

Stochastic Volatility Jump-Diffusion Model for Option Pricing

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Abstract

An alternative option pricing model is proposed, in which the asset prices follow the jump-diffusion model with square root stochastic volatility. The stochastic volatility follows the jump-diffusion with square root and mean reverting. We find a formulation for the European-style option in terms of characteristic functions of tail probabilities.

Keywords: Jump-Diffusion Model, Stochastic Volatility, Characteristic Function, Option Pricing

1. Introduction

Let (Ω, \mathcal{F}, P) be a probability space with filtration $\mathcal{F} = (\mathcal{F}_t)_{0 \leq t \leq T}$. All processes that we shall consider in this section will be defined in this space. An asset price model with stochastic volatility has been defined by Heston [1] which has the following dynamics:

$$\begin{aligned} dS_t &= S_t (\mu dt + \sqrt{v_t} dW_t^S), \\ dv_t &= \kappa(\theta - v_t) dt + \sigma \sqrt{v_t} dW_t^v, \end{aligned} \quad (1)$$

where S_t is the asset price, $\mu \in \mathcal{R}$ is the rate of return of the asset, v_t is the volatility of asset returns, $\kappa > 0$ is a mean-reverting rate, $\theta \in \mathcal{R}$ is the long term variance, $\sigma > 0$ is the volatility of volatility, W_t^S and W_t^v are standard Brownian motions corresponding to the processes S_t and v_t , respectively, with constant correlation ρ . In 1996, Bate [2] introduced the jump-diffusion stochastic volatility model by adding log normal jump Y_t to the Heston stochastic volatility model. In the original formulation of Bate, the model has the following form:

$$\begin{aligned} dS_t &= S_t (\mu dt + \sqrt{v_t} dW_t^S) + S_{t-} Y_t dN_t^S, \\ dv_t &= \kappa(\theta - v_t) dt + \sigma \sqrt{v_t} dW_t^v, \end{aligned} \quad (2)$$

where N_t^S is the Poisson process which corresponds to the underlying asset S_t , Y_t is the jump size of asset price return with log normal distribution and S_{t-} means that there is a jump the value of the process before the jump is used on the left-hand side of the formula. Moreover, in 2003, Eraker Johannes and Polson [3] extended Bate's

work by incorporating jumps in volatility and their model is given by

$$\begin{aligned} dS_t &= S_t (\mu dt + \sqrt{v_t} dW_t^S) + S_{t-} Y_t dN_t^S, \\ dv_t &= \kappa(\theta - v_t) dt + \sigma \sqrt{v_t} dW_t^v + Z_v dN_t^v. \end{aligned} \quad (3)$$

Eraker *et al.* [3] developed a likelihood-based estimation strategy and provided estimates of parameters, spot volatility, jump times, and jump sizes using S&P 500 and Nasdaq 100 index returns. Moreover, they examined the volatility structure of the S&P and Nasdaq indices and indicated that models with jumps in volatility are preferred over those without jumps in volatility. But they did not provide a closed-form formula for the price of a European call option.

In this paper, we would like to consider the problem of finding a closed-form formula for a European call option where the underlying asset and volatility follow the Model (3). This formula will be useful for option pricing rather than an estimation of it as appeared in Eraker's work.

The rest of the paper is organized as follows. In Section 2, we briefly discuss the model descriptions for the option pricing. The relationship between stochastic differential equations and partial differential equations for the jump-diffusion process with jump stochastic volatility is presented in Section 3. Finally, a closed-form formula for a European call option in terms of characteristic functions is presented.

2. Model Descriptions

It is assumed that a risk-neutral probability measure \mathcal{M}

exists, the asset price S_t under this measure follows a jump-diffusion process, and the volatility v_t follows a pure mean reverting and square root diffusion process with jump, *i.e.* our models are governed by the following dynamics:

$$dS_t = S_t \left((r - \lambda^S m) dt + \sqrt{v_t} dW_t^S \right) + S_{t-} Y_t dN_t^S, \quad (4)$$

$$dv_t = \kappa(\theta - v_t) dt + \sigma \sqrt{v_t} dW_t^v + Z_t dN_t^v,$$

where S_t , v_t , κ , θ , σ , W_t^S and W_t^v are defined as in Bate's model, r is the risk-free interest rate, N_t^S and N_t^v are independent Poisson processes with constant intensities λ^S and λ^v respectively. Y_t is the jump size of the asset price return with density $\phi_Y(y)$ and $E[Y_t] := m < \infty$ and Z_t is the jump size of the volatility with density $\phi_Z(z)$. Moreover, we assume that the jump processes N_t^S and N_t^v are independent of standard Brownian motions W_t^S and W_t^v .

