

Lessons Learned from Practical Independent Verification and Validation Based on IEEE 1012

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Received July 27th, 2012; revised August 31st, 2012; accepted September 13th, 2012

ABSTRACT

IEEE 1012 [1] describes the SDLC phase activities for software independent verification and validation (IV & V) for nuclear power plant in truly general and conceptual manner, which requires the upward and/or downward tailoring on its interpretation for practical IV & V. It contains crucial and encompassing check points and guidelines to analyze the design integrity, without addressing the formalized and the specific criteria for IV & V activities confirming the technical integrity. It is necessary to list up the inspection viewpoint via interpretation of the standard that is practical review points checking design consistency. For fruitful IV & V of Control Element Driving Mechanism Control System (CEDMCS) software for Yonggwang Nuclear Power Plant unit 3 & 4, the specific viewpoints and approach are necessary based on the guidelines of IEEE 1012 to enhance the system quality by considering the level of implementation of the theoretical and the practical IV & V. Additionally IV & V guideline of IEEE 1012 does not specifically provide the concrete measure considering the system characteristics of CEDMCS. This paper provides the seven (7) characteristic criteria for CEDMCS IV & V, and by applying these viewpoints, the design analysis such as function, performance, interface and exception, backward and forward requirement traceability analysis has been conducted. The requirement, design, implementation, and test phase were only considered for IV & V in this project. This article also provides the translation of code to map theoretical verification and validation into practical verification and validation. This paper emphasizes the necessity of the intensive design inspection and walkthrough for requirement phase to resolve the design faults because the IV & V of early phase of SDLC obviously contributes to find out most of critical design inconsistency. Especially for test phase IV & V, it is strongly recommended to prepare the test plan document which is going to be the basis for the test coverage selection and test strategy. This test plan document should be based on the critical characteristics of function and performance of CEDMCS. Also to guarantee the independency of V & V organization participating in this project, and to acquire the full package of design details for IV & V, the systematic approach and efforts with an aspect of management is highlighted among the participants.

Keywords: Korea Standard Nuclear Plant (KSNP); Instrumentation and Control (I & C); Control Element Drive Mechanism Control System (CEDMCS); Software Development Life Cycle (SDLC); Independent Verification and Validation (IV & V); Reactor Regulating System (RRS)

1. Introduction

Due to the hardware aging and obsolescence, the upgrade of CEDMCS for Yonggwang 3 & 4, and Ulchin 3 & 4 nuclear power plants was brought up as necessary. In the course of upgrade, IV & V is requested to validate the design integrity of the system which is classified to safety-related.

For the transparency of V & V activity, the design team and review team is officially separated for managing the independent review of system design, which is also the requirement from licensing organization of Korea

Institute of Nuclear Safety (KINS) shown in **Figure 1**.

However IEEE 1012 code is conceptual that is applicable to all the software of various fields including CEDMCS, it was necessary to devise application-specific review points. This approach is enhancing the reliability of the CEDMCS software system.

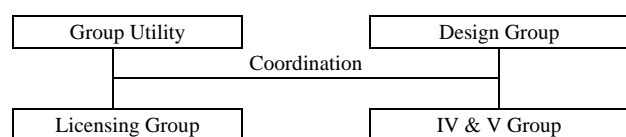


Figure 1. The organization for CEDMCS IV & V in Yonggwang Nuclear Power Plant 3 & 4.

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2. IV & V of CEDMCS in KSNP

CEDMCS on Korea Standard Nuclear Plant (KSNP) was independently verified and validated. Based on the conceptual IV & V activities of IEEE 1012, the major viewpoint is selected as below through the system function and performance analysis of CEDMCS.

- 1) Identification of the critical functional characteristics for the CEDMCS;
- 2) Identification of the interface between the internal and external sub-components like the communication and its transmission frequency (including the serial data links);
- 3) Identification of the performance characteristics for the target system;
- 4) Identification of the appropriateness on the functional cohesion and coupling for final implementation [1,2];
- 5) Reliability of the function and performance;
- 6) Exceptional handling;
- 7) Identification of the test coverage.

The following section will address the detail of the item enumerated above.

2.1. Identification of Critical Characteristics

There are following design factors for CEDMCS, when an independent review is conducted.

- 1) Profile to drive the control rod up, down, and hold;
- 2) Conditions that interlock the rod driving;
- 3) Engagement condition for the rod driving;
- 4) Operation mode of the rod driving.

In addition to the above, there are many design factors for controlling rods which are regulated by CEDMCS. These factors are identified as critical design characteristics

and should be highlighted when an independent review is conducted.

