

The Research of Voltage Sag and Power Frequency Overvoltage on 110kV Resistance Grounding System

Guo Zeng¹, Guangliang Feng¹, Yanping Lv², Shan Sun²

¹Huangshi Power Supply Company, Huangshi, China

²School of Electrical Engineering, Wuhan University, Wuhan, China

Email: sun07126111@163.com

Received January, 2013

ABSTRACT

This paper researches the voltage transfer characteristics when one-phase ground fault occurred in the resistance grounding system, by using the theory of the asymmetric variable characteristics and the sequence network analysis of the -11 transformer, and concludes the scope of voltage sag and swell and the degree of power frequency overvoltage and their influencing factors in the 110 kV resistance grounding system. Accordingly this paper puts forward the resistance choosing principle: the resistance grounding coefficient must be equal to or greater than 10. So it can not only wipe out the voltage sag and voltage swell but also make sure the overvoltage is limited to electrical equipment allowing range. The method mentioned above is verified by simulation results of a 110 kV power system in ATP.

Keywords: Neutral Grounding System by Resistance; One-phase Grounding Fault; Power Frequency Overvoltage

1. Introduction

In China, Most of 110 kV distribution grid use neutral solid ground[1], in this neutral grounding mode, single-phase fault current is very large, sometimes even more than the three-phase fault current. And the single-phase fault will cause a serious voltage sag in the load side which can not satisfy the sensitive users' requirements for high power quality. Therefore terminal substation of 110 kV side using neutral solid grounding method has been difficult to meet the sensitivity to the requirements of the quality of the electric power load.

According to this problem, this paper puts forward the 110 kV neutral grounding system by resistance, and researches the relationship between the neutral grounding resistance and the voltage sag degree, power frequency overvoltage level, and tries to make the terminal substation of 110 kV neutral grounding by resistance. After this change, the 110 kV side can eliminate the voltage sag and limit the voltage dip rising and also can ensure the power frequency overvoltage degree not more than the existing 110 kV electrical equipment in the insulation level when one-phase ground fault happened.

2. Voltage Sag and Voltage Swell and Their Trans Ferred by Transformer

Voltage sag (also called the voltage drop) is transient

electric energy quality problems. It is point to the voltage root-mean-square value to suddenly down or rise in a short time, the typical duration is 0.5 - 30 cycles. IEEE standard defined as: in the power supply system, a certain point's power frequency voltage RMS suddenly dropped to 10% - 90% of the rating called voltage sag^[2]. And these phenomena are returned to normal after the short duration of the next 10 ms - 1 min.

3. The Voltage Sag and Swell in the Resistance Grounding System

If the transformer high voltage side happened the A phase grounding fault, the line voltage relationship between high and low voltage side of Y/ Δ -11 transformer can described by the following formula (1):

$$\begin{bmatrix} \dot{U}_{ab} \\ \dot{U}_{bc} \\ \dot{U}_{ca} \end{bmatrix} = \frac{1}{\sqrt{3}k} \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ -1 & 0 & 1 \end{bmatrix} \begin{bmatrix} \dot{U}_{AB} \\ \dot{U}_{BC} \\ \dot{U}_{CA} \end{bmatrix} \quad (1)$$

Where, k is the transformation ration.

In 110 kV resistance grounding system occurring gold attribute ground fault for a phase, we can deduce 110 kV phase voltages per-unit expression after the fault occurring [3].

$$\begin{cases} \dot{U}_{A^*} = 0 \\ \dot{U}_{B^*} = -\frac{3}{2} - \frac{\sqrt{3}}{2}j + \frac{j3}{\frac{Z_0}{X_1} + 2j} \\ \dot{U}_{C^*} = -\frac{3}{2} + \frac{\sqrt{3}}{2}j + \frac{j3}{\frac{Z_0}{X_1} + 2j} \end{cases} \quad (2)$$

where, the Z_0 is the zero sequence impedance in the resistance grounding system. It can be shown in the equivalent circuit in **Figure 1**

$$Z_0 = (R_0 + jX_0) // (1 / j\omega C_0) \quad (3)$$

where, R_n is the neutral grounding resistance; X_0 is the system equivalent zero sequence impedance which from the fault point. If the X_C in the zero sequence system have the same order of magnitude with the neutral grounding resistance R_0 , the X_C cannot be ignored.

According to the type (1) and (2), we deduced:

$$\begin{cases} \dot{U}_{ab^*} = \frac{1}{2} + \frac{\sqrt{3}}{2}j - \frac{j}{\frac{Z_0}{X_1} + 2j} \\ \dot{U}_{bc^*} = \frac{1}{2} - \frac{\sqrt{3}}{2}j - \frac{j}{\frac{Z_0}{X_1} + 2j} \\ \dot{U}_{ca^*} = -1 + \frac{2j}{\frac{Z_0}{X_1} + 2j} \end{cases} \quad (4)$$

We can concluded that when one-phase grounding fault occurred in the resistance grounding system, the voltage of the load side are closely related to the Z_0/X_1 .