3. Partial Integro-Differential Equations

Consider the process $X_t = (X_t^{(1)}, X_t^{(2)})$ where $X_t^{(1)}$ and $X_t^{(2)}$ are processes in \mathfrak{R} and satisfy the following equations:

$$dX_t^{(1)} = f_1(X_t^{(1)}, X_t^{(2)}, t) dt + g_1(X_t^{(1)}, X_t^{(2)}, t) dW_t^{(1)} + X_{t-}^{(1)} Y_t dN_t^{(1)} \quad (5)$$

$$dX_t^{(2)} = f_2(X_t^{(1)}, X_t^{(2)}, t) dt + g_2(X_t^{(1)}, X_t^{(2)}, t) dW_t^{(2)} + Z_t dN_t^{(2)}$$

where f_1, g_1, f_2 and g_2 are all continuously differentiable, $W_t^{(1)}$ and $W_t^{(2)}$ are standard Brownian motions with $Corr[dW_t^{(1)}, dW_t^{(2)}] = \rho$, $N_t^{(1)}$ and $N_t^{(2)}$ are independent Poisson processes with constant intensities $\lambda^{(1)}$ and $\lambda^{(2)}$ respectively.

Since every compound Poisson process can be represented as an integral form of a Poisson random measure [4] then the last term on the right hand side of (5) can be written as follows:

$$\int_0^t X_{s-}^{(1)} Y_s dN_s^{(1)} = \sum_{n=1}^{N_t^{(1)}} X_{s-}^{(1)} Y_n = \int_0^t \int_{\mathfrak{R}} X_{s-}^{(1)} q J_Q(ds dq),$$

$$\int_0^t Z_s dN_s^{(2)} = \sum_{n=1}^{N_t^{(2)}} Z_n = \int_0^t \int_{\mathfrak{R}} r J_R(ds dr),$$

where Y_n are i.i.d. random variables with density $\phi_Y(y)$ and $\mathcal{N}_Q^{(1)}$ is a Poisson random measure of the process $Q_t = \sum Y_n$ with intensity measure $\lambda^{(1)} \phi_Y(dq) dt$, Z_n are i.i.d. random variables with density $\phi_Z(z)$, and J_R is a

Poisson random measure of the process $R_t = \sum_{n=1}^{N_t^{(2)}} Z_n$ with intensity measure $\lambda^{(2)} \phi_Z(dr) dt$.

Let $U(x_1, x_2)$ be a bounded real-valued function and twice continuously differentiable with respect to x_1 and x_2 and

$$u(x_1, x_2, t) = E \left[U \left(X_T^{(1)}, X_T^{(2)} \right) \middle| X_t^{(1)} = x_1, X_t^{(2)} = x_2 \right] \quad (6)$$

By the two dimensional Dynkin formula [5], u is a solution of the partial integro-differential equation (PIDE)

$$0 = \frac{\partial u(x_1, x_2, t)}{\partial t} + \bar{A}u(x_1, x_2, t) + \lambda^{(1)} \int_{\mathfrak{R}} [u(x_1 + y, x_2, t) - u(x_1, x_2, t)] \phi_Y(y) dy + \lambda^{(2)} \int_{\mathfrak{R}} [u(x_1, x_2 + z, t) - u(x_1, x_2, t)] \phi_Z(z) dz$$

subject to the final condition $u(x_1, x_2, T) = U(x_1, x_2)$.

The notation \bar{A} is defined by

$$\bar{A}u(x_1, x_2, t) = f_1 \frac{\partial u(x_1, x_2, t)}{\partial x_1} + f_2 \frac{\partial u(x_1, x_2, t)}{\partial x_2} + \frac{1}{2} g_1^2 \frac{\partial^2 u(x_1, x_2, t)}{\partial x_1^2} + \rho g_1 g_2 \frac{\partial^2 u(x_1, x_2, t)}{\partial x_1 \partial x_2} + \frac{1}{2} g_2^2 \frac{\partial^2 u(x_1, x_2, t)}{\partial x_2^2} \quad (7)$$

4. A Closed-Form Formula for the Price of a European Call Option

Let C denote the price at time t of a European style call option on the current price of the underlying asset S_t with strike price K and expiration time T .

The terminal payoff of a European call option on the underlying stock S_t with strike price K is

$$\max(S_T - K, 0).$$

This means that the holder will exercise his right only if $S_T > K$ and then his gain is $S_T - K$. Otherwise, if $S_T \leq K$, then the holder will buy the underlying asset from the market and the value of the option is zero.

Assuming the risk-free interest rate r is constant over the lifetime of the option, the price of the European call at time t is equal to the discounted conditional expected payoff

$$\begin{aligned}
 & C(S_t, v_t, t; K, T) \\
 &= e^{-r(T-t)} E_{\mathcal{M}} [\max(S_T - K, 0) | S_t, v_t] \\
 &= e^{-r(T-t)} \left(\int_K^\infty S_T P_{\mathcal{M}}(S_T | S_t, v_t) dS_T - K \int_K^\infty P_{\mathcal{M}}(S_T | S_t, v_t) dS_T \right) \\
 &= S_t \left(\frac{1}{e^{r(T-t)} S_t} \int_K^\infty S_T P_{\mathcal{M}}(S_T | S_t, v_t) dS_T \right) \\
 &\quad - K e^{-r(T-t)} \int_K^\infty P_{\mathcal{M}}(S_T | S_t, v_t) dS_T \\
 &= S_t \left(\frac{1}{E_{\mathcal{M}}[S_T | S_t, v_t]} \int_K^\infty S_T P_{\mathcal{M}}(S_T | S_t, v_t) dS_T \right) \\
 &\quad - K e^{-r(T-t)} \int_K^\infty P_{\mathcal{M}}(S_T | S_t, v_t) dS_T \\
 &= S_t P_1(S_t, v_t, t; K, T) - K e^{-r(T-t)} P_2(S_t, v_t, t; K, T)
 \end{aligned}$$

