

# Dramatic Influence of the Magnetoelectric Effect on the Existence of the New SH-SAWs Propagating in Magnetoelastic Composites

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## Abstract

This comparative study acquaints the reader with some properties of the eighth and tenth new shear-horizontal surface acoustic waves (SH-SAWs) propagating along the free surface of the magnetoelastic (6 mm) medium. These new nondispersive SH-SAWs cannot exist when the electromagnetic constant  $\alpha$  is equal to zero. The piezoelectromagnetic SH bulk acoustic wave and the surface Bleustein-Gulyaev-Melkumyan (BGM) wave are also chosen for comparison. The main problem of this report is the demonstration of the fact that the new waves can propagate slower than the BGM wave. This problem can be very important due to the fact that among the other known SH-SAWs the BGM wave can propagate significantly slower than the corresponding SH bulk acoustic wave. Two new SH-SAWs are analytically and graphically studied in dependence on the electromagnetic constant  $\alpha$ . For the graphical study, two (6 mm) composites are used: BaTiO<sub>3</sub>-CoFe<sub>2</sub>O<sub>4</sub> and PZT-5H-Terfenol-D. For the second composite it is solidly demonstrated that for small values of  $\alpha$ , the eighth new SH-SAW cannot exist and its velocity starts with zero at some small threshold value of  $\alpha$  rapidly reaching the BGM-wave velocity. This means that a weak magnetoelectric effect can dramatically slow down the speed of either new SH-SAW. As a result, the studied new SH-SAWs can be suitable for creation of new technical devices to sense the magnetoelectric effect. For the analytical study, extreme and inflexion points were evaluated in the velocities' dependencies on the value of the electromagnetic constant  $\alpha$ .

## Keywords

Magnetoelasticity, Magnetoelectric Effect, New SH-SAW, Bleustein-Gulyaev-Melkumyan Wave

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## 1. Introduction

Two researchers, Bleustein [1] and Gulyaev [2], are responsible for the creation of new knowledge because they have discovered the surface Bleustein-Gulyaev (BG) waves to the end of the 1960s. The researchers have theoretically studied the acoustic wave propagation along the surface of a piezoelectric (PE) 6 mm solid when the shear-horizontal surface acoustic wave (SH-SAW) propagates perpendicular to and is polarized along the sixfold symmetry axis [3]. The slower BG-wave possesses an important feature such as its velocity can be significantly slower than the corresponding shear-horizontal bulk acoustic wave (SH-BAW). The difference between the surface BG-wave and SH-BAW velocities illuminates the following fact: the stronger the piezoelectric effect is, the larger the difference and smaller the penetration depth would be. This is also true for the transversely isotropic (6 mm) piezomagnetics (PM) that can also support the piezomagnetic BG-wave propagation.

In addition to the PE and PM solids there are piezoelectromagnetic (PEM) continua, also known as magneto-electroelastics. The SAW peculiarities mentioned above for the PEs and PMs are also true for the PEMs. In the 6 mm PEM continua, the surface Bleustein-Gulyaev-Melkumyan (BGM) wave can propagate. The BGM wave was recently discovered by Melkumyan [4] and called the BGM wave in works [5]-[7]. According to review [7], Wang, Mai, and Niraula [8] and Wei, Liu, and Fang [9] have theoretically obtained the same result but after the Melkumyan discovery. It was also found in book [10] that the BGM wave can exist in certain propagation directions along the free surface of cubic PEM solids. Many cuts can be found in the transversely isotropic (6 mm) PEM materials when the propagation directions satisfy the perpendicularity condition to the sixfold symmetry axis [3]. The surface BGM wave [5] [10] can actually propagate significantly slower than the corresponding piezoelectromagnetic SH-BAW. In this paper, the eighth and tenth new PEM SH-SAWs discovered in papers [11] and [12], respectively, are studied to record the possible fact that these new waves can propagate (significantly) slower than the BGM wave. These new waves can propagate under the following boundary conditions applied to the suitable free surface of a PEM solid (interface between the solid and a vacuum): mechanically free surface, continuity of both the electrical ( $\varphi$ ) and magnetic ( $\psi$ ) potentials, and the continuity of both the electrical ( $D_3$ ) and magnetic ( $B_3$ ) displacement components that are normal to the surface. The BGM wave can propagate under the following boundary conditions: mechanically free, electrically closed ( $\varphi = 0$ ), and magnetically open ( $\psi = 0$ ) surface of the piezoelectromagnetics. All the SH-waves mentioned above relate to pure waves [13] [14] with the anti-plane polarization.

Piezoelectromagnetics similar to piezoelectrics must be noncentrosymmetric monocrystals or two-phase materials to possess the piezoelectric effect. Besides, magneto-electroelastics as a class of magnetoelectric materials can have the piezomagnetic and magnetoelectric effects. The smart magnetoelectric materials have mechanical, electrical, and magnetic subsystems and the last two subsystems can affect each other via the first one. This property makes these smart materials multi-promising for various technical applications, for instance, see in review papers [15]-[19]. These smart materials can be also called for development of spintronics representing an electronics free of electric charges. It is obvious that piezoelectromagnetics can be used instead of piezoelectrics in wireless SAW devices. For instance, the development of the SAW sensing technology towards wireless and batteryless can provide cost effective and elegant solutions to the challenges posed by rotating machine components [20]. So, SAW temperature sensors cannot demand either batteries or an external power supply and can offer a lower maintenance and environmentally friendly solution of indoor and outdoor temperature measurements. It is worth here noticing that the utilization of piezoelectromagnetics instead of piezoelectrics is more preferable to experimentally generate anti-plane polarized acoustic waves with the noncontact method [21]-[23] called the electromagnetic acoustic transducers (EMATs).

The following section acquaints the reader with the analytical study of the nondispersive SH-waves. The main purpose is to investigate the eighth [11] and tenth [12] new PEM SH-SAWs in comparison with the other known SH-SAW called the surface BGM wave and the corresponding SH-BAW. These SH-waves are treated as functions of the electromagnetic constant  $\alpha$  to record possible peculiarities. For instance there can exist some crossing and extreme points and existence conditions are also of an interest. Therefore, Sections 3, 4, 5, and 6 serve to brace the theoretical research of the following section.

## 2. Analytical Study

It is natural to first introduce the definition for the speed of the shear-horizontal bulk acoustic wave (SH-BAW), propagation of which is coupled with both the electrical and magnetic potentials. This is useful because the value

of the SH-BAW velocity  $V_{tem}$  must be larger than the values of the corresponding SH-SAW velocities, for instance, the surface Bleustein-Gulyaev-Melkumyan (BGM) wave velocity  $V_{BGM}$ . The SH-BAW velocity  $V_{tem}$  can then be defined by the following well-known formula:

$$V_{tem} = V_t (1 + K_{em}^2)^{1/2} \quad (1)$$

In Equation (1),  $V_t = \text{sqrt}(C/\rho)$  is the purely mechanical SH-BAW velocity. This means that this SH-BAW is uncoupled with both the electrical and magnetic potentials. Also,  $C$ ,  $\rho$ , and  $K_{em}^2$  stand for the elastic stiffness constant, mass density, and the coefficient of the magnetoelctromechanical coupling (CMEMC), respectively. The CMEMC being a very important characteristic of a piezoelectromagnetics couples all the material parameters, but the mass density  $\rho$ , and reads as follows:

$$K_{em}^2 = \frac{\mu e^2 + \varepsilon h^2 - 2\alpha e h}{C(\varepsilon\mu - \alpha^2)} = \frac{e(e\mu - h\alpha) - h(e\alpha - h\varepsilon)}{C(\varepsilon\mu - \alpha^2)} \quad (2)$$

In definition (2) one can find the following independent nonzero material constants: the stiffness constant  $C$ , piezomagnetic coefficient  $h$ , piezoelectric constant  $e$ , dielectric permittivity coefficient  $\varepsilon$ , magnetic permeability coefficient  $\mu$ , and electromagnetic constant  $\alpha$  [5] [10]-[12].

