the gas concentration varies depending on the axial direction of the cucumber section [29]. To facilitate understanding, $a_E = \beta_E$ and $a_C = \beta_C$.

3) The relationships between the potential power of the PS and the gas production reaction were assumed as follows. "In winter, the potential power P_1 suppresses gas generation due to the α reaction and the gas concentration decreases by $G(P_1)$. As a result, α_E of G_{E1} and G_{E2} becomes $\alpha_{E(\text{winter})}$. Throughout the year, the potential power P_2 facilitates gas generation due to the β reaction and the gas concentration increases by $G(P_2)$. As a result, β_E of G_{E1} and G_{E2} becomes $\beta_{E(\text{year})}$."

The introduction process of 1) - 3) made it possible to qualitatively understand the moving average of the $\Psi_{(E-CAL)}$. From Equation (5), $\Psi_{(E-CAL)} = \Psi_{(E-CAL)LayerAve}$. Therefore, the moving average of $\Psi_{(E-CAL)}$ matches the moving average of $\Psi_{(E-CAL)LayerAve}$ (Figure 10(a)). Thus, it was found that the change of the moving average of $\Psi_{(E-CAL)LayerAve}$ can be understood by the PS potential powers P_1 , P_2 and the gas generation reactions α , β . The $\Psi_{(E-CAL)LayerAve}$ is the average of $\Psi_{1(E-CAL)Layer1}$ and $\Psi_{2(E-CAL)Layer2}$ that calibrate the difference between the lower and upper layers. Therefore, like $\Psi_{(E-CAL)LayerAve}$, we thought that the moving average of



Figure 11. Comparison of psi indices between summer and winter. (a) compares the summer and winter seasons for $\Psi_1 - \Psi_4$ plotted in Figure 6(b). (b) compares the summer and winter seasons for $\Psi_{1(E-CAL)Layer1}$ and $\Psi_{2(E-CAL)Layer2}$ plotted in Figure 9. The black squares are winter and the orange squares are for summer.

 $\Psi_{1(E-CAL)Layer1}$ and $\Psi_{2(E-CAL)Layer2}$ can also be explained by the PS potential powers P_1 , P_2 and gas generation reactions α , β .

4.2. Moving Average of $\Psi_{1(E-CAL)Layer1}$ and $\Psi_{2(E-CAL)Layer2}$, and Proposal of "Model 2"

As a result of data analysis, we found that $\Psi_{1(\text{E-CAL})\text{Layer1}} < \Psi_{2(\text{E-CAL})\text{Layer2}}$. The surprising result ($p = 4.0 \times 10^{-7}$) was obtained that the non-contact effect on the biosensors in the upper layer was larger than that in the lower layer at the PS apex (**Figure 9**). The reason was considered to be the difference between the upper and lower environments, for example, the difference in brightness and the weight applied to the Petri dish. However, since $\Psi_{(\text{E-CAL})\text{Layer}}$ calibrated the difference between the upper and lower environments, the effects due to the environment should have been removed. In order to theoretically understand that the non-contact effect differs depending on the difference between the upper and lower layers, we propose a new "Model 2" that is a modification of "Model 1" (**Figure 13** and **Figure 14**). In "Model 2", the relationships between potential powers P_1 , P_2 of the PS and gas generation reactions α , β are the same as in "Model 1". The P_1 is distributed near the PS apex in a region including G_{E1} and G_{E2} . However, P_2 is assumed as in the following (i)-(ii).

(i) The P_2 spreads out in a cone starting from the PS apex (Figure 13(a) and Figure 13(b)).

(ii) The P_2 only affects biosensors inside the cone and does not affect biosensors outside the cone.

