# **Polyhedral symmetry and quantum mechanics**

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# ABSTRACT

A thorough study of regular and guasi-regular polyhedra shows that the symmetries of these polyhedra identically describe the quantization of orbital angular momentum, of spin, and of total angular momentum, a fact which permits one to assign quantum states at the vertices of these polyhedra assumed as the average particle positions. Furthermore, if the particles are fermions, their wave function is anti-symmetric and its maxima are identically the same as those of repulsive particles, e.g., on a sphere like the spherical shape of closed shells, which implies equilibrium of these particles having average positions at the aforementioned maxima. Such equilibria on a sphere are solely satisfied at the vertices of regular and guasi-regular polyhedra which can be associated with the most probable forms of shells both in Nuclear Physics and in Atomic Cluster Physics when the constituent atoms possess half integer spins. If the average sizes of the constituent particles are known, then the average sizes of the resulting shells become known as well. This association of Symmetry with Quantum Mechanics leads to many applications and excellent results.

# **KEYWORDS**

Symmetry; Polyhedral Symmetry; Angular Momentum and Polyhedra; Nuclear Structure and Symmetry; Isomorphic Shell Model; Shell Clustering in Nuclei; Binding Energies; Radii

# **1. INTRODUCTION**

Geometry in the form of symmetry has been extensively applied in many areas of physics and chemistry. Specifically, in nuclear physics, the employment of polyhedral symmetry has been employed in the form of several models, particularly in the effort to explain the structure of magic numbers [1-7], that is, to explain the exceptional stability of nuclei with the number of neutrons or protons or both equal to 2, 8, 20, 28, 50, 82, and 126. However, in all of these models, the employment of polyhedra, even though successful for several times, was based mainly on intuition and not in rigorous ways, particularly in relation to Quantum Mechanics, which is the physics of the micro-world. Quantum Mechanics was employed later in these models, and their applicability and accuracy of results were limited as well.

In the present work, the relationship between the symmetry of the polyhedra employed and Quantum Mechanics is the starting point before any effort to explain nuclear phenomena. First, it is proved that the quantization of angular momenta  $\ell$ , s, and j expected for central forces is inherent in the structure of the regular and semi-regular polyhedra employed by the model. No approximation whatsoever is involved in this proof. In other words, the relationship of Polyhedral Symmetry to Quantum Mechanics here is on the level of identity.

Another important feature of the present work which is absent from any other model employing polyhedra [1-7] is that here the nucleons are not considered point particle, but as particles having finite size as predicted from particle physics for neutrons and protons

In addition, we will refer to some significant applications of the model to strengthen our arguments even more.

Overall, the motivation of the present work is to make clear that when one deals with regular and semi-regular polyhedra, Quantum Mechanics is inherently involved. This fact permits us to have a pure quantum mechanical treatment of a problem and at the same time to have a geometrical representation. In particular in nuclear physics, the present work provides a way to unite the two milestone models of the field, the Independent Particle Shell Model and the Collective Model, under one common assumption.

## 2. RELATION OF POLYHEDRAL SYMMETRIES TO QUANTUM MECHANICS

## 2.1. Orbital Angular Momentum

For central forces we have the quantization of direction of the angular momentum as a result of quantization of both the angular momentum itself and its projection on the z-axis. This quantization of direction for the onebody problem leaves the angle  $\varphi$  unspecified, while it specifies the azimuthal angle  $\theta$  according to the relationship

$$\theta_{\ell}^{m} = \cos^{-1} \left[ m / \sqrt{\ell \left( \ell + 1 \right)} \right]$$
(1)

In the case of the many-body problem, however, it seems that both the angles  $\theta$  and  $\varphi$  are specified as a re-

sult of the restrictions imposed on each particle from the neighbouring particles. When all  $2(2\ell+1)$  particles for a certain  $\ell$  value are considered simultaneously, it seems that only one value of  $\varphi$  is permissible for each m value. These angles, as we rigorously show shortly, are related to the regular and semi-regular polyhedra [8].

In Figure 1 the quantization of directions for  $\ell = 1 \div 6$ and all associated m values  $(m = -\ell, \dots, +\ell)$  is shown in relation to the cubic-octahedral symmetry in two rows. The first row refers to  $\ell + 1$  values of m, while the second row refers to  $\ell$  values of m with respect to an octahedron, a cube (hexahedron), or a cube-octahedron. The choice of polyhedron each time is made for reasons of clarity, while the z-axis has the same direction. The vectors  $\ell$  forming the appropriate angles pass through char acteristic points of the polyhedra employed marked with a solid circle •. Specifically, these points for  $\ell = 1$  are



**Figure 1.** Orbital angular momentum ( $\ell$ ) quantization of direction for  $\ell = 1 \div 6$  and  $m = -\ell, \dots, \ell$  in relation to the cube-octahedral symmetry. The vectors  $\ell$  form *accurately* with the z-axis the angle  $\theta_{\ell}^{m}$  of **Eq.1**. In row 3 the  $\ell$  vectors for all m of each  $\ell$ value are shown, while in rows 1 and 2 the same vectors are shown in two groups with  $\ell + 1$  and  $\ell$  values of m, respectively. In all parts of **Figures 1(a)**-(**r**) the z-axis has the same direction and all polyhedra shown are oriented with respect to the octahedron of **Figure 1(a)**. The vectors  $\ell$  pass through characteristic points of the polyhedra which are marked with a solid circle •, as explained in the text. **Figures 1(v)**, (**w**), and (**x**) show an equivalent representation of  $\ell$  vectors shown in **Figures 1(k**), (**n**), and (**q**), respectively and, in addition, two more  $\ell$  vectors (shown with broken lines) already present in **Figures 1(j**), (**m**), and (**p**). **Figures 1(s)**-(**u**) show the relationships among the polyhedra of the (o) group.