It is a natural choice to compare the velocity behaviors of the eighth and tenth new SH-SAWs recently discovered in papers [11] and [12], respectively, with the SH-BAW  $V_{tem}$  and SH-SAW  $V_{BGM}$ . This is constructive because there is an assumption that the new SH-waves can propagate even slower than the surface BGM wave in dependence on the electromagnetic constant  $\alpha$ . This statement must be demonstrated in the analysis developed below. It is essential to state right away that the SH-SAW  $V_{BGM}$  can propagate when the following mechanical, electrical, and magnetic boundary conditions are applied to the interface between the PEM solid and a vacuum: mechanically free surface, electrically closed surface (electrical potential  $\varphi = 0$ ) and magnetically open surface (magnetic potential  $\psi = 0$ ). For the same mechanical boundary condition, the propagation of the eighth and tenth new SH-SAWs [11] [12] requires more complicated electrical and magnetic boundary conditions at the interface: the continuity of both the electrical and magnetic potentials and the continuity of both the normal components of the electrical and magnetic displacements.

So, let's now introduce the formula for calculation of the BGM wave velocity  $V_{BGM}$  that can be derived in the following form:

$$V_{BGM} = V_{tem} [1 - b_M^2]^{1/2} = V_t \left( \frac{1 + 2K_{em}^2}{1 + K_{em}^2} \right)^{1/2} \quad (3)$$

where

$$b_M = \frac{K_{em}^2}{1 + K_{em}^2} = \frac{\mu e^2 + \varepsilon h^2 - 2\alpha e h}{C\varepsilon\mu - C\alpha^2 + \mu e^2 + \varepsilon h^2 - 2\alpha e h} \quad (4)$$

The eighth new SH-SAW velocity  $V_{new8}$  [11] can be also expressed in the following explicit form:

$$V_{new8} = V_{tem} [1 - b_{n8}^2]^{1/2} \quad (5)$$

where

$$b_{n8} = \frac{\varepsilon\mu_0}{\varepsilon\mu - \alpha^2} \frac{K_e^2 - K_\alpha^2}{1 + K_{em}^2} = \frac{e\mu_0}{h\alpha} \frac{h(e\alpha - h\varepsilon)}{C\varepsilon\mu - C\alpha^2 + \mu e^2 + \varepsilon h^2 - 2\alpha e h} \quad (6)$$

It is clearly seen in expressions (5) and (6) that the eighth new SH-SAW cannot exist for the case of zero value of the electromagnetic constant,  $\alpha = 0$ , because  $K_\alpha^2 (\alpha \rightarrow 0) \rightarrow \infty$  occurs. This is similar to the fifth new PEM SH-SAW discovered in book [5] for the other electrical and magnetic boundary conditions, because its speed is equal to zero as soon as  $\alpha = 0$ . It was demonstrated in paper [24] that the value of the fifth new PEM SH-SAW velocity is too close, namely significantly closer than the other new SH-SAW velocities [5], to the value of the SH-BAW velocity  $V_{tem}$ . Therefore, it is expected that the penetration depth of this new SH-SAW must be significantly larger than that for the other SH-SAWs.

In expression (6),  $\mu_0$  is the magnetic constant for a vacuum and the following useful equalities were exploited:

$$K_{em}^2 - K_e^2 = \frac{(e\alpha - h\varepsilon)^2}{C\varepsilon(\varepsilon\mu - \alpha^2)} \quad (7)$$

$$K_{em}^2 - K_\alpha^2 = \frac{(e\alpha - h\varepsilon)(e\mu - h\alpha)}{C\alpha(\varepsilon\mu - \alpha^2)} \quad (8)$$

In expressions (6) and (7), the coefficient of the electromechanical coupling (CEMC) denoted by  $K_e^2$  is defined as follows:

$$K_e^2 = \frac{e^2}{C\varepsilon} \quad (9)$$

The other parameter denoted by  $K_\alpha^2$  in expressions (6) and (8) couples only the terms with the electromagnetic constant  $\alpha$  and equals to the following:

$$K_\alpha^2 = \frac{eh}{C\alpha} = \frac{\alpha eh}{C\alpha^2} \quad (10)$$

The second new wave for comparison called the tenth new SH-SAW [12] is characterized by the following propagation speed:

$$V_{new10} = V_{tem} [1 - b_{n10}^2]^{1/2} \quad (11)$$

where

$$b_{n10} = \frac{\varepsilon_0\mu}{\varepsilon\mu - \alpha^2} \frac{K_m^2 - K_\alpha^2}{1 + K_{em}^2} = -\frac{h\varepsilon_0}{e\alpha} \frac{e(e\mu - h\alpha)}{C\varepsilon\mu - C\alpha^2 + \mu e^2 + \varepsilon h^2 - 2\alpha eh} \quad (12)$$

It is also clearly seen in expressions (11) and (12) that the tenth new SH-SAW cannot exist for  $\alpha = 0$ . This is like the eighth new SH-SAW introduced and in some measure discussed above. In expression (12),  $\varepsilon_0$  is the electric constant for a vacuum and the coefficient of the magnetomechanical coupling (CMMC,  $K_m^2$ ) is written as follows:

$$K_m^2 = \frac{h^2}{C\mu} \quad (13)$$

Also, equality (8) and the following equality were used in expression (12):

$$K_{em}^2 - K_m^2 = \frac{(e\mu - h\alpha)^2}{C\mu(\varepsilon\mu - \alpha^2)} \quad (14)$$

It is clearly seen in expressions (5) and (6) that the velocity  $V_{new8}$  can reach the SH-BAW velocity  $V_{tem}$  as soon as the following condition is completed:

$$e\alpha = h\varepsilon \quad \text{or} \quad \alpha = \varepsilon h/e \quad (15)$$

Analyzing expressions (11) and (12), one can also find the following condition for the case of  $V_{new10} = V_{tem}$ :

$$e\mu = h\alpha \quad \text{or} \quad \alpha = \mu e/h \quad (16)$$

It is necessary to state that conditions (15) and (16) are also fulfilled when the  $K_{em}^2$  has extreme points due to the existence of extreme points of the separated exchange coefficient  $K_{ex}^2$  [25]. It is worth noting that the condition of  $V_{BGM} = V_{tem}$  can also exist when  $K_{em}^2 = 0$  that results in the following:

$$\mu e^2 + \varepsilon h^2 = 2\alpha eh \quad \text{or} \quad \alpha = \frac{\mu e^2 + \varepsilon h^2}{2eh} \quad (17)$$

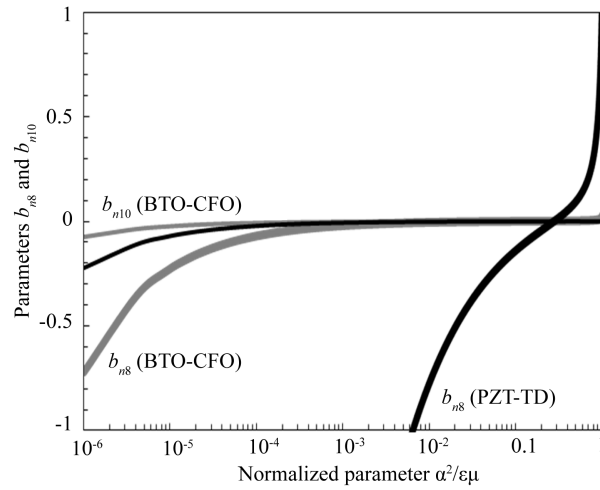
It is apparent that three conditions from (15) to (17) require corresponding large values of the electromagnetic constant  $\alpha$ . It is also essential to provide the other conditions relating to the existence of the eighth and tenth new SH-SAWs. It is flagrant in definition (10) that  $K_\alpha^2 \rightarrow \infty$  as soon as  $\alpha \rightarrow 0$ . Indeed, a large value of  $K_\alpha^2$  can

result in the lack of existence of either new wave. Using definitions (5) and (11), the existence conditions can be respectively inscribed as follows:

