

Stability of Triangular Points of the Generalized Photogravitational Robes Restricted Three-Body Problem

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ABSTRACT

The linear stability of the triangular points was studied for the Robes restricted three-body problem when the bigger primary (rigid shell) is oblate spheroid and the second primary is radiating. The critical mass obtained depends on the oblateness of the rigid shell and radiation of the second primary as well as the density parameter k . The stability of the triangular points depends largely on the values of k . The destabilizing tendencies of the oblateness and radiation factors were enhanced when $k > 0$ and weakened for $k < 0$.

Keywords: Stability; Triangular Points; Robes Problem; Density Parameter

1. Introduction

Robe [1] introduced a new kind of restricted three-body problem that incorporates the effect of buoyancy force. One of the primaries m_1 is a rigid shell of mass filled with homogeneous incompressible fluid of density ρ_1 . The second primary m_2 is a point mass located outside the shell. The third body m_3 is the particle of negligible mass of density ρ_3 which moves inside the shell under the influences of the gravitational attraction of the primaries and the buoyancy force of the fluid of density ρ_1 . Robe studied the motion of the infinitesimal mass when m_2 describes both circular and elliptic orbits. He obtained the equilibrium points and showed that, for the circular case, the equilibrium point is linearly stable when $\rho_3 < \rho_1$ and unstable when $\rho_1 < \rho_3$.

Robes model may be useful for studying the small oscillations of the earth's inner core by taking into consideration the moon's attraction. The model is also applicable to the study of the motion of the artificial satellite under the influence of the earth's attraction.

Robes problem has been modified to define a new problem (Shrivastava and Garain [2], Plastino and Plastino [3], Giordano, Plastino and Plastino [4], Hallan and Rana [5] and Hallan and Mangang [6]).

In our model we consider a rigid shell which is oblate spheroid and the second primary which radiates to study the effect of oblateness of the first primary and radiation of the second primary on the stability of the triangular

equilibrium points of the Robes restricted three-body problem.

The paper consists of four sections. Section one establishes the relevant equations of motion that incorporates the effect of buoyancy force using some basic assumptions. In the second section we obtained the equilibrium points. Section three deals with the variational equations of motion of the problem and solutions of the resulting characteristic equation obtained. In section four, we obtained the critical mass of the mass parameter. This is followed by the conclusion on the findings.

2. Equations of Motion

Let the mass of the rigid shell be m_1 and the point mass be m_2 . Let the density of the incompressible fluid inside the shell be ρ_1 and that of the infinitesimal mass be ρ_3 and its mass m . Let A denote the oblateness coefficient of the first primary such that $0 < A \ll 1$ and q the radiation force of the second primary which given by $F_p = F_g(1-q)$ such that $0 < 1-q \ll 1$.

Let M_1 , M_2 and M_3 be the centers of m_1 , m_2 and m respectively such that $M_1M_3 = r_1$ and $M_2M_3 = r_2$. Let G be the gravitational constant and (x, y) the coordinates of the infinitesimal mass m . Let the line joining m_1 and m_2 be the x -axis. Then the total potential acting on m is

$$\frac{-Gm_2q}{r_2} + \frac{4}{3}\pi G\rho_1\left(1 - \frac{\rho_1}{\rho_3}\right)r_1^2 - \frac{Gm_1}{r_1} - \frac{Gm_1A}{2r_1^3} \quad (1)$$

where

$$\begin{aligned} r_1^2 &= (x - x_1)^2 + y^2 \\ r_2^2 &= (x - x_2)^2 + y^2 \end{aligned} \tag{2}$$

Let the coordinates of m_1 and m_2 be $(x_1, 0)$ and $(x_2, 0)$ respectively. In the dimensionless rotational coordinate system we choose the unit of mass to be the sum of the masses of the primaries ($m_1 = 1 - \mu$ and $m_2 = \mu$). We take the unit of length equal to the distance between the primaries and is chosen such that $G = 1$.

The equations of motion of the infinitesimal body are (AbdulRaheem and Singh, [7]),

$$\begin{aligned} \ddot{x} - 2n\dot{y} &= \Omega_x \\ \ddot{y} + 2n\dot{x} &= \Omega_y \end{aligned} \tag{3}$$

where

$$\Omega = \frac{1}{2}n^2(x^2 + y^2) - kr_1^2 + \frac{1-\mu}{r_1} + \frac{\mu}{r_2}q + \frac{1-\mu}{2r_1^3}A \tag{4}$$

$$k = \frac{4}{3}\pi\rho_1\left(1 - \frac{\rho_1}{\rho_3}\right), \mu = \frac{m_2}{m_1 + m_2},$$

$$0 < \mu \leq \frac{1}{2}, n^2 = 1 + \frac{3}{2}A$$

$$\begin{aligned} r_1^2 &= (x + \mu)^2 + y^2 \\ r_2^2 &= (x - 1 + \mu)^2 + y^2 \end{aligned} \tag{5}$$