the vertices of an octahedron for both sets of m values (**Figures 1(a)** and (**b**)); for  $\ell = 2$  the vertices and the shown golden section point of a cube (**Figures 1(d)** and (**e**)), respectively); for  $\ell = 3$  the middles of the edges of a cube-octahedron for both sets of m (**Figures 1(g)**, (**h**)); for  $\ell = 4$  the vertices of an octahedron (**Figure 1(g)**) and the vertices of a cub-octahedron (**Figure 1(k**)); for  $\ell = 5$  the middle points of the shown line segments of an octahedron (**Figure 1(m)**) and of a cube-octahedron (**Figure 1(n)**); and for  $\ell = 6$  the third of the shown line segments of the shown line segments of a cube (**Figure 1(p)**) and the middle points of the shown line segments of a cube (**Figure 1(p)**) and the middle points of the shown line segments of a cube (**Figure 1(p)**) and the middle points of the shown line segments of a cube (**Figure 1(p)**) and the middle points of the shown line segments of a cube (**Figure 1(p)**) and the middle points of the shown line segments of a cube (**Figure 1(p)**) and the middle points of the shown line segments of a cube (**Figure 1(p)**) and the middle points of the shown line segments of a cube (**Figure 1(p)**) and the middle points of the shown line segments of a cube (**Figure 1(p)**) and the middle points of the shown line segments of a cube (**Figure 1(p)**) and the middle points of the shown line segments of a cube (**Figure 1(p)**) and the middle points of the shown line segments of a cube (**Figure 1(p)**) and the middle points of the shown line segments of a cube octahedron (**Figure 1(q)**) [8].

There is an important feature of  $\ell$  vectors. When  $\ell = 1 \div 3$ , the  $\ell$  vectors of both rows of m (*i.e.*, row 1 and row 2 in **Figure 1**) transform into each other by using a single transformation of the cube-octahedron symmetry group. But as one can see in **Figure 1** when  $\ell = 4 \div 6$ , the  $\ell$  vectors transform into each other again by a single operation of the cubeoctahedral symmetrygroup but by a different operation for each row of m.

We have demonstrated above that the degenerate states of the same  $\ell$  value for the cases  $\ell = 4 \div 6$  have a rotational invariance of Orbital Angular Momentum Quantization of Direction which splits into two sets of m, *i.e.*, one referring to row 1 with  $\ell + 1$  values of m and another referring to row 2 with  $\ell$  values of m.

In general, we may argue that the Orbital Angular Momentum Quantization of Direction implies the existence of a fundamental symmetry in nature which could be used as a basis of a physical theory of the structure of matter.

For more details see [8].

#### 2.2. Spin and Total Angular Momentum

In this section the quantization of spin (s) and total (j) angular momenta, in relation to the geometry of regular and semi-regular polyhedra, is presented. That is, in relation to the same polyhedra employed earlier to demonstrate the quantization of the orbital angular momentum ( $\ell$ ). These polyhedra are shown in Figure 2 and are considered superimposed on each other in such a way that they have a common center, a common z-axis, and the most symmetric relative orientation to each other.

In **Figure 3** the quantization of direction of the orbital ( $\ell$ ), spin (**s**), and total (**j**) angular momenta is shown in parts a), b), and c), respectively, where their relative magnitudes are also shown for  $\ell = 1$ , s = 1/2, and j = 3/2. Apparently, the direction of each is unspecified in the polar angle  $\varphi$ , but it is specified in the azimuthal angle  $\theta$  according to the relationship of **Eq.2** 

$$\theta_a^{m\alpha} = \cos^{-1} \left[ m_a / \sqrt{\alpha \left( \alpha + 1 \right)} \right]$$
(2)

where  $\alpha$  stands for  $\ell$ , or *s*, or *j* and  $m_{\alpha}$  is the corresponding z-component.

In **Figure 2** the geometry of quantization of the orbital angular momentum is shown for the cases  $\ell = 1, 2, 3, 4$  for all m, and  $\ell = 5$  for  $m_{\ell} = 5$ .

The quantization of direction of the spin, according to **Eq.2**, is given by the angles

$$\theta_{s=1/2}^{ms=1/2} = 54^{\circ}44'08'' \text{ and } \theta_{s=1/2}^{ms=-1/2} = 125^{\circ}15'52''$$
 (3)

These two angles are identical to characteristic angles of the cube-octahedron (**Figure 2(c)**). The points A, B, C are the middles of the edges of the cube-octahedron. These spin angles are also characteristic angles of the hexa-hedron, dodeca-hedron, octa-hedron and all other polyhedra of **Figure 2** because of their interrelationships shown in **Figures 2(e)** and (**f**).

The geometry of the quantization of the total angular momentum is demonstrated in **Figures 2(a)-(d)**. For example consider  $\ell = 3(m_{\ell} = 1)$ ,  $s = 1/2(m_s = 1/2)$ ,  $j = 7/2(m_j = 3/2)$  illustrated in **Figure 2(c)**. **Eq.2** now gives

$$\theta_{\ell=3}^{m\ell=1} = 73^{\circ}13'17'', \theta_{s=1/2}^{ms=1/2} = 54^{\circ}44'08'', \theta_{j=7/2}^{mj=3/2} = 67^{\circ}47'32''$$
(4)

Both vectors  $\ell$  and s go through the middle of edges of the cube-octa-hedron (the number 1 in 1<sub>6-8</sub> stands for the middle of the edge). Applying the parallelogram rule to these vectors, we find that the resultant vector has a magnitude  $\sqrt{7/2*9/2}$  and a projection on the z-axis 3/2, and forms an angle  $\theta = 67^{\circ}47'32''$  with the z-axis. That is, this resultant vector is identical to.  $J = \ell + s$  with j = 7/2 and  $m_j = 3/2$ .

