

A Physiologically-Based Adaptive Three-Gaussian Function Model for Image Enhancement

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Abstract

Image enhancement is an important pre-processing step for various image processing applications. In this paper, we proposed a physiologically-based adaptive three-Gaussian model for image enhancement. Comparing to the standard three-Gaussian model inspired by the spatial structure of the receptive field (RF) of the retinal ganglion cells, the proposed model can dynamically adjust its parameters according to the local image luminance and contrast based on the physiological findings. Experimental results on several images show that the proposed adaptive three-Gaussian model achieves better performance than the classical method of histogram equalization and the standard three-Gaussian model.

Keywords

Image Enhancement, Receptive Field, Visual System, Three-Gaussian Model

1. Introduction

Images play an important role in transferring information. In order to obtain more information from collected images, image enhancement techniques are commonly required to improve image quality. Traditional image enhancement methods can be roughly divided into two categories: 1) spatial domain methods, such as gray-level transformation, piecewise-linear transformation, and histogram equalization, etc. 2) frequency domain methods,

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which include high-pass filtering, high-frequency emphasizing filtering, and homomorphic filtering etc. However, these methods mentioned above are in general difficult to balance well among various requirements of image quality, such as contour enhancement, dynamic range, denoising and so on. In addition, the ability of traditional image enhancement methods is far behind the human visual system in almost all aspects.

Early physiological studies have revealed that the retinal ganglion cells have a receptive field (RF) consisting of concentric regions, *i.e.*, an approximately circular center and an annular surround [1] [2]. DOG model was proposed by Rodieck to describe the classical receptive field (CRF) of the ganglion cells [1]. Li *et al.* found that the cells at some distance from the contrast borders were less affected, while the border enhancement might become quite stronger when the centre was close to the corner of a bright contour [2]. Ramachandran found that the luminance gradients of an area are essential for producing perception of three-dimensional visual scenes [3]. By analyzing the length-response functions of lateral geniculate neurons in the cat, Li *et al.* have demonstrated an extensive disinhibitory region (DIR, *i.e.*, non-CRF) outside the classical inhibitory surround of the receptive field [4]. According to this finding, a three-Gaussian function model was proposed in [5]. By setting appreciate parameters of the three-Gaussian model, good fit could be obtained almost for all data that show disinhibitory phenomenon [5]. Functionally, the three-Gaussian model can not only enhance the edge information but also transmit brightness information with low spatial frequency [5] [6].

However, the three-Gaussian model cannot dynamically adjust its parameters according to the local stimulus. In fact, the adaptation to the stimulus features (e.g., the luminance contrast) of the receptive field in the visual system has been deeply studied [7]-[12]. Some experiments [7] showed that the responses of retinal ganglion cells first increased abruptly, and then decayed exponentially to a lower value following the abrupt increase in stimulus contrast. Based on extracellular recordings from 69 LGN cells in the anesthetized cat, Nolt *et al.* found that the spatial summation within their receptive fields was dependent on the contrast of the stimuli presented. They reported that the contrast-dependency in the retinal ganglion cells directly resulted from a reduction in the size of the center mechanism due to an increase in contrast [8]. By characterizing the adaptation of neurons in the cat lateral geniculate nucleus (LGN) to changes in stimulus contrast and correlations, Lesica *et al.* found that the space constant of the excitatory center increased with a decreasing in stimulus contrast [9]. In addition, it has been shown that spatial summation in the primary visual cortex of the cat and monkey is strongly dependent on stimulus contrast; the area (length and width) over which responses summate generally increases as the stimulus contrast decreases; fitting summation curves with a DOG model shows that this contrast-dependent spatial summation seems to derive from a change in the actual size of the receptive field [10]-[12].

To simulate the dynamic properties of the RF, in this work we present an adaptive three-Gaussian function model to automatically adjust its parameters according to the properties of local stimulus, *i.e.*, local contrast and luminance, for image enhancement.

2. Computational Model

2.1. Three-Gaussian Function Model

Figure 1 shows the model of three-Gaussian model, in which the center and surround denote respectively the excitatory region (Center) and inhibitory region (Surround) of CRF. The disinhibitory region usually covers a larger range of visual field. The response amplitude of cells with stimulus radius is shown in the top-right corner of **Figure 1**. The three-Gaussian function model is described as [5]

$$f(x, y) = A_1 e^{\frac{-(x^2 + y^2)}{\sigma_1^2}} - A_2 e^{\frac{-(x^2 + y^2)}{\sigma_2^2}} + A_3 e^{\frac{-(x^2 + y^2)}{\sigma_3^2}}$$
(1)

where A_1 and σ_1 are the strength and space constant of the excitatory center, A_2 and σ_2 are the strength and space constant of the inhibitory surround, and A_3 and σ_3 are the strength and space constant of the disinhibitory outer-surround region.

