# The Quality Properties of Integral Type Problems for Wave Equations and Applications 

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#### Abstract

In this paper, the integral problem for linear and nonlinear wave equations is studied. The equation involves abstract operator $A$ in Hilbert space $H$. Here, assuming enough smoothness on the initial data and the operators, the existence, uniqueness, regularity properties of solutions are established. By choosing the space $H$ and $A$, the regularity properties of solutions of a wide class of wave equations in the field of physics are obtained.


## Keywords

Abstract Differential Equations, Boussinesq Equations, Wave Equations, Regularity Property of Solutions, Fourier Multipliers

## 1. Introduction, Definitions and Background

The aim here, is to study the existence, uniqueness, regularity properties of solutions of the integral problem (IP) for abstract wave equation (WE)

$$
\begin{gather*}
u_{t t}-a \Delta u+A u=f(u),(x, t) \in \mathbb{R}_{T}^{n}=\mathbb{R}^{n} \times(0, T),  \tag{1.1}\\
u(x, 0)=\varphi(x)+\int_{0}^{T} \eta(\sigma) u(x, \sigma) \mathrm{d} \sigma  \tag{1.2}\\
u_{t}(x, 0)=\psi(x)+\int_{0}^{T} \beta(\sigma) u_{t}(x, \sigma) \mathrm{d} \sigma
\end{gather*}
$$

where $A$ is a linear and $f(u)$ is a nonlinear operator in a Hilbert space $H$, $\eta(\sigma), \beta(\sigma)$ are measurable functions on $(0, T)$, a is a complex number, $T \in(0, \infty]$. Here, $\Delta$ denotes the Laplace operator with respect to $x \in \mathbb{R}^{n}$, $\varphi(x)$ and $\psi(x)$ are the given $H$-valued initial functions.

Wave type equations occur in a wide variety of physical systems, such as in the propagation of longitudinal deformation waves in an elastic rod, hydro-dynamical process in plasma, in materials science which describes spinodal decomposition and in the absence of mechanical stresses (see [1] [2] [3] [4]). The nonlocal theory of elasticity was introduced (see [5] [6] [7] [8] [9] and the references cited therein). The global existence of the Cauchy problem for Boussinesq type equations has been studied by many authors (see [10] [11] [12]). Note that, the existence and uniqueness of solutions and regularity properties of a wide class of wave equations were considered e.g. in [13]-[22]. The abstract evolution equations were studied e.g. in [23]-[32]. Unlike in these studies, in this paper the abstract wave equation (1.1) is considered. The $L^{p}$ well-posedness of the Cauchy problem (1.1)-(1.2) depends crucially on the presence of the linear operator $A$ and nonlinear operator $f(u)$. Then the question that naturally arises is which of the possible forms of the operator functions and kernel functions are relevant for the global well-posedness of the Cauchy problem (1.1)-(1.2). We find the class of operator $A$ such that provides the existence, uniqueness, regularity properties and blow up of solutions (1.1)-(1.2) in terms of fractional powers of operator $A$. By choosing the space $H$, operator $A$ in (1.1)-(1.2), we obtain a wide class of wave equations which occur in application. Let we put $H=L^{2}(0,1)$ and consider the operator $A=A_{1}$ defined by

$$
\begin{gather*}
D\left(A_{1}\right)=W^{2,2}\left(0,1, L_{k}\right), A_{1} u=b_{1} u^{(2)}+b_{0} u  \tag{1.3}\\
L_{k} u=\left[\alpha_{k} u^{\left(m_{k}\right)}(0)+\beta_{k} u^{\left(m_{k}\right)}(1)\right]=0, k=1,2,
\end{gather*}
$$

where $b_{1}(),. b_{0}($.$) are VMO functions (see definitions below), m_{k} \in\{0,1\}$, $\alpha_{k}, \beta_{k}$ are complex numbers.

Consider the following mixed problem for WE with discontinuous coefficients

$$
\begin{gather*}
\frac{\partial^{2} u}{\partial t^{2}}-a \Delta_{x} u+b_{1} \frac{\partial^{2} u}{\partial y^{2}}+b_{0} u=f(u), t \in(0, T), x \in \mathbb{R}^{n}  \tag{1.4}\\
u(x, y, 0)=\varphi(x, y)+\int_{0}^{T} \eta(\sigma) u(x, y, \sigma) \mathrm{d} \sigma \\
u_{t}(x, y, 0)=\psi(x, y)+\int_{0}^{T} \beta(\sigma) u_{t}(x, y, \sigma) \mathrm{d} \sigma \\
\alpha_{k} u^{\left(m_{k}\right)}(x, 0, t)+\beta_{k} u^{\left(m_{k}\right)}(x, 1, t)=0, k=1,2
\end{gather*}
$$

where $a$ is a complex number. From our results we obtain the existence, uniqueness, regularity properties and blow up of solutions of (1.4) in $L^{\mathbf{p}}\left(\mathbb{R}^{n} \times(0,1)\right)$ with terms of fractional powers of the operator $A_{1}$, where $\mathbf{p}=(2, p, p)$ and $L^{\mathrm{p}}\left(\mathbb{R}^{n} \times(0,1)\right)$ denotes the space of all $\mathbf{p}$-summable complex-valued measurable functions $f$ defined on $\Omega$ with the mixed norm

$$
\|f\|_{L^{\mathrm{p}}(\Omega)}=\left(\int_{\mathbb{R}^{n}} \int_{0}^{T}\left(\int_{0}^{1}|f(x, y, t)|^{p_{1}} \mathrm{~d} y\right)^{\frac{2}{p_{1}}} \mathrm{~d} x \mathrm{~d} t\right)^{\frac{1}{2}}<\infty
$$

Let $E$ be a Banach space. $L^{p}(\Omega ; E)$ denotes the space of strongly measurable $E$-valued functions that are defined on the measurable subset $\Omega \subset \mathbb{R}^{n}$ with the norm

$$
\begin{gathered}
\|f\|_{p}=\|f\|_{L^{p}(\Omega ; E)}=\left(\int_{\Omega}\|f(x)\|_{E}^{p} \mathrm{~d} x\right)^{\frac{1}{p}}, 1 \leq p<\infty, \\
\|f\|_{L^{\infty}(\Omega ; E)}=\underset{x \in \Omega}{\operatorname{ess} \sup _{\Omega}}\|f(x)\|_{E} .
\end{gathered}
$$

Let $E_{1}$ and $E_{2}$ be two Banach spaces. $\left(E_{1}, E_{2}\right)_{\theta, p}$ for $\theta \in(0,1), \quad p \in[1, \infty]$ denotes the real interpolation spaces defined by $K$-method ([33], Section 1.3.2). Let $E_{1}$ and $E_{2}$ be two Banach spaces. $B\left(E_{1}, E_{2}\right)$ will denote the space of all bounded linear operators from $E_{1}$ to $E_{2}$. For $E_{1}=E_{2}=E$ it will be denoted by $B(E)$.

Here,

$$
S_{\phi}=\{\lambda \in \mathbb{C}, \lambda \neq 0,|\arg \lambda| \leq \phi, 0 \leq \phi<\pi\} .
$$

A closed linear operator $A$ is said to be sectorial in a Banach space $E$ with bound $M>0$ if $D(A)$ and $R(A)$ are dense on $E, N(A)=\{0\}$ and

$$
\left\|(A+\lambda I)^{-1}\right\|_{B(E)} \leq M|\lambda|^{-1}
$$

for any $\lambda \in S_{\phi}, \quad 0 \leq \phi<\pi$, where $I$ is the identity operator in $E, D(A)$ and $R(A)$ denote domain and range of the operator $A$, respectively. It is known that (see e.g. [33], Section 1.15.1) there exist the fractional powers $A^{\theta}$ of a sectorial operator $A$. Let $E\left(A^{\theta}\right)$ denote the space $D\left(A^{\theta}\right)$ with the graphical norm

$$
\|u\|_{E\left(A^{\theta}\right)}=\left(\|u\|^{p}+\left\|A^{\theta} u\right\|^{p}\right)^{\frac{1}{p}}, 1 \leq p<\infty, 0<\theta<\infty
$$

A sectorial operator $A(\xi)$ is said to be uniformly sectorial in $E$ for $\xi \in \mathbb{R}^{n}$, if $D(A(\xi))$ is independent of $\xi$ and the following uniform estimate

$$
\left\|(A+\lambda I)^{-1}\right\|_{B(E)} \leq M|\lambda|^{-1}
$$

holds for any $\lambda \in S_{\phi}$.
A function $\Psi \in L^{\infty}\left(\mathbb{R}^{n}\right)$ is called a Fourier multiplier from $L^{p}\left(\mathbb{R}^{n} ; E\right)$ to $L^{q}\left(\mathbb{R}^{n} ; E\right)$ if the map $P: u \rightarrow \mathbb{F}^{-1} \Psi(\xi) \mathbb{F} u$ is well defined for $u \in S\left(\mathbb{R}^{n} ; E\right)$ and extends to a bounded linear operator.

Definition 1.1. Let $U$ be an open set in a Banach space $X$, let $Y$ be a Banach space. A function $f: U \rightarrow Y$ is called (Frechet) differentiable at $x \in U$ if there is a bounded linear operator $D f(x): X \rightarrow Y$, called the derivative of $f$ at a, such that

$$
\lim _{h \rightarrow 0} \frac{\|f(x+h)-f(x)-D f(x) h\|_{Y}}{\|h\|_{X}}=0
$$

If $f$ is differentiable at each $x \in U$, then $f$ is called differentiable. This function may also have a derivative, the second order derivative of $f$, which, by the
definition of derivative, will be a map

$$
D^{2} f: U \rightarrow L(X, L(X, Y))
$$

Let $E$ be a Banach space. $S=S\left(\mathbb{R}^{n} ; E\right)$ denotes $E$-valued Schwartz class, i.e. the space of all $E$-valued rapidly decreasing smooth functions on $\mathbb{R}^{n}$ equipped with its usual topology generated by seminorms. $S\left(\mathbb{R}^{n} ; \mathbb{C}\right)$ denoted by $S$. Let $S^{\prime}\left(\mathbb{R}^{n} ; E\right)$ denote the space of all continuous linear functions from $S$ into $E$, equipped with the bounded convergence topology. Recall $S\left(\mathbb{R}^{n} ; E\right)$ is norm dense in $L^{p}\left(\mathbb{R}^{n} ; E\right)$ when $1 \leq p<\infty$. Let $m$ be a positive integer. $W^{m, p}(\Omega ; E)$ denotes an $E$-valued Sobolev space of all functions $u \in L^{p}(\Omega ; E)$ that have the generalized derivatives $\frac{\partial^{m} u}{\partial x_{k}^{m}} \in L^{p}(\Omega ; E)$ with the norm

$$
\|u\|_{W^{m, p}(\Omega ; E)}=\|u\|_{L^{p}(\Omega ; E)}+\sum_{k=1}^{n}\left\|\frac{\partial^{m} u}{\partial x_{k}^{m}}\right\|_{L^{p}(\Omega ; E)}<\infty .
$$

Let $W^{s, p}\left(\mathbb{R}^{n} ; E\right)$ denotes the fractional Sobolev space of order $s \in \mathbb{R}$, that is defined as:

$$
\begin{aligned}
& W^{s, p}(E)=W^{s, p}\left(\mathbb{R}^{n} ; E\right) \\
& =\left\{u \in S^{\prime}\left(\mathbb{R}^{n} ; E\right),\|u\|_{W^{s, p}(E)}=\left\|\mathbb{F}^{-1}\left(I+|\xi|^{2}\right)^{\frac{s}{2}} \hat{u}\right\|_{L^{p}\left(\mathbb{R}^{n} ; E\right)}<\infty\right\} .
\end{aligned}
$$