$$-1 < b_{n8} < 1 \quad (18)$$

$$-1 < b_{n10} < 1 \quad (19)$$

**Figure 1** shows the dependence of the dimensionless parameters  $b_{n8}$  and  $b_{n10}$  on the normalized value of  $\alpha^2/\varepsilon\mu$ . The logarithmic scale is used for the later parameter in the figure to soundly demonstrate the peculiarity of the wave existence. The value of  $\varepsilon\mu$  is constant in the calculation. This means that only the value of the electromagnetic constant  $\alpha$  is changed. The used material parameters of a vacuum are well-known: the magnetic permeability constant is  $\mu_0 = 4\pi \times 10^{-7} \text{ [H/m]} = 1.25663706144 \times 10^{-6} \text{ [N/A}^2\text{]}$  and the dielectric permittivity constant is  $\varepsilon_0 = 10^{-7} / (4\pi C_L^2) = 0.08854187817 \times 10^{-10} \text{ [F/m]}$  where  $C_L = 2.99782458 \times 10^8 \text{ [m/s]}$  is the speed of light in a vacuum. These parameters for the composite materials listed in **Table 1** are:  $\mu = 2.61 \times 10^{-6} \text{ [N/A}^2\text{]}$  and  $\varepsilon = 75.0 \times 10^{-10} \text{ [F/m]}$  for PZT-5H–Terfenol-D;  $\mu = 81.0 \times 10^{-6} \text{ [N/A}^2\text{]}$  and  $\varepsilon = 56.4 \times 10^{-10} \text{ [F/m]}$  for



**Figure 1.** The dimensionless parameters  $b_{n8}$  (black lines) and  $b_{n10}$  (gray lines) versus the normalized value of  $\alpha^2/\varepsilon\mu$  for the PZT-5H–Terfenol-D (PZT-TD, thick lines) and BaTiO<sub>3</sub>–CoFe<sub>2</sub>O<sub>4</sub> (BTO-CFO, thinner lines) piezoelectromagnetic composites.

**Table 1.** The material parameters of the (6 mm) piezoelectromagnetic composites: BaTiO<sub>3</sub>–CoFe<sub>2</sub>O<sub>4</sub> (BTO-CFO) and PZT-5H–Terfenol-D (PZT-TD). Here, the values of  $K_\alpha^2$ ,  $K_{em}^2$ ,  $V_{tem}$ ,  $V_{BGM}$ ,  $V_{new10}$ , and  $V_{new8}$  are calculated for  $\alpha^2/\varepsilon\mu$  (BTO-CFO)  $\sim 4.84 \times 10^{-4}$  and  $\alpha^2/\varepsilon\mu$  (PZT-TD)  $\sim 0.143641$  when the velocity  $V_{new8}$  has the maximum value.

Composite material	$C, 10^{10}, \text{N/m}^2$	$e, \text{C/m}^2$	$h, \text{T}$	$\varepsilon, 10^{-10}, \text{F/m}$	$\mu, 10^{-6}, \text{N/A}^2$
BaTiO <sub>3</sub> –CoFe <sub>2</sub> O <sub>4</sub>	4.40	5.80	275.0	56.4	81.00
PZT-5H–Terfenol-D	1.45	8.50	83.8	75.0	2.61
Composite material	$\varepsilon\mu, 10^{-16}$	$\rho, \text{kg/m}^3$	$K_\alpha^2$	$K_e^2$	$K_m^2$
BaTiO <sub>3</sub> –CoFe <sub>2</sub> O <sub>4</sub>	4568.40	5730	2.4378	0.1356	0.0212
PZT-5H–Terfenol-D	195.75	8500	0.9264	0.6644	0.1856
Composite material	$K_{em}^2$	$V_{tem}, \text{m/s}$	$V_{BGM}, \text{m/s}$	$V_{new8}, \text{m/s}$	$V_{new10}, \text{m/s}$
BaTiO <sub>3</sub> –CoFe <sub>2</sub> O <sub>4</sub>	0.1545	2977.450	2950.670	2976.023	2977.434
PZT-5H–Terfenol-D	0.6817	1693.7503	1548.350	1687.238	1693.7500

BaTiO<sub>3</sub>–CoFe<sub>2</sub>O<sub>4</sub>. It is necessary here to state that the magnetic permeability constant  $\mu$  for the first composite is only twice as much in comparison with that for a vacuum. It is possible that this fact results in some peculiarities discussed below.

For comparison, the calculations are performed for the following two piezoelectromagnetic composite materials: PZT-5H–Terfenol-D and BaTiO<sub>3</sub>–CoFe<sub>2</sub>O<sub>4</sub>. The material constants of the composites together with the other characteristics are listed in **Table 1**. The values of the material constants of the studied composites were borrowed from papers [24] [26]–[28]. According to the table, the value of the CMEMC (2) for the PZT-5H–Terfenol-D composite is significantly larger than that for the second material. This fact actually results in the possible existence of the studied new SH-SAWs at small values of the electromagnetic constant  $\alpha$  and therefore small normalized values of  $\alpha^2/\varepsilon\mu$ . The eighth new SH-SAWs cannot exist when the value of  $\alpha^2/\varepsilon\mu$  is smaller than  $\sim 6.4 \times 10^{-3}$  for the PZT-5H–Terfenol-D composite because the parameter  $b_{n8}$  becomes less than  $-1$ , see also **Figure 1** and existence condition (18). For BaTiO<sub>3</sub>–CoFe<sub>2</sub>O<sub>4</sub>, the values of  $\alpha^2/\varepsilon\mu$  must be smaller than  $\sim 5.0 \times 10^{-7}$  to get  $b_{n8} < -1$ . This means that there is the threshold value of  $\alpha^2/\varepsilon\mu$  to allow the eighth new SH-SAW to exist for either studied composite:  $\alpha^2/\varepsilon\mu \sim 6.4 \times 10^{-3}$  for the PZT-5H–Terfenol-D and  $\alpha^2/\varepsilon\mu \sim 5.0 \times 10^{-7}$  for BaTiO<sub>3</sub>–CoFe<sub>2</sub>O<sub>4</sub>.

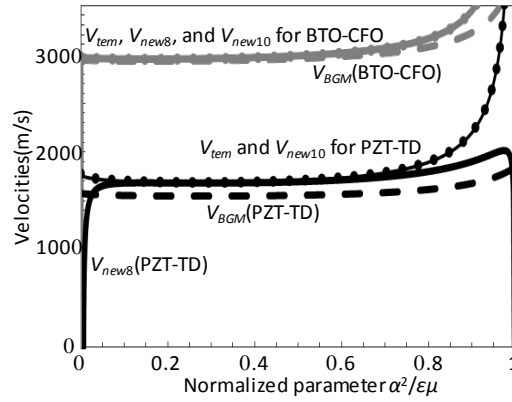
For the tenth new SH-SAW existence satisfying condition (19), the threshold values of  $\alpha^2/\varepsilon\mu$  are significantly smaller, namely  $\alpha^2/\varepsilon\mu \sim 4.8 \times 10^{-8}$  for the PZT-5H–Terfenol-D and  $\alpha^2/\varepsilon\mu \sim 5.0 \times 10^{-9}$  for BaTiO<sub>3</sub>–CoFe<sub>2</sub>O<sub>4</sub>. This means that the propagating waves can exist when the value of  $\alpha$  is larger than the threshold value,  $\alpha_{th}$ . In fact, a measured value of  $\alpha$  is in general very small. This is not undesirable for a piezoelectromagnetic composite material concerning the existence of the eighth and tenth new SH-SAWs because a small proper value of  $\alpha$  can cause a significant slowing down of at least one of the new SH-SAW velocities. This is the dramatic influence of the weak magnetoelectric effect on the existence and propagation of the new waves. It is also possible to shortly note that this theoretical report has an interest in a study of propagating (nondissipative) new SH-SAWs characterized by real speeds. Therefore, any dissipation corresponding to the case of  $\alpha < \alpha_{th}$  resulting in an imaginary speed is not treated here.