3. Equilibrium Points

Equilibrium points exist when

$$\Omega_x = \Omega_y = 0 \tag{6}$$

For $k \neq 0$ we have

$$\begin{aligned} \Omega_x &= n^2x - 2k(x + \mu) - \frac{(1-\mu)(x + \mu)}{r_1^3} \\ &\quad - \frac{\mu(x - 1 + \mu)}{r_2^3}q - \frac{3(1-\mu)(x + \mu)}{2r_1^5}A \end{aligned} \tag{7}$$

$$\Omega_y = n^2y - 2ky - \frac{(1-\mu)y}{r_1^3} - \frac{\mu y}{r_2^3}q - \frac{3(1-\mu)y}{2r_1^5}A. \tag{8}$$

Triangular Points

The triangular points are given by the equations

$$\Omega_x = 0, \quad \Omega_y = 0, \quad y \neq 0.$$

That is

$$\begin{aligned} x \left[n^2 - 2k - \frac{1-\mu}{r_1^3} - \frac{\mu}{r_2^3}q - \frac{3(1-\mu)}{2r_1^5}A \right] \\ - \mu \left[2k + \frac{1-\mu}{r_1^3} - \frac{1-\mu}{r_2^3}q - \frac{3(1-\mu)}{2r_1^5}A \right] = 0 \end{aligned} \tag{9}$$

and

$$y \left[n^2 - 2k - \frac{1-\mu}{r_1^3} - \frac{\mu}{r_2^3}q - \frac{3(1-\mu)}{2r_1^5}A \right] = 0. \tag{10}$$

Equations (9) and (10) give

$$n^2 - 2k - \frac{1}{r_1^3} - \frac{3}{2} \frac{A}{r_1^5} = 0 \tag{11}$$

$$n^2 - 2k - \frac{q}{r_2^3} = 0 \tag{12}$$

Knowing r_1 and r_2 from Equations (11) and (12) the exact coordinates of the triangular points are obtained by using Equation (5) for x and y .

Thus

$$\begin{aligned} x &= \frac{1}{2} - \mu + \frac{1}{2}(r_1^2 - r_2^2) \\ y &= \pm \left[\frac{1}{2}(r_1^2 + r_2^2) - \frac{1}{4} - \frac{1}{4}(r_1^2 - r_2^2)^2 \right]^{\frac{1}{2}} \end{aligned} \tag{13}$$

When the bigger primary is not oblate, the smaller primary is not radiating and $\rho_1 = \rho_3$

$$r_i = 1 \quad (i = 1, 2). \tag{14}$$

We assume the solutions of equations (11) and (12) are

$$r_i = 1 + \alpha_i \quad (i = 1, 2) \tag{15}$$

where α_1 and α_2 are very small perturbations. Using Equations (11) and (12) and restricting ourselves to linear terms in A , $1 - q$ and k , we obtain

$$\begin{aligned} x &= \frac{1}{2} - \mu + \left(\frac{3 + 4k}{3 + 2k} \right) \left[-\frac{1}{3}(1 - q) + \frac{1}{2}A \right] \\ y &= \pm \sqrt{\frac{9 + 16k}{12}} \left[1 + \frac{3}{2(3 + 2k)} \left\{ -\frac{1}{3}(1 - q) - \frac{1}{2}A \right\} \right] \end{aligned} \tag{16}$$

The coordinates $(x, \pm y)$ obtained in Equation (16) are the triangular points and are denoted by L_4 and L_5 .

4. Stability of Triangular Points

Putting $x = x_0 + \xi$, $y = y_0 + \eta$ in Equation (3), in order to study the motion near the triangular points L_4 and L_5 , we obtain the variational equations of motion as

$$\begin{aligned} \ddot{\xi} - 2n\dot{\eta} &= \Omega_{xx}(x_0, y_0)\xi + \Omega_{xy}(x_0, y_0)\eta \\ \dot{\eta} + 2n\dot{\xi} &= \Omega_{xy}(x_0, y_0)\xi + \Omega_{yy}(x_0, y_0)\eta \end{aligned} \tag{17}$$

