

True Random Bit Generator Using ZCDPLL Based on TMS320C6416

Qassim NASIR

Department of Electrical and Computer Engineering College of Engineering, University of Sharjah, Sharjah, UAE
Email: nasir@sharjah.ac.ae

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ABSTRACT

A True Random Binary Generator (TRBG) based on a zero crossing digital phase-locked loop (ZCDPLL) is proposed. In order to face the challenges of using the proposed TRBG in cryptography, the proposed TRBG is subjected to the AIS 31 test suite. The ZCDPLL operate as chaotic generator for certain loop filter gains and this has been used to generate TRBs. The generated binary sequences have a good autocorrelation and cross-correlation properties as seen from the simulation results. A prototype of TRBG using ZCDPLL has been developed through Texas Instruments TMS320C6416 DSP development kit. The proposed TRBG successfully passed the AIS 31 test suit.

Keywords: True Random Binary Sequence, Zero Crossing Digital Phase Locked Loop, Spreading Sequences, Cryptography, TMS320C64x

1. Introduction

Random and pseudo-random numbers are used in many areas including test data generation, Monte-Carlo simulation techniques, generation of spreading sequences for spread spectrum communications, and cryptography [1]. Pseudo-random spreading sequences used in spread spectrum communications must be repeatable, while for most simulations using random numbers this is not necessary. In cryptographic applications, security depends on the randomness of the source and the unpredictability of the used random bits [1].

Chaotic circuits represent an efficient alternative to classical TRBG [2]. Studies in nonlinear dynamics show that many of the seemingly complex systems in nature are described by relatively mathematical equations [3]. Although chaotic systems appear to be highly irregular, they are also deterministic in the sense that it is possible to reproduce them with certainty. These promising features of chaotic systems attracted many researchers to try chaos as a possible medium for secure communication.

The nonlinear phenomenon of chaos poses a promising alternative for pseudo-random number generation due to its unpredictable behaviour.

The chaotic system generates “unpredictable” pseudo random orbits which can be used to generate RNGs (Random Number Generators). Many different chaotic systems have been used to generate RNGs such as Logistic map [4], and its generalized version [5], Chebyshev map, [1] piecewise linear chaotic maps [6] and piecewise nonlinear chaotic maps [7]. Chaotic systems are characterized by a “sensitivity dependence on initial conditions”, and with such initial uncertainties, the system behaviour leads to large uncertainty after some time.

The aim of this paper is to show how to use a second order zero crossing digital phase locked loop (ZCDPLL) operating in a chaotic mode as True Random Binary Generator (TRBG). Digital Phase locked Loops (DPLLs) were introduced to minimize some of the problems associated with the analogue loops such as sensitivity to DC drift and the need for periodic adjustments [8,9]. The most commonly used DPLL is the Zero Crossing Digital Phase Locked Loop (ZCDPLL). The ZCDPLL operation is based on non uniform sampling techniques. The loop is simple to implement and easy to model. The ZCDPLL consists of a sampler that acts as phase detector, a digital filter, and a Digital Controlled Oscillator (DCO) [8].

The global dynamics of the second order ZCDPLL shows chaos operation for certain values of filter gains [10]. The non-linear behaviour of ZCDPLL shows period doubling or bifurcation instabilities to its route to chaos. The chaotic behaviour has been confirmed through the use of phase error spectrum, bifurcation diagram, and Lyapunov exponent [3,10]. The proposed TRBG pass the statistical tests described by AIS 31 documents [11] However, one should notice that the statistical tests prove that the generator is an ideal random bit generator (the tests are in fact necessary but not sufficient) [12]. The proposed TRBG is implemented on a Texas Instruments TMS320C6416 DSP development platform [13].

The remainder of the paper is organized as follows. In Section 2, the ZCDPLL model is presented. Random bit sequence generation using ZCDPLL is presented in Section 3. Simulation results are discussed in Section 4. Section 5 draws the conclusion.