It is also possible to compare with some experimental data for the BaTiO<sub>3</sub>–CoFe<sub>2</sub>O<sub>4</sub> composite:  $\alpha^2/\varepsilon\mu \sim 4 \times 10^{-5}$  [29] and  $\alpha^2/\varepsilon\mu \sim 5 \times 10^{-6}$  [30]. The smaller experimental value of  $\alpha$  [30] can lead to slower speed of either new wave. It is well-known that composite materials are used because they can demonstrate significantly larger values of the electromagnetic constant  $\alpha$  in comparison with magnetoelectric monocrystals. The difference can even reach several orders. However, the Sr<sub>3</sub>Co<sub>2</sub>Fe<sub>24</sub>O<sub>41</sub> Z-type hexaferrite [15] with a hexagonal structure was discovered in 2010 that possesses the sufficient magnetoelectric effect for practical applications. For the purpose of slowing down the new wave, the suitable smaller values of  $\alpha$  are sensationally more preferable. Therefore, magnetoelectroelastic monocrystals with a weak magnetoelectric effect are welcomed for the purpose of the new wave research. It is necessary to record their material parameter in the literature, including the electromagnetic constant  $\alpha$ .

However there is also one peculiarity for the eighth new SH-SAW existence for the PZT-5H–Terfenol-D composite that can be seen in **Figure 1** and **Figure 2**. Indeed, this SH-wave cannot also exist when the value of  $\alpha^2/\varepsilon\mu$  is larger than  $\sim 0.997$ , assuming that  $\alpha^2/\varepsilon\mu < 1$  must occur due to the following limitation:  $\alpha^2 < \varepsilon\mu$  [18] [19]. It is clearly seen in the figures that this peculiarity can be revealed only for the eighth new SH-SAW in the PZT-5H–Terfenol-D. This also results in a dramatic slowing down of the eighth new SH-SAW. It is thought however that such large values of  $\alpha$  do not represent an interest because they are hardly reachable for known composite materials. One can find an extra oddness in **Figure 2**: the eighth and tenth new SH-SAW speeds can actually be dramatically slower than the speed of the surface Bleustein-Gulyaev-Melkumyan wave for small enough values of  $\alpha$ , and  $V_{BGM} < V_{tem}$  should always occur. These facts are more clearly seen in figure 2 for the eighth new SH-SAW (thick solid black line) in the PZT-5H–Terfenol-D. Therefore, it is possible to analytically treat the possible cases of  $V_{new8} = V_{BGM}$  and  $V_{new10} = V_{BGM}$  similar to the cases of  $V_{new8} = V_{tem}$  and  $V_{new10} = V_{tem}$  considered above.

### 3. Comparison of $V_{new8}$ and $V_{new10}$ with $V_{BGM}$

**Figure 2** shows the dependence of the velocities  $V_{new8}$ ,  $V_{new10}$ ,  $V_{BGM}$ , and  $V_{tem}$  on the electromagnetic constant  $\alpha$  ( $\alpha^2/\varepsilon\mu$  with  $\varepsilon\mu = \text{const}$ ) when the calculations are carried out for both the PZT-5H–Terfenol-D and BaTiO<sub>3</sub>–CoFe<sub>2</sub>O<sub>4</sub> composites. It is clearly seen in the figure that for the first composite the velocities  $V_{new8}$  (thick



**Figure 2.** The velocities  $V_{new8}$  (thick solid lines),  $V_{new10}$  (thinner solid lines),  $V_{BGM}$  (dashed lines), and  $V_{tem}$  (dotted lines) [all in m/s] versus the normalized value of  $\alpha^2/\epsilon\mu$  for the PZT-5H–Terfenol-D (PZT-TD, black lines) and BaTiO<sub>3</sub>–CoFe<sub>2</sub>O<sub>4</sub> (BTO-CFO, gray lines).

solid black line) and  $V_{BGM}$  (dashed black line) can have a crossing point at a small value of the  $\alpha$ . For a significantly smaller value of the  $\alpha$ , the velocities  $V_{new10}$  and  $V_{BGM}$  can also have a crossing point. Besides, **Figure 2** evidently shows that the velocities  $V_{new8}$  and  $V_{BGM}$  can have two crossing points for the PZT-5H–Terfenol-D composite: at  $\alpha^2/\epsilon\mu \ll 1$  and  $\alpha^2/\epsilon\mu \sim 1$  when  $\alpha^2/\epsilon\mu < 1$  [18] [19] should occur. This is not true for the velocities  $V_{new8}$  and  $V_{BGM}$  for the same composite because sole crossing point can exist. For BaTiO<sub>3</sub>–CoFe<sub>2</sub>O<sub>4</sub>, only single crossing point at  $\alpha^2/\epsilon\mu \ll 1$  can be found in either case when  $0 < \alpha^2/\epsilon\mu < 1$  is fulfilled in **Figure 2**. Probably, the second crossing point can be found at  $\alpha^2/\epsilon\mu > 1$  that must be analytically illuminated.

So, let's first treat the following case:

$$V_{new8} = V_{BGM} \quad (20)$$

It is more convenient to treat the following equality instead of equality (20), see formulae (4) and (6):

$$b_{n8} = b_M \quad (21)$$

Employing formulae (4) and (6), equality (21) leads to the following quadratic equation to find unknown values of the electromagnetic constant  $\alpha$ :

$$2\alpha^2 eh - \alpha [(\mu - \mu_0)e^2 + \epsilon h^2] - \epsilon\mu_0 eh = 0 \quad (22)$$

So, two crossing points must exist in the common case because Equation (22) can have two equation roots. They can be calculated with the following expression:

$$\alpha_{1,2}(V_{new8} = V_{BGM}) = \frac{(\mu - \mu_0)e^2 + \epsilon h^2}{4eh} \mp \sqrt{\left[\frac{(\mu - \mu_0)e^2 + \epsilon h^2}{4eh}\right]^2 - \frac{\epsilon\mu_0}{2}} \quad (23)$$

To have real values of the electromagnetic constant  $\alpha$ , it is apparent that the following inequality must be satisfied under the square root in expression (23):

$$\left[\frac{(\mu - \mu_0)e^2 + \epsilon h^2}{4eh}\right]^2 > \frac{\epsilon\mu_0}{2} \quad (24)$$

It is obvious that the left-hand part in the inequality can always be larger than zero. The case of  $\epsilon > 0$  results in the fact that the right-hand part must be also larger than zero because the vacuum magnetic constant  $\mu_0 > 0$ . **Figure 2** clearly shows that the crossing point occurs at a small value of  $\alpha^2/\epsilon\mu$ . Therefore, inequality (24) can be surely written as follows:

$$\left[\frac{(\mu - \mu_0)e^2 + \epsilon h^2}{4eh}\right]^2 \gg \frac{\epsilon\mu_0}{2} \quad (25)$$

Inequality (24) allows one to simplify formula (23). Indeed, formula (23) can be schematically introduced as  $\alpha_{1,2} = a_1 \mp \sqrt{a_1^2 - a_2}$ . The case of  $a_1^2 \gg a_2$  allows one rewrite it as follows:

$\alpha_{1,2} = a_1 \left[ 1 \mp \sqrt{1 - a_2/a_1^2} \right] \sim a_1 \left[ 1 \mp 1 \pm a_2/2a_1^2 \right]$ . Consequently, two equation roots (23) can be rewritten in the following approximate forms:

$$\alpha_1 (V_{new8} = V_{BGM}) \sim \frac{\varepsilon\mu_0 eh}{(\mu - \mu_0)e^2 + \varepsilon h^2} \quad (26)$$

$$\alpha_2 (V_{new8} = V_{BGM}) \sim \frac{(\mu - \mu_0)e^2 + \varepsilon h^2}{2eh} - \frac{\varepsilon\mu_0 eh}{(\mu - \mu_0)e^2 + \varepsilon h^2} \quad (27)$$