Other cases examined are apparent in Figures 2(a)-(d). For more details see [9].

# 3. APPLICATIONS OF SYMMETRIES TO QUANTUM MECHANICS

## 3.1. Symmetry Description of the Independent Particle Model (IPM)

In Figure 4(a) in relation of an octahedron, the quantization of the direction of the orbital angular momentum for  $\ell = 1$  is given. All expected directions are axes of symmetry passing through pairs of two opposite vertices of the octahedron, while in Figure 4(b) the quantization of direction for the spin 1/2 are given in relation to the same polyhedron. The two directions of spin shown pass through the middles of two opposite edges of a cub-octahedron. In Figures 4(c) and (d) the total angular momentum j for j = 1/2,  $m_j = \pm 1/2$  and j = 3/2,  $m_j = \pm 3/2$ , respectively, are derived by applying the parallelogram rule to the orbital angular momentum of Figure 4(a) and to the spin of Figure 4(b). In Figure 4(e),



**Figure 2.** Equilibrium (Leech) polyhedra for the demonstration of the quantization of orbital, intrinsic, and total angular momenta. The numbers 0, 1, 2, 3 stand for the vertex, the middle of an edge, the center of a face, and the center of a polyhedron, respectively. The prefixes 6, 8, 6-8, 12, and r-30 refer to a hexa-hedron (cube) (part a), an octa-hedron (part d), a cube-octahedron (part c), a dodeca-hedron (part b) (where an inscribed cube marked with dotted lines is shown as well), and a rhombic triaconta-hedron, respectively. The symbol  $\theta_{\ell}^{m}$  stands for an orbital-angular-momentum vector  $\boldsymbol{\ell}$  having a projection  $m_{\ell}$  on the z-axis, which is common for all polyhedra. All the  $\theta$  vectors shown correspond to the quantization of direction when  $\boldsymbol{\ell}$  is a constant of the motion. The symbol  $\theta_{s}^{ms}$  stands for a spin vector s having a projection  $m_{s}$  on the z-axis. When the parallelogram rule is applied to add a  $\theta_{\ell}^{m\ell}$  vector and another  $\theta_{s}^{ms}$  vector, for the cases shown, the correct total-angular momentum vector  $\boldsymbol{j}$  results (having the correct projection  $m_{j}$  on the z-axis) marked as  $\theta_{j}^{mj}$ . Part e): Interconnections among a tetra-hedron (only vertices are shown marked with o), a hexa-hedron, an octa-hedron, a cube-octahedron (dot-dashed lines) and a rhombic dodecahedron. Part f): Interconnection among a dodeca-hedron, an icosa-hodron, an icosi-dodeca-hedron and a rhombic triaconta-hedron (dot-dashed line).



Figure 3. Relationship between the magnitudes of orbital angular momentum a), spin b), and total angular momentum c), and their z-components.

however, the case j = 3/2,  $m_j = \pm 1/2$  is presented, where neither  $\ell$  nor s come from Figures 4(a) and (b). In Figures 4(c)-(e) j, and not  $\ell$  or s, is the constant of the motion, thus the l and s do not necessarily maintain the same directions in space as in Figures 4(a) and (b). The **j** in Figure 4(e) is determined in relation to the **j** of Fig-

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**ures 4(c)** and (d) according to the law of addition of angular momenta, as will become apparent in a short time. As shown, this is the only case in which **j** does not pass through the middle of the relevant line segment. For simplicity in **Figures 4(c)-(e)** the cases of *j* with negative  $m_j$  are omitted. However, *j* (with  $+m_i$ ) equals -j (with  $-m_i$ ).

So far, in **Figures 4(c)-(e)**, we have determined in relation to an octahedron, the total angular momenta for individual particles which have pairs of *j* and *m<sub>j</sub>* values appropriate for an assignment to p states. This, of course, guarantees only that the angles of *j* with the z-axis, *i.e.* the angles  $\theta_j^{mj}$ , are correct and does not guarantee that the vectors *j* themselves are those expected by the IPM for p states, which is the purpose of this section. The vectors *j* of **Figures 4(c)-(e)** must have, in addition, the appropriate relative orientation in such a way that, when the *j* of two individual particles (e.g.  $j_1$  and  $j_2$ ) are coupled together, the correct total *J* of the system results. That is the vectors  $j_1$  and  $j_2$  must form the appropriate angle.

**Figures 4(f)-(n)** shows that the *j* vectors of **Figures 4(c)-(e)**, in the framework of the symmetry of an octahedron, possess the appropriate relative orientations which lead to the correct coupling of the total angular momenta of two particles for all cases with  $\ell = 1$ . Specifically, **Figures 4(f)** and (g) demonstrate that the *j* of **Figures 4(c)-(e)** result in the correct total *J* for the system of two particles with  $j_1 = j_2 = 1/2$ . **Figures 1(h)-(l)** demonstrate that these *j* also result in the correct *J*, where  $j_1 = j_2 = 3/2$ . **Figures 4(m)-(n)** demonstrate the same when  $j_1 = 1/2$  and  $j_2 = 3/2$  as registered on each relevant part of the figure. Thus it has been found that the *j* vectors of **Figures 1(c)-(e)** are indeed the IPM *j*.

For more details see [10].