(8) where $E_{\mathcal{M}}$ is the expectation with respect to the risk-neutral probability measure, $P_{\mathcal{M}}(S_T | S_t, v_t)$ is the corresponding conditional density given (S_t, v_t) and

$$P_1(S_t, v_t, t; K, T) = \left(\int_K^\infty S_T P_{\mathcal{M}}(S_T | S_t, v_t) dS_T \right) / E_{\mathcal{M}}[S_T | S_t, v_t]$$

Note that P_1 is the risk-neutral probability that $S_T > K$ (since the integrand is nonnegative and the integral over $[0, \infty)$ is one), and finally that

$$\begin{aligned}
 P_2(S_t, v_t, t; K, T) &= \int_K^\infty P_{\mathcal{M}}(S_T | S_t, v_t) dS_T \\
 &= \text{Pr ob}(S_T > K | S_t, v_t)
 \end{aligned}$$

is the risk-neutral in-the-money probability. Moreover,

$$E_{\mathcal{M}}[S_T | S_t, v_t] = e^{r(T-t)} S_t \text{ for } t \geq 0.$$

Assume that the asset price S_t and the volatility v_t satisfy (4), we would like to compute the price of a European call option with strike price K and maturity T . To do this, we make a change of variable from S_t to $L_t = \ln S_t$, i.e. where S_t satisfies (4) and its inverse $S_t = e^{L_t}$. Denote $k = \ln K$ the logarithm of the strike price. By the jump-diffusion chain rule, $\ln S_t$ satisfies the SDE

$$d \ln S_t = \left(r - \lambda^s m - \frac{v_t}{2} \right) dt + \sqrt{v_t} dW_t^S + \ln(1 + Y_t) dN_t^S \quad (9)$$

Applying the two-dimensional Dynkin formula [5] for the price dynamics (9) and volatility v_t in system (4), we obtain the value of a European-style option, as a

function of the stock log-return L_t denoted by

$$\begin{aligned}
 \tilde{C}(L_t, v_t, t; k, T) &\equiv C(e^{L_t}, v_t, t; e^k, T) \\
 &= C(e^{\ln S_t}, v_t, t; e^{\ln K}, T) \\
 &= C(S_t, v_t, t; K, T),
 \end{aligned}$$

i.e.,

$$\tilde{C}(l, v, t; k, T) = e^{-r(T-t)} E_{\mathcal{M}} [\max(e^{L_t} - K, 0) | L_t = l, v_t = v]$$

and satisfies the following PIDE:

$$\begin{aligned}
 0 &= \frac{\partial \tilde{C}}{\partial t} + \bar{\mathcal{A}}[\tilde{C}](l, v, t; k, T) \\
 &\quad + \lambda^s \int_{\mathfrak{R}} [\tilde{C}(l + y, v, t; k, T) - \tilde{C}(l, v, t; k, T)] \phi_y(y) dy \\
 &\quad + \lambda^v \int_{\mathfrak{R}} [\tilde{C}(l, v + z, t; k, T) - \tilde{C}(l, v, t; k, T)] \phi_z(z) dz
 \end{aligned} \quad (10)$$

Here the operator $\bar{\mathcal{A}}$ as in (7) is defined by

$$\begin{aligned}
 \bar{\mathcal{A}}[\tilde{C}](l, v, t; k, T) &= \left(r - \lambda^s m - \frac{1}{2} v \right) \frac{\partial \tilde{C}}{\partial l} + \kappa(\theta - v) \frac{\partial \tilde{C}}{\partial v} \\
 &\quad + \frac{1}{2} v \frac{\partial^2 \tilde{C}}{\partial l^2} + \rho \sigma v \frac{\partial^2 \tilde{C}}{\partial l \partial v} \\
 &\quad + \frac{1}{2} \sigma^2 v \frac{\partial^2 \tilde{C}}{\partial v^2} - r \tilde{C}
 \end{aligned}$$

In the current state variable, the last line of (8) becomes

$$\tilde{C}(l, v, t; k, T) = e^l \tilde{P}_1(l, v, t; k, T) - e^{k-r(T-t)} \tilde{P}_2(l, v, t; k, T) \quad (11)$$

where $\tilde{P}_j(l, v, t; k, T) := P_j(e^l, v, t; e^k, T)$, $j = 1, 2$.

The following lemma shows the relationship between \tilde{P}_1 and \tilde{P}_2 in the option value of (11).