Let's now analyze the existence of the crossing points between the velocities  $V_{new10}$  and  $V_{BGM}$ . They occur when the following equality is satisfied:

$$V_{new10} = V_{BGM} \quad (28)$$

Analogically, it is more convenient to use the following equality instead:

$$b_{n10} = b_M \quad (29)$$

Utilizing formulae (4) and (12), equality (29) can be expanded to the following quadratic equation:

$$2\alpha^2 eh - \alpha \left[ \mu e^2 + (\varepsilon - \varepsilon_0) h^2 \right] - \varepsilon_0 \mu eh = 0 \quad (30)$$

Accordingly, two equation roots can be inscribed as follows:

$$\alpha_{1,2} (V_{new10} = V_{BGM}) = \frac{\mu e^2 + (\varepsilon - \varepsilon_0) h^2}{4eh} \mp \sqrt{\left[ \frac{\mu e^2 + (\varepsilon - \varepsilon_0) h^2}{4eh} \right]^2 - \frac{\varepsilon_0 \mu}{2}} \quad (31)$$

One has to deal here with the case of real roots of quadratic equation (30). This requires satisfaction of the following inequality:

$$\left[ \frac{\mu e^2 + (\varepsilon - \varepsilon_0) h^2}{4eh} \right]^2 > \frac{\varepsilon_0 \mu}{2} \quad (32)$$

It is even possible to write the following inequality because equality (28) occurs at a very small value of the electromagnetic constant  $\alpha$ :

$$\left[ \frac{\mu e^2 + (\varepsilon - \varepsilon_0) h^2}{4eh} \right]^2 \gg \frac{\varepsilon_0 \mu}{2} \quad (33)$$

Using condition (33), equation roots (31) can be rewritten in the following simplified forms:

$$\alpha_1 (V_{new10} = V_{BGM}) \sim \frac{\varepsilon_0 \mu eh}{\mu e^2 + (\varepsilon - \varepsilon_0) h^2} \quad (34)$$

$$\alpha_2 (V_{new10} = V_{BGM}) \sim \frac{\mu e^2 + (\varepsilon - \varepsilon_0) h^2}{2eh} - \frac{\varepsilon_0 \mu eh}{\mu e^2 + (\varepsilon - \varepsilon_0) h^2} \quad (35)$$

Comparing the cases of  $V_{new8} = V_{BGM}$  and  $V_{new10} = V_{BGM}$ , it is possible to conclude that the presence of the vacuum electric constant  $\varepsilon_0$  results in the smaller value of the electromagnetic constant  $\alpha$ , at which there is the crossing point. Two crossing points can actually exist in either case but the second crossing point can be revealed at  $\alpha^2/\varepsilon\mu > 1$ . Therefore, **Figure 2** shows two crossing points only for the case of the eighth new SH-SAW propagating on the surface of the PZT-5H–Terfenol-D composite.



## 4. The First Derivatives

The analysis carried out above is not complete because one can find several extreme points in the dependence of the eighth new SH-SAW velocity on the normalized value of  $\alpha^2/\varepsilon\mu$  shown in **Figure 2** for the PZT-5H–Terfenol-D composite. Indeed, it is necessary to know the number of the extreme and inflexion points for both the dependences  $V_{new8}(\alpha)$  and  $V_{new10}(\alpha)$ . It is well-known that there is a closely linear dependence around an inflexion point and this quasi-linear regime can be used in construction of different technical devices. Also, one can find that the  $V_{tem}$  and  $V_{BGM}$  velocities can have a smooth minimum in **Figure 2**. Therefore, it is natural to begin the analysis of the dependencies  $V_{tem}(\alpha)$  and  $V_{BGM}(\alpha)$ .

The dependence  $V_{tem}(\alpha)$  is given by formula (1) at the beginning of this section. The first derivative of the SH-BAW velocity  $V_{tem}$  [6] [24] with respect to the electromagnetic constant  $\alpha$  can be expressed as follows:

$$\frac{\partial V_{tem}}{\partial \alpha} = \frac{V_t^2}{2V_{tem}} \frac{\partial K_{em}^2}{\partial \alpha} \quad (36)$$

where the purely mechanical SH-BAW velocity  $V_t$  is defined right away after Equation (1).

This first derivative must be equal to zero at an extreme point. This can happen when the first derivative on the right-hand side is equal to zero. In expression (36), the first derivative of the coefficient of the magneto-electromechanical coupling  $K_{em}^2$  (2) with respect to the  $\alpha$  can be borrowed from papers [6] [24]. So, the extreme points of the dependence  $V_{tem}(\alpha)$  can be defined by solving the following equation:

$$\frac{\partial K_{em}^2}{\partial \alpha} = \frac{2\alpha(K_{em}^2 - K_\alpha^2)}{\varepsilon\mu - \alpha^2} = 0 \quad (37)$$

where the coefficient  $K_\alpha^2$  is defined by expression (10).

Utilizing expression (8), one can solidly find that there are two extreme points for the dependence  $V_{tem}(\alpha)$ . They are given by equalities (15) and (16). Indeed, the dependence  $K_{em}^2(\alpha)$  has the same extreme points compared with those of the dependence of the separated exchange coefficient  $K_{ex}^2(\alpha)$  [25].

Concerning the dependence  $V_{BGM}(\alpha)$  defined by expressions (3) and (4), its first derivative with respect to the  $\alpha$  can be also borrowed from recently published paper [6]. So, one can write down:

$$\frac{\partial V_{BGM}}{\partial \alpha} = \left[ \frac{V_t^2 V_{BGM}}{2V_{tem}^2} - \frac{V_{tem}^2}{V_{BGM}} \frac{K_{em}^2}{(1+K_{em}^2)^3} \right] \frac{\partial K_{em}^2}{\partial \alpha} = \frac{V_t^2}{2V_{BGM}} \frac{1}{(1+K_{em}^2)^2} \frac{\partial K_{em}^2}{\partial \alpha} \quad (38)$$

Next, it is clearly seen in expression (38) that the dependencies  $V_{tem}(\alpha)$  and  $V_{BGM}(\alpha)$  actually have the same extreme points defined by equalities (15) and (16). This is so because this problem reduces to the treatment of Equation (37) for both the cases. However, one can also find an extra possibility given by the expression in the square brackets on the right-hand side of expression (38). Therefore, one must equal to zero the square brackets to check a possible existence of some extra extreme point. After several transformations, one can find that this problem is reduced to the following equality  $2K_{em}^2 = 1 + 2K_{em}^2$  that can never happen. This soundly states that the dependencies  $V_{tem}(\alpha)$  and  $V_{BGM}(\alpha)$  can truly have only the same extreme points.

It is now possible to find the extreme points for both the dependences  $V_{new8}(\alpha)$  and  $V_{new10}(\alpha)$  defined by expressions (5) and (11), respectively. Expressions (6) and (12) depend on the coefficient  $K_\alpha^2$  and therefore, the following derivative can be useful in further analysis:

$$\frac{\partial K_\alpha^2}{\partial \alpha} = -\frac{K_\alpha^2}{\alpha} \quad (39)$$