According to the assumptions (i)-(ii), P_2 affects only a small part of the surface of the four cucumber



Figure 12. Features of "Model 1". In (a), two types of potential powers P_1 and P_2 are assumed near the PS apex. Potential powers P_1 and P_2 affect G_{E1} and G_{E2} at the PS apex. In (b), there are at least two types of biosensor gas generation reactions (*a* reaction and β reaction). The a_E and β_E are the average gas concentrations generated from the experimental sample (G_E) by the *a* and β reactions. The a_C and β_C are the average gas concentrations generated from the control sample (G_C) by the *a* and β reactions. In the *a* reaction, the gas concentration decreases by $G(P_1)$ in winter due to P_1 . In the β reaction, P_2 increases the gas concentration by $G(P_2)$ throughout the year.

sections in the Petri dish for the lower G_{E1} (Figure 13(c): lower). On the other hand, it is considered that P_2 affects the entire surface of four cucumber sections in the Petri dish for G_{E2} in the upper layer (Figure 13(c): upper).

Figure 14 shows changes in gas concentrations in summer (**Figure 14(a)**) and winter (**Figure 14(b)**) due to the potential powers P_1 and P_2 . In summer, P_2 increases the gas concentration of β_E of G_{E2} by $G(P_2)$ (β_E of G_{E1} does not change because P_2 has almost no effect on G_{E1}). In winter, the effect of P_2 is the same as in summer, but the gas concentration of α_E of G_{E1} and G_{E2} decreases by $G(P_1)$ due to P_1 . The introduction of "Model 2" enables a qualitative understanding of the moving average of $\Psi_{1(E-CAL)Layer1}$ and $\Psi_{2(E-CAL)Layer2}$.

4.3. Quantification of α_E , α_C , β_E , β_C in "Model 2"

Figure 2 showed the average gas concentration (ppm) of each biosensors G_{E1} - G_{E4} , G_{C1} - G_{C4} , and the average value was (G_{E1} , G_{E2} , G_{E3} , G_{C1} , G_{C2} , G_{C3} , G_{C4}) = (344.7, 355.5, 356.2, 343.6, 358.5, 351.9, 359.7, 355.7). From these results, it was confirmed that G_{E1} and G_{E2} at the PS apex had abnormalities as compared with the biosensors G_{E3} , G_{E4} , and G_{C1} - G_{C4} placed at the calibration control point. In order to clarify the abnormality of G_{E1} and G_{E2} , we tried to find the model value of gas concentration based on the gas concentration at the calibration control point. The average gas concentration of the four biosensors G_{C1} - G_{C4} was 356.5 ppm and the average of G_{E3} and G_{E4} was 350 ppm. The average difference between the upper and lower layers was 5 ppm between G_{C1} and G_{C4} and 13 ppm between G_{E3} and G_{E4} . From these results, assuming that the biosensors at the PS apex had the same reaction as the calibration control point, we obtained the model value of the gas concentration as follows: (G_{E1} , G_{E2} , G_{E3} , G_{C4}) = (356.4, 343.4,



Figure 13. Features of "Model 2". In (a) and (b), P_1 is distributed near the PS apex including G_{E1} and G_{E2} as in "Model 1". It is assumed that P_2 , unlike "Model 1", extends conically from the PS apex. In (c), P_2 affects only a part of the surface of the four cucumber sections in the Petri dish for G_{E1} in the lower layer. For the upper G_{E2} , P_2 affects the entire surface of the four cucumber sections in the Petri dish.

356.4, 343.4, 359.1, 353.8, 359.1, 353.8). These measured and model values are graphed in **Figure 15**. When the measured and model values were compared, they almost matched at the calibration control point, but change at the PS apex had the opposite tendency. **Figure 16(a)** and **Figure 16(b)** shows the summer and winter gas concentrations of G_{E1} - G_{E4} and G_{C1} - G_{C4} based on this model value. As described above, since it was assumed that $\alpha_E = \beta_E$ and $\alpha_C = \beta_C$ in the gas generation reactions α and β , the values of α and β were half of the model values. As in **Figure 14**, the gas concentration of β_E of G_{E2} increased by $G(P_2)$ in summer. In winter, β_E of G_{E2} increased by $G(P_2)$, and α_E of G_{E1} and G_{E2} decreased by $G(P_1)$. Next, the magnitudes of $G(P_1)$ and $G(P_2)$ were estimated from the measured gas concentration.