2. Second Order ZCDPLL

The structure of second order ZCDPLL is shown in Figure 1. As soon as the filter finishes its operation, the stored data are transferred to the register II. The input signal to the loop is taken as $x(t) = s(t) + n(t)$, where $s(t) = A\sin(\omega_0 t + \theta(t))$, and $n(t)$ is additive white Gaussian Noise (AWGN); $\theta(t) = \theta_0 + \Omega_0 t$ by which the signal dynamics are modelled; θ_0 is the initial phase which we will assume to be zero; Ω_0 is the frequency offset from the nominal value ω_0 . The input signal is sampled at time instances t_k determined by the Digital Controlled Oscillator (DCO). The DCO period control algorithm is given by [14] is

$$T_k = T_0 - c_{k-1} = t_k - t_{k-1} \tag{1}$$

where $T_0=(2\pi/\omega_0)$ is the nominal period, c_{k-1} is the loop

digital filter. The sample value of the incoming signal $x(t)$ at t_k is

$$x(t_k) = s(t_k) + n(t_k) \tag{2}$$

Or simply

$$x_k = s_k + n_k \tag{3}$$

where $s_k = A\sin(\omega_0 t_k + \theta(t_k))$. The sequence x_k is passed through a digital filter whose transfer function is $D(z)$ whose output c_k is used to control the period of the DCO. For noise free analysis, then

$$x_k = A\sin[\omega_0 (kT_0 - \sum_{i=0}^{k-1} c_i + \theta_k)] \tag{4}$$

The phase error is defined to be

$$\phi_k = \theta_k - \omega_0 \sum_{i=0}^{k-1} c_i \tag{5}$$

Then

$$\phi_k - \phi_{k-1} = \theta_k - \theta_{k-1} - \omega_0 c_{k-1} \tag{6}$$

Using z-operator, equation (6) can be written as

$$(1 - z^{-1})\phi_k = (1 - z^{-1})\theta_k - \omega_0 z^{-1} c_k \tag{7}$$

The control signal c_k is the output of the digital filter and is formed by

$$c_k = D(z)x_k = D(z)\sin(\phi_k) \tag{8}$$

Substituting (8) into (7) yields

$$\phi_k = \theta_k - \frac{\omega_0 z^{-1} D(z)}{1 - z^{-1}} \sin(\phi_k) \tag{9}$$

In the second order ZCDPLL, the digital filter

$D(z) = G_1 + \frac{G_2}{1 - z^{-1}}$, then (6) becomes

$$\phi_k = 2\phi_{k-1} - \phi_{k-2} + K_1 \sin(\phi_{k-2}) - rK_1 \sin(\phi_{k-1}) = f(\phi_k) \tag{10}$$

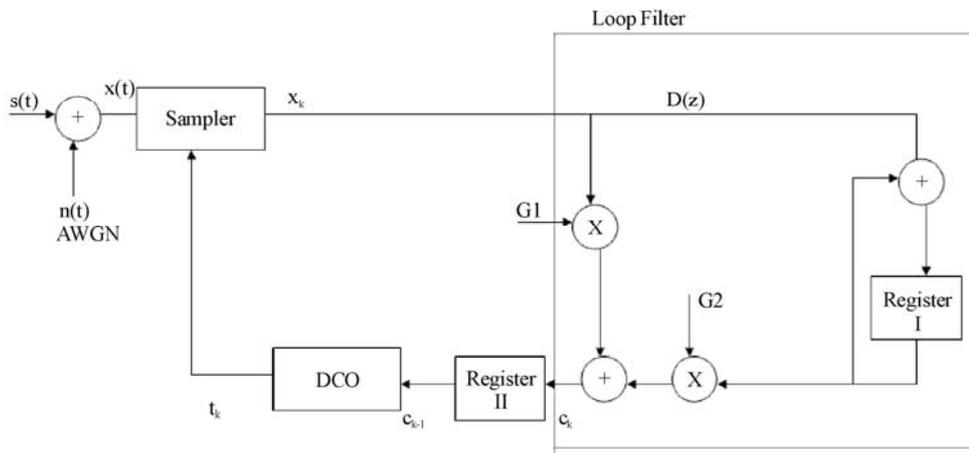


Figure 1. Block diagram of the second order ZCDPLL.

where $K_1 = AG_1\omega_0$ and $r = 1 + \frac{G_2}{G_1}$. Let $x_k = \phi_k$, $y_k = \phi_{k-1}$,

$\mathbf{X} = (x, y)^T$ then (1) can be rewritten as

$$\begin{aligned} \begin{pmatrix} x_{k+1} \\ y_{k+1} \end{pmatrix} &= \begin{pmatrix} 2x_k - y_k + K_1 \sin(y_k) - rK_1 \sin(x_k) \\ x_k \end{pmatrix} \\ \vdots &= \begin{pmatrix} g(\mathbf{X}_k) \\ g(\mathbf{X}_k) \end{pmatrix} = G(x_k) \end{aligned} \tag{11}$$