It is clear that $W^{0, p}\left(\mathbb{R}^{n} ; E\right)=L^{p}\left(\mathbb{R}^{n} ; E\right)$. Let $E_{0}$ and $E$ be two Banach spaces and $E_{0}$ is continuously and densely embedded into $E$. Here, $W^{s, p}\left(\mathbb{R}^{n} ; E_{0}, E\right)$ denote the Sobolev-Lions type space i.e.,

$$
\begin{aligned}
& W^{s, p}\left(\mathbb{R}^{n} ; E_{0}, E\right)=\left\{u \in W^{s, p}\left(\mathbb{R}^{n} ; E\right) \cap L^{p}\left(\mathbb{R}^{n} ; E_{0}\right),\right. \\
& \left.\|u\|_{W^{s, p}\left(\mathbb{R}^{n} ; E_{0}, E\right)}=\|u\|_{L^{p}\left(\mathbb{R}^{n} ; E_{0}\right)}+\|u\|_{W^{s, p}\left(\mathbb{R}^{n} ; E\right)}<\infty\right\} .
\end{aligned}
$$

In a similar way, we define the following Sobolev-Lions type space:

$$
\begin{aligned}
& W^{2, s, p}\left(\mathbb{R}_{T}^{n} ; E_{0}, E\right)=\left\{u \in L^{p}\left(\mathbb{R}_{T}^{n} ; E_{0}\right), \partial_{t}^{2} u \in L^{p}\left(\mathbb{R}_{T}^{n} ; E\right),\right. \\
& \mathbb{F}_{\chi}^{-1}\left(I+|\xi|^{2}\right)^{\frac{s}{2}} \hat{u} \in L^{p}\left(\mathbb{R}_{T}^{n} ; E\right),\|u\|_{W^{2, s, p}\left(\mathbb{R}_{T}^{n} ; E_{0}, E\right)} \\
& \left.=\|u\|_{L^{p}\left(\mathbb{R}_{T}^{n} ; E_{0}\right)}+\left\|\partial_{t}^{2} u\right\|_{L^{p}\left(\mathbb{R}_{T}^{n} ; E\right)}+\left\|\mathbb{F}_{x}^{-1}\left(I+|\xi|^{2}\right)^{\frac{s}{2}} \hat{u}\right\|_{L^{p}\left(\mathbb{R}_{T}^{n} ; E\right)}<\infty\right\} .
\end{aligned}
$$

Let $L_{q}^{*}(E)$ denote the space of all $E$-valued function space such that

$$
\|u\|_{L_{q}^{*}(E)}=\left(\int_{0}^{\infty}\|u(t)\|_{E}^{q} \frac{\mathrm{~d} t}{t}\right)^{\frac{1}{q}}<\infty, 1 \leq q<\infty,\|u\|_{L_{\infty}^{*}(E)}=\sup _{0<t<\infty}\|u(t)\|_{E}
$$

Let $s>0$. Fourier-analytic representation of $E$-valued Besov space on $\mathbb{R}^{n}$ is defined as:

$$
\begin{aligned}
& B_{p, q}^{s}\left(\mathbb{R}^{n} ; E\right)=\left\{u \in S^{\prime}\left(\mathbb{R}^{n} ; E\right),\right. \\
& \|u\|_{B_{p, q}^{s}\left(\mathbb{R}^{n} ; E\right)}=\left\|\mathbb{F}^{-1} \sum_{k=1}^{n} t^{\varkappa-s}\left(1+|\xi|^{2}\right)^{\frac{\varkappa}{2}} \mathrm{e}^{-t|\xi|^{2}} \mathbb{F} u\right\|_{L_{q}^{*}\left(L^{p}\left(\mathbb{R}^{n} ; E\right)\right)}, \\
& p \in(1, \infty), q \in[1, \infty], \varkappa>s\} .
\end{aligned}
$$

It should be noted that, the norm of Besov space does not depend on $\varkappa$ (see e.g. [33], Section 2.3 for $E=\mathbb{C}$ ).

Let $A$ be a sectorial operator in $H$. Here,

$$
\begin{gathered}
X_{p}=L^{p}\left(\mathbb{R}^{n} ; H\right), X_{p}\left(A^{\gamma}\right)=L^{p}\left(\mathbb{R}^{n} ; H\left(A^{\gamma}\right)\right), 1 \leq p, q \leq \infty, \\
Y^{s, p}=Y^{s, p}(H)=W^{s, p}\left(\mathbb{R}^{n} ; H\right), Y_{q}^{s, p}(H)=Y^{s, p}(H) \cap X_{q}, \\
\|u\|_{Y_{q}^{s, p}}=\|u\|_{W^{s, p}\left(\mathbb{R}^{n} ; H\right)}+\|u\|_{X_{q}}<\infty, \\
W^{s, p}\left(A^{\gamma}\right)=W^{s, p}\left(\mathbb{R}^{n} ; H\left(A^{\gamma}\right)\right), 0<\gamma \leq 1, \\
Y^{s, p}=Y^{s, p}(A, H)=W^{s, p}\left(\mathbb{R}^{n} ; H(A), H\right), \\
Y^{2, s, p}=Y^{2, s, p}(A, H)=W^{2, s, p}\left(\mathbb{R}_{T}^{n} ; H(A), H\right), \\
Y_{q}^{s, p}(A ; H)=Y^{s, p}(H) \cap X_{q}(A), \\
\|u\|_{Y_{q}^{s, p}(A, H)}=\|u\|_{Y^{s, p}}(H)+\|u\|_{X_{q}(A)}<\infty, \\
\mathbb{E}_{0 p}=\left(Y^{s, p}(A, H), X_{p}\right)_{\frac{1}{2 p}, p}, \mathbb{E}_{1 p}=\left(Y^{s, p}(A, H), X_{p}\right)_{\frac{1+p}{2 p}, p},
\end{gathered}
$$

where $\left(Y^{s, p}, X_{p}\right)_{\theta, p}$ denotes the real interpolation space between $Y^{s, p}$ and $X_{p}$ for $\theta \in(0,1), \quad p \in[1, \infty]$ (see e.g. [33], Section 1.3).

Remark 1.1. By Fubini's theorem we get

$$
L^{p}\left(\mathbb{R}_{T}^{n} ; H\right)=L^{p}\left(0, T ; X_{p}\right) \text { for } X_{p}=L^{p}\left(\mathbb{R}^{n} ; H\right)
$$

Then by definition of spaces $Y^{2, s, p}, Y^{s, p}=H^{s, p}\left(\mathbb{R}^{n} ; H(A), H\right)$ and $X_{p}$ we have

$$
\begin{aligned}
Y^{2, s, p}= & \left\{u: u \in W^{2, p}\left(0, T ; Y^{s, p}, X_{p}\right),\|u\|_{W^{2, p}\left(0, T ; Y^{s, p}, X_{p}\right)}\right. \\
& \left.=\|u\|_{L^{p}\left(0, T ; Y^{s, p}\right)}+\left\|u^{(2)}\right\|_{L^{p}\left(0, T ; X_{p}\right)}\right\} .
\end{aligned}
$$

By J. lions-J. Peetre result (see e.g. [33], Section 1.8.2) for $u \in W^{2, p}\left(0, T ; Y^{s, p}, X_{p}\right)$ the trace operator $u \rightarrow \frac{\mathrm{~d}^{i} u}{\mathrm{~d} t^{i}}\left(t_{0}\right)=\frac{\partial^{i} u}{\partial t^{i}}\left(., t_{0}\right)$ is bounded from $Y^{2, s, p}$ into

$$
C\left(0, T ;\left(Y^{s, p}, X_{p}\right)_{\theta_{j}, p}\right), \theta_{j}=\frac{1+j p}{2 p}, j=0,1
$$

Moreover, if $u(x,.) \in\left(Y^{s, p}, X_{p}\right)_{\theta_{j}, p}$, then under some assumptions that will be stated in Section 3, $f(u) \in H$ for all $x, t \in \mathbb{R}_{T}^{n}$ and the map $u \rightarrow f(u)$ is bounded from $\left(Y^{s, p}, X_{p},\right)_{\frac{1}{2 p}, p}$ into $E$. Hence, the nonlinear Equation (1.1) is satisfied in the Banach space $H$. Here, $H(A)$ denotes a domain of $A$ equipped with graphical norm.

Sometimes we use one and the same symbol $C$ without distinction in order to denote positive constants which may differ from each other even in a single context. When we want to specify the dependence of such a constant on a parameter, say $\alpha$, we write $C_{\alpha}$. Moreover, for $u, v>0$ the relations $u \lesssim v$, $u \approx v$ means that there exist positive constants $C, C_{1}, C_{2}$ independent on $u$ and $v$ such that, respectively

$$
u \leq C v, C_{1} v \leq u \leq C_{2} v
$$

The paper is organized as follows: In Section 1, some definitions and background are given. In Section 2, we obtain the existence of unique solution and a priory estimates for solution of the linearized problem (1.1)-(1.2). In Section 3, we show the existence and uniqueness of local strong solution of the problem (1.1)-(1.2). In Section 4, the existence and uniqueness of global strong solution of the problem (1.1)-(1.2) is derived. Section 5 is devoted to blow up property of the solution of (1.1)-(1.2). In Section 6, we show some applications of the problem (1.1)-(1.2).

Sometimes we use one and the same symbol $C$ without distinction in order to denote positive constants which may differ from each other even in a single context. When we want to specify the dependence of such a constant on a parameter, say $h$, we write $C_{h}$.

## 2. Estimates for Linearized Equation

In this section, we make the necessary estimates for solutions of the integral problem for linear WE

$$
\begin{gather*}
u_{t t}-a \Delta u+A u=g(x, t), x \in \mathbb{R}^{n}, t \in(0, T), T \in(0, \infty]  \tag{2.1}\\
u(x, 0)=\varphi(x)+\int_{0}^{T} \eta(\sigma) u(x, \sigma) \mathrm{d} \sigma  \tag{2.2}\\
u_{t}(x, 0)=\psi(x)+\int_{0}^{T} \beta(\sigma) u_{t}(x, \sigma) \mathrm{d} \sigma
\end{gather*}
$$

where $A$ is a linear operator in a Banach space $E$, a is a complex number and $\eta(s), \beta(s)$ are measurable functions on $(0, T)$.

Remark 2.1. By properties of real interpolation of Banach spaces and interpolation of the intersection of the spaces (see e.g. [33], Section 1.3) we obtain

$$
\begin{aligned}
\mathbb{E}_{0 p} & =\left(Y^{s, p}(A, H) \cap X_{p}, X_{p}\right)_{\frac{1}{2 p}, p} \\
& =\left(Y^{s, p}(H), X_{p}\right)_{\frac{1}{2 p}, p} \cap\left(X_{p}(A), X_{p}\right)_{\frac{1}{2 p}, p}
\end{aligned}
$$

$$
\begin{aligned}
& =W^{s\left(1-\frac{1}{2 p}\right), p}\left(\mathbb{R}^{n} ; H\right) \cap L^{p}\left(\mathbb{R}^{n} ;(H(A), H)_{\frac{1}{2 p}, p}\right) \\
& =W^{s\left(1-\frac{1}{2 p}\right), p}\left(\mathbb{R}^{n} ;(H(A), H)_{\frac{1}{2 p}, p}, H\right)
\end{aligned}
$$

In a similar way, we have

$$
\mathbb{E}_{1 p}=\left(Y^{s, p}(A, H) \cap X_{p}, X_{p}\right)_{\frac{1+p}{2 p}, p}=W^{\frac{s(p-1)}{2 p}, p}\left(\mathbb{R}^{n} ;(H(A), H)_{\frac{1+p}{2 p}, p}, H\right)
$$

Remark 2.2. Let $A$ be a sectorial operator in a Banach space $E$. In view of interpolation of sectorial operators (see e.g. [33], Section 1.8.2) we have the following relation

$$
E\left(A^{1-\theta-\varepsilon}\right) \subset(E(A), E)_{\theta, p} \subset E\left(A^{1-\theta+\varepsilon}\right)
$$

for $0<\theta<1$ and $0<\varepsilon<1-\theta$.
Note that from J. lions-J. Peetre result (see e.g. [33], Section 1.8.2) we obtain the following result.