Lemma 1 *The functions \tilde{P}_1 and \tilde{P}_2 in the option value of (11) satisfy the following PIDEs*

$$\begin{aligned}
 0 &= \frac{\partial \tilde{P}_1}{\partial t} + \mathcal{A}[\tilde{P}_1](l, v, t; k, T) + v \frac{\partial \tilde{P}_1}{\partial l} \\
 &\quad + \rho \sigma v \frac{\partial \tilde{P}_1}{\partial v} + (r - \lambda^s m) \tilde{P}_1 \\
 &\quad + \lambda^s \int_{\mathfrak{R}} [(e^y - 1) \tilde{P}_1(l + y, v, t; k, T)] \phi_y(y) dy
 \end{aligned}$$

and subject to the boundary condition at expiration time $t = T$;

$$\tilde{P}_1(l, v, T; k, T) = 1_{l > k} \quad (12)$$

moreover, \tilde{P}_2 satisfies the equation

$$0 = \frac{\partial \tilde{P}_2}{\partial t} + \mathcal{A}[\tilde{P}_2](l, v, t; k, T) + r \tilde{P}_2,$$

and subject to the boundary condition at expiration time $t = T$;

$$\tilde{P}_2(l, v, T; k, T) = 1_{l > k}, \tag{13}$$

The operator \mathcal{A} is defined by

$$\begin{aligned} & \mathcal{A}[f](l, v, t; k, T) \\ & := \left(r - \lambda^s m - \frac{1}{2} v \right) \frac{\partial f}{\partial l} + \kappa(\theta - v) \frac{\partial f}{\partial v} + \frac{1}{2} v \frac{\partial^2 f}{\partial l^2} \\ & + \rho \sigma v \frac{\partial^2 f}{\partial l \partial v} + \frac{1}{2} \sigma^2 v \frac{\partial^2 f}{\partial v^2} - r f \\ & + \lambda^s \int_{\mathfrak{R}} [f(l + y, v, t; k, T) - f(l, v, t; k, T)] \phi_Y(y) dy \\ & + \lambda^v \int_{\mathfrak{R}} [f(l, v + z, t; k, T) - f(l, v, t; k, T)] \phi_Z(z) dz. \end{aligned} \tag{14}$$

Note that $1_{l > k} = 1$ if $l > k$ and otherwise $1_{l > k} = 0$.

The following lemma shows how to calculate the functions \tilde{P}_1 and \tilde{P}_2 as they appeared in Lemma 1.

Lemma 2 The functions \tilde{P}_1 and \tilde{P}_2 can be calculated by the inverse Fourier transforms of the characteristic function, i.e.

$$\tilde{P}_j(l, v, t; k, T) = \frac{1}{2} + \frac{1}{\pi} \int_0^{+\infty} \text{Re} \left[\frac{e^{-ixk} f_j(l, v, t; k, T)}{ix} \right] dx,$$

for $j = 1, 2$ with $\text{Re}[\cdot]$ denoting the real component of a complex number. By letting $\tau = T - t$.

1) The characteristic function f_1 is given by

$$f_1(l, v, t; x, t + \tau) = \exp(g_1(\tau) + v h_1(\tau) + i x l),$$

where

$$\begin{aligned} h_1(\tau) &= \frac{(\eta_1^2 - \Delta_1^2)(e^{\Delta_1 \tau} - 1)}{\sigma^2(\eta_1 + \Delta_1 - (\eta_1 - \Delta_1)e^{\Delta_1 \tau})} \\ g_1(\tau) &= \left((r - \lambda^s m) i x - \lambda^s m \right) \tau \\ & - \frac{\kappa \theta}{\sigma^2} \left(2 \ln \left(1 - \frac{(\Delta_1 + \eta_1)(1 - e^{-\Delta_1 \tau})}{2 \Delta_1} \right) + (\Delta_1 + \eta_1) \tau \right) \\ & + \lambda^s \tau \int_{-\infty}^{\infty} (e^{(ix+1)y} - 1) \phi_Y(y) dy \\ & + \lambda^v \tau \int_{-\infty}^{\infty} (e^{zh_1(\tau)} - 1) \phi_Z(z) dz \\ \eta_1 &= \rho \sigma (ix + 1) - \kappa \end{aligned}$$

and

$$\Delta_1 = \sqrt{\eta_1^2 - \sigma^2 ix (ix + 1)}.$$

2) The characteristic function f_2 is given by

$$f_2(l, v, t; x, t + \tau) = \exp(g_2(\tau) + v h_2(\tau) + i x l + r \tau),$$

$$\begin{aligned} \text{where } h_2(\tau) &= \frac{(\eta_2^2 - \Delta_2^2)(e^{\Delta_2 \tau} - 1)}{\sigma^2(\eta_2 + \Delta_2 - (\eta_2 - \Delta_2)e^{\Delta_2 \tau})}, \\ g_2(\tau) &= \left((r - \lambda^s m) i x - r \right) \tau \\ & - \frac{\kappa \theta}{\sigma^2} \left(2 \ln \left(1 - \frac{(\Delta_2 + \eta_2)(1 - e^{-\Delta_2 \tau})}{2 \Delta_2} \right) + (\Delta_2 + \eta_2) \tau \right) \\ & + \lambda^s \tau \int_{-\infty}^{\infty} (e^{ixy} - 1) \phi_Y(y) dy + \lambda^v \tau \int_{-\infty}^{\infty} (e^{zh_2(\tau)} - 1) \phi_Z(z) dz \\ \eta_2 &= i \rho \sigma x - \kappa \end{aligned}$$

and

$$\Delta_2 = \sqrt{\eta_2^2 - \sigma^2 ix (ix - 1)}.$$

In summary, we have just proved the following main theorem.