If the above system equation is linearized around the equilibrium points $\mathbf{X}^*_k=0$, so that $\sin(x^*_k) \approx x^*_k$ and $\sin(y^*_k) \approx y^*_k$. Then (11) becomes

$$\begin{aligned} \begin{pmatrix} x_{k+1} \\ y_{k+1} \end{pmatrix} &= \begin{pmatrix} (2-rK_1)x_k + (K_1-1)y_k \\ x_k \end{pmatrix} \\ &= \begin{pmatrix} (2-rK_1) & (K_1-1) \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x_k \\ y_k \end{pmatrix} \end{aligned} \tag{12}$$

Consequently the Jacobian $\mathbf{G}'(x) = \partial g_i / \partial x$ is given by

$$G'(x^*) = \begin{pmatrix} (2-rK_1) & (K_1-1) \\ 0 & 1 \end{pmatrix} \tag{13}$$

The loop will converge if the eigen values $\mathbf{G}'(x^*)$ are be less than one. Following [14] the operational regions of the second order ZCDPLL are given by (as shown in Figure 2): region (I), the loop converges locally to $\mathbf{x}^*=0$,

2π , region (II), the loop phase error ϕ oscillates between two values, region (III), the loop phase error ϕ oscillates between n values or diverges, while in region (IV), the loop phase error ϕ diverges.

Fundamental to most definitions of chaos is the concept that two trajectories of the system, no matter how closely they start to one another, will eventually diverge. This divergence is of exponential order. The Lyapunov exponent is used to measure the average rate of divergence of nearby trajectories. It is defined as [3,10]:

$$\lambda = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{n=0}^N \ln |f'(\phi_n)| \tag{14}$$

A positive Lyapunov exponent indicates chaos. The largest Lyapunov exponent for the two dimensional a dynamical ZCDPLL system is defined as [3]

$$\lambda = \lim_{N \rightarrow \infty} \frac{1}{2N} \sum_{n=0}^N \ln \left| \frac{(a + bY'_n)^2 + (c + dY'_n)^2}{1 + Y_n'^2} \right| \tag{15}$$

where Y' is the tangent of the direction of maximum growth which evolves according to

$$Y'_{n+1} = \frac{c + dY'_n}{a + bY'_n} \tag{16}$$

where $a = \partial g_1 / \partial x_k$, $b = \partial g_1 / \partial y_k$, $c = \partial g_2 / \partial x_k$, $d = \partial g_2 / \partial y_k$, are members of Jacobian matrix of (13).

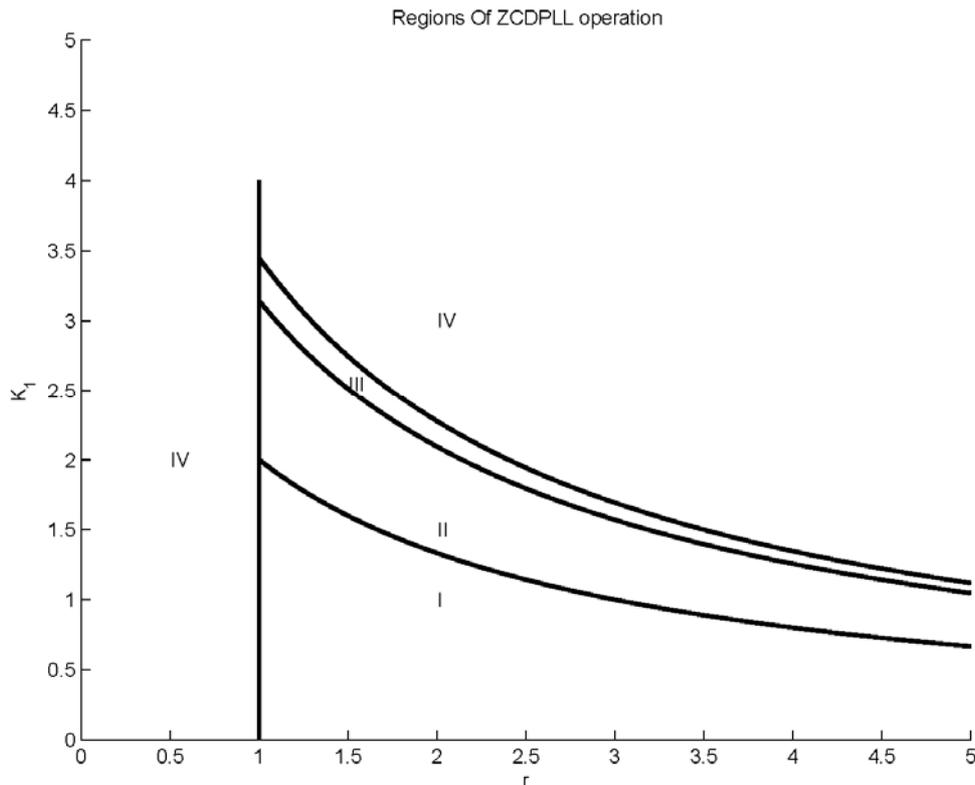


Figure 2. Loop behaviour as a function of K_1 and r for second-order ZCDPLL.