The existence of the extreme points requires that the first derivatives of the velocities  $V_{new8}(\alpha)$  and  $V_{new10}(\alpha)$  with respect to the electromagnetic constant  $\alpha$  must be equal to zero. Therefore, the following expressions must be considered:

$$\begin{aligned} \frac{\partial V_{new8}}{\partial \alpha} &= \frac{V_{new8}}{V_{tem}} \frac{\partial V_{tem}}{\partial \alpha} - \frac{b_{n8} V_{tem}^2}{V_{new8}} \frac{\partial b_{n8}}{\partial \alpha} \\ &= \frac{\alpha^2 V_{new8} (K_{em}^2 - K_\alpha^2)}{\alpha (\varepsilon\mu - \alpha^2) (1 + K_{em}^2)} - \frac{b_{n8} V_{tem}^2}{V_{new8}} \frac{\varepsilon\mu_0 K_\alpha^2 + 2\alpha^2 b_{n8} (1 + K_\alpha^2)}{\alpha (\varepsilon\mu - \alpha^2) (1 + K_{em}^2)}. \end{aligned} \quad (40)$$

$$\begin{aligned} \frac{\partial V_{new10}}{\partial \alpha} &= \frac{V_{new10}}{V_{tem}} \frac{\partial V_{tem}}{\partial \alpha} - \frac{b_{n10} V_{tem}^2}{V_{new10}} \frac{\partial b_{n10}}{\partial \alpha} \\ &= \frac{\alpha^2 V_{new10} (K_{em}^2 - K_\alpha^2)}{\alpha (\varepsilon\mu - \alpha^2) (1 + K_{em}^2)} - \frac{b_{n10} V_{tem}^2}{V_{new10}} \frac{\varepsilon_0 \mu K_\alpha^2 + 2\alpha^2 b_{n10} (1 + K_\alpha^2)}{\alpha (\varepsilon\mu - \alpha^2) (1 + K_{em}^2)}. \end{aligned} \quad (41)$$

where

$$\frac{\partial b_{n8}}{\partial \alpha} = \frac{\varepsilon\mu_0 K_\alpha^2 + 2\alpha^2 b_{n8} (1 + K_\alpha^2)}{\alpha (\varepsilon\mu - \alpha^2) (1 + K_{em}^2)} \quad (42)$$

$$\frac{\partial b_{n10}}{\partial \alpha} = \frac{\varepsilon_0 \mu K_\alpha^2 + 2\alpha^2 b_{n10} (1 + K_\alpha^2)}{\alpha (\varepsilon\mu - \alpha^2) (1 + K_{em}^2)} \quad (43)$$

First of all, it is necessary to analyze expression (40). Using expressions (6) and (8), it is possible to mark that two terms on the right-hand side of Equation (40) have the same factor such as  $(e\alpha - h\varepsilon)$ . This fact illuminates the first extreme point defined by expression (15) that also exists for the dependencies  $V_{tem}(\alpha)$  and  $V_{BGM}(\alpha)$  analyzed above. This extreme point corresponds to the smooth minimum shown in **Figure 2**. Using expressions (40) and (42), the equation for determination of all extreme points can be written as follows:

$$\frac{\alpha^2 V_{new8} (K_{em}^2 - K_\alpha^2)}{\alpha (\varepsilon\mu - \alpha^2) (1 + K_{em}^2)} - \frac{V_{tem}^2}{V_{new8}} \frac{\varepsilon\mu_0 K_\alpha^2 b_{n8} + 2\alpha^2 (1 + K_\alpha^2) b_{n8}^2}{\alpha (\varepsilon\mu - \alpha^2) (1 + K_{em}^2)} = 0 \quad (44)$$

This equation can be simplified to the following form:

$$\alpha^2 (1 + K_\alpha^2 + 1 + K_{em}^2) b_{n8}^2 + \varepsilon\mu_0 K_\alpha^2 b_{n8} - \alpha^2 (K_{em}^2 - K_\alpha^2) = 0 \quad (45)$$

It is possible to exclude the factor of  $(e\alpha - h\varepsilon)$  corresponding to the found extreme point mentioned above and further transform equation (45). For the transformations, expressions (2), (6), (8), and (10) are useful. The reader can also exploit the following equality to simplify expression (6):

$$K_e^2 - K_\alpha^2 = K_\alpha^2 \frac{(e\alpha - h\varepsilon)}{h\varepsilon} \quad (46)$$

As a result, the final equation representing a polynomial of the eight degree in the unknown parameter  $\alpha$  must also have several extreme points. It reads:

$$(C\alpha^2 + \alpha eh)(\varepsilon\mu - \alpha^2)(e\alpha - h\varepsilon) + \left[ \alpha^2 (e\alpha - h\varepsilon) + h\varepsilon (\varepsilon\mu - \alpha^2) \right] x - \frac{\alpha^3}{e^2 \mu_0^2} (e\mu - h\alpha) x^2 = 0 \quad (47)$$

where

$$x = C\varepsilon\mu - C\alpha^2 + \mu e^2 + \varepsilon h^2 - 2\alpha eh = C(\varepsilon\mu - \alpha^2) + e(e\mu - h\alpha) - h(e\alpha - h\varepsilon) \quad (48)$$

For the analysis of expression (41), it is essential to use expressions (8) and (12). With expression (8), it is obvious that  $K_{em}^2 - K_\alpha^2 = 0$  if  $e\alpha = h\varepsilon$  (15) or  $e\mu = h\alpha$  (16). For expression (12), the parameter  $b_{n10}$  is proportional to the vacuum dielectric permittivity constant  $\varepsilon_0$  that is several orders smaller than the dielectric permittivity constant  $\varepsilon$  for either composite listed in the table. Therefore, it is possible to conclude that the first term in expression (41) is significantly larger than the second because the later term even has a factor of  $\varepsilon_0^2$ . This fact provides extreme points at the values of the electromagnetic constant  $\alpha$  being close to those defined by equalities (15) and (16). Also, both terms on the right-hand side of Equation (41) have the same factor such as  $(e\mu - h\alpha)$ . This means that the extreme point for this case is actually defined by expression (16). It is necessary to remind that this extreme point is also true for the dependencies  $V_{tem}(\alpha)$  and  $V_{BGM}(\alpha)$ . However, it is not shown in **Figure 2** because it can exist at  $\alpha^2/\varepsilon\mu > 1$  that is out of current interest.

All the extreme points can be revealed by solving the following homogeneous equation:

$$\frac{\alpha^2 V_{new10} (K_{em}^2 - K_\alpha^2)}{\alpha (\varepsilon\mu - \alpha^2) (1 + K_{em}^2)} - \frac{V_{tem}^2}{V_{new10}} \frac{\varepsilon_0 \mu K_\alpha^2 b_{n10} + 2\alpha^2 (1 + K_\alpha^2) b_{n10}^2}{\alpha (\varepsilon\mu - \alpha^2) (1 + K_{em}^2)} = 0 \quad (49)$$

Proper transformations based on expressions (2), (8), (10), and (12) can lead to the following simplified form:

$$\alpha^2 (1 + K_\alpha^2 + 1 + K_{em}^2) b_{n10}^2 + \varepsilon_0 \mu K_\alpha^2 b_{n10} - \alpha^2 (K_{em}^2 - K_\alpha^2) = 0 \quad (50)$$

This form can be further simplified. For instance, the following equality must be employed for expression (12):

$$K_m^2 - K_\alpha^2 = -K_\alpha^2 \frac{(e\mu - h\alpha)}{e\mu} \quad (51)$$

Thus, the reader has to cope with the following polynomial of the eighth degree in the unknown parameter  $\alpha$ , where the function  $x(\alpha)$  is defined by expression (48):

$$(C\alpha^2 + \alpha eh)(\varepsilon\mu - \alpha^2)(e\mu - h\alpha) + \left[ \alpha^2 (e\mu - h\alpha) - e\mu (\varepsilon\mu - \alpha^2) \right] x - \frac{\alpha^3}{h^2 \varepsilon_0^2} (e\alpha - h\varepsilon) x^2 = 0 \quad (52)$$