4.4. Quantification of G(P₁) and G(P₂) in "Model 2"

Here, we attempted to quantitatively estimate the magnitude of $G(P_1)$ and $G(P_2)$ in "Model 2" of **Figure 16**. First, the magnitude of $G(P_2)$ was estimated from Ψ_2 in summer that was given in **Figure 14**. From **Figure 14(a)**, summer Ψ_2 was expressed as follows.

$$\Psi_2 = 100 \ln \left(G_{E2} / G_{C2} \right) = 100 \ln \left(\left(\alpha_E + \beta_E + G(P_2) \right) / (\alpha_C + \beta_C) \right).$$
(6)

From Figure 16(a), $\alpha_E + \beta_E = 344$ for G_{E2} and $\alpha_C + \beta_C = 354$ for G_{C2} . From Figure 11(a), the measured value of summer Ψ_2 was 4.047. From these results, we estimated that $G(P_2) = 25.6$ ppm. Next, the magnitude of $G(P_1)$ was estimated in two ways, from winter Ψ_1 and winter Ψ_2 given in Figure 14.

1) From winter Ψ_1

In **Figure 14(b)**, Ψ_1 could be expressed as follows.

$$\Psi_1 = 100 \ln \left(G_{E1} / G_{C1} \right) = 100 \ln \left(\left(\alpha_E + \beta_E - G(P_1) \right) / (\alpha_C + \beta_C) \right).$$
(7)



Figure 14. Change in gas concentration due to potential powers P_1 and P_2 in "Model 2". In (a), P_2 increases the gas concentration by $G(P_2)$ only for β_E of G_{E2} in summer. In (b), the effect of P_2 is the same as in summer, but the gas concentration of α_E of G_{E1} and G_{E2} decreases by $G(P_1)$ due to P_1 in winter.

From Figure 16(b), $\alpha_E + \beta_E = 356$ for G_{E1} , and $\alpha_C + \beta_C = 360$ for G_{C1} . From Figure 11(a), the measured value of Ψ_1 in winter was -7.694. From these results, it was estimated that $G(P_1) = 23.6$ ppm.

2) From winter Ψ_2

In **Figure 14(b)**, Ψ_2 could be expressed as follows.

$$\Psi_2 = 100 \ln \left(G_{E2} / G_{C2} \right) = 100 \ln \left(\left(\alpha_E + \beta_E - G(P_1) + G(P_2) \right) / \left(\alpha_C + \beta_C \right) \right).$$
(8)

From Figure 16(b), $\alpha_E + \beta_E = 344$ for G_{E2} and $\alpha_C + \beta_C = 354$ for G_{C2} . From Figure 11(a), the measured value of Ψ_2 in winter was -1.924. By substituting $G(P_2) = 25.6$ ppm obtained by Equation (6), it was estimated that $G(P_1) = 21.4$ ppm.

The average value of $G(P_1)$ obtained by the two methods was 22.5 ppm. Figure 17(a) and Figure 17(b) show the respective summer and winter psi indices $\Psi_1 - \Psi_4$ calculated using the $G(P_1)$ and $G(P_2)$ estimates. Although there was some deviation, the results calculated from the measured values and the results obtained from "Model 2" were qualitatively consistent. The $G(P_2)$ was constant throughout the year, while $G(P_1)$ was an amount that appeared only in winter. Therefore, $G(P_1)$ was considered to fluctuate in the annual cycle. Next, we considered the annual fluctuation of $G(P_1)$.

4.5. Annual Variation of G(P1) in "Model 2"

In "Model 2", the gas concentration due to α reaction was suppressed by $G(P_1)$ in winter due to the potential power P_1 . On the other hand, the suppression of gas concentration was zero in summer, that is,



Figure 15. Comparison of measured and model values of average gas concentration of each biosensor The red circles are the measured values and the gray squares are the model values.