In order to see where the loop has chaotic behavior, Lyapunov exponent has been calculated for all possible values of the loop parameters (K_1 and r) and has been given black dot when they have values greater than 1 (positive Lyapunov represents chaotic operation). The distribution of these black dots is shown in Figure 4. In order to produce chaotic sequence of phase error, one should work in black regions.

The chaotic phase φ_k distribution generated by the second order ZCDPLL distribution is shown in Figure 5 where $K_1 = 2.5$, and $r = 2.5$. Sample 2 is shown in Figure 6 for $K_1 = 3.0$, and $r = 2.5$. The two phase sequences are random. The one million bits extracted from the phase sequence of ZCDPLL have been collected ($\varphi \in [0, \pi)$ corresponds to a "1" and $\varphi \in [\pi, 2\pi)$ corresponds to a "0". The autocorrelation properties of the outputs are shown in Figure 7. Chaotic sequence have very low cross correlation as shown in Figure 8 for the two binary streams generated using two different loop parameters. This is an important issue with regard to the security, because the receiver can not be determined from a few points in the sequence.

The chaotic bit stream generated by the second order ZCDPLL of length 20000 bits is subject to each of the tests. The Monobit test is projected as evidence if the

number of 1's and 0's in the sequence are nearly equal. The AIS standard specified the value of the number of 1's in the bit stream to be somewhere between 9654 and 10346. The Pocker Test requires the division of the initial sequence into 4 bit contiguous segments, the counting and the storing of each of the 16 possible 4 bit values. Denoting as $f(k)$ the number of each value, $0 \leq k \leq 15$, the X statistic is computed by means of (The test will pass if $1.03 \leq X \leq 57.4$):

$$X = \frac{16}{5000} (\sum (f(k))^2 - 5000) \tag{16}$$

The third test used is runs test. If we describe a run as the maximal sequence of consecutive bits of the same kind then the incidence of runs for both consecutive zeros and consecutive ones of all lengths of what between 1 and 6 in the sample stream should be in the corresponding interval as specified in Table 1.

It is worth noticing the fact that the sequences longer than 6 are considered of length 6 when counting them. The test is passed if for the generated sequence the number of consecutive bits of each length is between the limits given in the Table 2. The long run test is passed if there are no runs of length 34 or more.

