

A Note on the Characterization of Zero-Inflated Poisson Model

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Received 14 March 2015; accepted 16 April 2015; published 20 April 2015

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Abstract

Zero-Inflated Poisson model has found a wide variety of applications in recent years in statistical analyses of count data, especially in count regression models. Zero-Inflated Poisson model is characterized in this paper through a linear differential equation satisfied by its probability generating function [1] [2].

Keywords

Zero-Inflated Poisson Model, Probability Generating Function, Linear Differential Equation

1. Introduction

A random variable X is said to have a zero-inflated Poisson distribution if its probability mass function is given by

$$p(x; \theta, \varphi) = \begin{cases} \varphi + (1 - \varphi)e^{-\theta}, & x = 0 \\ (1 - \varphi) \frac{e^{-\theta} \theta^x}{x!}, & x = 1, 2, \dots \end{cases} \quad (1)$$
$$= \varphi p_0(x) + (1 - \varphi) p_1(x), \quad 0 < \varphi < 1$$

where $p_0(x) = \begin{cases} 1, & x = 0 \\ 0, & x \neq 0 \end{cases}$ and $p_1(x) = \frac{e^{-\theta} \theta^x}{x!}$, $x = 0, 1, 2, \dots$, $\theta > 0$.

Thus, the distribution of X is a mixture of a distribution degenerate at zero and a Poisson distribution with mean θ .

2. Probability Generating Function

The probability generating function (pgf) of X is given by

$$\begin{aligned} f(s) &= E(s^X) \\ &= \sum_{k=0}^{\infty} p_k s^k \\ &= \varphi + (1-\varphi)e^{-\theta} + (1-\varphi)e^{-\theta} \sum_{k=1}^{\infty} \frac{(\theta s)^k}{k!}, \quad 0 < s < 1. \end{aligned}$$

$$f(s) = \varphi + (1-\varphi)e^{\theta(s-1)}.$$

3. Characterization

Let X be a non-negative integer valued random variable with $0 < P(X=0) < 1$ and the pgf $f(s)$. Then, the distribution of X is zero-inflated Poisson if and only if $f(s) = a + bf'(s)$, where $0 < a < 1$, b are constants and $f'(s)$ is the first derivative of $f(s)$.

Proof:

1) Suppose that X has a zero-inflated Poisson distribution specified in (1.1). Then the pgf of X is given by

$$f(s) = \varphi + (1-\varphi)e^{\theta(s-1)}$$

On differentiation, we get

$$\begin{aligned} f'(s) &= (1-\varphi)e^{\theta(s-1)}\theta \\ &= \theta\{f(s) - \varphi\}, \end{aligned}$$

$$f(s) = \varphi + \frac{1}{\theta}f'(s).$$

Hence $f(s)$ satisfies the linear differential equation

$$f(s) = a + bf'(s). \quad (2)$$

2) Suppose that the pgf $f(s)$ of X satisfies

$$f(s) = a + bf'(s).$$

If $b=0$, then $f(s)=a$ and in turn $f(0)=f(1)=a$. By the property of the pgf, $f(1)=1=a$. But $f(0)=P(X=0)=a$, which is not possible because $P(X=0) < 1$.

Therefore $b \neq 0$.

3) The Linear Differential Equation

The linear differential equation $f(s) = a + bf'(s)$ is of the form

$$\frac{dy}{dx} + Py = Q$$

where P and Q are functions of x .

Then its solution is given by

$$ye^{\int P dx} = \int Q e^{\int P dx} dx + c,$$

where c is an arbitrary constant.

Here

$$bf'(s) - f(s) = -a$$

$$\Rightarrow f'(s) - \frac{1}{b}f(s) = -\frac{a}{b}.$$

Hence $P = -\frac{1}{b}$, $Q = -\frac{a}{b}$.

Therefore the solution of the Equation (2) is given by

$$f(s) = a + ce^{s/b}.$$

We now extract the probabilities $P(X=k) = p_k$, $k = 0, 1, 2, \dots$ using the above solution.

Since $f(s)$ is a pgf, $p_k = \frac{f^{(k)}(0)}{k!}$, where $f^{(k)}(s)$ is the k -th derivative of $f(s)$.

We get

$$p_0 = a + c, \quad p_1 = c \frac{1}{b}, \quad p_2 = c \frac{1}{2!} \frac{1}{b^2}, \text{ and so on.}$$

Now,

$$f(s) = \sum_{k=0}^{\infty} p_k = a + ce^{1/b}$$

Since $f(1) = 1$, it is easy to see that $c = (1-a)e^{-1/b}$,

We have

$$p_k = \begin{cases} a + (1-a)e^{-1/b}, & k = 0; \\ (1-a) \frac{e^{-1/b} (1/b)^k}{k!}, & k = 1, 2, 3, \dots. \end{cases}$$

with $\varphi = a$ and $\theta = 1/b$.

Therefore X has the pgf specified in Equation (1). □

References

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