Lemma $\mathbf{A}_{1}$. The trace operator $u \rightarrow \frac{\partial^{i} u}{\partial t^{i}}(x, t)$ is bounded from $Y^{2, s, p}(A, H)$ into

$$
C\left(\mathbb{R}^{n} ;\left(Y^{s, p}(A, H), X_{p}\right)_{\theta_{j}, p}\right), \theta_{j}=\frac{1+j p}{2 p}, j=0,1
$$

We assume that $A$ is a sectorial operator in a Hilbert space $H$. Let $A$ be a generator of a strongly continuous cosine operator function in a Banach space $E$ defined by formula

$$
C(t)=C_{A}(t)=\frac{1}{2}\left(\mathrm{e}^{i t A^{\frac{1}{2}}}+\mathrm{e}^{-i i A^{\frac{1}{2}}}\right)
$$

(see e.g. [25], Section 11 or [23], Section 3). Then, from the definition of sine operator-function $S(t)$ we have

$$
S(t)=S_{A}(t)=\int_{0}^{t} C(\sigma) \mathrm{d} \sigma \text {, i.e. } S(t)=\frac{1}{2 i} A^{-\frac{1}{2}}\left(\mathrm{e}^{i t A^{\frac{1}{2}}}-\mathrm{e}^{-i t A^{\frac{1}{2}}}\right)
$$

Remark 2.3. Let $A$ be a densely defined operator in $H$. By virtue of ([23], Theorem 3.15.3) if $A$ be the generator of a cosine function $C(t)$, i.e.

$$
R\left(\lambda^{2}, A\right)=\frac{1}{\lambda} \int_{0}^{\infty} \mathrm{e}^{-\lambda t} C(t) \mathrm{d} t \text { for } \lambda>\omega
$$

Let

$$
\begin{gather*}
A_{ \pm}(\xi)=\mathrm{e}^{i t A(\xi)} \pm \mathrm{e}^{-i t A(\xi)}, C(t)=C(\xi, t)=\frac{A_{+}(\xi)}{2}  \tag{2.3}\\
S(t)=S(\xi, t)=S(\xi, t, A)=\frac{1}{2 i} A^{-1}(\xi) A_{-}(\xi)
\end{gather*}
$$

Condition 2.1. Assume: 1)

$$
\begin{equation*}
\left|1+\int_{0}^{T} \eta(\sigma) \beta(\sigma) \mathrm{d} \sigma\right|>\int_{0}^{T}(|\eta(\sigma)|+|\beta(\sigma)|) \mathrm{d} \sigma \tag{2.0}
\end{equation*}
$$

2) $A$ is a $\phi$-sectorial operator in the Hilbert space $H$ and $A$ is a generator of a cosine function; 3) $a \in S_{\phi_{1}}$ for $0 \leq \phi_{1}<\pi, \phi_{1}<\pi-\phi$; 4) $\varphi \in \mathbb{E}_{0 p}$ and $\psi \in \mathbb{E}_{1 p}$.

Definition 1.1. Let $T>0, \varphi \in \mathbb{E}_{0 p}$ and $\psi \in \mathbb{E}_{1 p}$. The function $u \in C^{2}\left(Y_{1}^{s, p}(A)\right)$ satisfies of the problem (1.1)-(1.2) is called the continuous solution or the strong solution of (1.1)-(1.2). If $T<\infty$, then $u(x, t)$ is called the local strong solution of (1.1)-(1.2). If $T=\infty$, then $u(x, t)$ is called the global strong solution of (1.1)-(1.2).

First we need the following lemmas:
Lemma 2.1. Let the Condition 2.1 holds. Then, problem (2.1)-(2.2) has a solution.

Proof. By using of the Fourier transform, we get from (2.1)-(2.2):

$$
\begin{gather*}
\hat{u}_{t t}(\xi, t)+A_{\xi}^{2} \hat{u}(\xi, t)=\hat{g}(\xi, t)  \tag{2.4}\\
\hat{u}(\xi, 0)=\hat{\varphi}(\xi)+\int_{0}^{T} \eta(\sigma) \hat{u}(\xi, \sigma) \mathrm{d} \sigma  \tag{2.5}\\
\hat{u}_{t}(\xi, 0)=\hat{\psi}(\xi)+\int_{0}^{T} \beta(\sigma) \hat{u}_{t}(\xi, \sigma) \mathrm{d} \sigma
\end{gather*}
$$

where $\hat{u}(\xi, t)$ is a Fourier transform of $u(x, t)$ in $x$ and $\hat{\varphi}(\xi), \hat{\psi}(\xi)$ are Fourier transform of $\varphi$ and $\psi$, respectively and

$$
A_{\xi}=\left[a|\xi|^{2}+A\right]^{\frac{1}{2}}
$$

Consider first, the Cauchy problem

$$
\begin{gather*}
\hat{u}_{t t}(\xi, t)+A_{\xi}^{2} \hat{u}(\xi, t)=\hat{g}(\xi, t),  \tag{2.6}\\
\hat{u}(\xi, 0)=u_{0}(\xi), \hat{u}_{t}(\xi, 0)=u_{1}(\xi), \xi \in \mathbb{R}^{n}, t \in[0, T]
\end{gather*}
$$

where $u_{0}(\xi), u_{1}(\xi) \in D(A)$ for $\xi \in \mathbb{R}^{n}$. By virtue of ([25], Section 11.2, 11.4) we obtain that $A_{\xi}$ is a generator of a strongly continuous cosine operator function and the Cauchy problem (2.6) has a unique solution for all $\xi \in \mathbb{R}^{n}$. Moreover, the solution of (2.6) can be expressed as

$$
\begin{equation*}
\hat{u}(\xi, t)=C(t) u_{0}(\xi)+S(t) u_{1}(\xi)+\int_{0}^{T} S(t-\tau, \xi, A) \hat{g}(\xi, \tau) \mathrm{d} \tau, t \in(0, T) \tag{2.7}
\end{equation*}
$$

where $C(t)$ is a cosine and $S(t)$ is a sine operator-functions generated by $A_{\xi}$, i.e.

$$
\begin{gathered}
C(t)=C(t, \xi, A)=\frac{1}{2}\left(\mathrm{e}^{t A_{\xi}}+\mathrm{e}^{-t A_{\xi}}\right) \\
S(t)=S(t, \xi, A)=\frac{1}{2} A_{\xi}^{-1}\left(\mathrm{e}^{t A_{\xi}}-\mathrm{e}^{-t A_{\xi}}\right) .
\end{gathered}
$$

Using the formula (2.7) and the first integral condition (2.5) we get

$$
\begin{aligned}
u_{0}(\xi)= & \hat{\varphi}(\xi)+\int_{0}^{T} \eta(\sigma)\left[u_{0}(\xi)+\frac{1}{2 i} A^{-1}(\xi) u_{1}(\xi)\right] \mathrm{d} \sigma \\
& +\int_{0}^{T} \eta(\sigma)\left[C(\sigma) u_{0}(\xi)+S(\sigma) u_{1}(\xi)\right] \mathrm{d} \sigma \\
& +\int_{0}^{T} \int_{0}^{T} \eta(\sigma) S(\sigma-\tau, \xi, A) \hat{g}(\sigma, \xi) \mathrm{d} \tau \mathrm{~d} \sigma, \tau \in(0, T),
\end{aligned}
$$

i.e. we obtain the first equation with respect to $u_{0}(\xi), u_{1}(\xi)$ :

$$
\begin{equation*}
b_{10}(\xi) u_{0}(\xi)+b_{11}(\xi) u_{1}(\xi)=g_{10}(\xi), \tag{2.8}
\end{equation*}
$$

where

$$
\begin{gathered}
b_{10}(\xi)=\left[1-\int_{0}^{T} \eta(\sigma)[1+C(\sigma)] \mathrm{d} \sigma\right], \\
b_{11}(\xi)=-\frac{1}{2 i} A_{\xi}^{-1} \int_{0}^{T} \eta(\sigma) C(\sigma) \mathrm{d} \sigma-\int_{0}^{T} \eta(\sigma) S(\sigma) \mathrm{d} \sigma, \\
g_{10}(\xi)=\hat{\varphi}(\xi)+\int_{0}^{T} \int_{0}^{T} \eta(\sigma) S(\sigma-\tau, \xi, A) \hat{g}(\sigma, \xi) \mathrm{d} \tau \mathrm{~d} \sigma
\end{gathered}
$$

Differentiating both sides of formula (2.7) and using the seconf integral condition (2.5), we have

$$
\begin{aligned}
u_{1}(\xi)= & \hat{\psi}(\xi)+\int_{0}^{T} \beta(\sigma)\left[\frac{1}{2 i} u_{0}(\xi)+u_{1}(\xi)\right] \mathrm{d} \sigma \\
& +\int_{0}^{T} \int_{0}^{T} \beta(\sigma) C(\sigma-\tau, \xi, A) \hat{g}(\xi, \sigma) \mathrm{d} \tau \mathrm{~d} \sigma
\end{aligned}
$$

i.e. we get the second equation with respect to $u_{0}(\xi), u_{1}(\xi)$ :

$$
\begin{equation*}
b_{20}(\xi) u_{0}(\xi)+b_{21}(\xi) u_{1}(\xi)=g_{20}(\xi) \tag{2.9}
\end{equation*}
$$

where

$$
\begin{gathered}
b_{20}(\xi)=-\frac{1}{2 i} \int_{0}^{T} \beta(\sigma) \mathrm{d} \sigma, b_{21}(\xi)=1-\int_{0}^{T} \beta(\sigma) \mathrm{d} \sigma \\
g_{20}(\xi)=\hat{\psi}(\xi)+\int_{0}^{T} \int_{0}^{T} \beta(\sigma) C(\sigma-\tau, \xi, A) \hat{g}(\xi, \sigma) \mathrm{d} \tau \mathrm{~d} \sigma
\end{gathered}
$$