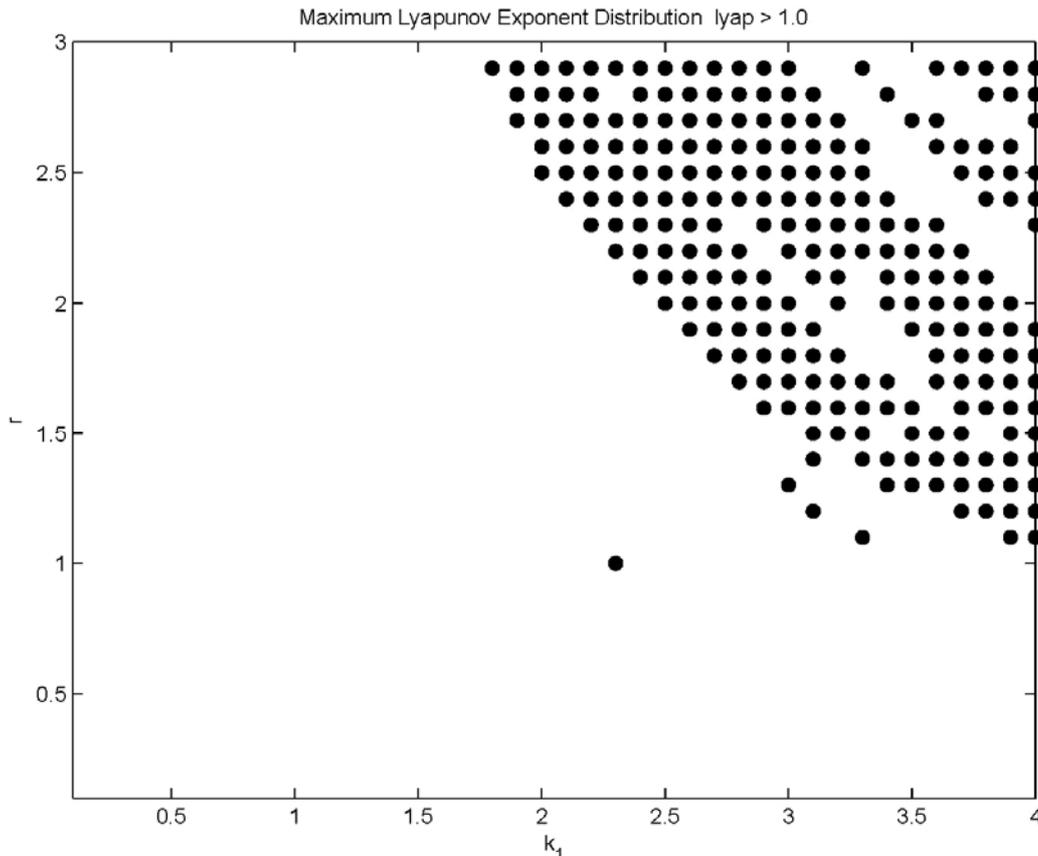


Figure 4. Largest Lyapunov Exponent of ZCDPLL - dot when it is greater than 1.0.

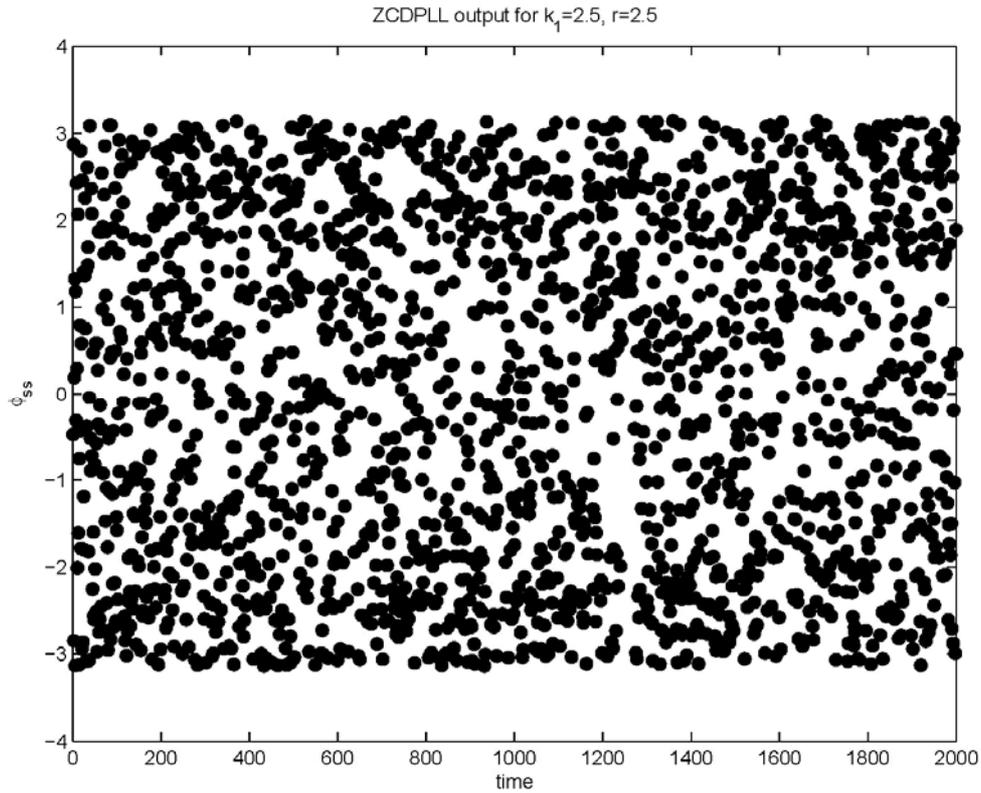


Figure 5. Distribution of ZCDPLL output (Sample 1) for a set of filter gain.