 $G(P_1) = 0$. Then, the periodic change of $G(P_1)$ was considered. In order to determine the annual fluctuation of $G(P_1)$, first, the periodic approximate curves $\Psi_1(t)$ and $\Psi_2(t)$ of the moving average of Ψ_1 and Ψ_2 shown in **Figure 7(a)** were obtained. Then, a periodic approximation curve $G(P_1(t))$ of $G(P_1)$ was obtained. Here, we assumed that both $\Psi_1(t)$ and $\Psi_2(t)$ could be expressed by the following equations.

$$\Psi_{1}(t), \Psi_{2}(t) = a + b \sin\left(\frac{2\pi t}{366}\right) + c \cos\left(\frac{2\pi t}{366}\right)$$
$$= a + \sqrt{b^{2} + c^{2}} \sin\left(\frac{2\pi t}{366} + \phi\right),$$
$$\phi = \arcsin\left(\frac{c}{\sqrt{b^{2} + c^{2}}}\right).$$
(9)

Here, *a*, *b*, and *c* are constants, π is the geometrical constant pi and t represents time (day). Assuming that January 1 of each year in which the experiment was performed is 1, and taking into account occurrence of leap years, the value of *t* will be 1 to 366 (days) (**Figure 7**). As a result of simulating the periodic approximation curves of $\Psi_1(t)$ and $\Psi_2(t)$, the constants were determined as follows. In the case of $\Psi_1(t)$, (a,b,c) = (-4.713, -0.658, -2.817), and in the case of $\Psi_2(t)$, (a,b,c) = (1.308, 0.807, -2.697). The equation for calculating the periodic approximation curve $G(P_1(t))$ of $G(P_1)$ from $\Psi_1(t)$ could be expressed as follows from Equation (7) and **Figure 16**.

$$\Psi_1(t) = 100 \ln\left(\left(356 - G(P_1(t)) \right) / 360 \right).$$
(10)



Figure 16. The gas concentration change in "Model 2". This is the gas concentration of G_{E1} - G_{E4} and G_{C1} - G_{C4} using the model values given in Figure 15. (a) is for summer and (b) is for winter. In summer, the gas concentration of β_E of G_{E2} increases by $G(P_2)$. In winter, β_E of G_{E2} increases by $G(P_2)$, and α_E of G_{E1} and G_{E2} decreases by $G(P_1)$.

Further, the expression for calculating $G(P_1(t))$ from $\Psi_2(t)$ could be expressed as follows from Equation (8) and Figure 16.

$$\Psi_{2}(t) = 100 \ln\left(\left(344 - G(P_{1}(t)) + 25.6 \right) / 354 \right).$$
(11)

Here, $G(P_2) = 25.6$ ppm obtained by Equation (6) was used.

The $G(P_1(t))$ calculated from Equation (10) is the gray dashed line indicated in Figure 18(a), and $G(P_1(t))$ calculated from Equation (11) is the gray dotted line, also in Figure 18(a). The average of $G(P_1(t))$ obtained by the two methods is the gray solid line in Figure 18(b), which was defined as a periodic approximation curve $G(P_1(t))$ of $G(P_1)$.

Next, using the periodic approximation curve of $G(P_1(t))$, the approximation curves of Ψ_1 and Ψ_2 shown in **Figure 7(a)** were obtained. Then, we attempted simulation of $\Psi_{1(E-CAL)Layer1}$ and $\Psi_{2(E-CAL)Layer2}$.

4.6. The Approximate Periodic Curves of Ψ_1 and Ψ_2 , and Comparison of the Experimental and Theoretical Values of $\Psi_{1(E-CAL)Layer1}$ and $\Psi_{2(E-CAL)Layer2}$

Figure 19(a) shows Ψ_1 (red solid line) and Ψ_2 (red dotted line) given in **Figure 7(a)**, and the results of simulating Ψ_1 and Ψ_2 from $G(P_1(t))$ (gray solid line). The simulated results reasonably approximated the moving average calculated from the experimental values.