Now, we consider the system of Equations (2.8)-(2.9) in $u_{0}(\xi)$ and $u_{1}(\xi)$. By assumption (2.0) and due to uniformly boundedness of $A_{\xi}^{-1}$, the main determinant of this system

$$
\begin{aligned}
& D(\xi)=\left|\begin{array}{ll}
b_{10}(\xi) & b_{11}(\xi) \\
b_{20}(\xi) & b_{21}(\xi)
\end{array}\right|=\left[1-\int_{0}^{T} \eta(\sigma)[1+C(\sigma)] \mathrm{d} \sigma\right]\left[1-\int_{0}^{T} \beta(\sigma) \mathrm{d} \sigma\right] \\
& -\left[-\frac{1}{2 i} \int_{0}^{T} \beta(\sigma) \mathrm{d} \sigma\right]\left[-\frac{1}{2 i} A_{\xi}^{-1} \int_{0}^{T} \eta(\sigma) C(\sigma) \mathrm{d} \sigma-\int_{0}^{T} \eta(\sigma) S(\sigma) \mathrm{d} \sigma\right] \\
& =1-\int_{0}^{T} \beta(\sigma) \mathrm{d} \sigma-\int_{0}^{T} \eta(\sigma)[1+C(\sigma)] \mathrm{d} \sigma+\left(\int_{0}^{T} \beta(\sigma) \mathrm{d} \sigma\right) \int_{0}^{T} \eta(\sigma)[1+C(\sigma)] \mathrm{d} \sigma \\
& +-\frac{1}{4} A_{\xi}^{-1}\left(\int_{0}^{T} \beta(\sigma) \mathrm{d} \sigma\right)\left(\int_{0}^{T} \eta(\sigma) C(\sigma) \mathrm{d} \sigma\right)-\frac{1}{2 i}\left(\int_{0}^{T} \beta(\sigma) \mathrm{d} \sigma\right)\left[\int_{0}^{T} \eta(\sigma) S(\sigma) \mathrm{d} \sigma\right]
\end{aligned}
$$

$$
\begin{aligned}
& =1-\int_{0}^{T} \beta(\sigma) \mathrm{d} \sigma+\left[\int_{0}^{T} \eta(\sigma)[1+C(\sigma)] \mathrm{d} \sigma\right]\left[\int_{0}^{T} \beta(\sigma) \mathrm{d} \sigma-1\right] \\
& -\left(\int_{0}^{T} \beta(\sigma) \mathrm{d} \sigma\right)\left[\frac{1}{4} A_{\xi}^{-1} \int_{0}^{T} \eta(\sigma) C(\sigma) \mathrm{d} \sigma+\frac{1}{2 i} \int_{0}^{T} \eta(\sigma) S(\sigma) \mathrm{d} \sigma\right] \\
& \neq 0
\end{aligned}
$$

for all $\xi \in \mathbb{R}^{n}$. By solving the system (2.8)-(2.9) we get

$$
\begin{gather*}
u_{0}(\xi)=D_{1}(\xi) D^{-1}(\xi), u_{1}(\xi)=D_{2}(\xi) D^{-1}(\xi)  \tag{2.10}\\
D_{1}(\xi)=b_{21}(\xi) g_{10}(\xi)-b_{11}(\xi) g_{20}(\xi) \\
D_{2}(\xi)=b_{10}(\xi) g_{20}(\xi)-b_{20}(\xi) g_{10}(\xi)
\end{gather*}
$$

By substituting the values $u_{0}(\xi)$ and $u_{1}(\xi)$ in (2.7), we obtain

$$
\begin{align*}
\hat{u}(\xi, t)= & C(\xi, t) D_{1}(\xi) D^{-1}(\xi)+S(\xi, t) D_{2}(\xi) D^{-1}(\xi) \\
& +\int_{0}^{t} S(\xi, t-\tau) \hat{g}(\xi, \tau) \mathrm{d} \tau \tag{2.11}
\end{align*}
$$

i.e. problem (2.1)-(2.2) has a unique solution

$$
\begin{equation*}
u(x, t)=C_{1}(t) \varphi+S_{1}(t) \psi+Q g \tag{2.12}
\end{equation*}
$$

where $C_{1}(t), S_{1}(t), Q$ are linear operator functions defined by

$$
\begin{gathered}
C_{1}(t) \varphi=\mathbb{F}^{-1}\left[C(\xi, t) D_{1}(\xi)\right], S_{1}(t) \psi=\mathbb{F}^{-1}\left[S(\xi, t) D_{2}(\xi)\right] \\
Q g=\mathbb{F}^{-1} \tilde{Q}(\xi, t), \tilde{Q}(\xi, t)=\int_{0}^{t} \mathbb{F}^{-1}[S(\xi, t-\tau) \hat{g}(\xi, \tau)] \mathrm{d} \tau
\end{gathered}
$$

Theorem 2.1. Assume the Condition 2.1 holds and

$$
\begin{equation*}
s>\frac{2 p n}{2 p-1}\left(\frac{2}{q}+\frac{1}{p}\right) \tag{2.13}
\end{equation*}
$$

for $p \in[1, \infty]$ and for a $q \in[1,2]$. Let $0 \leq \alpha<1-\frac{1}{2 p}$. Then for $\varphi \in \mathbb{E}_{0 p} \cap X_{1}\left(A^{\alpha}\right), \psi \in \mathbb{E}_{1 p} \cap X_{1}\left(A^{\alpha-\frac{1}{2}}\right), g(., t) \in Y_{1}^{s, p} \quad$ for $t \in[0, T]$ and $g(x,.) \in L^{1}\left(0, T ; Y_{1}^{s, p}\right)$ for $x \in \mathbb{R}^{n}$ problem (2.1)-(2.2) has a unique solution $u(x, t) \in C^{2}\left([0, T] ; X_{\infty}\right)$. Moreover, the following estimate holds

$$
\begin{align*}
\left\|A^{\alpha} u\right\|_{X_{\infty}}+\left\|A^{\alpha} u_{t}\right\|_{X_{\infty}} \leq & C_{0}\left[\|\varphi\|_{\mathbb{E}_{0 p}}+\left\|A^{\alpha} \varphi\right\|_{X_{1}}+\|\psi\|_{\mathbb{E}_{1 p}}+\left\|A^{\alpha-\frac{1}{2}} \psi\right\|_{X_{1}}\right.  \tag{2.14}\\
& \left.+\int_{0}^{t}\left(\|g(., \tau)\|_{Y_{1}^{s, p}}+\|g(., \tau)\|_{X_{1}}\right) \mathrm{d} \tau\right]
\end{align*}
$$

uniformly in $t \in[0, T]$, where the constant $C_{0}>0$ depends only on $A$, the space $H$ and initial data.

Proof. By Lemma 2.1, the problem (2.1)-(2.2) has a solution $u(x, t) \in C^{2}\left([0, T] ; Y^{s, p}(A ; H)\right)$ for $\varphi \in \mathbb{E}_{0 p}, \psi \in \mathbb{E}_{1 p}$ and $g(., t) \in Y_{1}^{s, p}$. Let $N \in \mathbb{N}$ and

$$
\Pi_{N}=\left\{\xi: \xi \in \mathbb{R}^{n},|\xi| \leq N\right\}, \Pi_{N}^{\prime}=\left\{\xi: \xi \in \mathbb{R}^{n},|\xi| \geq N\right\}
$$

From (2.12) we deduced that

$$
\begin{align*}
\left\|A^{\alpha} u\right\|_{X_{\infty}} \lesssim & \lesssim \mathbb{F}^{-1} C(\xi, t) A^{\alpha} D_{1}(\xi) D^{-1}(\xi) \|_{L^{\infty}\left(\Pi_{N}\right)} \\
& +\left\|\mathbb{F}^{-1} S(\xi, t) A^{\alpha} D_{2}(\xi) D^{-1}(\xi)\right\|_{L^{\infty}\left(\Pi_{N}\right)} \\
& +\left\|\mathbb{F}^{-1} C(\xi, t) A^{\alpha} D_{1}(\xi) D^{-1}(\xi)\right\|_{L^{\infty}\left(\Pi_{N}^{\prime}\right)} \\
& +\left\|\mathbb{F}^{-1} S(\xi, t) A^{\alpha} D_{2}(\xi) D^{-1}(\xi)\right\|_{L^{\infty}\left(\Pi_{N}^{\prime}\right)}  \tag{2.15}\\
& +\frac{1}{2}\left\|\mathbb{F}^{-1} A^{\alpha} \tilde{Q}(\xi, t) \hat{g}(\xi, \tau)\right\|_{L^{\infty}\left(\Pi_{N}\right)} \\
& +\frac{1}{2}\left\|\mathbb{F}^{-1} A^{\alpha} \tilde{Q}(\xi, t) \hat{g}(\xi, \tau)\right\|_{L^{\infty}\left(\Pi_{N}^{\prime}\right)} .
\end{align*}
$$

By virtue of Remakes 2.1, 2.2 and the properties of sectorial operators we get the following uniform estimate

$$
\left\|\mathbb{F}^{-1} A^{\alpha} \tilde{Q}(\xi, t) \hat{g}(\xi, \tau)\right\|_{L^{\infty}\left(\Pi_{N}\right)} \leq C\|g\|_{X_{1}}
$$

Hence, due to uniform boundedness of operator functions $C(\xi, t), S(\xi, t)$, by (2.3), in view of (2.8)-(2.10) and by Minkowski's inequality for integrals we get the uniform estimate

$$
\begin{align*}
& \left\|\mathbb{F}^{-1} C(\xi, t) A^{\alpha} D_{1}(\xi) D^{-1}(\xi)\right\|_{L^{\infty}\left(\Pi_{N}\right)} \\
& +\left\|\mathbb{F}^{-1} S(\xi, t) A^{\alpha} D_{2}(\xi) D^{-1}(\xi)\right\|_{L^{\infty}\left(\Pi_{N}\right)}  \tag{2.16}\\
& \lesssim\left[\left\|A^{\alpha} \varphi\right\|_{X_{1}}+\left\|A^{\alpha} \psi\right\|_{X_{1}}+\|g\|_{X_{1}}\right]
\end{align*}
$$

Let

$$
l=s\left(1-\frac{1}{2 p}\right)-\delta \text { for a } \delta>0
$$

Moreover, in a similar way, we deduced that

$$
\begin{align*}
& \left\|\mathbb{F}^{-1} C(\xi, t) A^{\alpha} D_{1}(\xi) D^{-1}(\xi)\right\|_{L^{\infty}\left(\Pi_{N}^{\prime}\right)}+\left\|\mathbb{F}^{-1} S(\xi, t) A^{\alpha} D_{2}(\xi) D^{-1}(\xi)\right\|_{L^{\infty}} \\
& \lesssim\left\|\mathbb{F}^{-1} C(\xi, t) A^{\alpha} D_{1}(\xi) D^{-1}(\xi)\right\|_{L^{\infty}}+\left\|\mathbb{F}^{-1} S(\xi, t) A^{\alpha} D_{2}(\xi) D^{-1}(\xi)\right\|_{L^{\infty}} \\
& \quad+\left\|\mathbb{F}^{-1} S(\xi, t) A^{\alpha} \tilde{Q}(\xi, t) \hat{g}(\xi, \tau)\right\|_{L^{\infty}} \\
& \lesssim\left\|\mathbb{F}^{-1}\left(1+|\xi|^{2}\right)^{-\frac{l}{2}} C(\xi, t)\left(1+|\xi|^{2}\right)^{\frac{l}{2}} A^{\alpha} \hat{\varphi}(\xi)\right\|_{L^{\infty}}  \tag{2.17}\\
& \quad+\left\|\mathbb{F}^{-1}\left(1+|\xi|^{2}\right)^{-\frac{l}{2}} S(\xi, t)\left(1+|\xi|^{2}\right)^{\frac{l}{2}} A^{\alpha} \hat{\psi}(\xi)\right\|_{L^{\infty}} \\
& \quad+\left\|\mathbb{F}^{-1}\left(1+|\xi|^{2}\right)^{-\frac{l}{2}} S(\xi, t)\left(1+|\xi|^{2}\right)^{\frac{l}{2}} A^{\alpha} \tilde{Q}(\xi, t) \hat{g}(\xi, \tau)\right\|_{L^{\infty}},
\end{align*}
$$