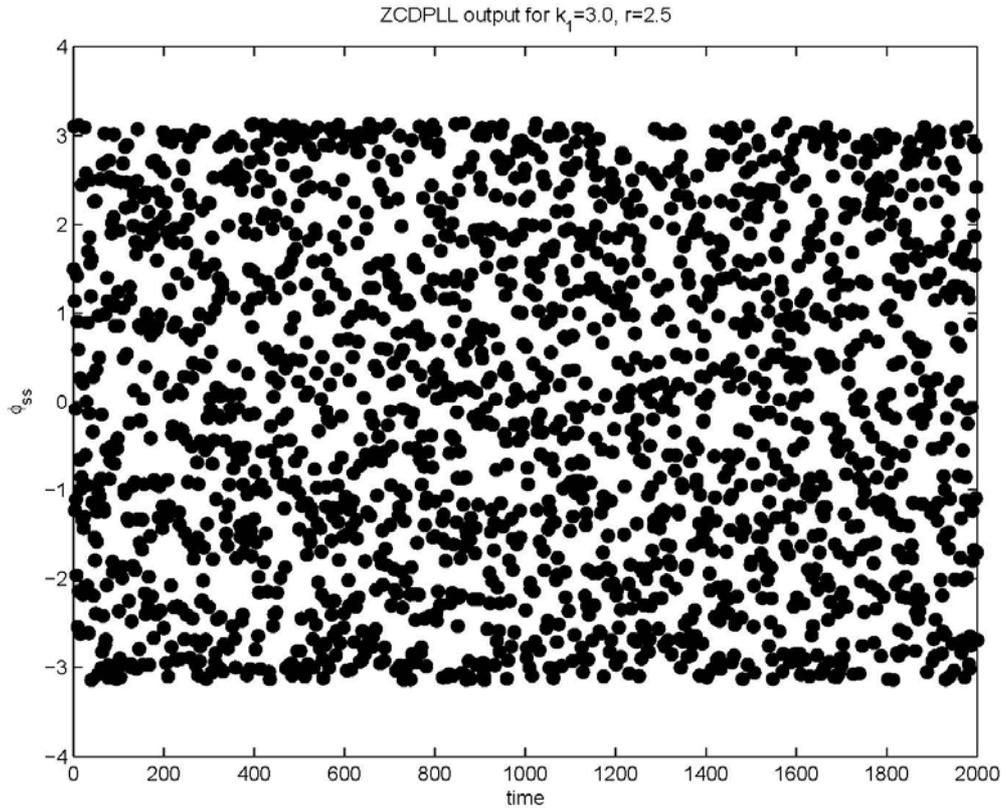


Figure 6. Distribution of ZCDPLL output (Sample 2) for other set of filter gain.