Theorem 3 The value of a European call option of (4) is

$$\tilde{C}(l, v, t; k, T) = e^l \tilde{P}_1(l, v, t; k, T) - e^{k-r(T-t)} \tilde{P}_2(l, v, t; k, T)$$

where \tilde{P}_1 and \tilde{P}_2 are given in Lemma 2.

5. Conclusions

This paper has proposed asset price dynamics to accommodate both jump-diffusion and jump stochastic volatility. Under this proposed model, an analytical solution is derived for a European call option via the characteristic function.

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Appendix

Proof of Lemma 1. We plan to substitute (11) into (10). Firstly, we compute

$$\begin{aligned} \frac{\partial \tilde{C}}{\partial t} &= e^l \frac{\partial \tilde{P}_1}{\partial t} - e^{k-r(T-t)} \frac{\partial \tilde{P}_2}{\partial t} - r e^{k-r(T-t)} \tilde{P}_2 \\ \frac{\partial \tilde{C}}{\partial l} &= e^l \frac{\partial \tilde{P}_1}{\partial l} + e^l \tilde{P}_1 - e^{k-r(T-t)} \frac{\partial \tilde{P}_2}{\partial l} \\ \frac{\partial \tilde{C}}{\partial v} &= e^l \frac{\partial \tilde{P}_1}{\partial v} - e^{k-r(T-t)} \frac{\partial \tilde{P}_2}{\partial v} \\ \frac{\partial^2 \tilde{C}}{\partial l^2} &= e^l \frac{\partial^2 \tilde{P}_1}{\partial l^2} + 2e^l \frac{\partial \tilde{P}_1}{\partial l} + e^l \tilde{P}_1 - e^{k-r(T-t)} \frac{\partial^2 \tilde{P}_2}{\partial l^2} \\ \frac{\partial^2 \tilde{C}}{\partial l \partial v} &= e^l \frac{\partial^2 \tilde{P}_1}{\partial l \partial v} + e^l \frac{\partial \tilde{P}_1}{\partial v} - e^{k-r(T-t)} \frac{\partial^2 \tilde{P}_2}{\partial l \partial v} \\ \frac{\partial^2 \tilde{C}}{\partial v^2} &= e^l \frac{\partial^2 \tilde{P}_1}{\partial v^2} - e^{k-r(T-t)} \frac{\partial^2 \tilde{P}_2}{\partial v^2}, \end{aligned}$$

$$\tilde{C}(l+y, v, t; k, T) - \tilde{C}(l, v, t; k, T)$$

$$= \begin{bmatrix} e^{(l+y)} \tilde{P}_1(l+y, v, t; k, T) \\ -e^{k-r(T-t)} \tilde{P}_1(l+y, v, t; k, T) \end{bmatrix}$$

$$\begin{aligned} 0 &= \frac{\partial \tilde{P}_1}{\partial t} + \left(r - \lambda^s m - \frac{1}{2} v \right) \left(\frac{\partial \tilde{P}_1}{\partial l} + \tilde{P}_1 \right) + \kappa(\theta - v) \frac{\partial \tilde{P}_1}{\partial v} + \frac{1}{2} v \left(\frac{\partial^2 \tilde{P}_1}{\partial l^2} + 2 \frac{\partial \tilde{P}_1}{\partial l} + \tilde{P}_1 \right) \\ &+ \rho \sigma v \left(\frac{\partial^2 \tilde{P}_1}{\partial l \partial v} + \frac{\partial \tilde{P}_1}{\partial v} \right) + \frac{1}{2} \sigma^2 v \frac{\partial^2 \tilde{P}_1}{\partial v^2} - r \tilde{P}_1 + \lambda^s \int_{\mathfrak{Y}} \left[(e^y - 1) \tilde{P}_1(l+y, v, t; k, T) + \tilde{P}_1(l+y, v, t; k, T) - \tilde{P}_1(l, v, t; k, T) \right] \phi_Y(y) dy \\ &+ \lambda^v \int_{\mathfrak{Z}} \left[\tilde{P}_1(l, v+z, t; k, T) - \tilde{P}_1(l, v, t; k, T) \right] \phi_Z(z) dz \end{aligned} \tag{15}$$

subject to the boundary condition at the expiration time $t = T$ according to (12).

By using the notation in (14), PIDE (15) becomes

$$\begin{aligned} 0 &= \frac{\partial \tilde{P}_1}{\partial t} + \mathcal{A}[\tilde{P}_1](l, v, t; k, T) + v \frac{\partial \tilde{P}_1}{\partial l} \\ &+ \rho \sigma v \frac{\partial \tilde{P}_1}{\partial v} + \left(r - \lambda^s m \right) \tilde{P}_1 \\ &+ \lambda^s \int_{\mathfrak{Y}} \left[(e^y - 1) \tilde{P}_1(l+y, v, t; k, T) \right] \phi_Y(y) dy \\ &:= \frac{\partial \tilde{P}_1}{\partial t} + \mathcal{A}_1[\tilde{P}_1](l, v, t; k, T) \end{aligned}$$