#### **3.2. Applications to Nuclear Structure**

#### 3.2.1. Semi-Classical Isomorphic Shell Model

Here, we present the semiclassical part of the model, which has been used many times [11-13] in place of the quantum mechanical part of the model [14], in the spirit of the Ehrenfest theorem [15,16] (that for the average values, the laws of Classical Mechanics are valid). The vertices of the polyhedra of Figure 5 stand for the distribution of the maxima of the wave function for nucleons due to the anti-symmetric requirement of this function. The Ehrenfest theorem for the observables of position (R) and momentum (P) takes the form (see all details in [16]).

$$\mathrm{d}\langle \boldsymbol{R} \rangle / \mathrm{d}t = (1/m) \langle \boldsymbol{P} \rangle \tag{5}$$

$$d\langle \boldsymbol{P} \rangle / dt = -\langle \nabla V(\boldsymbol{R}) \rangle$$
 (6)

For simplicity here, the case of a spinless particle in a scalar stationary potential V(r) is considered.

The quantity  $\langle \mathbf{R} \rangle$  represents a set of three time-dependent numbers  $\{\langle X \rangle, \langle Y \rangle, \langle Z \rangle\}$  and the point  $\langle \mathbf{R} \rangle(t)$  is the center of the wave function at the instant *t*. The set of those points which correspond to the various values of *t* constitutes the trajectory followed by the center of the wave packet.

From Eqs.5 and 6 we get

$$m\mathrm{d}^{2}\left\langle \boldsymbol{R}\right\rangle /\mathrm{d}t^{2} = -\left\langle V\left(\boldsymbol{R}\right)\right\rangle \tag{7}$$

Furthermore, it is known [16] that for special cases of force, e.g., for the harmonic oscillator potential assumed by the model, the following relationship is valid:

$$\langle V(\boldsymbol{R}) \rangle = [V(\boldsymbol{r})]_{\boldsymbol{r}=\langle \boldsymbol{R} \rangle},$$
 (8)

where

$$-\left[V\left(\boldsymbol{r}\right)\right]_{\boldsymbol{r}=\langle\boldsymbol{R}\rangle}=\boldsymbol{F}.$$
(9)

That is, for this potential the average of the force over the whole wave function is **rigorously** equal to the classical force F at the point where the center of the wave function is considered. Thus, for the special case of potential considered here, the motion of the center of the wave function **precisely** obeys the laws of classical mechanics [16]. Any difference between the quantum and the classical description of the nucleon motion exclusively depends on the degree that the wave function may be approximated by its center. Any such difference would contribute to deviations between the experimental data and the predictions of the semiclassical part of the model employed.

Thus, in the present semiclassical treatment the nuclear problem is reduced to that of studying the centers of the wave functions of the constituent nucleons or, in other words, of studying the average positions of these nucleons [17].

We further proceed with the help of **Figure 5** which is identical to that figure employed in [11-13], where the most probable forms and average sizes of the first three proton and the first three neutron shells are presented. It is essential to mention that these average sizes **solely** depend on the average size of a proton,  $r_p = 0.860$  fm, and that of a neutron,  $r_n = 0.974$  fm. Each occupied vertex configuration of this figure corresponds to a quantum state configuration with definite angular momentum and energy. More details of the figure are given in its caption.

The expressions of the two-body (two Yukava) potential V employed [18], for the present semi-classical treatment, of the kinetic energy T [19], of the spin-orbit energy  $V_{LS}$  [20], and of the binding energy  $E_B$  are given in **Eqs.10-14**, respectively. Isospin term in **Eq.14** is not

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and



**Figure 4.** Octa-hedral symmetry description of the Independent Particle Model (IPM) for the 1p-shell. Each mark • stands for the middle point of the corresponding straight-line segment, while large • stands for the center of the octa-hedron. Dark arrows stand for protons and open ones for neutrons, or the opposite, but no mixed [10]. Orbital angular-momentum vectors stand for both protons and neutrons and are presented by dark-open arrows [10]. All **j** shown are in a relative scale; a) and b) quantisation of direction, when the orbital angular momentum  $\mathbf{\ell}$  or spin **s** are constants of the motion, respectively; c)-e) considered together: quantization of direction when the total angular momentum **j** is a constant of the motion; f)-n) total angular momentum **J** of two particles with  $j_1$  and  $j_2$  as registered on each related part; o) assignment of a set of five quantum numbers (n,  $\ell$ , j,  $m_j$  and  $\tau$ ) to each **j** vector of an IPM description of p-shells.

needed since the isospin is here taken care of by the different shell structure (forms and sizes) between proton and neutron shells, as apparent from Figure 5.

$$V_{ij} = 0.993 * 10^{17} * e^{-31.2334 r_{ij}} / r_{ij} - 241.193 * e^{-1.4534 r_{ij}} / r_{ij}$$
(10)

$$\left\langle T \right\rangle_{n\ell m} = \left( \hbar^2 / 2M \right) \left[ 1 / R_{\max}^2 + \ell \left( \ell + 1 \right) / \rho_{n\ell m}^2 \right]$$
(11)

$$\Sigma_i V_{LiSi} = \lambda \Sigma_i * (\hbar \omega_i)^2 / (\hbar^2 / m) * \ell_i s_i \quad (\lambda = 0.03,$$
(12)

the third parameter of the model)

$$\hbar\omega_i = \left(\hbar^2/M\right) \left(n + 3/2\right) / \left\langle r_i^2 \right\rangle \tag{13}$$

$$E_B = \Sigma_{ij} V_{ij} - \Sigma \left\langle T \right\rangle_n m - \Sigma_i V_{LiSi} , \qquad (14)$$

where

- *V<sub>ij</sub>* is the potential energy between a pair of nucleons *i*, *j* at a distance *r<sub>ij</sub>*,
- n, l, m are the quantum numbers characterizing a polyhedral vertex standing for the average position of

a nucleon at the quantum state  $n, \ell, m$ .