here, the space $L^{\infty}(\Omega ; H)$ is denoted by $L^{\infty}$. Let

$$
\left.\begin{array}{rl}
\Phi_{0}(\xi)= & {\left[A^{1-\frac{1}{2 p}-\varepsilon_{0}}+\left(1+|\xi|^{2}\right)^{s\left(1-\frac{1}{2 p}\right)-\varepsilon_{0}}\right]^{-1}, 0<\varepsilon_{0}<1-\frac{1}{2 p}}  \tag{2.18}\\
\Phi_{1}(\xi)= & {\left[A^{\frac{1}{2}-\frac{1}{2 p}-\varepsilon}+\left(1+|\xi|^{2}\right)^{s\left(\frac{1}{2}-\frac{1}{2 p}\right)-\varepsilon_{1}}\right]^{-1}, 0<\varepsilon_{1}<\frac{1}{2}-\frac{1}{2 p}} \\
\Phi_{01}(\xi)= & 2 \xi_{k} s\left(1-\frac{1}{2 p}-\varepsilon_{0}\right)\left[\left(1+|\xi|^{2}\right)^{s\left(1-\frac{1}{2 p}\right)-\varepsilon_{0}-1}\right] \\
& \times\left[A^{1-\frac{1}{2 p}-\varepsilon_{0}}+\left(1+|\xi|^{2}\right)^{s\left(1-\frac{1}{2 p}\right)-\varepsilon_{0}}\right]^{-2}, \\
\Phi_{11}(\xi)= & 2 \xi_{k} s\left(S^{s}\left(\frac{1}{2}-\frac{1}{2 p}\right)-\varepsilon_{1}\right)\left[\left(1+|\xi|^{2}\right)^{s\left(\frac{1}{2}-\frac{1}{2 p}\right)-\varepsilon_{1}-1}\right] \\
& {\left[A^{\frac{1}{2}-\frac{1}{2 p}-\varepsilon}+\left(1+|\xi|^{2}\right)^{s}\left(\frac{1}{2}-\frac{1}{2 p}\right)-\varepsilon_{1}\right]^{-2}}
\end{array}\right] .
$$

By using the resolvent properties of sectorial operators, we have

$$
\begin{gather*}
\left\|A^{\alpha} \Phi_{i}(\xi)\right\|_{B(E)} \lesssim|\xi|^{-\varepsilon}, 0<\varepsilon<\frac{1}{2}-\frac{1}{2 p}, i=1,2,  \tag{2.19}\\
\left\|A^{\alpha} C(\xi, t) \Phi_{0}(\xi)\right\|_{B(E)} \leq C\left\|A^{\alpha} A^{-\left(1-\frac{1}{2 p}-\varepsilon_{0}\right)}(\xi)\right\|_{B(E)} \leq C_{0}, \\
\left\|A^{\alpha} S(\xi, t) \Phi_{1}(\xi)\right\|_{B(E)} \leq\left\|A^{\frac{1}{2}} \eta^{-1}(\xi)\right\|_{B(E)}\left\|A^{\alpha} A^{-\frac{1}{2}} \Phi_{1}(\xi)\right\|_{B(E)} \\
\leq C\left\|A^{\alpha} A^{-\left(1-\frac{1}{2 p-\varepsilon_{0}}\right)}(\xi)\right\|_{B(E)} \leq C_{1} .
\end{gather*}
$$

Then by calculating $\frac{\partial}{\partial \xi_{k}} \Phi_{0}(\xi), \frac{\partial}{\partial \xi_{k}} \Phi_{1}(\xi)$, we obtain

$$
A^{\alpha} \frac{\partial}{\partial \xi_{k}} \Phi_{0}(\xi) \in B(H), A^{\alpha} \frac{\partial}{\partial \xi_{k}} \Phi_{1}(\xi) \in B(H)
$$

Let we show that $G_{i}(., t) \in B_{q, 1}^{n\left(\frac{1}{q}+\frac{1}{p}\right)}\left(\mathbb{R}^{n} ; H\right)$ for some $q \in(1,2)$ and for all $t \in[0, T]$, where

$$
G_{i}(\xi, t)=\left(1+|\xi|^{2}\right)^{-\frac{l}{2}} A C(\xi, t) \Phi_{i}(\xi), i=0,1
$$

By embedding properties of Sobolev and Besov spaces it is sufficient to derive that $G_{i} \in W_{q}^{n\left(\frac{1}{q}+\frac{1}{p}\right)+\varepsilon}\left(\mathbb{R}^{n}\right)$ for some $\varepsilon>0$. Indeed by contraction, by Condition 2.2 and by (2.18) we get $G_{i} \in L^{q}\left(\mathbb{R}^{n}\right)$. Let $\sigma>n\left(\frac{1}{r}+\frac{1}{p}\right)$. For deriving the embedding relations $G_{i} \in W_{q}^{\sigma+\varepsilon}\left(\mathbb{R}^{n}\right)$, it sufficient to show

$$
\left(1+|\xi|^{2}\right)^{\frac{\sigma}{2}} G_{i}(., t) \in L^{\sigma}\left(\mathbb{R}^{n}\right) \text { for al } t \in[0, T]
$$

Indeed, in view of (2.18), $\left(1+|\xi|^{2}\right)^{\frac{\sigma}{2}} \Phi_{i}(\xi)$ are uniformly bounded for $\xi \in \mathbb{R}^{n}$. By virtue of (2.3), (2.19), by Condition 2.2 for $l<s\left(1-\frac{1}{2 p}\right)$ and $(l-\sigma) q>n$ we have

$$
\begin{aligned}
& \int_{\mathbb{R}^{n}}\left(1+|\xi|^{2}\right)^{\frac{\sigma}{2} q}\left|G_{i}(\xi, t)\right|^{q} \mathrm{~d} \xi \\
& =\int_{\mathbb{R}^{n}}\left(1+|\xi|^{2}\right)^{-\frac{l-\sigma}{2} q}\|C(\xi, t)\|^{q}\left\|A^{\alpha} \Phi_{i}(\xi)\right\|_{B(E)}^{q} \mathrm{~d} \xi \\
& \lesssim \int_{\mathbb{R}^{n}}\left(1+|\xi|^{2}\right)^{\frac{\sigma-l+\varepsilon}{2} q}|\xi|^{-\varepsilon q} \mathrm{~d} \xi \\
& \lesssim \int_{\mathbb{R}^{n}}\left(1+|\xi|^{2}\right)^{-\left(\frac{l-\sigma}{2}\right) q} \mathrm{~d} \xi<\infty
\end{aligned}
$$

Hence, by Fourier multiplier theorems (see e.g. [32], Theorem 4.3) we get that the functions $G_{i}(\xi, t)$ are Fourier multipliers from $L^{p}\left(\mathbb{R}^{n} ; H\right)$ to $L^{\infty}\left(\mathbb{R}^{n} ; H\right)$. In a similar way we obtain that

$$
\begin{gathered}
\left(1+|\xi|^{2}\right)^{-\frac{s}{2}} S(\xi, t)\left(1+|\xi|^{2}\right)^{\frac{s}{2}} A^{\alpha} \hat{\psi}(\xi) \\
\left(1+|\xi|^{2}\right)^{-\frac{s}{2}} S(\xi, t)\left(1+|\xi|^{2}\right)^{\frac{s}{2}} A^{\alpha} \tilde{Q}(\xi, t) \hat{g}(\xi, \tau)
\end{gathered}
$$

are $L^{p}\left(\mathbb{R}^{n} ; H\right) \rightarrow L^{\infty}\left(\mathbb{R}^{n} ; H\right)$ Fourier multipliers. Then by Minkowski's inequality for integrals, from (2.3), (2.16)-(2.18) and by Remake 2.3 we have

$$
\begin{align*}
& \left\|F^{-1} C(\xi, t) A^{\alpha} \hat{\varphi}(\xi)\right\|_{L^{\infty}}+\left\|\mathbb{F}^{-1} S(\xi, t) A^{\alpha} \hat{\psi}(\xi)\right\|_{L^{\infty}} \\
& \lesssim\left\|F^{-1} C(\xi, t) \eta^{-2} \hat{\varphi}\right\|_{L^{\infty}}+\left\|\mathbb{F}^{-1} S(\xi, t) \eta^{-1} \hat{\psi}\right\|_{L^{\infty}}  \tag{2.20}\\
& \lesssim\left[\|\varphi\|_{\mathbb{E}_{0 p}}+\|\psi\|_{\mathbb{E}_{1 p}}+\|g\|_{W^{s, p}}\right] .
\end{align*}
$$

Moreover, by virtue of Remakes 2.1-2.3 and by reasoning as the above, we have the following estimate

$$
\begin{equation*}
\left\|F^{-1} A^{\alpha} \tilde{Q}(\xi, t)\right\|_{X_{\infty}} \leq C_{0}^{t}\left(\|g(., \tau)\|_{W^{s, p}}+\|g(., \tau)\|_{X_{1}}\right) \mathrm{d} \tau \tag{2.21}
\end{equation*}
$$

uniformly in $t \in[0, T]$. Thus, from (2.12), (2.20) and (2.21) we obtain

$$
\begin{align*}
\left\|A^{\alpha} u\right\|_{X_{\infty}} \leq & C\left[\|\varphi\|_{\mathbb{E}_{0_{p}}}+\left\|A^{\alpha} \varphi\right\|_{X_{1}}+\|\psi\|_{\mathbb{E}_{1 p}}+\left\|A^{\alpha} \psi\right\|_{X_{1}}\right. \\
& \left.+\int_{0}^{t}\left(\|g(., \tau)\|_{Y^{s, p}}+\|g(., \tau)\|_{X_{1}}\right) \mathrm{d} \tau\right] . \tag{2.22}
\end{align*}
$$

By differentiating (2.12) in a similar way, we get

$$
\begin{align*}
\left\|A^{\alpha} u_{t}\right\|_{X_{\infty}} \leq & C\left[\|\varphi\|_{\mathbb{E}_{0_{p}}}+\left\|A^{\alpha} \varphi\right\|_{X_{1}}+\left\|A^{\alpha} \psi\right\|_{\mathbb{E}_{1 p}}+\left\|A^{\alpha} \psi\right\|_{X_{1}}\right. \\
& \left.+\int_{0}^{t}\left(\|g(., \tau)\|_{Y^{s, p}}+\|g(., \tau)\|_{X_{1}}\right) \mathrm{d} \tau\right] \tag{2.23}
\end{align*}
$$

Then from (2.22) and (2.23) in view of Remarks 2.1, 2.2 we obtain the estimate (2.14).