For $\tilde{P}_2(l, v, t; k, T)$:

$$0 = \frac{\partial \tilde{P}_2}{\partial t} + r \tilde{P}_2 + \left(r - \lambda^s m - \frac{1}{2} v \right) \frac{\partial \tilde{P}_2}{\partial l} + \kappa(\theta - v) \frac{\partial \tilde{P}_2}{\partial v}$$

$$\begin{aligned} &- \left[e^l \tilde{P}_1(l, v, t; k, T) - e^{k-r(T-t)} \tilde{P}_2(l, v, t; k, T) \right] \\ &= \begin{bmatrix} e^l \left(e^y \tilde{P}_1(l+y, v, t; k, T) - \tilde{P}_1(l+y, v, t; k, T) \right) \\ + \left(e^l \tilde{P}_1(l+y, v, t; k, T) - e^l \tilde{P}_1(l, v, t; k, T) \right) \\ - e^{k-r(T-t)} \left[\tilde{P}_1(l+y, v, t; k, T) - \tilde{P}_1(l, v, t; k, T) \right] \end{bmatrix} \\ &= e^l \left(e^y - 1 \right) \tilde{P}_1(l+y, v, t; k, T) \\ &+ e^l \tilde{P}_1 \left((l+y, v, t; k, T) - \tilde{P}_1(l, v, t; k, T) \right) \\ &- e^{k-r(T-t)} \left[\tilde{P}_2(l+y, v, t; k, T) - \tilde{P}_2(l, v, t; k, T) \right] \end{aligned}$$

and

$$\begin{aligned} &\tilde{C}(l, v+z, t; k, T) - \tilde{C}(l, v, t; k, T) \\ &= \begin{bmatrix} e^l \tilde{P}_1(l, v+z, t; k, T) - e^{k-r(T-t)} \tilde{P}_2(l, v+z, t; k, T) \\ - \left[e^l \tilde{P}_1(l, v, t; k, T) - e^{k-r(T-t)} \tilde{P}_2(l, v, t; k, T) \right] \end{bmatrix} \\ &= e^l \left[\tilde{P}_1(l, v+z, t; k, T) - \tilde{P}_1(l, v, t; k, T) \right] \\ &- e^{k-r(T-t)} \left[\tilde{P}_2(l, v+z, t; k, T) - \tilde{P}_2(l, v, t; k, T) \right] \end{aligned}$$

We substitute all terms above into (10) and separate it by assumed independent terms of \tilde{P}_1 and \tilde{P}_2 . This gives two PIDEs for the risk-neutralized probability for $\tilde{P}_j(l, v, t; k, T)$, $j = 1, 2$: (Equation (15))

$$\begin{aligned} &+ \frac{1}{2} v \frac{\partial^2 \tilde{P}_2}{\partial l^2} + \rho \sigma v \frac{\partial^2 \tilde{P}_2}{\partial l \partial v} + \frac{1}{2} \sigma^2 v \frac{\partial^2 \tilde{P}_2}{\partial v^2} - r \tilde{P}_2 \\ &+ \lambda^s \int_{\mathfrak{Y}} \left[\tilde{P}_2(l+y, v, t; k, T) - \tilde{P}_2(l, v, t; k, T) \right] \phi_Y(y) dy \\ &+ \lambda^v \int_{\mathfrak{Z}} \left[\tilde{P}_2(l, v+z, t; k, T) - \tilde{P}_2(l, v, t; k, T) \right] \phi_Z(z) dz \end{aligned} \tag{16}$$

subject to the boundary condition at the expiration time $t = T$ according to (13). Again, by using the notation in (14), PIDE (16) becomes

$$\begin{aligned} 0 &= \frac{\partial \tilde{P}_2}{\partial t} + \mathcal{A}[\tilde{P}_2](l, v, t; k, T) + r \tilde{P}_2 \\ &:= \frac{\partial \tilde{P}_2}{\partial t} + \mathcal{A}_2[\tilde{P}_2](l, v, t; k, T). \end{aligned}$$

The proof of Lemma 1 is now completed.

For $j=1,2$ the characteristic functions for

$$\tilde{P}_j(l, v, t; k, T),$$

with respect to the variable k are defined by

$$f_j(l, v, t; x, T) := - \int_{-\infty}^{\infty} e^{ixk} d\tilde{P}_j(l, v, t; k, T),$$

with a minus sign to account for the negativity of the measure $d\tilde{P}_j$.

Note that f_j also satisfies similar PIDEs

$$\frac{\partial f_j}{\partial t} + \mathcal{A}_j[f_j](l, v, t; x, T) = 0, \tag{17}$$

with the respective boundary conditions

$$\begin{aligned} f_j(l, v, t; x, T) &= - \int_{-\infty}^{\infty} e^{ixk} d\tilde{P}_j(l, v, t; k, T) \\ &= - \int_{-\infty}^{\infty} e^{ixk} (-\delta(k-l) dk) \\ &= e^{ixl} \end{aligned}$$

since $d\tilde{P}_j(l, v, T; k, T) = d\mathbb{1}_{l>k} = dH(l-k) = -\delta(k-l) dk$.