This three-Gaussian model assumes that the sensitivity profiles of the three regions (*i.e.*, center, surround and outer-surround) are distributed as Gaussians, which are circularly concentric with their peaks overlapped at the center point of the RF center region. This model also assumes that the three parts summate linearly from all parts of the receptive field. Functionally, the combination of the first two Gaussians (*i.e.*, the DOG model) serves to detect and enhance the edges, and the third Gaussian serves for the brightness information transmission by compensating the loss of the low frequency components resulted from the almost balanced center and sur-

round mechanisms in the DOG model of most cells [5].

2.2. Adaptive Mechanism

Based on the experimental findings about the stimulus-dependant RF properties, we specifically introduce two dynamic RF features: 1) the excitatory strength of the center (A_1) increases nonlinearly with the increasing of the local contrast; 2) the inhibitory space constant (σ_2) of the RF surround is decreased with the increasing of the local luminance.

In this paper, we define the feature of local luminance contrast as the standard deviation within a small image patch around each pixel in the image. We denote local luminance contrast as Con. In addition, we use a modified sigmoid function to simulate the nonlinear transformation of neural information. The relationship between A_1 and Con is experimentally defined as

$$A_{1} = 6 + \frac{1}{1 + e^{-10 \times (Con - 0.5)}}$$
(2)

Figure 2 shows the relationship of center excitation (A_1) along with the local contrast (*Con*).

On the other hand, in order to improve the contrast of shading regions of the image, another parameter (σ_2) is adjusted with local luminance. In our adaptive three-Gaussian function model, we can reduce inhibitory space constant (σ_2) to weaken the surround inhibition when the luminance value of the pixel to be processed is high.



Local Contrast



We use L to denote local luminance value of each pixel in the image. Similar to Equation (2), we also employ a modified sigmoid function to represent the relationship between the inhibitory space constant (σ_2) and the local luminance feature. The relationship between σ_2 and L is experimentally defined as

$$\sigma_2 = 1.25 + \frac{0.1}{1 + e^{10 \times (L - 0.45)}} \tag{3}$$

Figure 3 shows the relationship between σ_2 and L. Note that a simple smoothing filtering is applied on the map of *Con* and L to removing noises.

As described in Equations (2) and (3), the kernel idea of our adaptive three-Gaussian model is that two important parameters (*i.e.*, A_1 and σ_2 in Equation (1)) are adaptively adjusted based on the features of local contrast and local luminance, respectively.

It should be pointed out that the curves in Figure 2 and Figure 3 are sigmoid shaped, because sufficient experimental evidence indicates that the change of receptive field properties (e.g., the sensitivity and spatial size) with the stimulus features (e.g., the luminance contrast) seems nonlinear [7]-[12]. Note that the constants in Equations (2) and (3) determining the shapes of the sigmoid curves (e.g., the slope) were experimentally obtained and we have found that these settings are suitable for most of the real-world images, as indicated by several examples shown in the next section.

3. Results

In this experiment, we compared our adaptive three-Gaussian method with the popular method of histogram equalization and the standard (non-adaptive) three-Gaussian model. Experimental results on several images are shown in **Figure 4**, **Figure 5**, **Figure 6**, and **Figure 7**. Note that the zoomed in view of each test image is also listed in **Figures 4-7**, respectively. From the figures, the results of the standard three-Gaussian model usually include more details than original images, but some regions are over-enhanced (especially in the high contrast place); in addition, the contrast of high-light and shading regions are not enhanced enough. Histogram equalization is efficient in adjusting global dynamic range of images, but it is difficult to obtain good local contrast. In addition, three-Gaussian model usually obtains better performance than histogram equalization.

Our adaptive three-Gaussian function model performs better in both enhancing the local contrast and adjusting global dynamic range. Meanwhile, the proposed method is capable of overcoming the phenomenon of overenhancement. In addition, the performance of our new approach in edge enhancement is much better than the other two methods mentioned above, which can be clearly seen from **Figures 4-7**, especially from the zoomed in view of each test image.