Let now show that problem (2.1) has a unique solution $u \in C^{(1)}\left([0, T] ; Y^{s, p}\right)$. Let's admit it is the opposite. So let's assume that the problem (2.1) has two solutions $u_{1}, u_{2} \in C^{(1)}\left([0, T] ; Y^{s, p}\right)$. Then by linearity of (2.1), we get that $v=u_{1}-u_{2}$ is also a solution of the corresponding homogenous equation

$$
u_{t t}-a \Delta u+A u=0, v(x, 0)=0, v_{t}(x, 0)=0, x \in \mathbb{R}^{n}, t \in(0, T)
$$

Moreover, by (2.7) we have the following estimate

$$
\left\|A^{\alpha} v\right\|_{X_{\infty}} \leq 0
$$

Since $N(A)=\{0\}$, the above estimate implies that $v=0$, i.e. $u_{1}=u_{2}$.
Theorem 2.2. Assume the Condition 2.1 and (2.13) is satisfied. Let $0 \leq \alpha<1-\frac{1}{2 p}$. Then for $\varphi \in \mathbb{E}_{0 p}, \psi \in \mathbb{E}_{1 p}, g(., t) \in Y^{s, p}$ for $t \in[0, T]$ and $g(x,.) \in L^{1}\left(0, T ; Y^{s, p}\right)$ for $x \in \mathbb{R}^{n}$ problem (2.1)-(2.2) has a unique solution $u \in C^{2}\left([0, T] ; Y^{s, p}\right)$ and the following estimate holds

$$
\begin{equation*}
\left(\left\|A^{\alpha} u\right\|_{Y^{s, p}}+\left\|A^{\alpha} u_{t}\right\|_{Y^{s, p}}\right) \leq C_{0}\left[\|\varphi\|_{\mathbb{E}_{0 p}}+\|\psi\|_{\mathbb{E}_{1 p}}+\int_{0}^{t}\|g(., \tau)\|_{Y^{s}, p} \mathrm{~d} \tau\right] \tag{2.24}
\end{equation*}
$$

for all $t \in[0, T]$.
Proof. From (2.11) and (2.17) we get the following uniform estimate

$$
\begin{align*}
& \left(\left\|\mathbb{F}^{-1}\left(1+|\xi|^{2}\right)^{\frac{s}{2}} A^{\alpha} \hat{u}\right\|_{X_{p}}+\left\|\mathbb{F}^{-1}\left(1+|\xi|^{2}\right)^{\frac{s}{2}} A^{\alpha} \hat{u}_{t}\right\|_{X_{p}}\right) \\
& \leq C\left\{\left\|\mathbb{F}^{-1}\left(1+|\xi|^{2}\right)^{\frac{s}{2}} C(\xi, t) A^{\alpha} \hat{\varphi}\right\|_{X_{p}}+\left\|\mathbb{F}^{-1}\left(1+|\xi|^{2}\right)^{\frac{s}{2}} A^{\alpha} S(\xi, t) \hat{\psi}\right\|_{X_{p}}\right.  \tag{2.25}\\
& \left.\quad+\int_{0}^{t}\left\|\left(1+|\xi|^{2}\right)^{\frac{s}{2}} A^{\alpha} \tilde{Q}(\xi, t) \hat{g}(\xi, \tau)\right\|_{X_{p}} \mathrm{~d} \tau\right\}
\end{align*}
$$

By using the Fourier multiplier theorem ([32], Theorem 4.3) and by reasoning as in Theorem 2.1 we get that $\left(1+|\xi|^{2}\right)^{-\frac{s}{2}} C(\xi, t),\left(1+|\xi|^{2}\right)^{-\frac{s}{2}} S(\xi, t)$ and $\left(1+|\xi|^{2}\right)^{-\frac{s}{2}} A^{\alpha} S(\xi, t)$ are Fourier multipliers in $L^{p}\left(\mathbb{R}^{n} ; H\right)$ uniformly with respect to $t \in[0, T]$. So, the estimate (2.25) by using the Minkowski's inequality for integrals implies (2.24).

The uniquness of (2.1)-(2.2) is obtained by reasoning as in Theorem 2.1.

## 3. Local Well Posedness of IVP for Nonlinear WE

In this section, we will show the local existence and uniqueness of solution of the nonlinear problem (1.1)-(1.2).

For this aim we need the following lemmas. By reasoning as in [7] [18] [35], we show the following lemmas concerning the behaviour of the nonlinear term in $E$-valued space $Y^{s, p}$. Here, let $E$ be a Banach algebra.

Lemma 3.1. Let $s \geq 0, f \in C^{[s]+1}(\mathbb{R} ; E)$ with $f(0)=0$. Then for any $u \in Y^{s, p} \cap L^{\infty}$, we have $f(u) \in Y^{s, p} \cap X_{\infty}$. Moreover, there is some constant $A(M)$ depending on $M$ such that for all $u \in Y^{s, p} \cap L^{\infty}$ with $\|u\|_{X_{\infty}} \leq M$,

$$
\begin{equation*}
\|f(u)\|_{Y^{s, p}} \leq C(M)\|u\|_{Y^{s, p}} \tag{3.1}
\end{equation*}
$$

Proof. For $s=0$ in view of $f(0)=0$, we get

$$
f(u)=\int_{0}^{1} f^{(1)}(\sigma u) \mathrm{d} \sigma
$$

It follows that

$$
\|f(u)\|_{X_{p}} \leq C(M)\|u\|_{X_{p}} .
$$

If $s$ is a positive integer, we have

$$
\begin{equation*}
\|f(u)\|_{Y^{s, p}} \leq C\left[\|f(u)\|_{X_{p}}+\sum_{k=1}^{n}\left\|\frac{\partial^{s}}{\partial x_{k}} f(u)\right\|_{X_{p}}\right] . \tag{3.2}
\end{equation*}
$$

By calculation of derivative and applying Holder inequality, we get

$$
\begin{align*}
\left\|\frac{\partial^{s}}{\partial x_{i}} f(u)\right\|_{X_{p}} & \leq \sum_{l=1}^{s} \sum_{\alpha}\left\|f^{(l)}(u) \frac{\partial^{\beta_{1}} u}{\partial x_{i}} \frac{\partial^{\beta_{2}} u}{\partial x_{i}} \cdots \frac{\partial^{\beta_{l}} u}{\partial x_{i}}\right\|_{X_{p}}  \tag{3.3}\\
& \leq \sum_{l=1}^{s} \sum_{\alpha}\left\|f^{(l)}(u)\right\|_{X_{\infty}} \prod_{k=1}^{l}\left\|\frac{\partial^{\beta_{k}} u}{\partial x_{i}}\right\|_{X_{p_{k}}}, i=1,2, \cdots, n,
\end{align*}
$$

where

$$
\beta=\left(\beta_{1}, \beta_{2}, \cdots, \beta_{l}\right), \beta_{k} \geq 1, \beta_{1}+\beta_{2}+\cdots+\beta_{l}=l, p_{k}=\frac{p l}{\beta_{k}} .
$$

Applying Gagliardo-Nirenberg's inequality in $E$-valued $\quad X_{p}$ spaces, we have

$$
\begin{equation*}
\left\|\frac{\partial^{\beta_{k}} u}{\partial x_{i}}\right\|_{X_{p_{k}}} \leq C\|u\|_{X_{\infty}}^{1-\frac{\beta_{k}}{l}}\left\|\frac{\partial^{s} u}{\partial x_{i}^{s}}\right\|_{X_{p}}^{\frac{\beta_{k}}{l}} . \tag{3.4}
\end{equation*}
$$

Hence, from (3.3) and (3.4) we get

$$
\begin{equation*}
\left\|\frac{\partial^{s}}{\partial x_{i}} f(u)\right\|_{X_{p}} \leq C(M)\left\|\frac{\partial^{s} u}{\partial x_{i}^{s}}\right\|_{X_{p}} \tag{3.5}
\end{equation*}
$$

Then combining (3.2), (3.3) and (3.5) we obtain (3.1).
Let $s$ is not integer number and $m=[s]$. From the above proof, we have

$$
\|f(u)\|_{Y^{m, p}} \leq C(M)\|u\|_{Y^{m, p}},\|f(u)\|_{Y^{m+1, p}} \leq C(M)\|u\|_{Y^{m+1, p}} .
$$

Then using interpolation between $W^{m+1, p}$ and $W^{m, p}$ yields (3.1) for all $s \geq 0$.

By using Lemma 3.1 and properties of convolution operators we obtain.
Corollary 3.1. Let $s \geq 0, f \in C^{[s]+1}(\mathbb{R} ; H)$ with $f(0)=0$. Moreover, assume $\Phi \in L^{\infty}\left(\mathbb{R}^{n} ; B(H)\right)$. Then for any $u \in Y^{s, p} \cap L^{\infty}$ we have, $f(u) \in Y^{s, p} \cap X_{\infty}$. Moreover, there is some constant $A(M)$ depending on $M$ such that for all $u \in Y^{s, p} \cap L^{\infty}$ with $\|u\|_{X_{\infty}} \leq M$,

$$
\|\Phi * f(u)\|_{Y^{s, p}} \leq C(M)\|u\|_{Y^{s, p}} .
$$

Lemma 3.2. Let $s \geq 0, f \in C^{[s]+1}(\mathbb{R} ; H)$. Then for any $M$ there is some constant $K(M)$ depending on $M$ such that for all $u, v \in Y^{s, p} \cap X_{\infty}$ with $\|u\|_{X_{\infty}} \leq M,\|v\|_{X_{\infty}} \leq M,\|u\|_{Y^{s, p}} \leq M,\|v\|_{Y^{s, p}} \leq M$,

$$
\|f(u)-f(v)\|_{Y^{s, p}} \leq K(M)\|u-v\|_{Y^{s, p}},\|f(u)-f(v)\|_{X_{\infty}} \leq K(M)\|u-v\|_{X_{\infty}} .
$$

Corollary 3.2. Let $s>\frac{n}{2}, f \in C^{[s]+1}(\mathbb{R} ; H)$. Then for any positive $M$ there is a constant $K(M)$ depending on $M$ such that for all $u, v \in Y^{s, p}$ with $\|u\|_{Y^{s, p}} \leq M,\|v\|_{Y^{s, p}} \leq M$,

$$
\|f(u)-f(v)\|_{Y^{s, p}} \leq K(M)\|u-v\|_{Y^{s, p}} .
$$

Lemma 3.3. If $s>0$, then $Y_{\infty}^{s, p}$ is an algebra. Moreover, for $f, g \in Y_{\infty}^{s, p}$,

$$
\|f g\|_{Y^{s, p}} \leq C\left[\|f\|_{X_{\infty}}+\|g\|_{Y^{s, p}}+\|f\|_{Y^{s, p}}+\|g\|_{X_{\infty}}\right] .
$$

By using, the Corollary 3.1 and Lemma 3.3 we obtain.
Lemma 3.4. Let $s \geq 0, f \in C^{[s]+1}(\mathbb{R} ; H)$ and $f(u)=O\left(|u|^{\gamma+1}\right)$ for $u \rightarrow 0$, $\gamma \geq 1$ be a positive integer. If $u \in Y_{\infty}^{s, p}$ and $\|u\|_{X_{\infty}} \leq M$, then

$$
\begin{gathered}
\|f(u)\|_{Y^{s, p}} \leq C(M)\left[\|u\|_{Y^{s, p}}\|u\|_{X_{\infty}}^{\gamma}\right] \\
\|f(u)\|_{X_{1}} \leq C(M)\|u\|_{X_{p}}^{p}\|u\|_{X_{\infty}}^{\gamma-1} .
\end{gathered}
$$

Corollary 3.3. Let $s \geq 0, \quad f \in C^{[s]+1}(\mathbb{R} ; H)$ and $f(u)=O\left(|u|^{\gamma+1}\right)$ for $u \rightarrow 0, \gamma \geq 1$ be a positive integer. Moreover, assume $\Phi \in L^{\infty}\left(\mathbb{R}^{n} ; B(E)\right)$. If $u \in Y_{\infty}^{s, p}$ and $\|u\|_{X_{\infty}} \leq M$, then

$$
\begin{gathered}
\|\Phi * f(u)\|_{Y^{s, p}} \leq C(M)\left[\|u\|_{Y^{s, p}}\|u\|_{X_{\infty}}^{\gamma}\right] \\
\|\Phi * f(u)\|_{X_{1}} \leq C(M)\|u\|_{X_{p}}^{p}\|u\|_{X_{\infty}}^{\gamma-1} .
\end{gathered}
$$