Proof of Lemma 2

1) To solve for the characteristic function explicitly, letting $\tau = T - t$ be the time-to-go, we conjecture that the function f_1 is given by

$$f_1(l, v, t; x, t + \tau) = \exp(g_1(\tau) + v h_1(\tau) + i x l) \tag{18}$$

and the boundary condition

$$g_1(0) = 0 = h_1(0).$$

This conjecture exploits the linearity of the coefficient in PIDE (17).

Note that the characteristic function f_1 always exists.

In order to substitute (18) into (17), firstly we compute

$$\begin{aligned} \frac{\partial f_1}{\partial t} &= (-g_1'(\tau) - v h_1'(\tau)) f_1 & \frac{\partial f_1}{\partial l} &= i x f_1 \\ \frac{\partial f_1}{\partial v} &= h_1(\tau) f_1 & \frac{\partial^2 f_1}{\partial l^2} &= -x^2 f_1 \\ \frac{\partial^2 f_1}{\partial l \partial v} &= i x h_1(\tau) f_1 & \frac{\partial^2 f_1}{\partial v^2} &= h_1^2(\tau) f_1 \\ f_1(l + y, v, t; x, t + \tau) - f_1(l, v, t; x, t + \tau) & & & \\ &= (e^{ixy} - 1) f_1(l, v, t; x, t + \tau) \\ f_1(l, v + z, t; x, t + \tau) - f_1(l, v, t; x, t + \tau) & & & \\ &= (e^{zh_1(\tau)} - 1) f_1(l, v, t; x, t + \tau) \end{aligned}$$

and

$$\begin{aligned} (e^y - 1) f_1(l + y, v, t; x, t + \tau) &= (e^y - 1) e^{g_1(\tau) + v h_1(\tau) + i x (l + y)} \\ &= (e^y - 1) e^{ixy} f_1(l, v, t; x, t + \tau) \end{aligned}$$

Substituting all the above terms into (17) and after canceling the common factor of f_1 , we get a simplified form as follows:

$$\begin{aligned} 0 &= -g_1'(\tau) - v h_1'(\tau) + \left(r - \lambda^s m + \frac{1}{2} v \right) i x \\ &+ (\kappa(\theta - v) + \rho \sigma v) h_1(\tau) - \frac{1}{2} v x^2 \\ &+ \rho \sigma v i x h_1(\tau) + \frac{1}{2} \sigma^2 v h_1^2(\tau) - \lambda^s m \\ &+ \lambda^s \int_{\mathbb{R}} (e^{(ix+1)y} - 1) \phi_Y(y) dy \\ &+ \lambda^v \int_{\mathbb{R}} (e^{zh_1(\tau)} - 1) \phi_Z(z) dz. \end{aligned}$$

By separating the order v and ordering the remaining terms, we can reduce it to two ordinary differential equation (ODEs),

$$h_1'(\tau) = \frac{1}{2} \sigma^2 h_1^2(\tau) + (\rho \sigma (1 + ix) - \kappa) h_1(\tau) + \frac{1}{2} ix - \frac{1}{2} x^2 \tag{19}$$

and

$$\begin{aligned} g_1'(\tau) &= \kappa \theta h_1(\tau) + (r - \lambda^s m) i x - \lambda^s m \\ &+ \lambda^s \int_{-\infty}^{\infty} (e^{(ix+1)y} - 1) \phi_Y(y) dy \\ &+ \lambda^v \int_{-\infty}^{\infty} (e^{zh_1(\tau)} - 1) \phi_Z(z) dz. \end{aligned} \tag{20}$$

Let $\eta_1 = \rho \sigma (ix + 1) - \kappa$ and substitute it into (19). We get

$$\begin{aligned} h_1'(\tau) &= \frac{1}{2} \sigma^2 \left(h_1^2 + \frac{2\eta_1}{\sigma^2} h_1 + \frac{1}{\sigma^2} ix(ix+1) \right) \\ &= \frac{1}{2} \sigma^2 \left(h_1 + \frac{2\eta_1 + \sqrt{4\eta_1^2 - 4\sigma^2 ix(ix+1)}}{2\sigma^2} \right) \\ &\quad \times \left(h_1 + \frac{2\eta_1 - \sqrt{4\eta_1^2 - 4\sigma^2 ix(ix+1)}}{2\sigma^2} \right) \\ &= \frac{1}{2} \sigma^2 \left(h_1 + \frac{\eta_1 + \Delta_1}{\sigma^2} \right) \left(h_1 + \frac{\eta_1 - \Delta_1}{\sigma^2} \right) \end{aligned}$$

where $\Delta_1 = \sqrt{\eta_1^2 - \sigma^2 ix(ix+1)}$.