For quantitative comparison, we employed EME (a measure of enhancement) [13] and SNR (Signal to Noise Ratio) [14] for performance evaluation of image enhancement. SNR is usually defined as the mean target signal to the standard deviation of the noise [13]. In this paper, we define E as the mean value of the all pixels in the



constant (σ_2) along with local lumiance (*L*).



Figure 4. Results on the Lenna image. (a) Original image; (b) Results of histogram equalization; (c) Results of three-Gaussian function model; (d) Results of the proposed method (adaptive three-Gaussian function model). The zoomed in view of the patch in the red rectangle is also shown for each image.





Figure 5. Results on the Goldhill image. (a) Original image; (b) Results of histogram equalization; (c) Results of three-Gaussian function model; (d) Results of the proposed method (adaptive three-Gaussian function model).



Figure 6. Results on the Sailboat image. (a) Original image; (b) Results of histogram equalization; (c) Results of three-Gaussian function model; (d) Results of the proposed method (adaptive three-Gaussian function model).



Results of histogram equalization; (c) Results of three-Gaussian function model; (d) Results of the proposed method (adaptive three-Gaussian function model).

image and σ as the standard deviation of the all pixels in the image. Therefore, SNR is computed as

$$SNR = 10\log_{10}\frac{E}{\sigma^2}$$
(4)

EME is computed as [14]

$$EME = \frac{1}{k_1 k_2} \sum_{l=1}^{k_2} \sum_{k=1}^{k_1} 20 \ln \frac{V_{\max,k,l} - V_{\min,k,l}}{V_{\max,k,l} + V_{\min,k,l} + c}$$
(5)

where $V_{\min,k,l}$ and $V_{\max,k,l}$ are respectively the minimum and maximum inside a certain block w(k,l) when the whole image is split into k_1k_2 blocks w(k,l) of equal sizes. *c* is a small constant that equals to 0.0001 to avoid dividing by zero. In general, a higher EME indicates a better enhancement in image details.

EME and SNR of four considered images shown in **Figures 4-7** are listed in **Table 1** and **Table 2**. Note that the EME and SNR were calculated from the whole images. From **Table 1**, the evaluation of EME shows that our adaptive three-Gaussian function model obtains the best performance on edge enhancement. From **Table 2**, we can see that our new approach achieves competitive performance compared with the standard three-Gaussian function model and histogram equalization in suppressing image noise. This indicates that our adaptive model can well balance the requirements of enhancing edges and inhibiting image noises.

4. Discussion

It is generally accepted that the computational image processing methods are far behind the human visual system. They met difficulties to balance well among various requirements of image quality, e.g., contour enhancement and denoising which often cannot be well achieved at the same time. By seeking inspiration from the physiological findings, this paper proposes a physiologically based adaptive three-Gaussian model, which dynamically adjusts the parameters of the three-Gaussian model. The results on several real-world images show that the performance of our new model is better than the standard three-Gaussian function model, especially in overcoming over-enhancement and raising the contrast of highlight and shading regions. Our approach can keep the SNR of an image in an acceptable level; meanwhile, it can effectively enhance the edge profiles and local details of the image. Specifically, in the regions of low luminance, we increase the excitatory strength (A_1) in the regions with high local contrast, which helps enhance the edges with high contrast. Differently, we increase the inhibitory space constant (σ_2) in the regions of low brightness, which helps improve the contrast of shading regions.

Our physiologically-based adaptive three-Gaussian function model only simulates the change of inhibitory space constant (σ_2) and excitatory strength (A_1) based on the local contrast and local brightness, and don't involve inhibitory strength (A_2) and excitatory space constant, (σ_1) which should be improved in the future work. In addition, how to effectively suppress image noise is also an important future direction for us.

Table 1. EME for the testing images.							
Index Test image	EME						
	Original image	Histogram equalization	Three-Gaussian	Adaptive three-Gaussian			
Lenna	22.9578	55.8410	74.2137	91.6041			
Goldhill	16.2290	40.3469	67.6001	130.0269			
Sailboat	23.2728	40.4264	81.2151	135.1900			
Zelda	17.1172	55.7354	67.2700	94.1577			

Table 2. SNR for the testing images.

Index Test image	SNR			
	Original image	Histogram equalization	Three-Gaussian	Adaptive three-Gaussian
Lenna	64.6106	62.6490	61.8363	61.9148
Goldhill	64.9061	62.4141	61.8287	61.5272
Sailboat	62.8929	60.6578	61.8346	60.4178
Zelda	65.6947	61.8349	63.3216	62.8684

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