Figure 19(b) shows $\Psi_{1(E-CAL)Layer1}$ and $\Psi_{2(E-CAL)Layer2}$ (red squares) given in Figure 9. And Figure 19(b)



Figure 17. Comparison of $\Psi_1 - \Psi_4$ calculated from experimental data and $\Psi_1 - \Psi_4$ obtained from "Model 2". (a) shows $\Psi_1 - \Psi_4$ of summer (orange square) taken from Figure 11(a) and it shows $\Psi_1 - \Psi_4$ (gray rhombus) calculated from $G(P_2)$ estimated values in "Model 2" in summer. (b) shows $\Psi_1 - \Psi_4$ of winter (black square) taken from Figure 11(a) and it shows $\Psi_1 - \Psi_4$ (gray rhombus) calculated from $G(P_2)$ estimated values in "Model 2" in summer. (b) shows Ψ_1 - Ψ_4 of winter (black square) taken from Figure 11(a) and it shows $\Psi_1 - \Psi_4$ (gray rhombus) calculated from $G(P_1)$ and $G(P_2)$ estimated values in "Model 2" in winter.



Figure 18. Time change of $G(P_1(t))$. (a) shows $G(P_1(t))$ (gray dashed line) obtained from Equation (10) and $G(P_1(t))$ (gray dotted line) obtained from Equation (11). (b) shows the average value of $G(P_1(t))$ obtained by two methods.



Figure 19. Comparison of experimental and theoretical values of moving average of Ψ_1 , Ψ_2 , and comparison of experimental and theoretical values of $\Psi_{1(E-CAL)Layer1}$, $\Psi_{2(E-CAL)Layer2}$. (a) shows the moving averages of Ψ_1 (red solid line) and Ψ_2 (red dotted line) given in Figure 7(a). Also, (a) shows the simulated results of $\Psi_1(t)$ and $\Psi_2(t)$ (solid gray line) using $G(P_1(t))$ given in Figure 18(b). (b) shows the results of $\Psi_{1(E-CAL)Layer1}$ and $\Psi_{2(E-CAL)Layer2}$ (red square) given in Figure 9. Also, (b) shows the results of $\Psi_{1(E-CAL)Layer1}$ and $\Psi_{2(E-CAL)Layer2}$ (gray circles) which were obtained from Ψ_1 , Ψ_2 (solid gray line) in Figure 19(a).

also shows $\Psi_{1(E-CAL)Layer1}$ and $\Psi_{2(E-CAL)Layer2}$ (gray circles) which were obtained from Ψ_1, Ψ_2 (solid gray line) in **Figure 19(a)**. When calculating $\Psi_{1(E-CAL)Layer1}$ and $\Psi_{2(E-CAL)Layer2}$, values of Ψ_3 and Ψ_4 are required (Equation (4)). Here, as the values of Ψ_3 and Ψ_4 , the average values of the moving averages of Ψ_3 and Ψ_4 shown in **Figure 7(b)**, $\Psi_3 = -1.534$, $\Psi_4 = -4.172$, were used. At the PS apex a strange phenomenon that the non-contact effect on the biosensors differs depending on the difference between the upper and lower layers could be reproduced with a very good approximation by simulation using "Model 2".

5. CONCLUSIONS AND IMPACT

In the experiment using the PS, the biosensors were placed on the PS apex and the calibration control point, in two layers, the upper and lower. The non-contact effect on the biosensors at the PS apex ($\Psi_{(E-CAL)}$) was considered as the average of the non-contact effects on the lower (G_{E1}) and upper (G_{E2}) biosensors. This time, in examining the potential power of the PS, we focused on the difference between the upper and lower biosensors that were placed in two layers at the PS apex. As shown in **Figure 9**, we obtained the surprising result that the non-contact effect on the upper biosensors (farther from the PS) was larger than that on the lower biosensors (closer to the PS) ($p = 4.0 \times 10^{-7}$).

Until now, there has been little reliable academic research or collection of statistically significant data on the "pyramid power". Since 2007, we have been conducting scientifically rigorous experiments and analyzes using biosensors to elucidate the unexplained "power" of the PS. As a result, the existence of the "pyramid power", which was often recognized as having no scientific basis, was demonstrated with high statistical accuracy. While this field is still often regarded as heresy in the academic world, our experimental results are the world's first truly scientific work in this field. It is expected that these results will be widely recognized in the future, and they will become part of a new research field in science, and that there will be widespread applications.

CONFLICTS OF INTEREST

The authors declare no conflicts of interest regarding the publication of this paper.

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