By the method of variable separation, we have

$$\frac{2dh_1}{\left(h_1 + \frac{\eta_1 + \Delta_1}{\sigma^2} \right) \left(h_1 + \frac{\eta_1 - \Delta_1}{\sigma^2} \right)} = \sigma^2 d\tau.$$

Using partial fractions, we get

$$\frac{1}{\Delta_1} \left(\frac{1}{h_1 + \frac{\eta_1 - \Delta_1}{\sigma^2}} - \frac{1}{h_1 + \frac{\eta_1 + \Delta_1}{\sigma^2}} \right) dh_1 = d\tau.$$

Integrating both sides, we obtain

$$\ln \left(\frac{h_1 + \frac{\eta_1 - \Delta_1}{\sigma^2}}{h_1 + \frac{\eta_1 + \Delta_1}{\sigma^2}} \right) = \Delta_1 \tau + C.$$

Using boundary condition $h_1(\tau = 0) = 0$, we get

$$C = \ln \left(\frac{\eta_1 - \Delta_1}{\eta_1 + \Delta_1} \right).$$

Solving for h_1 , we obtain

$$h_1(\tau) = \frac{(\eta_1^2 - \Delta_1^2)(e^{\Delta_1 \tau} - 1)}{\sigma^2(\eta_1 + \Delta_1 - (\eta_1 - \Delta_1)e^{\Delta_1 \tau})}.$$

In order to solve $g_1(\tau)$ explicitly, we substitute $h_1(\tau)$ into (20) and integrate with respect to τ on both sides. Then we get

$$\begin{aligned} g_1(\tau) &= ((r - \lambda^s m)ix - \lambda^s m)\tau \\ &\quad - \frac{\kappa\theta}{\sigma^2} \left(2 \ln \left(1 - \frac{(\Delta_1 + \eta_1)(1 - e^{-\Delta_1 \tau})}{2\Delta_1} \right) + (\Delta_1 + \eta_1)\tau \right) \\ &\quad + \lambda^s \tau \int_{-\infty}^{\infty} (e^{(ix+1)y} - 1)\phi_y(y) dy \\ &\quad + \lambda^v \tau \int_{-\infty}^{\infty} (e^{zh_1(\tau)} - 1)\phi_z(z) dz \end{aligned}$$

Proof of 2). The details of the proof are similar to case 1). Hence, we have

$$f_2(l, v, t; x, t + \tau) = \exp(g_2(\tau) + v h_2(\tau) + ixl + r\tau)$$

where $g_2(\tau)$, $h_2(\tau)$, η_2 and Δ_2 are as given in the Lemma.

We can thus evaluate the characteristic functions in explicit form. However, we are interested in the risk-neutral probabilities \tilde{P}_j , $j = 1, 2$. These can be inverted from the characteristic functions by performing the following integration

$$\tilde{P}_j(l, v, t; k, T) = \frac{1}{2} + \frac{1}{\pi} \int_{0^+}^{+\infty} \text{Re} \left[\frac{e^{-ixk} f_j(l, v, t; k, T)}{ix} \right] dx \quad (21)$$

for $j = 1, 2$.

To verify (21), firstly we note that

$$\begin{aligned} &E_{\mathcal{M}} \left[e^{ix(\ln S_t - \ln K)} \mid \ln S_t = L_t, v_t = v \right] \\ &= E_{\mathcal{M}} \left[e^{ix(L_t - k)} \mid L_t = l, v_t = v \right] = \int_{-\infty}^{\infty} e^{ix(l-k)} d\tilde{P}_j(l, v, t; k, T) \\ &= e^{-ixk} \int_{-\infty}^{\infty} e^{ixl} d\tilde{P}_j(l, v, t; k, T) = e^{-ixk} \int_{-\infty}^{\infty} e^{ixk} (-\delta(l-k) dk) \\ &= e^{-ixk} f_j(l, v, t; k, T). \end{aligned}$$

Then

$$\begin{aligned} &\frac{1}{2} + \frac{1}{\pi} \int_{0^+}^{+\infty} \text{Re} \left[\frac{e^{-ixk} f_j(l, v, t; k, T)}{ix} \right] dx \\ &= \frac{1}{2} + \frac{1}{\pi} \int_{0^+}^{+\infty} \text{Re} \left[\frac{E_{\mathcal{M}} \left[e^{ix(\ln S_t - \ln K)} \mid \ln S_t = L_t, v_t = v \right]}{ix} \right] dx \\ &= E_{\mathcal{M}} \left[\frac{1}{2} + \frac{1}{\pi} \int_{0^+}^{+\infty} \text{Re} \left[\frac{e^{ix(l-k)}}{ix} \right] dx \mid L_t = l, v_t = v \right] \\ &= E_{\mathcal{M}} \left[\frac{1}{2} + \frac{1}{\pi} \int_{0^+}^{+\infty} \frac{\sin(x(l-k))}{x} dx \mid L_t = l, v_t = v \right] \\ &= E_{\mathcal{M}} \left[\frac{1}{2} + \text{sgn}(l-k) \frac{1}{\pi} \int_{0^+}^{+\infty} \frac{\sin x}{x} dx \mid L_t = l, v_t = v \right] \\ &= E_{\mathcal{M}} \left[\frac{1}{2} + \frac{1}{2} \text{sgn}(l-k) \mid L_t = l, v_t = v \right] \\ &= E_{\mathcal{M}} [1_{l \geq k} \mid L_t = l, v_t = v] \end{aligned}$$

where we have used the Dirichlet formula $\int_{0^+}^{+\infty} \frac{\sin x}{x} dx = 1$

and the sgn function is defined as $\text{sgn}(x) = 1$ if $x > 0$, 0 if $x = 0$ and -1 if $x < 0$.