Unfortunately, polynomials (47) and (52) are not simple to analyze and therefore, they can be studied numerically. All the extreme points corresponding to the values of  $\alpha^2/\varepsilon\mu$  from zero to unity are shown in **Figure 2**. For the eighth new SH-SAW, the calculated extreme points, see also in **Figure 2**, can exist at the following values of the normalized parameter  $\alpha^2/\varepsilon\mu$ : (1)  $\alpha^2/\varepsilon\mu \sim 0.143641$  (maximum,  $V_{new8} \sim 1687.238$  m/s), (2)  $\alpha^2/\varepsilon\mu \sim 0.278784$  (minimum,  $V_{new8} \sim 1684.997$  m/s), and (3)  $\alpha^2/\varepsilon\mu \sim 0.974169$  (maximum,  $V_{new8} \sim 2019.895$  m/s) for PZT-5H–Terfenol-D; and (1)  $\alpha^2/\varepsilon\mu \sim 0.000484$  (maximum,  $V_{new8} \sim 2976.023$  m/s) and (2)  $\alpha^2/\varepsilon\mu \sim 0.156816$  (minimum,  $V_{new8} \sim 2952.933$  m/s) for BaTiO<sub>3</sub>–CoFe<sub>2</sub>O<sub>4</sub>. It is worth noting that with a thorough analysis of the computation data for PZT-5H–Terfenol-D, the value of  $\alpha^2/\varepsilon\mu \sim 0.278784$  corresponding to the minimum of the velocity  $V_{new8}$  is the same for the other velocities mention in this theoretical research such as  $V_{new10}$ ,  $V_{BGM}$ , and  $V_{tem}$ . It is interesting to compare this value of  $\alpha^2/\varepsilon\mu \sim 0.278784$  obtained in the numerical calculation with the value of  $\alpha^2/\varepsilon\mu \sim 0.2793$  calculated from equality  $e\alpha = h\varepsilon$  (15). There is therefore a good enough agreement. For comparison,  $\alpha^2/\varepsilon\mu \sim 3.58$  is calculated from equality  $e\mu = h\alpha$  (16). However, this value is significantly bigger than unity. For BaTiO<sub>3</sub>–CoFe<sub>2</sub>O<sub>4</sub>, the value of  $\alpha^2/\varepsilon\mu \sim 0.156816$  also corresponds to the minimum for all these velocities:  $V_{new8}$ ,  $V_{new10}$ ,  $V_{BGM}$ , and  $V_{tem}$ . It is worth mentioned here anew that this minimum corresponds to the minimum in the dependence of the separated exchange coefficient  $K_{ex}^2(\alpha)$  [25].

For the tenth new SH-SAW, the calculated extreme points can be also given here below. They correspond to the following values of the normalized parameter  $\alpha^2/\varepsilon\mu$ : (1)  $\alpha^2/\varepsilon\mu \sim 4.096 \times 10^{-5}$  (maximum,  $V_{new10} \sim 1773.2165$  m/s) and (2)  $\alpha^2/\varepsilon\mu \sim 0.278784$  (minimum,  $V_{new10} \sim 1684.997$  m/s) for PZT-5H–Terfenol-D; and (1)  $\alpha^2/\varepsilon\mu \sim 2.401 \times 10^{-5}$  (maximum,  $V_{new10} \sim 2979.395$  m/s) and (2)  $\alpha^2/\varepsilon\mu \sim 0.156816$  (minimum,  $V_{new10} \sim 2952.933$  m/s) for BaTiO<sub>3</sub>–CoFe<sub>2</sub>O<sub>4</sub>. It is also possible to write down the values of  $\alpha^2/\varepsilon\mu$  calculated with conditions  $e\alpha = h\varepsilon$  (15) and  $e\mu = h\alpha$  (16):  $\alpha^2/\varepsilon\mu \sim 0.156532$  and  $\alpha^2/\varepsilon\mu \sim 3.7395$ , respectively. One can see that there is a good correlation between the value computed at the minimum and that calculated with condition (15).

## 5. The Second Derivatives

The second derivative can provide information on all possible inflexion points and therefore, reveal a linear regime around an inflexion point that can be useful for experimentalists and theoreticians. It is natural to start the analysis with the partial second derivative of the SH-BAW velocity  $V_{tem}$  with respect to the electromagnetic constant  $\alpha$ . It can be also borrowed from work [6]. Thus, all possible inflexion points can be computed by equaling to zero the right-hand side of the following expression:

$$\frac{\partial^2 V_{tem}}{\partial \alpha^2} = \frac{V_t^2}{2V_{tem}} \frac{\partial^2 K_{em}^2}{\partial \alpha^2} - \frac{V_t^2}{2V_{tem}^2} \frac{\partial V_{tem}}{\partial \alpha} \frac{\partial K_{em}^2}{\partial \alpha} \quad (53)$$

where

$$\frac{\partial^2 K_{em}^2}{\partial \alpha^2} = \frac{2K_{em}^2 + 4\alpha \partial K_{em}^2 / \partial \alpha}{\varepsilon\mu - \alpha^2} \quad (54)$$

It is convenient to utilize the following definition to calculate the partial second derivative of the velocity  $V_{BGM}$ :

$$\begin{aligned} \frac{\partial^2 V_{BGM}}{\partial \alpha^2} &= \frac{V_t^2}{2V_{BGM}} \frac{1}{(1+K_{em}^2)^2} \frac{\partial^2 K_{em}^2}{\partial \alpha^2} - \frac{V_t^2}{2V_{BGM}^2} \frac{1}{(1+K_{em}^2)^2} \frac{\partial V_{BGM}}{\partial \alpha} \frac{\partial K_{em}^2}{\partial \alpha} \\ &\quad - \frac{V_t^2}{V_{BGM}} \frac{1}{(1+K_{em}^2)^3} \left( \frac{\partial K_{em}^2}{\partial \alpha} \right)^2. \end{aligned} \quad (55)$$

where the first and second derivatives of the  $K_{em}^2$  are defined by expressions (37) and (54), respectively.

Regarding the partial second derivatives of the new SH-SAWs with respect to the material parameter  $\alpha$ , they can be evaluated with the following complicated formulae:

$$\begin{aligned} \frac{\partial^2 V_{new8}}{\partial \alpha^2} &= \frac{V_{new8}}{V_{tem}} \frac{\partial^2 V_{tem}}{\partial \alpha^2} - \frac{V_{tem}^2}{V_{new8}} \left( \frac{\partial b_{n8}}{\partial \alpha} \right)^2 - b_{n8} \frac{V_{tem}^2}{V_{new8}} \frac{\partial^2 b_{n8}}{\partial \alpha^2} \\ &\quad - 3b_{n8} \frac{V_{tem}}{V_{new8}} \frac{\partial V_{tem}}{\partial \alpha} \frac{\partial b_{n8}}{\partial \alpha} + b_{n8} \left( \frac{V_{tem}}{V_{new8}} \right)^2 \frac{\partial V_{new8}}{\partial \alpha} \frac{\partial b_{n8}}{\partial \alpha}. \end{aligned} \quad (56)$$

$$\begin{aligned} \frac{\partial^2 V_{new10}}{\partial \alpha^2} &= \frac{V_{new10}}{V_{tem}} \frac{\partial^2 V_{tem}}{\partial \alpha^2} - \frac{V_{tem}^2}{V_{new10}} \left( \frac{\partial b_{n10}}{\partial \alpha} \right)^2 - b_{n10} \frac{V_{tem}^2}{V_{new10}} \frac{\partial^2 b_{n10}}{\partial \alpha^2} \\ &\quad - 3b_{n10} \frac{V_{tem}}{V_{new10}} \frac{\partial V_{tem}}{\partial \alpha} \frac{\partial b_{n10}}{\partial \alpha} + b_{n10} \left( \frac{V_{tem}}{V_{new10}} \right)^2 \frac{\partial V_{new10}}{\partial \alpha} \frac{\partial b_{n10}}{\partial \alpha}. \end{aligned} \quad (57)$$