- $\ell_i$  and  $s_i$  stand for the orbital angular momentum quantum number  $\ell$  and the intrinsic spin quantum number s of any nucleon *i*.
- M is the mass of a proton  $M_p$  or of a neutron  $M_n$ ,
- $R_{\text{max}}$  is the outermost proton or neutron polyhedral radius (*R*) plus the relevant average nucleon radius  $r_p$  for a proton and  $r_n$  for a neutron, (*i.e.*,  $R_{\text{max}}$  is the radius of the nuclear volume in which protons or neutrons are confined),
- $\rho_{n\ell m}$  is the distance of a nucleon average position at a quantum state  $(n, \ell, m)$  from its orbital angular momentum at the direction  ${}_{n}\theta {}_{\ell}{}^{m}$ .

The parameters of the model are the following five: the two-size parameters  $r_p$  and  $r_n$ , the two parameters from the second term of **Eq.10** (since the first term is applicable only for scattering problems), and the one parameter,  $\lambda$ , from **Eq.12**. With the help of these parameters all quantities  $R_{\text{max}}$ ,  $\rho_{n\ell m}$ , and  $\hbar \omega_i$  in **Eqs.10-14** are obtainable by employing the coordinates of the nucleon



**Figure 5.** The space of the Isomorphic Shell Model for nuclei up to N = 20 and Z = 20. The equilibrium polyhedra in row 1 (2) stand for the most probable forms and average sizes of the first three neutron (proton) shells. The vertices of polyhedra (numbered as shown) stand for average positions of nucleons in definite quantum states ( $\tau$ , n,  $\ell$ ,  $m_{\ell}$ , s). Central axes standing for the quantization of directions of the orbital angular momentum are labelled as  $\theta_{\ell}^m$  and pass through the points marked by small solid circles •. At the bottom-left of each block the numbering of this polyhedron proceeded by the letter Z (N) for protons (neutrons) is given. Over this the number of polyhedral vertices and the number of possible unoccupied vertices (holes, h) are also given. At the bottom-right of each block the radius of polyhedron is listed. Over this the cumulative number of vertices of all previous polyhedra and of this polyhedron is also given. Finally, at the bottom-center of each block the distance  $\rho_{n\ell m}$  of the nucleon average position n $\ell$ m from the relevant axis  $\theta_{\ell}^m$  is given.

average positions derived by the information given in **Fi**-gure 5.

In **Table 1** the results of applying the present version of the model for <sup>4</sup>He, <sup>12</sup>C, <sup>16</sup>O, and <sup>40</sup>Ca, together with corresponding experimental energies are given. The good comparisons between model predictions and experimental energies are apparent. Here, calculations of radii are not presented. Such predictions for more nuclei are given in the next section with a full quantum mechanical description of the Isomorphic Shell Model. In the framework of predictions of radii, results are identical for both versions of the model.

Further interesting applications of this version of the model on nuclear structure and reactions are included in Refs. [11-13] and [21,22], respectively.

## 3.2.2. Quantum Mechanical Isomorphic Shell Model

As is well known the constituent of a nucleus are protons and neutrons which all are fermions, thus their total wave function is anti-symmetric. The locations of maxima of such a wave function on a sphere (like the spherical shape of a complete nuclear shell) are identical to those expected if a repulsive force (of unknown nature) is acting among the constituent fermions (protons and neutrons) [23]. For stability these maxima, under the aforementioned repulsive force, should be in equilibrium.

This problem of equilibria of repulsive particles on a sphere was solved by John Leech in1957 [24]. Such equilibria are obtained **only** for specific number of particles and are related either to the number of vertices, or to the number of middles of edges, or to the number of middles of faces, or to combinations of numbers of these categories of a regular or semi-regular polyhedron [14].

Such equilibria lead to polyhedral most probable forms which, taken in specific sequence, are presented in **Figure 6** and are related to specific nuclear shells and sub-shells. If further, nucleons of finite sizes are considered (specifically,  $r_p = 0.860$  fm and  $r_n = 0.974$  fm, which constitute the only **size** parameters of the model) the **average** size R of the aforementioned polyhedral



**Figure 6.** Most probable forms and average sizes of nuclear shells and sub-shells for nuclei up to Z = 82 and N = 126. Other notations are as in the caption of **Figure 5**.

shells and subshells are obtained. They are those written at the bottom of each block of the figure.

Apparently, the polyhedra of Figure 6 present the most probable forms and average sizes of nuclear shells and sub-shells and at the same time are the same polyhedra as the ones of Figures 1-4, *i.e.*, they are again the regular and semi-regular polyhedra. That is, these polyhedra inherently possess quantum mechanics and at the same time they are those polyhedra possessing equilibrium of forces when repulsive particles (or equivalently fermion average positions) fill up their vertices, or mid-

dles of edges, or middles of faces.

Some more comments should be made concerning the polyhedra of **Figure 6** and the major models of nuclear structure, *i.e.*, the Shell Model and the Collective Model.