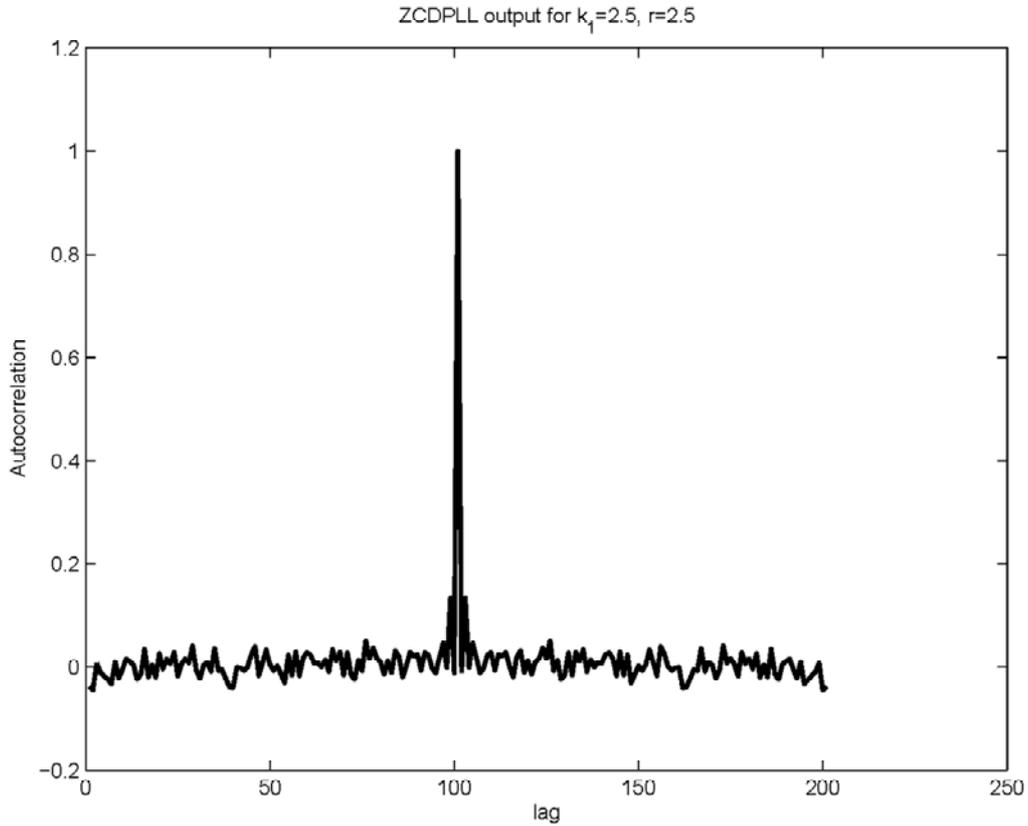


Figure 7. Autocorrelation of ZCDPLL mm output (Sample 1).

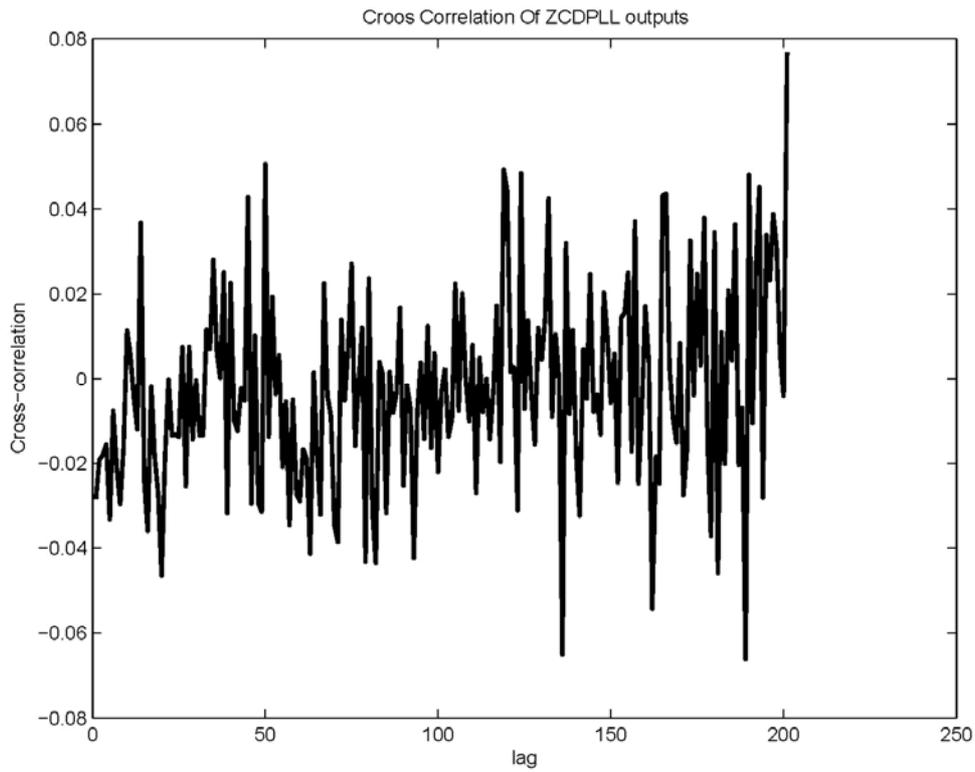


Figure 8. Cross Correlation of two ZCDPLL outputs (Sample 1 and Sample 2).

Table 1. Number of occurrences versus length.

Length	1	2	3	4	5	6+
Number Of occurrences	$\frac{2267}{2733}$	$\frac{1079}{1421}$	$\frac{502}{748}$	$\frac{223}{402}$	$\frac{90}{223}$	$\frac{90}{223}$

Table 2. Simulation test results.

AIS 31 Statistical Test	Result	Limits
Test 1 (Monobit Test)	Monobit = 9986 9645	$9645 < \text{Monobit} < 10346$
Test 2 (Poker Test)	$X = 44.498$	$1.03 < X < 57.4$
Test 3 (Runs Test)	All Passed	
Test 4 (Long Run Test)	Long Run = 16	Long Run = 34

The proposed true random bit generator successfully passes all four statistical tests for every run. Table 2 shows the results of AIS 31 Standard Statistical Tests ran over 1 million random bits generated by ZCDPLL with $K_1=2.5$, $r=2.5$. As can be seen, all results are within the accepted range of the tests.