Lemma 3.5. Let $s \geq 0, f \in C^{[s]+1}(\mathbb{R} ; H)$ and $f(u)=O\left(|u|^{\gamma+1}\right)$ for $u \rightarrow 0$. Moreover, let $\gamma \geq 0$ be a positive integer. If $u, v \in Y_{\infty}^{s, p},\|u\|_{Y^{s, p}} \leq M$, $\|v\|_{Y^{s, p}} \leq M$ and $\|u\|_{X_{\infty}} \leq M,\|v\|_{X_{\infty}} \leq M$, then

$$
\|f(u)-f(v)\|_{Y^{s, p}} \leq C(M)\left[\left(\|u\|_{X_{\infty}}-\|v\|_{X_{\infty}}\right)\left(\|u\|_{Y^{s, p}}+\|v\|_{Y^{s, p}}\right)\left(\|u\|_{X_{\infty}}+\|v\|_{X_{\infty}}\right)^{\gamma-1}\right.
$$

$$
\|f(u)-f(v)\|_{X_{1}} \leq C(M)\left(\|u\|_{X_{\infty}}+\|v\|_{X_{\infty}}\right)^{\gamma-1}\left(\|u\|_{X_{p}}+\|v\|_{X_{p}}\right)\|u-v\|_{X_{p}} .
$$

Let $\mathbb{E}_{0}$ denotes the real interpolation space between $Y^{s, p}(A, H)$ and $X_{p}$ with $\theta=\frac{1}{2 p}$, i.e.

$$
\mathbb{E}_{0 p}=\left(Y^{s, p}(A, H), X_{p}\right)_{\frac{1}{2 p}, p}
$$

Remark 3.1. By using J. Lions-J. Peetre result (see e.g. [33], Section 1.8) we obtain that the map $u \rightarrow u\left(t_{0}\right), t_{0} \in[0, T]$ is continuous and surjective from $Y^{2, s, p}(A, H)$ onto $\mathbb{E}_{0 p}$ and there is a constant $C_{1}$ such that

$$
\begin{equation*}
\left\|u\left(t_{0}\right)\right\|_{\mathbb{E}_{0_{p}}} \leq C_{1}\|u\|_{Y^{2, s, p}(A, E)}, 1 \leq p \leq \infty . \tag{3.6}
\end{equation*}
$$

Let

$$
C^{2}\left(Y_{1}^{s, p}(A)\right)=C^{(2)}\left([0, T] ; Y_{1}^{s, p}(A, H)\right), C^{2, s}(A, H)=C^{(2)}\left([0, T] ; Y^{s, p}(A, H)\right) .
$$

Condition 3.1. Assume:

1) the Condition 2.1 holds for $s>\frac{2 p n}{2 p-1}\left(\frac{2}{q}+\frac{1}{p}\right), \quad p \in[1, \infty]$, for a $q \in[1,2]$ and $0 \leq \alpha<1-\frac{1}{2 p} ;$
2) the function $u \rightarrow f(u)$ : continuous from $u \in \mathbb{E}_{0 p}$ into $H$, $f \in C^{k}(\mathbb{R} ; H)$ with $k$ an integer, $k \geq s>\frac{n}{p}$ and $f(u)=O\left(|u|^{\gamma+1}\right)$ for $u \rightarrow 0, \gamma \geq 1$ be a positive integer.

Let

$$
\begin{gathered}
Y_{1}^{s, p}\left(A^{\alpha} ; H\right)=Y^{s, p}\left(A^{\alpha} ; H\right) \cap X_{1}\left(A^{\alpha}\right), Y^{s, p}\left(A^{\alpha} ; H\right)=\left\{u \in Y^{s, p}\left(A^{\alpha} ; H\right),\right. \\
\left.\|u\|_{Y^{s, p}\left(A^{\alpha} ; E\right)}=\left\|A^{\alpha} u\right\|_{X_{p}}+\left\|\mathbb{F}^{-1}\left(1+|\xi|^{2}\right)^{\frac{s}{2}} \hat{u}\right\|_{X_{p}}<\infty\right\} .
\end{gathered}
$$

Main aim of this section is to prove the following results:
Theorem 3.1. Let the Condition 3.1 holds. Then there exists a constant $\delta>0$ such that for any $\varphi \in Y_{0}\left(A^{\alpha}\right)$ and $\psi \in Y_{1}\left(A^{\alpha}\right)$ satisfying

$$
\begin{equation*}
\|\varphi\|_{\mathbb{E}_{0 p}}+\left\|A^{\alpha} \varphi\right\|_{X_{1}}+\|\psi\|_{\mathbb{E}_{1 p}}+\left\|A^{\alpha} \psi\right\|_{X_{1}} \leq \delta, \tag{3.7}
\end{equation*}
$$

problem (1.1)-(1.2) has a unique local strange solution $u \in C^{2}\left(Y_{1}^{s, p}(A)\right)$. Moreover,

$$
\begin{equation*}
\sup _{t \in[0, T]}\left(\|u(., t)\|_{\hat{Y}_{1}^{s, p}\left(A^{\alpha}, H\right)}+\left\|u_{t}(., t)\right\|_{\hat{Y}_{1}^{s, p}\left(A^{\alpha} ; H\right)}\right) \leq C \delta, \tag{3.8}
\end{equation*}
$$

where the constant $C$ depends only on $A, E, g, f$ and initial values.
Proof. By (2.5), (2.6) the problem of finding a solution $u$ of (1.1)-(1.2) is equivalent to finding a fixed point of the mapping

$$
\begin{equation*}
G(u)=C_{1}(t) \varphi(x)+S_{1}(t) \psi(x)+Q(u), \tag{3.9}
\end{equation*}
$$

where $C_{1}(t), S_{1}(t)$ are defined by (2.6) and $Q(u)$ is a map defined by

$$
Q(u)=-\int_{0}^{t} \mathbb{F}^{-1}[U(\xi, t-\tau) \hat{f}(u)(\xi, \tau)] \mathrm{d} \tau
$$

We define the metric space

$$
C(T, A)=C_{\delta}^{2}\left(Y_{1}^{s, p}(A)\right)=\left\{u \in C^{2, s}(A, E),\|u\|_{C^{2, s, p}(T, A)} \leq 5 C_{0} \delta\right\}
$$

equipped with the norm defined by

$$
\|u\|_{C(T, A)}=\sup _{t \in[0, T]}\left[\left\|A^{\alpha} u(., t)\right\|_{X_{\infty}}+\|u(., t)\|_{Y^{s, p}}+\left\|A^{\alpha} u_{t}(., t)\right\|_{X_{\infty}}+\left\|u_{t}(., t)\right\|_{Y^{s, p}}\right],
$$

where $\delta>0$ satisfies (3.7) and $C_{0}$ is a constant in Theorem 2.1 and 2.2. It is easy to prove that $C(T, A)$ is a complete metric space. From imbedding in So-bolev-Lions space $Y^{s, p}(A, E)$ (see e.g. [27], Theorem 1) and trace result (3.6) we got that $\|u\|_{X_{\infty}} \leq 1$ if we take that $\delta$ is enough small. For $\varphi \in Y_{0}\left(A^{\alpha}\right)$ and $\psi \in Y_{1}\left(A^{\alpha}\right)$, let

$$
\|\varphi\|_{\mathbb{E}_{0 p}}+\left\|A^{\alpha} \varphi\right\|_{X_{1}}+\|\psi\|_{\mathbb{E}_{1 p}}+\left\|A^{\alpha} \psi\right\|_{X_{1}}=\delta
$$

So, we will find $T$ and $M$ so that $G$ is a contraction in $C^{2, s, p}(T, A)$. By Theorems 2.1, 2.2 and Corollary $3.3 f(u) \in Y_{1}^{s, p}$. So, problem (1.1)-(1.2) has a solution that satisfies the following

$$
\begin{equation*}
G(u)(x, t)=C_{1}(t) \varphi+S_{1}(t) \psi+Q(u) \tag{3.10}
\end{equation*}
$$

where $C_{1}(t), S_{1}(t)$ are defined by (2.5) and (2.6). By assumptions, it is easy to see that the map $G$ is well defined for $f \in C^{[s]+1}\left(\mathbb{E}_{0 p} ; H\right)$. First, let us prove that the map $G$ has a unique fixed point in $C(T, A)$. For this aim, it is sufficient to show that the operator $G$ maps $C(T, A)$ into $C(T, A)$ and $G$ is strictly contractive if $\delta$ is suitable small. In fact, by (2.7) in Theorem 2.1, Corollary 3.3 and in view of (3.7), we have

$$
\begin{align*}
& \left\|A^{\alpha} G(u)\right\|_{X_{\infty}}+\left\|A^{\alpha} G_{t}(u)\right\|_{X_{\infty}} \\
& \leq 2 C_{0}\left[\|\varphi\|_{Y_{0}^{\alpha}\left(A^{\alpha}\right)}+\|\psi\|_{Y_{1}^{\alpha}}\left(A^{\alpha}\right)+\int_{0}^{t}\left(\|\hat{f}((u))\|_{Y^{s, p}}+\|\hat{f}((u))\|_{X_{1}}\right) \mathrm{d} \tau\right]  \tag{3.11}\\
& \leq 2 C_{0} \delta+C \int_{0}^{t}\left(\|u(\tau)\|_{Y^{s}, p}\|u(\tau)\|_{X_{\infty}}^{\gamma}+\|u(\tau)\|_{X_{p}}^{p}\|u(\tau)\|_{X_{\infty}}^{\gamma-1}\right) \mathrm{d} \tau \\
& \leq 2 C_{0} \delta+C\|u\|_{C^{2, s, p}(\tau, A)}^{\gamma+1} .
\end{align*}
$$

On the other hand, by (2.17), Corollary 3.3 and (3.7), we get

$$
\begin{align*}
& \left(\left\|A^{\alpha} G(u)\right\|_{Y^{s, p}}+\left\|A^{\alpha} G_{t}(u)\right\|_{Y^{s, p}}\right) \\
& \leq 2 C_{0}\left(\|\varphi\|_{\mathbb{E}_{0 p}}+\|\psi\|_{\mathbb{E}_{1 p}}+\int_{0}^{t}\|\hat{f}((u))\|_{Y^{s, p}} \mathrm{~d} \tau\right)  \tag{3.12}\\
& \leq 2 C_{0} \delta+\int_{0}^{t}\left[\|u(\tau)\|_{Y^{s, p}}\|u(\tau)\|_{X_{\infty}}^{\gamma}\right] \mathrm{d} \tau \\
& \leq 2 C_{0} \delta+C\|u\|_{C^{2, s, p}(T, A)}^{\gamma+1} .
\end{align*}
$$

Hence, combining (3.11) with (3.12) we obtain

$$
\begin{equation*}
\left\|A^{\alpha} G(u)\right\|_{Y_{\infty}^{s, p}}+\left\|A^{\alpha} G_{t}(u)\right\|_{Y_{\infty}^{s, p}} \leq 4 C_{0} \delta+C\|u\|_{C^{2, s, p}(T, A)}^{\gamma+1} . \tag{3.13}
\end{equation*}
$$

So, taking that $\delta$ is enough small such that $C\left(5 C_{8} \delta\right)^{\gamma}<\frac{1}{5}$, by Theorems 2.1, 2.2 and (3.13), $G$ maps $C(T, A)$ into $C(T, A)$.