The first model assumes independent particle motion of the constituent particles of a nucleus, which is equivalent to assuming zero forces among these particles in a strong field of strong interactions like a nucleus. In addition, this model it does not give the range of applicability of the assumption and how one can understand the difference of stability (if any) between the magic numbers

Nuclei	<sup>4</sup> He	<sup>12</sup> C	<sup>16</sup> O (0p-0h)	<sup>16</sup> O (4p-4h)	<sup>40</sup> Ca
n	1-2	1-2	1-2	1-2	1-2
		5-8	5-10	5-8	5-10
Occupation			25-27		17-28
р	3-4	3-4	3-4	3-4	3-4
		11-14	11-16	11-14	11-16
			29-31		29-40
$\Sigma_{ij} V_{ij}$	44.61	185.43	262.52	259.93	771.70
$\Sigma < T >_{nlm}$	-14.23	-85.32	-124.57	-115.44	-362.97
$\Sigma_{\rm i} V_{\rm lisi}$	0.00	+0.76	1.02		0.00
$V_{Coul}$	-0.46	-6.75	-12.35	-11.39	-64.81
$E_{\text{rotHe}}$	-1.70	-1.70	-1.70	-1.70.	-1.70
E <sub>B</sub> mod.	28.24	92.46	123.90*0.55	+132.42*0.45 = 127.73	342.22
E <sub>B</sub> exp.	28.30	92.16		127.62	342.06

Table 1. Binding energies in MeV according to semi-classical isomorphic shell model.

and the other (about 300) stable nuclei spread in the chart of the nuclides. Moreover, the shell model tries to explain the magic numbers by arbitrarily assuming a strong spin orbit interaction valid only for magic numbers, which is not a necessary assumption for other models (like the present one) to explain these numbers.

The second model assumes strong interaction among the constituent particles of a nucleus leading to an average form of the nucleus which can possess collective motion. This assumption apparently contradicts the shell model assumption of zero forces among the constituent particles of a nucleus. The model has many successes through out the periodic table of the elements. However, it cannot predict the moment of inertia of the resulting rotational spectra at the same time. This moment of inertia is empirically derived each time from the rotational spectrum offered by relevant experiments.

Apparently, these two models were milestones at the time when they appeared. Without these two basic models we could not have reached the present level of understanding about the nucleus. After so many years since their appearance, there is an effort to try to go beyond them.

The Isomorphic Shell Model takes advantage of the equilibrium polyhedra to explain the magic numbers without assuming strong spin orbit interaction and at the same time provides the average structure of a nucleus via the average nucleon positions of the constituent nucleons. Thus, it provides the necessary moment of inertia as the moment of inertia of a specific part of the nucleus which rotates around an axis perpendicular to a symmetry axis of this rotating part. Also, the equilibrium of forces obtained when an equilibrium polyhedron is filled is equivalent to the zero forces assumed by the shell model. However, this equilibrium of forces happens not only for magic numbers, but at any time an equilibrium polyhedron is filled up, a fact which explains stable nuclei throughout the periodic chart of nuclides.

In applying the quantum isomorphic shell model a central potential of the following form is applied for the nucleons of each proton or neutron shell (and not for all nucleons in a nucleus):

$$V(r) = v_o + 1/2 m\omega^2 r^2$$
 (15)

where  $v_0$  and  $\omega$  are different parameters for each proton or neutron shell. Due to the two assumptions below, however, the final number of parameters is substantially reduced.

1) The  $\hbar\omega$ , for each shell, is determined [20] according to **Eq.16**,

$$\hbar\omega = \left(\hbar^2/m\right)\left(n+3/2\right)/\left\langle r^2\right\rangle \tag{16}$$

where  $\langle r^2 \rangle^{1/2}$  is the average size of a specific proton or neutron shell which remains constant for all nuclei. All these sizes of polyhedra are given in **Figure 6**. The only parameters necessary in determining these sizes are the two size parameters  $r_p$  and  $r_n$ , as explained earlier.

2) The parameter of the depth of the potential for each proton or neutron shell is determined according to **Eq.17** 

$$E_{j} = v_{j} - \hbar \omega_{j} (n_{j} + 3/2) = v_{i} - \hbar \omega_{i} (n_{i} + 3/2) = E_{i},$$

or

$$v_{j} = v_{i} - \hbar\omega_{i} \left( n_{i} + 3/2 \right) + \hbar\omega_{j} \left( n_{j} + 3/2 \right) = V_{0} + \hbar\omega_{j} \left( n_{j} + 3/2 \right)$$
(17)

This assumption implies that all nucleons in a nucleus are equally bound in their own potentials (excluding Coulomb and spin-orbit interactions).

It is apparent from **Eq.17** that, since according to the previous assumption **a**) all  $\hbar\omega$  are already determined as above by applying **Eq.16** with respect only to the two size parameters  $r_p$  and  $r_n$ , the depth  $v_i$  of the potential for each shell *i* can be defined with the knowledge of only

one additional parameter  $V_0$  (This is the third universal parameter of the present model equal to 40.268 MeV.)

Solving Schroedinger's equation for the potential of **Eq.15**, the following general equation for the wave function is obtained [20]:

$$L_{k}^{\ell+1/2}(z) = \left\{ \left[ \Gamma(1/2N + 1/2\ell + 1) \right]^{2} / k! \Gamma(\ell+3/2) \right\}_{1}, (18)$$
  
  $\cdot F_{1}(-k; \ell+3/2; z)$ 

where  ${}_{1}F_{1}(\alpha;c;z) = 1 + (\alpha/c)z + \alpha(\alpha+1)z^{2}/c(c+1)2! + \alpha(\alpha+1)(\alpha+2)z^{3}/c(c+1)(c+2)3! + \cdots$ , with  $\alpha = -k, z = 2\alpha r^{2}$ , and  $\alpha = m\omega/2\hbar$ . The series terminates with the term  $(-1)^{k} [\Gamma(c)/\Gamma(c+k)]z^{k}$  and the various quantum numbers involved are  $n = 0, 1, 2, \cdots; k = 0, 1, 2, \cdots; \ell \le n$ , and  $\ell = n - 2k$  [20].

The explicit forms of equations of the wave functions for a harmonic oscillator potential derived from the recursion formula **Eq.18** can be found in [14] for all wave functions of nuclei up to Z = 126 and N = 184.