5. TMS320C6416 Implementation

The TRBG using ZCDPLL has been implemented in the software code targeted at a Texas Instruments TMS 320C6416 DSP. The generated bits are collected by the host PC. The key issue in the realization of the TRBG using ZCDPLL is the implementation of variable sample

rate signal processing. In the realization based of DSP, variable sampling rate can be efficiently implemented using the DSP chip timer. At the beginning of the software program, the DSP timer (e.g Timer1) is set to be equal to maximum value of the sampling period. While the timer counts towards zero, an input (error) sample is read from the Analogue to Digital converter (ADC). On the basis of the error sample, the controller output and the actual value of the sampling period T are computed. Then the computed value of the sampling period is used to set the timer period. The DSP processor will enter an idle state till the timer expired, then the processed will be interrupted and the Interrupt Service Routine (ISR) will be called and the program loop repeats (see Figure 9).

Real-Time Data Exchange (RTDX) is used to provide real time, continuous visibility into the way TRBG software application operates in TMS320C6416. RTDX allows transfer the random bits generated in the DSP to a host PC for testing. On the host platform, an RTDX host library operates in conjunction with Code Composer Studio. In RTDX an output channel should be configured within ZCDPLL software. The generated data from ZCDPLL is written to the output channel. This data is immediately recorded into a C6416 DSP buffer defined in the RTDX C6416 library. The data from this buffer is then sent to the host PC through the JTAG interface. The RTDX host library receives this data from the JTAG interface and records it into either a memory buffer for testing purposes.

One million bits have been collected by the host PC. The same AIS 31 test suit has been used to check the truly randomness of the generated bits by the DSP kit. The results of these tests are shown in Table 3. It can be seen that the bits passed all the three proposed tests.

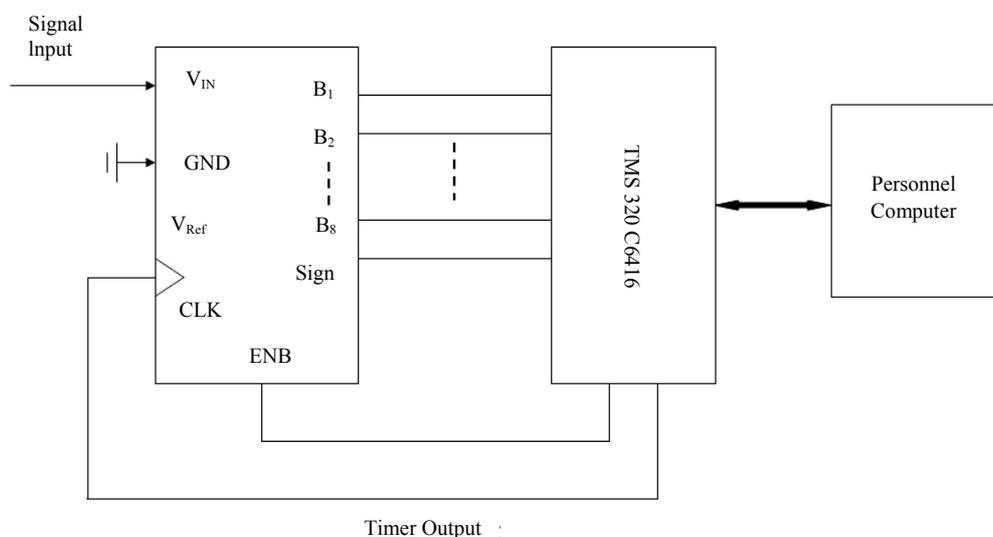
**Figure 9. TMS320C6416 based TRBG.**

Table 3. DSP card based test results.

AIS 31 Statistical Test	Result	Limits
Test 1 (Monobit Test)	Monobit = 10122	$9645 < \text{Monobit} < 10346$
Test 2 (Poker Test)	$X = 51.32$	$1.03 < X < 57.4$
Test 3 (Runs Test)	All Passed	
Test 4 (Long Run Test)	Long Run = 28	Long Run = 34

6. Conclusions

In this paper, True Random Binary Generator (TRBG) using second order ZCDPLL has been described and evaluated. The chaotic phase error produced by the ZCDPLL has been used to generate TRB. The proposed TRBG is subjected to statistical test suit AIS 31. The proposed TRBG successfully passed the tests described by AIS31 document. Another essential result of this paper is that the proposed TRBG based on ZCDPLL is implemented fully by software based on TMS320C6416 DSP kit. TRBG synchronization is still a challenging task which will be dealt within future work. Post processing is used to improve the statistical properties of the bit sequences generated by the ZCDPLL.

7. References

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