Figure 2 indicates the interconnection diagram between CEDMCS and other auxiliary system which provides the control input and output. The CEDMCS marked with cloud in Figure 2 is to control the reactivity by insertion and withdrawal of control rod. The main input from RRS is the control signal, and rod is also controlled by operator intervention. Thus integral IV & V is the critical task to guarantee the integrity of the system. Otherwise CEDMCS causes the plant trip bringing about the financial damage and public hazard.

2.2. Identification of the Interface

For the modernization or upgrade of CEDMCS, some of the hardwired interconnections between components are connected through a communication network. The main differences between these two configurations are discontinuity and continuity of data. In case of hardwired, the continuity of data is guaranteed, but when communication is used for data exchange, there might be a discontinuity of data when a network failure occurs and is recovered soon.

2.3. Identification for Performance Characteristic

As mentioned above 1) in 2.1, the profile should be implemented according to the tolerable range in time line. This could results in critical hazard of malfunction in insertion, withdrawal and holding of rod.

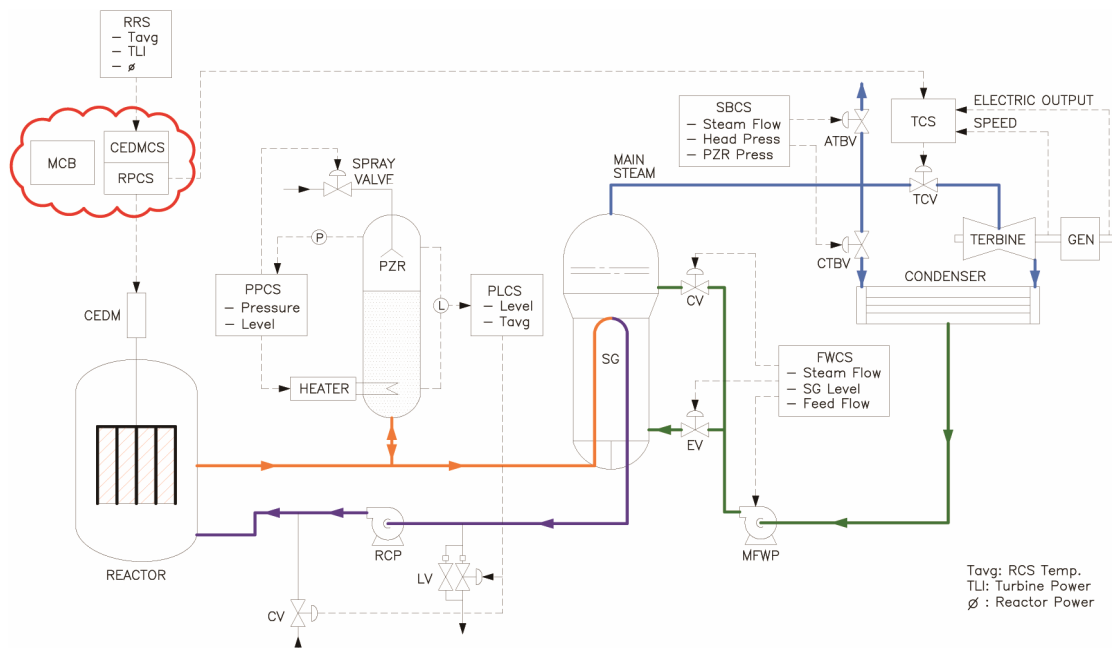


Figure 2. CEDMCS in Yonggwang Nuclear Power Plant 3 & 4.

2.4. Cohesion and Coupling

It is the design verification to check if the software module is constructed well based on the logical function decomposition, getting rid of implementation complexity and ambiguity that result from bad software design. It is a critical measure to judge the testability and maintainability of software [2].

2.5. Reliability of Function and Performance

It is a new aspect of verification and validation to check if the function to be implemented is implementable as software or hardware. Recently most of functions, even implemented with hardware in a legacy plant, are reformed as software, targeting a digital system.

2.6. Exception Handling

In any software function, there is an exception of partial function. This partial function shall be clearly designed and implemented, which supports a reliable test plan and procedure in the test phase.

2.7. Test Coverage

Practically exhaustive test coverage is not desirable and recommended for robust software testing. However, when the output of the software is actuating the hardware device that is connected, the maximum test coverage is recommended in test. For this systematic and concrete test coverage has been generated by designer as well as IV & V reviewer based on the 7 criteria. It was very helpful to remove the delicate failure sources, which was the solid platform of test procedure.