Due to the fact that in the model  $\hbar\omega$  is different for the different shells, the wave functions with the same orbital angular momentum quantum number  $\ell$  are not orthogonal. For these wave functions Gram-Smidth's technique is applied [25]. In [14] some relevant guide equations to facilitate this orthogonalization are given.

#### 1) Binding Energies

The binding energy for each quantum state in a harmonic oscillator potential is given by **Eq.19**:

$$E_{B} = v - \hbar\omega \left( n + 3/2 \right) \tag{19}$$

In **Eq.19** all  $\hbar\omega$  come from **Eq.16** (with respect to the only two size parameters  $r_p$  and  $r_n$ ) and all potential depths  $\nu$  come from **Eq.17** (with respect to the only one additional potential parameter  $V_0$ ). Thus,  $E_B$  from **Eq.19** is determined with respect to only 3 **universal** parameters.

Now, since the nuclear problem basically refers to two-body forces, in order to avoid the double counting, the potential portion of the second part of **Eq.19** should be divided by two. Furthermore, since according to the Virial theorem half of the quantity  $\hbar\omega(n+3/2)$  is potential energy and half is kinetic energy, **Eq.19** takes the form of **Eq.20** 

$$E_{B} = \frac{1}{2} \left[ v - \frac{1}{2} \hbar \omega (n + \frac{3}{2}) \right] -\frac{1}{2} \hbar \omega (n + \frac{3}{2}) = \frac{1}{2} v - \frac{3}{4} \hbar \omega (n + \frac{3}{2})$$
(20)

Given that the potential v, according to **Eq.17**, is

$$v = V_0 + \hbar\omega (n + 3/2),$$
 (21)

the final expression of binding energy for each proton or neutron state takes the form of **Eq.22**.

$$(E_B)_1 = \frac{1}{2} \left[ V_0 + \hbar \omega (n + \frac{3}{2}) \right] - \frac{3}{4} \hbar \omega (n + \frac{3}{2}) = \frac{1}{2} V_0 - \frac{1}{4} \hbar \omega_1 (n_1 + \frac{3}{2})$$
(22)

The index 1 in **Eq.22** refers to all states where the orbital angular momentum quantum number  $\ell$  appears for the first time.

However, for a second, a third and a fourth appearance of a state with the same  $\ell$ , in the place of the quantity  $\hbar\omega(n+3/2)$  in **Eq.22** we should take the corresponding quantity due to the necessary orthogonalization by using **Eqs.9-11** of [14]

Finally, the total binding energy of a nucleus in the model is given by **Eq.23** 

$$(E_B)_{\text{total}} = \sum_{i=1}^{A} (E_B)_i + \sum_{i=1}^{A} V_{LiSi} - \sum_{i \neq j}^{z} E_{Cij} , \qquad (23)$$

where the spin-orbit term is given [20] by Eq.24

$$\sum_{i=1}^{A} V_{LiSii} = \lambda \sum_{i=1}^{A} \left[ \frac{i}{r} * dV(r) / dr \right] \Re \ell_i s_i$$
  
=  $\lambda \sum_{i=1}^{A} (\hbar \omega_i)^2 / (\hbar^2 / m) * \ell_i s_i$  (24)

with  $\lambda = 0.03$  (This is the fourth and the last **universal** parameter of the present version) and the Coulomb term is given by **Eq.25**:

$$\sum_{i\neq j}^{Z} E_{Cij} = \sum_{i\neq j}^{Z} e^{2} / d_{ij} .$$
 (25)

The distance  $d_{ij}$  between any two proton average positions in **Figure 6** is calculated from the coordinates of the proton polyhedral vertices (standing for the proton average positions) in this figure (see section 2.2 of [14]).

As in the former section, an extra term in **Eq.23** due to isospin is not needed since the isospin is here taken care of by the different average shell structure between protons and neutrons as apparent from Figure 6.

#### 2) Mean Radii

Due to the way the wave functions have been correlated with the size of nuclear shells via **Eq.16**, average radii can be calculated by using simple formulas, as seen below.

Average charge radius:

$$\langle r^2 \rangle_{ch} = \sum_{i=1}^{Z} r_i^2 / Z + r_{ch..proton}^2 - r_{ch.neutron}^2 * N / Z$$
, (26)

where  $r_{\text{ch.proton}} = r_p = 0.86 \text{ fm and } r_{\text{ch.neutron}} = 0.34 \text{ fm [7]}.$ Average neutron radius:

$$\left\langle r^{2} \right\rangle_{n} = \sum_{i=1}^{N} r_{i}^{2} / N + r_{\text{neutron}}^{2} ,$$
 (27)

where  $r_{neutron} = r_n = 0.974 \text{ fm}$ . Average mass radius:

$$\left\langle r^{2} \right\rangle_{m} = \left[ \sum_{i=1}^{A} r_{i}^{2} + Z * r_{p}^{2} + N * r_{n}^{2} \right] / A.$$
 (28)

All values of  $r_i$  needed are included in **Figure 6** (see right corner at the bottom of each block).

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In **Table 2** the binding energies of <sup>40</sup>Ca, <sup>48</sup>Ca, <sup>54</sup>Fe, <sup>90</sup>Zr, <sup>108</sup>Sn, <sup>114</sup>Te, <sup>142</sup>Nd, and <sup>208</sup>Pb. are listed from [14]. Also for the same nuclei the average charge, neutron, and mass radii are listed again from [14]. For both energies and radii available experimental values are given for comparison. The very good agreements between predictions and experimental values are apparent.

#### 3.2.3. Other Applications

Besides the above given applications of the Isomorphic Shell Model, it is interesting to mention its application to super-heavy nuclei [26], to neutron nuclei [27], to exotic nuclei [28], and its extension to atomic clusters [29], when the constituents atoms have half integer spin and thus can be considered as atomic fermions. Again in these applications the dominant part is the relationship between Symmetry of regular and quasi-regular polyhedra and Quantum Mechanics.