The characteristic equation is

$$\lambda^4 - (\Omega_{xx}^0 + \Omega_{yy}^0 - 4n^2)\lambda^2 + \Omega_{xx}^0\Omega_{yy}^0 - (\Omega_{xy}^0)^2 = 0 \tag{18}$$

where the superscript 0 indicates that the partial derivatives are evaluated at the triangular points (x_0, y_0) , and are given by

$$\begin{aligned} \Omega_{xx}^0 &= 3\left(\frac{1-2k}{3+4k}\right)\left[\frac{3}{4}+a_1+\mu b_1\right] & \Omega_{xy}^0 &= 3\left(\frac{1-2k}{3+4k}\right)\sqrt{3+\frac{16}{3}k} \\ \Omega_{yy}^0 &= 3\left(\frac{1-2k}{3+4k}\right)\left[\frac{3}{4}\left(3+\frac{16}{3}k\right)+a_2+\mu b_2\right] & & \cdot\left[-\frac{3}{4}+a_3+\mu\left(\frac{3}{2}+b_3\right)\right] \end{aligned}$$

where

$$\begin{aligned} a_1 &= \frac{1}{4}\left[\frac{9}{2}\left(\frac{5-2k}{3-4k}\right)A+\left(\frac{9+4k}{3+2k}\right)A+\frac{9A}{3+4k}+4\left(\frac{3+4k}{3+2k}\right)(1-q)\right] \\ b_1 &= \frac{1}{4}\left[-3\left(\frac{9+16k}{3+2k}\right)A-\frac{9A}{3+4k}-2\left(\frac{9+16k}{3+2k}\right)(1-q)\right] \\ a_2 &= \frac{1}{12}\left(3+\frac{16}{3}k\right)\left[\frac{9}{2}\left(\frac{7+4k}{3-2k}\right)A-3\left(\frac{3-8k}{3+2k}\right)A+\frac{9(3+4k)}{3+4k}A-4\left(\frac{3+4k}{3+2k}\right)(1-q)\right] \\ b_2 &= \frac{1}{12}\left(3+\frac{16}{3}k\right)\left(\frac{18}{3+2k}\right)(1-q) \\ a_3 &= \frac{1}{12}\left[-\frac{3}{2}\left(\frac{57-20k}{3-2k}\right)A-3\left(\frac{3+16k}{3+2k}\right)A-\frac{9(3+4k)}{3+8k}A-4\left(\frac{3+4k}{3+2k}\right)(1-q)\right] \\ b_3 &= \frac{1}{4}\left[9\left(\frac{11-4k}{3-2k}\right)A-3\left(\frac{3-8k}{3+2k}\right)A+\frac{9(3+4k)}{3+8k}A+2\left(\frac{3-4k}{3+2k}\right)(1-q)\right] \end{aligned} \tag{19}$$

Each $|a_i|, |b_i|$ is very small.

The characteristic equation becomes

$$\begin{aligned} \lambda^4 - \left[3\left(\frac{1-2k}{3+4k}\right)(b_1+b_2)\right]\mu + 9\left(\frac{1-2k}{3+4k}\right) - 4 + 3\left(\frac{1-2k}{3+4k}\right)\left(\frac{16}{3}k+a_1+a_2\right) - 6A\varphi^2 \Big] \lambda^2 \\ - \frac{9}{4}\left(\frac{1-2k}{3+4k}\right)^2\left(3+\frac{16}{3}k\right)\left[3(3+4b_3)\mu^2 + \left(-9-3b_1-\frac{3b_2}{3+\frac{16}{3}k}+12a_3-6b_3\right)\mu\right] \times -3a_1 - \frac{3a_2}{3+\frac{16}{3}k} - 6a_3 = 0 \end{aligned}$$

Its roots are

$$\lambda^4 - \left[3\left(\frac{1-2k}{3+4k}\right)(b_1+b_2)\mu + 9\left(\frac{1-2k}{3+4k}\right) - 4 + 16k\left(\frac{1-2k}{3+4k}\right) + 3\left(\frac{1-2k}{3+4k}\right)a_1 + 3\left(\frac{1-2k}{3+4k}\right)a_2 - 6A \pm \sqrt{\Delta}\right]$$

We observe that the roots are functions of μ, q, A, k and they depends upon the nature of the discriminant Δ and is given by

$$\begin{aligned} \Delta &= 9\left(1-\frac{20}{3}k\right)\left(1+\frac{16}{9}k\right)(3+4b_3)\mu^2 + \left[\left\{-2\left(1-\frac{10}{3}k\right)\left(1+\frac{14}{3}k\right)-9\left(1-\frac{20}{3}k\right)\left(1+\frac{19}{9}k\right)\right\}b_1 \right. \\ &\left. \left\{-2\left(1-\frac{10}{3}k\right)\left(1+\frac{14}{3}k\right)-3\left(1-\frac{28}{3}k\right)\right\}b_2 + 18\left(1-\frac{20}{3}k\right)\left(1+\frac{16}{9}k\right)b_3 + 36\left(1-\frac{20}{3}k\right)\left(1+\frac{16}{9}k\right)a_3 \right. \\ &\left. - 27\left(1-\frac{20}{3}k\right)\left(1+\frac{16}{9}k\right)\right]\mu + \left(1+\frac{14}{3}k\right)^2 + \left\{-2\left(1-\frac{10}{3}k\right)\left(1+\frac{14}{3}k\right)-9\left(1-\frac{20}{3}k\right)\left(1+\frac{16}{9}k\right)\right\}a_1 \\ &+ \left\{-2\left(1-\frac{10}{3}k\right)\left(1+\frac{14}{3}k\right)-3\left(1-\frac{28}{3}k\right)\right\}a_2 - 18\left(1-\frac{20}{3}k\right)\left(1+\frac{16}{9}k\right)a_3 + 4(3+14k)A \end{aligned} \tag{20}$$