Based on the fundamental principles mentioned in IEEE 1012, the IV & V team extracts and summarizes the non-trivial points for verification and validation as described in 2.1 through 2.7, which is used for estimating the design integrity of whole CEDMCS system except hardware design and assembly part.

3. Statistical Distribution of Anomaly Data

The following is a number of anomaly reports issued at the each phase of SDLC, excluding the planning, installation and maintenance for simplicity. **Tables 1** and **2** show the anomaly pattern of each design segment throughout software development life cycle. As shown, most of design anomaly is identified in the early phase of requirement and design. And even thought that the number of anomaly is not so significant, most of anomaly topic in test phase is the coverage and the scope of each testing such as unit testing, integration testing, Factory Acceptance Testing (FAT) and Site Acceptance Testing (SAT).

Figure 3 is indicating the amount of the anomaly for

each design segment in total. There are several issues that we need to be aware of. The extent of Line of Code (LOC) and complexity of design is closely related to a number of anomalies, and especially the design segment of Man Machine Interface (MMI) that has human interface is relatively high number of Human Factor (HF) anomaly. Even though HF can be viewed as a different side of IV & V, there is obviously a tendency that the HF design is significantly overlooked in the design process.

Table 1. Anomaly pattern of CEDMCS software upgrade in Yonggwang Nuclear Power Plant 3 & 4.

	Req't	Design	Impl.	Test
Logic Controller	17	7	5	5
Logic Controller MTP	8	9	5	8
PC and DCHC Controller	2	5	4	3
PC and DCHC Controller FPGA	3	5	2	0
MCB OM	16	3	4	3
Total	71	78	29	23

Table 2. Anomaly pattern of CEDMCS software upgrade in Ulchin Nuclear Power Plant 3 & 4.

	Req't	Design	Impl.	Test
Logic Controller	10	8	6	5
Logic Controller MTP	12	14	9	4
SSPE Power Controller	5	10	1	2
SSPE Power Controller FPGA	4	5	0	0
Data Process Controller	21	21	5	5
Data Process Controller MTP	19	20	8	7
Total	71	78	29	23

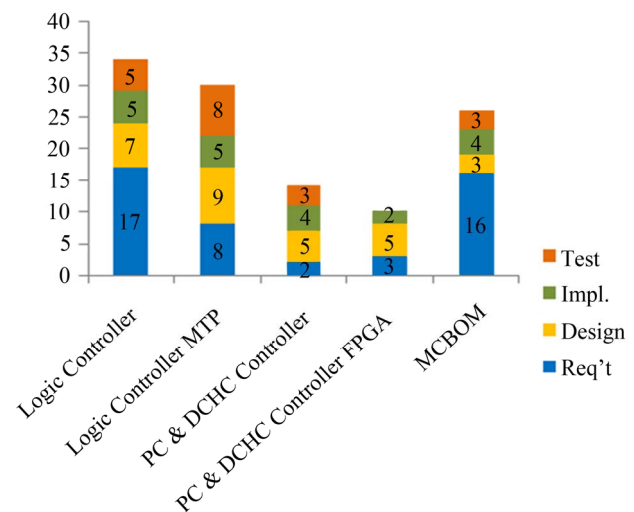


Figure 3. Diagram for AR distribution in Yonggwang Nuclear Power Plant 3 & 4.

4. Lesson Learned in V & V of KSNP CEDMCS

The following is the pattern found through the analysis of anomaly reports in each phase about CEDMCS of Yonggwang unit 3 & 4, and Ulchin unit 3 & 4 nuclear power plants.

4.1. High Level Design Error

Most of errors were found in the early stage of software development life cycle [3,4].

Requirement and design phases in SDLC are much more important in software development as indicated in **Tables 1** and **2**, and **Figure 3**. The fault of early phase design can cause the wrong implementation which is not verified because it is well designed based on the wrong early phase of design. The small number of anomaly in the phase behind requirement phase is truly based on the early stage of development phase.

For requirement IV & V, the contract, project planning documents, user (utility) requirements, technical meeting minutes, system design documents such as System Requirement (SR), Design Requirement (DR), Design Specification (DS), and Interface Requirement (IR), Performance Requirement (PR) and other design relevant documents were used for requirement phase IV & V input.

4.2. The Test Preparation of CEDMCS

With the result of requirement phase IV & V, the design and implementation phase is conducted without remarkable controversy. But in test phase, the hot debate for test coverage and plan has been done. The outstanding deviation between designer and IV & V reviewer was identified. To resolve these issues, each participating organization together had a meeting, and decided to prepare the test plan document based on IEEE code [5,6].