Now, we are going to prove that the map $G$ is strictly contractive. Let $u_{1}, u_{2} \in C(T, A)$ given. From (3.10) we get

$$
G\left(u_{1}\right)-G\left(u_{2}\right)=\int_{0}^{T}\left[S(x, t-\tau)\left(\hat{f}\left(u_{1}\right)(\tau)-\hat{f}\left(u_{2}\right)(\tau)\right)\right] \mathrm{d} \tau, t \in(0, T)
$$

By (2.7) in Theorem 2.1 and Corollary 3.3, we have

$$
\begin{align*}
& \left\|A^{\alpha}\left[G\left(u_{1}\right)-G\left(u_{2}\right)\right]\right\|_{X_{\infty}}+\left\|A^{\alpha}\left[G\left(u_{1}\right)-G\left(u_{2}\right)\right]_{t}\right\|_{X_{\infty}} \\
& \leq \int_{0}^{t}\left(\left\|\left[\hat{f}\left(u_{1}\right)-\hat{f}\left(u_{2}\right)\right]\right\|_{Y^{s, p}}+\left\|\left[\hat{f}\left(u_{1}\right)-\hat{f}\left(u_{2}\right)\right]\right\|_{X_{1}}\right) \mathrm{d} \tau \\
& \leq \int_{0}^{t}\left\{\left\|u_{1}-u_{2}\right\|_{X_{\infty}}\left(\left\|u_{1}\right\|_{Y^{s}, p}+\left\|u_{2}\right\|_{Y^{s, p}}\right)\left(\left\|u_{1}\right\|_{X_{\infty}}+\left\|u_{2}\right\|_{X_{\infty}}\right)^{\gamma-1}\right.  \tag{3.14}\\
& \quad+\left\|u_{1}-u_{2}\right\|_{Y^{s, p}}\left(\left\|u_{1}\right\|_{X_{\infty}}+\left\|u_{2}\right\|_{X_{\infty}}\right)^{\gamma} \\
& \left.\quad+\left(\left\|u_{1}\right\|_{X_{\infty}}+\left\|u_{2}\right\|_{X_{\infty}}\right)^{\gamma-1}\left\|u_{1}+u_{2}\right\|_{X_{p}}\left\|u_{1}-u_{2}\right\|_{X_{p}}\right\} \\
& \leq C\left(\left\|u_{1}\right\|_{C(T, A)}+\left\|u_{2}\right\|_{C(T, A)}\right)^{\gamma}\left\|u_{1}-u_{2}\right\|_{C(T, A)} .
\end{align*}
$$

On the other hand, by (2.17) in Theorem 2.2, Corollary 3.3 and (3.7), we get

$$
\begin{align*}
& \left(\left\|A^{\alpha}\left[G\left(u_{1}\right)-G\left(u_{2}\right)\right]\right\|_{Y^{s, p}}+\left\|A^{\alpha}\left[G\left(u_{1}\right)-G\left(u_{2}\right)\right]_{t}\right\|_{Y^{s, p}}\right) \\
& \leq C \int_{0}^{t}\left\|\hat{f}\left(u_{1}\right)(\tau)-\hat{f}\left(u_{2}\right)(\tau)\right\|_{Y^{s, p}} \mathrm{~d} \tau \\
& \leq C \int_{0}^{t}\left\{\left\|u_{1}-u_{2}\right\|_{X_{\infty}}\left(\left\|u_{1}\right\|_{Y^{s, p}}+\left\|u_{2}\right\|_{Y^{s, p}}\right)\left(\left\|u_{1}\right\|_{X_{\infty}}+\left\|u_{2}\right\|_{X_{\infty}}\right)^{\gamma-1}\right.  \tag{3.15}\\
& \left.\quad+\left\|u_{1}-u_{2}\right\|_{Y^{s, p}}\left(\left\|u_{1}\right\|_{X_{\infty}}+\left\|u_{2}\right\|_{X_{\infty}}\right)^{\gamma}\right\} \mathrm{d} \tau \\
& \leq C\left(\left\|u_{1}\right\|_{C(T, A)}+\left\|u_{2}\right\|_{C(T, A)}\right)^{\gamma}\left\|u_{1}-u_{2}\right\|_{C(T, A)} .
\end{align*}
$$

Combining (3.14) with (3.15) yields

$$
\begin{equation*}
\left\|G\left(u_{1}\right)-G\left(u_{2}\right)\right\|_{C(T, A)} \leq C\left(\left\|u_{1}\right\|_{C(T, A)}+\left\|u_{2}\right\|_{C(T, A)}\right)^{\gamma}\left\|u_{1}-u_{2}\right\|_{C(T, A)} . \tag{3.16}
\end{equation*}
$$

Taking $\delta$ is enough small, from (3.16) we obtain that $G$ is strictly contractive in $C(T, A)$. Using the contraction mapping principle, we get that $G(u)$ has a unique fixed point $u(x, t) \in C(T, A)$ and $u(x, t)$ is the solution of (1.1)-(1.2).

Let us show that this solution is a unique in $C^{2, s}(A, H)$. Let $u_{1}, u_{2} \in C^{2, s}(A, H)$ are two solutions of (1.1)-(1.2). Then for $u=u_{1}-u_{2}$, we have

$$
\begin{equation*}
u_{t t}-a \Delta u+A u=\left[f\left(u_{1}\right)-f\left(u_{2}\right)\right] \tag{3.17}
\end{equation*}
$$

Hence, by Minkowski's inequality for integrals and by Theorem 2.2 from (3.17) we obtain

$$
\begin{equation*}
\left\|u_{1}-u_{2}\right\|_{Y^{s, p}} \leq C_{2}(T) \int_{0}^{t}\left\|u_{1}-u_{2}\right\|_{Y^{s, p}} \mathrm{~d} \tau . \tag{3.18}
\end{equation*}
$$

From (3.18) and Gronwall's inequality, we have $\left\|u_{1}-u_{2}\right\|_{Y^{s, p}}=0$, i.e. problem (1.1)-(1.2) has a unique solution in $C^{2, s}(A, H)$.

Consider the problem (1.1)-(1.2), when $\varphi \in \mathbb{E}_{0 p}$ and $\psi \in \mathbb{E}_{1 p}$. Let

$$
C^{(i)}\left(Y^{s, 2}\right)=C^{(i)}\left([0, \infty) ; Y^{s, 2}(A, H)\right), i=0,1,2
$$

## 4. Application

Consider the problem (1.4). Let

$$
\begin{gathered}
X_{p, 2}=L^{p}\left(\mathbb{R}^{n} ; L^{2}(0,1)\right), Y^{s, p, 2}=H^{s, p}\left(\mathbb{R}^{n} ; L^{2}(0,1)\right), \\
Y_{q}^{s, p, 2}=H^{s, p}\left(\mathbb{R}^{n} ; L^{2}(0,1)\right) \cap L^{q}\left(\mathbb{R}^{n} ; L^{2}(0,1)\right), \\
Y^{s, p, 2}=H^{s, p}\left(\mathbb{R}^{n} ; H^{2,2}(0,1), L^{2}(0,1)\right), 1 \leq p, q \leq \infty \\
E_{0 p, 2}=\left(Y^{s, p}\left(A, L^{2}(0,1)\right) \cap X_{p .2}, X_{p, 2}\right)_{\frac{1}{2 p}, p} \\
E_{1 p, 2}=\left(Y^{s, p}\left(A, L^{2}(0,1)\right) \cap X_{p, p_{1}}, X_{p, 2}\right)_{\frac{1+p}{2 p}, p}
\end{gathered}
$$

Let $\omega_{1}=\omega_{1}(y), \omega_{2}=\omega_{2}(y)$ be roots of equation $b_{1}(y) \omega^{2}+1=0$. Let

$$
v(y)=\left|\begin{array}{ll}
\left(-\omega_{1}\right)^{m_{1}} & \alpha_{1}
\end{array} \beta_{1} \omega_{1}^{m_{1}}\right|, \eta_{1}(\xi)=\left[a|\xi|^{2}+A_{1}\right]^{\frac{1}{2}} .
$$

Here,

$$
\begin{gathered}
E_{i p}\left(L^{2}(0,1)\right)=W^{s\left(1-\theta_{i}\right), p}\left(\mathbb{R}^{n} ; L^{2}(0,1)\right) \cap L^{p}\left(\mathbb{R}^{n} ; H^{2\left(1-\theta_{i}\right), 2}(0,1)\right) \\
\theta_{i}=\frac{1+i p}{2 p}, i=0,1, p_{1} \in(1, \infty)
\end{gathered}
$$

From Theorem 3.1 we obtain the following result.
Theorem 4.1. Suppose the following conditions are satisfied:

1) $a \in S_{\phi_{1}}$ for $0 \leq \phi_{1}<\pi, \quad 0 \leq \alpha<1-\frac{1}{2 p}, \quad p \in[1, \infty]$ and $v(y) \neq 0$ for all $y \in[0,1]$;
2) $b_{1} \in V M O \cap L^{\infty}(0,1), \quad R e \omega_{k} \neq 0$ and $\frac{\lambda}{\omega_{k}} \in S\left(\phi_{1}\right)$ for a.e. $x \in(0,1)$, $\phi_{1} \in[0, \pi) ; \quad b_{0} \in V M O \cap L^{\infty}(0,1), \quad b_{1}(0)=b_{1}(1), \quad b_{0}(0)=b_{0}(1)$.
3) $\varphi \in Y_{1}^{s, p, 2}, \psi \in Y_{1}^{s-1, p, 2}$ and $f(., t) \in Y_{1}^{s, p, 2}$ for $s>\frac{2 p n}{2 p-1}\left(\frac{2}{r}+\frac{1}{p}\right)$ for $p \in[1, \infty], r \in[1,2]$ and $t \in[0, T]$.
4) The function $u \rightarrow F(u)$ is continuous in $u \in E_{02}$ for $x, t \in \mathbb{R}^{n} \times[0, T]$;
moreover $F(u) \in C^{(1)}\left(E_{02} ; L^{2}(0,1)\right)$.
Then problem (1.9)-(1.10) has a unique local strange solution

$$
u \in C^{(2)}\left(\left[0, T_{0}\right) ; Y_{\infty}^{s, p, 2}\right)
$$

where $T_{0}$ is a maximal time interval that is appropriately small relative to $M$. Moreover, if

$$
\|\varphi\|_{\mathbb{E}_{0 p, p 1}}+\left\|A^{\alpha} \varphi\right\|_{X_{1}}+\|\psi\|_{\mathbb{E}_{1 p, p_{1}}}+\left\|A^{\alpha} \psi\right\|_{X_{1}} \leq \delta
$$

then $T_{0}=\infty$.
Proof. By virtue of [30], $L^{2}(0,1)$ is a Fourier type space. By virtue of [30], the operator $A_{1}$ defined by (1.3) is sectorial in $L^{2}(0,1)$. Moreover, by interpolation of Banach spaces ([33], Section 1.3), we have

$$
\begin{aligned}
E_{02} & =\left(W^{s, p}\left(\mathbb{R}^{n} ; H^{2}(0,1), L^{2}(0,1)\right), L^{p}\left(\mathbb{R}^{n} ; L^{2}(0,1)\right)\right)_{\frac{1}{2 p}, p} \\
& =B_{p, 2}^{s\left(1-\frac{1}{2 p}\right)}\left(\mathbb{R}^{n} ; H^{2 l\left(1-\frac{1}{2 p}\right)}(0,1), L^{2}(0,1)\right) .
\end{aligned}
$$

Then, by using the properties of spaces $Y^{s, p, 2}, Y_{\infty}^{s, p, 2}, E_{02}$ we get that all conditions of Theorem 3.1 are hold, i.e., we obtain the conclusion.

## 5. Conclusion

Here, assuming enough smoothness on the initial data in terms of interpolation spaces $H(A), H$ and the sectorial operators, the existence, uniqueness, regularity properties of solutions are established. By choosing the space $H$ and $A$, the regularity properties of solutions of a wide class of wave equations in the field of physics are obtained.

## Data Availability

Data sharing is not applicable to this article as no datasets were generated or analysed during the current study.

## Conflicts of Interest

The authors declare no conflicts of interest regarding the publication of this paper.

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