Three cases can be discussed for Δ :

- 1) When $\Delta > 0$, we have that the roots are negative showing that the triangular points are linearly stable.
- 2) When $\Delta < 0$, we have that the real parts of two of the four roots are positive and equal, showing that the triangular points are unstable.
- 3) When $\Delta = 0$, we have that the double roots give

$$\begin{aligned} \mu_c = & \frac{1}{2} \left(1 - \sqrt{\frac{P-4Q}{P}} \right) \frac{1}{2} \left[-2 \left(1 - \frac{10}{3}k \right) \left(1 + \frac{14}{3}k \right) - 9 \left(1 - \frac{20}{3}k \right) \left(1 + \frac{19}{9}k \right) \right] \left[\frac{2a_1 + b_1}{\sqrt{P(P-4Q)}} - \frac{b_1}{P} \right] \\ & \frac{1}{2} \left[-2 \left(1 - \frac{10}{3}k \right) \left(1 + \frac{14}{3}k \right) - 9 \left(1 - \frac{20}{3}k \right) \left(1 + \frac{19}{9}k \right) \right] \left[\frac{2a_2 + b_2}{\sqrt{P(P-4Q)}} - \frac{b_2}{P} \right] \\ & \frac{1}{3} \left[\frac{4Q}{\sqrt{P(P-4Q)}} + 2 \frac{\sqrt{P-4Q}}{\sqrt{P}} - \frac{\sqrt{P}}{\sqrt{P(P-4Q)}} - 1 \right] b_3 - \frac{2}{3} a_3 + \frac{4(3+14k)}{\sqrt{P(P-4Q)}} A \end{aligned} \tag{21}$$

where $P = 9 \left(1 - \frac{20}{3}k \right) \left(3 + \frac{16}{3}k \right)$ and $Q = \left(-1 - \frac{14}{3}k \right)^2$. Restricting ourselves to linear terms in k , $1-q$ and A , and neglecting the product $(1-q)A$, we find that

$$\mu_c = \mu_0 + \mu_{br} + \mu_p \tag{22}$$

where

$$\begin{aligned} \mu_0 &= \frac{1}{2} \left(1 - \sqrt{\frac{23}{27}} \right) \\ \mu_{br} &= -\frac{2}{27\sqrt{69}}(1-q) - \frac{1}{9} \left(1 + \frac{13}{\sqrt{69}} \right) A \\ \mu_p &= -\frac{128}{27\sqrt{69}}k - \frac{64}{27} \left(1 + \frac{225073}{2208\sqrt{69}} \right) k(1-q) \\ &\quad - \frac{98}{81} \left(1 + \frac{38990441}{18032\sqrt{69}} \right) kA \end{aligned}$$

Equation (22) gives the critical mass value μ_c of the mass parameter. It reflects the effect of the oblateness of the first primary (rigid mass) and the radiation of the second primary on the critical mass of the Robes restricted three-body problem, indicating a destabilizing effect on the triangular equilibrium points.

The destabilizing tendencies of both the oblateness and radiating factors are further enhanced when $k > 0$ ($\rho_1 < \rho_3$) and weakened when $k < 0$ ($\rho_1 > \rho_3$).

When $k = 0$ we confirm the result of Abdul Raheem and Singh (2006) for $\varepsilon_1 = \varepsilon_2 = 0$, $q_1 = 1$ and $A_2 = 0$. When $k = 0$, $q = 1$ and $A = 0$ we obtain the critical mass value of the classical restricted three-body problem.

secular terms, showing that the triangular points are unstable.

5. Critical Mass

The solution of the equation $\Delta = 0$ gives the critical mass value μ_c of the mass parameter. That is

6. Conclusions

The effect of oblateness of the first primary (rigid shell) and radiation of the second primary on the stability of the triangular equilibrium points of the Robes restricted three-body problem was studied. The value of the critical mass value obtained depends on the oblateness coefficient of the rigid shell, radiation factor of the second primary and the density of the fluid and that of the infinitesimal mass in the shell.

It was observed that the oblateness and radiation factors have destabilizing tendencies on the triangular equilibrium points. These destabilizing tendencies are further enhanced or weakened, depending on whether the density of the fluid in the shell is less than that of the infinitesimal mass or the density of the infinitesimal mass is less than that of the fluid.

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