4.3. The Management of IV & V

According to Annex C “definition of independent V & V (IV & V)” of IEEE 1012-2004 [1], IV & V is defined by three parameters: technical independence, managerial independence, and financial independence as described in **Table 3**.

Table 3. Independent verification and validation form.

IV & V Form	Technical	Management	Financial
Classical	I	I	I
Modified	I	i	I
Integrated	i	I	I
Internal	i	i	i
Embedded	e	e	e

Note: I: Rigorous; i: Conditional Independence; e: Minimal Independence.

4.3.1. Technical Independence

Technical independence requires the V & V effort to utilize personnel who are not involved in the development of the software. The IV & V effort should formulate its own understanding of the problem and how the proposed system is solving the problem. Technical independence (“fresh viewpoint”) is an important method to detect subtle errors overlooked by those too close to the solution.

For software tools, technical independence means that the IV & V effort uses or develops its own set of test and analysis tools separate from the developer’s tools. But this type of tool independence is overlooked in this project for the reason of milestone, budget and suspicion that diverse and independent tool environment does not exactly guarantee the correctness and reliability of the system.

4.3.2. Managerial Independence

Managerial independence requires that the responsibility for the IV & V effort be vested in an organization separate from the development and program management organizations. Managerial independence also means that the IV & V effort independently selects the segments of the software and system to analyze and test, chooses the IV & V techniques, defines the schedule of IV & V activities, and selects the specific technical issues and problems to act upon. The IV & V effort provides its findings in a timely fashion simultaneously to both the development and program management organizations. The IV & V effort must be allowed to submit to program management the IV & V results, anomalies, and findings without any restrictions (e.g., without requiring prior approval from the development group) or adverse pressures, direct or indirect, from the development group. In this project this independence is kept almost in perfect manner via technical meeting and managerial meeting continuously.

4.3.3. Financial Independence

Financial Independence requires that control of the IV & V budget be vested in an organization independent of the development organization. This independence prevents situations where the IV & V effort cannot complete its analysis, or test or deliver timely results because funds have been diverted or adverse financial pressures or influences have been exerted. This is totally evident and there is no way out from this dilemma in this project.

4.3.4. Forms of Independence

The extent to which each of the three independence parameters (technical, managerial, financial) is vested in a V & V organization determines the degree of independence achieved.

Many forms of independence can be adopted for a V & V organization. The five most prevalent are: 1) Clas-

sical; 2) Modified; 3) Integrated; 4) Internal; and 5) Embedded. **Table 3** illustrates the degree of independence achieved by these five forms. The IV & V for CEMDCS upgrade has been conducted in the combination of “modified” and “integrated” in **Table 3**.

1) Classical IV & V

Classical IV & V embodies all three independence parameters. The IV & V responsibility is vested in an organization that is separate from the development organization. IV & V uses a close working relationship with the development organization to ensure that IV & V findings and recommendations are integrated rapidly back into the development process. Typically, classical IV & V is performed by one organization (e.g., supplier) and the development is performed by a separate organization (*i.e.*, another vendor). Classical IV & V is generally required for software integrity level 4 (*i.e.*, loss of life, loss of mission, significant social, or financial loss) through regulations and standards imposed on the system development.

2) Modified IV & V

Modified IV & V is used in many large programs where the system prime integrator is selected to manage the entire system development including the IV & V. The prime integrator selects organizations to assist in the development of the system and to perform the IV & V. In the modified IV & V form, the acquirer reduces its own acquisition time by passing this responsibility to the prime integrator. Since the prime integrator performs all or some of the development, the managerial independence is compromised by having the IV & V effort report to the prime integrator. Technical independence is preserved since the IV & V effort formulates an unbiased opinion of the system solution and uses an independent staff to perform the IV & V. Financial independence is preserved since a separate budget is set aside for the IV & V effort. Modified IV & V effort would be appropriate for systems with software integrity level 3 (*i.e.*, an important mission and purpose).

3) Integrated IV & V

This form is focused on providing rapid feedback of V & V results in the development process and is performed by an organization that is financially and managerially independent of the development organization to minimize compromises with respect to independence. The rapid feedback of V & V results in the development process is facilitated by the integrated IV & V organization: working side-by-side with the development organization; reviewing interim work products; and providing V & V feedback during inspections, walkthroughs, and reviews conducted by the development staff (potential impact on technical independence). Impacts on the technical independence are counterbalanced by the benefits associated with a focus on interdependence between the integrated IV & V organization and the development organization.