where

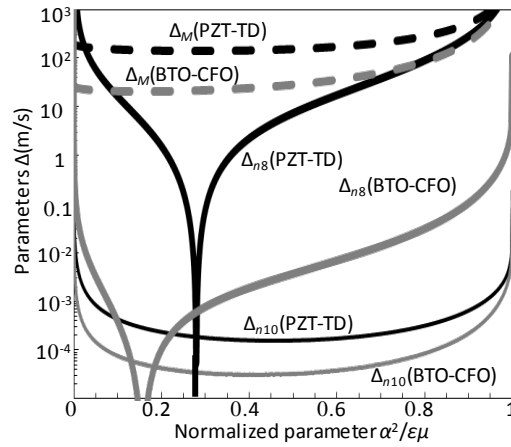
$$\begin{aligned} \frac{\partial^2 b_{n8}}{\partial \alpha^2} &= \frac{2\alpha^2 b_{n8} - 2\varepsilon\mu_0 K_\alpha^2}{\alpha^2 (\varepsilon\mu - \alpha^2) (1+K_{em}^2)} + \frac{2\alpha^2 (1+K_\alpha^2)}{\alpha (\varepsilon\mu - \alpha^2) (1+K_{em}^2)} \frac{\partial b_{n8}}{\partial \alpha} \\ &\quad + \frac{\varepsilon\mu_0 K_\alpha^2 + 2\alpha^2 b_{n8} (1+K_\alpha^2)}{\alpha^2 (\varepsilon\mu - \alpha^2)^2 (1+K_{em}^2)^2} \left( 2\alpha^2 (1+K_{em}^2) - \alpha (\varepsilon\mu - \alpha^2) \frac{\partial K_{em}^2}{\partial \alpha} \right). \end{aligned} \quad (58)$$

$$\begin{aligned} \frac{\partial^2 b_{n10}}{\partial \alpha^2} &= \frac{2\alpha^2 b_{n10} - 2\varepsilon_0 \mu K_\alpha^2}{\alpha^2 (\varepsilon\mu - \alpha^2) (1+K_{em}^2)} + \frac{2\alpha^2 (1+K_\alpha^2)}{\alpha (\varepsilon\mu - \alpha^2) (1+K_{em}^2)} \frac{\partial b_{n10}}{\partial \alpha} \\ &\quad + \frac{\varepsilon_0 \mu K_\alpha^2 + 2\alpha^2 b_{n10} (1+K_\alpha^2)}{\alpha^2 (\varepsilon\mu - \alpha^2)^2 (1+K_{em}^2)^2} \left( 2\alpha^2 (1+K_{em}^2) - \alpha (\varepsilon\mu - \alpha^2) \frac{\partial K_{em}^2}{\partial \alpha} \right). \end{aligned} \quad (59)$$

The extreme points' existence requires that the partial second derivatives of the functions  $V_{new8}(\alpha)$  and  $V_{new10}(\alpha)$  with respect to the electromagnetic constant  $\alpha$  must be equal to zero. All the partial first and second derivatives on the right-hand sides of expressions from (56) to (59) are defined above. Note that expressions from (56) to (59) are as difficult as those obtained for the other new wave velocities studied in papers [6] [24]. Therefore, these complicated dependencies can be studied only by a numerical simulation. This report has no purpose to develop a numerical method to study all the obtained derivatives.

## 6. The Parameters $\Delta$

The other useful parameter must be also discussed in this paper. This parameter denoted by  $\Delta$  was first introduced in book [5] and further studied in paper [24]. To treat the parameter  $\Delta$  is useful because the value of an SH-SAW velocity is frequently situated just below the value of the SH-BAW velocity  $V_{tem}$ . As a result, the difference between the velocities can be as small as several meters per second or even less, or even often mm/s for a weak piezoelectromagnetics. So, **Figure 3** compares the following parameters  $\Delta$ :



**Figure 3.** The values of established parameters  $\Delta_M$  (dashed lines),  $\Delta_{n8}$  (thick solid lines), and  $\Delta_{n10}$  (thinner solid lines) [all in m/s] versus the normalized electromagnetic constant  $\alpha^2/\epsilon\mu$  for the PZT-5H–Terfenol-D (PZT-TD, black lines) and BaTiO<sub>3</sub>–CoFe<sub>2</sub>O<sub>4</sub> (BTO-CFO, gray lines).

$$\Delta_M = V_{tem} - V_{BGM} \quad (60)$$

$$\Delta_{n8} = V_{tem} - V_{new8} \quad (61)$$

$$\Delta_{n10} = V_{tem} - V_{new10} \quad (62)$$

It is clearly seen in **Figure 3** that all the parameters  $\Delta$  cannot have a negative sign because an SH-SAW speed must be slower than the SH-BAW speed  $V_{tem}$ . The parameter  $\Delta_M$  never equals to zero because the BGM speed can never reach the SH-BAW speed  $V_{tem}$ , see the dashed lines in **Figure 3** for both the composites listed in the table. On the other hand, the other parameters such as  $\Delta_{n8}$  and  $\Delta_{n10}$  can be both larger and smaller than the parameter  $\Delta_M$ . Indeed, the value of the parameter  $\Delta_{n8}$  (thick solid lines) can be significantly larger than the  $\Delta_M$  value at small enough values of the electromagnetic constant  $\alpha$ . For significantly smaller values of the  $\alpha$  given in the context of Section 2 after existence conditions (18) and (19), this fact must be also true for the other parameter  $\Delta_{n10}$ . Also, it looks like that the  $\Delta_{n8}$  value can equal to zero for both the studied composites. This means that the speed of the eighth new SN-SAW can reach the SH-BAW speed  $V_{tem}$ . The dependencies  $\Delta_{n10}(\alpha)$  look like they have one smooth minimum for each composite and the tenth new SH-SAW speed cannot touch the bulk wave speed.

So, it is possible to analytically consider the extreme and inflection points of the discussed parameters  $\Delta$ . For the extreme points' determination, the following equalities must be treated:

$$\frac{\partial \Delta_M}{\partial \alpha} = \frac{\partial V_{tem}}{\partial \alpha} - \frac{\partial V_{BGM}}{\partial \alpha} \quad (63)$$

$$\frac{\partial \Delta_{n8}}{\partial \alpha} = \frac{\partial V_{tem}}{\partial \alpha} - \frac{\partial V_{new8}}{\partial \alpha} \quad (64)$$

$$\frac{\partial \Delta_{n10}}{\partial \alpha} = \frac{\partial V_{tem}}{\partial \alpha} - \frac{\partial V_{new10}}{\partial \alpha} \quad (65)$$

In expressions from (63) to (65), the partial first derivatives on the right-hand sides can be found in the previous sections. To find inflexion points in the dependencies  $\Delta(\alpha)$ , one has to consider the following partial second derivatives with respect to the electromagnetic constant  $\alpha$ :

$$\frac{\partial^2 \Delta_M}{\partial \alpha^2} = \frac{\partial^2 V_{tem}}{\partial \alpha^2} - \frac{\partial^2 V_{BGM}}{\partial \alpha^2} \quad (66)$$

$$\frac{\partial^2 \Delta_{n8}}{\partial \alpha^2} = \frac{\partial^2 V_{tem}}{\partial \alpha^2} - \frac{\partial^2 V_{new8}}{\partial \alpha^2} \quad (67)$$

$$\frac{\partial^2 \Delta_{n10}}{\partial \alpha^2} = \frac{\partial^2 V_{tem}}{\partial \alpha^2} - \frac{\partial^2 V_{new10}}{\partial \alpha^2} \quad (68)$$

The reader is already familiar with all the partial second derivatives present on the right-hand sides of equalities (66), (67), and (68). These derivatives are quite complicated and can be computed by using the theory developed in the previous section.

## 7. Conclusion

Exploiting the transversely isotropic (6 mm) magnetoelastoelectric composites such as BaTiO<sub>3</sub>-CoFe<sub>2</sub>O<sub>4</sub> and PZT-5H-Terfenol-D, it was demonstrated that the magnetoelectric effect can dramatically affect the velocities of the studied nondispersive new SH-SAWs. This is true even in the case of a very small electromagnetic constant  $\alpha$  because this small material parameter can result in dramatic slowing down the propagation speeds of the studied new SH-SAWs and even wave propagation loss. Also, analytical investigations of the studied new SH-SAW velocities were performed: the extreme and inflexion points were evaluated and discussed. The illuminated peculiarities can be useful for technical device construction based on the magnetoelectric effect and the effect of the slow speed can also find some practical applications, for instance, in filters such as delay lines, etc. The found peculiarities can be also involved in the study on better understanding of the magnetoelectric effect.

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