For valuable information concerning geometry, the books [30,31] are very instructive.

## 4. CONCLUSIONS

In the present work, the regular and semi-regular polyhedra were employed to derive the relationship between their symmetries and quantum mechanics. Particularly, we showed that the symmetries of these polyhedra inherently possess (on the level of identity) the quantization of  $\ell$ , s, and j expected from Quantum Mechanics for central forces. This is a unique property of the present model in comparison with the other models of the nucleus involving polyhedra to explain the magic numbers and other nuclear properties. No relationship of their polyhedra with Quantum Mechanics has been reported. This unique property of the present work to identically connect the symmetry of the regular and semi-regular polyhedra with Quantum Mechanics permits one to assign quantum states at the vertices of these polyhedra considered as the average positions of neutrons and protons in the way explained in the text.

Furthermore, an important feature of the polyhedra

employed in the present work (i.e., the regular and semiregular polyhedra) is that they possess the equilibrium property. That is, when repulsive particles (as implied by the Pauli principle for fermions) are assigned at their vertices, standing as their average positions, these particles are at equilibrium whatever the law of force between them may be. In addition, if two sets of fermions are assumed on the same sphere (as neutrons and protons), not only the particles of each set, but also the particles of both sets should be at equilibrium. This equilibrium should be conserved when more polyhedral shells are considered, which implies that the polyhedra should be concentric and in the most symmetric arrangement among themselves. This property of equilibrium of forces is practically equivalent to the assumption of the Shell Model of the nucleus that each nucleon acts as if it is under a zero force.

This equilibrium property leads to the most probable forms of nuclear shells. As mentioned in the introduction, neutrons and protons are not considered as point particles, but as particles with finite size, which have been established from particle physics. The consideration of nucleons with finite size leads to the average size of the nuclear shells and thus of all nuclei. These average positions for the nucleons participating in a collective nuclear rotation form an average shape whose symmetries permit the evaluation of moments of inertia and thus of the energies of the expected rotational bands for this nucleus. This is the way the present work is associated with the Collective Model of the nucleus.

However, there is an important difference between the Collective Model and the present model. In the former, it is assumed that the rotating nucleons strongly interact with each other (like in solid state physics) and form the rotating shape necessary for the rotational band. However, the Collective Model still cannot predict the moment of inertia. The present model does not need this additional assumption. It can predict the moment of inertia and the rotational band based on the average positions of rotating nucleons derived as above.

Table 2. Total	binding energies in	MeV, average charge	neutron. point neutron-	proton, and mass r	adii.in fm [14]
10000 10000	omanig energies m	nie , a erage enange	, near on, point near on	proton, and mass r	

	<sup>40</sup> Ca	<sup>48</sup> Ca	<sup>54</sup> Fe	<sup>90</sup> Zr	<sup>108</sup> Sn	<sup>114</sup> Te	<sup>142</sup> Nd	<sup>208</sup> Pb
E <sub>B</sub> mod.	342.3	416.5	471.3	783.0	915.2	961.1	1185.1	1636.4
E <sub>B</sub> exp.	342.1	416.0	471.8	783.2	914.7	961.2	1185.2	1636.5
$_{\rm ch} < r^2 >^{1/2} {\rm mod.}$	3.48	3.48	3.72	4.27	4.56	4.61	4.9	5.51
$_{\rm ch} < r^2 > ^{1/2} \exp$ .	3.48	3.48	3.69	4.27	4.56		4.91	5.51
$_{n} < r^{2} > ^{1/2} mod.$	3.25	3.65	3.73	4.4	4.7	4.86	5.43	6.18
$[n < r^2 > 1/2 - ch < r^2 > 1/2] \text{mod}$	-0.29	0.12	-0.03	0.09	0.1	0.22	0.5	0.64
$[n < r^2 > 1/2 - ch < r^2 > 1/2]$ exp.	-0.3	0.12	-0.04	0.09	0.11	-	-	0.55
$_{\rm m} < r^2 >^{1/2} {\rm mod.}$	3.38	3.56	3.81	4.36	4.69	4.8	5.22	5.93

A further strong support of this work is provided by its application to specific nuclear properties. First, the  $\hbar\omega$ values are estimated in both the semi-classical and pure quantum mechanical treatment of nuclei. Specifically, in Table 1 the nuclei <sup>4</sup>He <sup>12</sup>C, <sup>16</sup>O and <sup>40</sup>Ca are treated semi-classically and their binding energies have been estimated with a maximum deviation between predicted and experimental values of 0.30 MeV. In Table 2 the nuclei <sup>40</sup>Ca, <sup>48</sup>Ca, <sup>54</sup>Fe, <sup>90</sup>Zr, <sup>108</sup>Sn, <sup>114</sup>Te, <sup>142</sup>Nd, and <sup>208</sup>Pb are treated purely quantum mechanically. Properties examined there are the binding energies and radii. The maximum deviation between predicted and experimental values of binding energies is 0.5 MeV. For the average values of charge radii, predicted and experimental values are identical, with the only exception for <sup>54</sup>Fe where the difference is 0.03 fm. For the difference between neutron and proton average radii in the same table the deviation is 0.01 fm, except for <sup>208</sup>Pb, where the deviation is 0.09 fm and is considered significant. For the average neutron radii, there are no experimental values for comparison.

Other applications of the present model are given elsewhere [14]. Hence, a very strong connection between Polyhedral Symmetry and Quantum Mechanics is provided throughout this work.

Perhaps it is interesting to finish with Albert Einstein's words: Geometry is always the solution. The question is which geometry each time.

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