4) Internal IV & V

Internal IV & V exists when the developer conducts the IV & V with personnel from within its own organization, although preferably not the same personnel involved directly in the development effort. Technical, managerial, and financial independence are compromised. Technical independence is compromised because the IV & V analysis and test is vulnerable to overlooking errors by using the same assumptions or development environment that masked the error from the developers. Managerial independence is compromised because the internal IV & V effort uses the same common tools and corporate analysis procedures as the development group. Peer pressure from the development group may adversely influence how aggressively the software is analyzed and tested by the IV & V effort. Financial independence is compromised because the development group controls the IV & V budget. IV & V funds, resources, and schedules may be reduced as development pressures and needs redirect the IV & V funds into solving the development problems. The benefit of an internal IV & V effort is access to staff who knows the system and its software. This form of IV & V is used when the degree of independence is not explicitly stated and the benefits of preexisting staff knowledge outweigh the benefits of objectivity.

5) Embedded IV & V

This form is similar to an internal IV & V in that it uses personnel from the development organization who should not be involved directly in the development effort. Embedded V & V is focused on ensuring conformance to the development procedures and processes. The embedded V & V organization works side-by-side with the development organization and attends the same inspections, walkthrough, and reviews as the development staff (*i.e.*, compromise of technical independence). Embedded V & V is not tasked specifically to independently assess the original solution or conduct independent tests (*i.e.*, compromise of managerial independence). Financial independence is compromised because the V & V staff resource assignments are controlled by the development group. Embedded V & V allows rapid feedback of V & V results into the development process but compromises the technical, managerial, and financial independence of the V & V organization.

Regardless of the independence types and form of the IV & V, the most difficult thing to handle in the process of IV & V itself and AR resolution is the “financial independence” Anything else except this, IV & V activity has been conducted in reasonable manner to remove the design fault and to optimize the design products produced in the development cycle.

After analysis of IV & V form based on IEEE 1012, the realistic IV & V form will be described comparing to this project. **Table 4** shows the summary of IV & V form that is achievable and not achievable in the process of IV & V.

Table 4. Comparison between IEEE Std. 1012 and practical independent verification and validation.

	IEEE Std. 1012	Practical IV & V
Technical independence	Achievable	Achievable
Managerial independence	Achievable	Achievable
Financial independence	Achievable	Achievable, but partly influenced by adverse or distorted pressure
Forms of independence	The classic model of IV & V is desirable.	The "integrated model" of IV & V is realistic.

Financial independence seems to be tough to implement in realistic project environment. Thus it could be a concern to regulator for IV & V for safety-related system. It is complicated issue which might involve legal support.

5. Conclusions

Yonggwang unit 3 & 4 and Ulchin unit 3 & 4 that is one of the KSNP are upgraded with new hardware where the CEDMCS software is running. For software reliability, independent verification and validation has been conducted throughout the SDLC. It was important to correctly analyze and recognize the core function, performance and interface of CEDMCS to draw the seven (7) criteria for IV & V view points in starting point, which is used throughout the IV & V. These items were also prepared by identifying the hazardous failure event of CEDMCS [7]. The design result was reviewed to analyze the design error involved in the design process. They show that most of the design inconsistency occurs in the early stage of the design process such as the requirement phase and the design phase. Thus special care for design inception phase is required via well-known practices like technical meeting design inspection and walkthrough, and design iteration.

Regardless of the type of independency and IV & V, the sensitive difference between reality and standards is the aspect that it is difficult to overcome the circumstance of financial independency in a sense that the main contractor provides the money. If it is necessary, the legal support will be an efficient way to overcome financial independency. However the solution was technical meeting including licensing body in this project.

Once the completion of IV & V, issuing the anomaly report, a resolution meeting between IV & Ver and designer to obtain the optimal solution is held in every SDLC phases. Unfortunately there is a tendency that the desi-

gner will not partly accept the anomaly issued just because the function is anyway performed well even though there is room for optimization and documentation. In this case anomaly resolution process was efficiently and mandatorily used with the written verification and validation plan and procedure including anomaly report disposition procedure for approval.

Before commencing the test phase IV & V, it was very important to create and review the test plan to extract the essential test coverage and test scope of unit testing, integration testing, factory acceptance testing, and site acceptance testing. Likewise the SDLC design process, IV & V for SDLC design process has been iterated for software quality enhancement through technical meeting for anomaly report resolution. The activities for resolving these topics are completed successfully, resulting in that CEDMCS software system is running without errors or failures so far.

6. Acknowledgements

This work has been conducted with the support of Man-Machine Interface System (MMIS) group in Korea Atomic Energy Research Institute (KAERI), and reliability and nuclear engineering group in KOREA Reliability Technology System (KORTS).

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