Making the $X_0/X_1 = m$, $X_C/X_1 = n$, $R_0/X_1 = k$, and calling k is the grounding resistance coefficient:

$$\begin{cases} \dot{U}_{ab^*} = \frac{[mn - \sqrt{3}(2-n)k] + j[\sqrt{3}(m+2)n - nk]}{2(m+2)n - j2(n-2)k} \\ \dot{U}_{bc^*} = \frac{[mn + \sqrt{3}(2-n)k] - j[\sqrt{3}(m+2)n + nk]}{2(m+2)n - j2(n-2)k} \\ \dot{U}_{ca^*} = \frac{-mn + jnk}{(m+2)n - j(n-2)k} \end{cases} \quad (5)$$

For the existing 110 – 220 kV system, generally $0.23 \leq m = X_0/X_1 \leq 3$; And for the neutral non-grounding system, $X_C/X_1 = 26 \sim \infty$ [4]. Because when $n > 100$, the value of n has little affection to the value of voltage, so this paper mainly studies the value area of n is $26 \leq n \leq 100$.

The boundary value combination of the m, n go into the type (5), seeking the rule of load line voltages

changing with the coefficient k . we find the voltage drop seriously is U_{ab} as shown in **Figure 2**. Between the m and n range, other combination have the impaction on voltage amplitude should be between them.

From the **Figure 2** can be seen, when choosing appropriate resistance (such as $k \geq 10$), voltage sag of three line voltages in the load side will never more than 0.1p.u., that can ensure the load side line voltages in line with the requirements of power quality of voltage fluctuation range.

For a practical system, we can seek the biggest X_1 according to the change of the mode of operation and the structure of the system when one-phase fault occurred in the system, going into the $R_0/X_1 = k \geq 10$ to seek the resistance range were able to eliminate the voltage sag.

$$R_0 \geq 10X_1 \quad (6)$$

4. The Relationship between the Power Frequency and the Grounding Resistance

From the above discussion, when 110 kV using neutral grounding resistance method, if the resistance is appropriate, it can eliminate voltage sag. But it can lead to the power frequency overvoltage, also conversing the type (2) to the functions on m, n, k such as type (7) showing:

$$\begin{cases} \dot{U}_{A^*} = 0 \\ \dot{U}_{B^*} = \frac{-[3mn + \sqrt{3}(n-2)k] + j[-\sqrt{3}(m+2)n + 3nk]}{2(m+2)n - j2(n-2)k} \\ \dot{U}_{C^*} = \frac{[-3mn + \sqrt{3}(n-2)k] + j[\sqrt{3}(m+2)n + 3nk]}{2(m+2)n - j2(n-2)k} \end{cases} \quad (7)$$

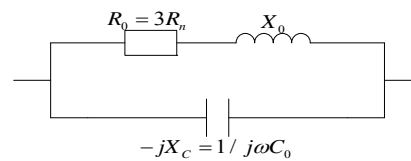


Figure 1. Equivalent circuit of zero sequence impedance Z_0 .

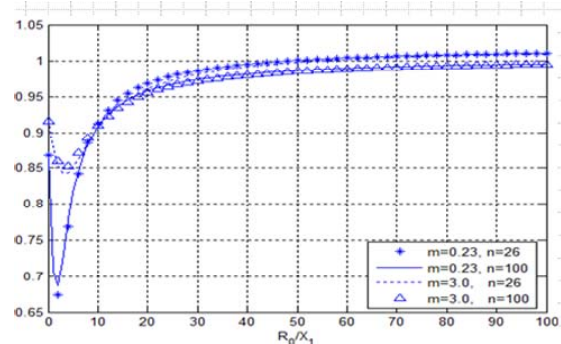


Figure 2. Load line voltage U_{ab} with R_0/X_1 changes.

when A phase grounding fault occurred, C phase power frequency overvoltage is the most serious. The boundary value combination of the m, n go into the type (7), seeking the rule of U_{C^*} changing with the coefficient k , as shown in **Figure 3**. In the m and n range, other combination have the impaction on voltage amplitude should be between them.

It shows that: The power frequency overvoltage extreme maximum value will be not more than 2.0p.u. When choosing the resistance meeting constraint conditions that $k \geq 10$.

Literature [5] regulated that the 1min withstanding voltage value of 110kV transformer and switch equipment is 200 kV (i.e. not less than 3.0p.u). Because of 110 kV system adopting the neutral grounding resistance method, relay protection is still in action trip, which can quickly resection fault, so the power frequency overvoltage would be for a very short time, and can be controlled in within 0.5 s[6]. So the power frequency overvoltage to the electric equipment insulation will not cause damage.

5. Based on the Simulation Results for ATP

A simulation model is established in the ATP-EMTP for a 220kV terminal substation, as shown in **Figure 4**. Where, power supply side equivalent impedance: $X_{smax.1^*} = 0.01583$, $X_{smax.0^*} = 0.03594$, $X_{smin.1^*} = 0.04934$, $X_{smin.0^*} = 0.12811$ ($S_B = 100\text{MVA}$, $U_B = U_{av}$); 1# and 2# main transformer are three winding step-down transformer, YNynd11, $S_e = 180\text{MVA}$, $U_{d1-2} = 14.10\%$, $U_{d1-3} = 23.10\%$, $U_{d2-3} = 7.9\%$. For the neutral point of 220 kV side, 1# directly grounded and 2# not grounded. The neutral point of 110 kV side, both of the transformers are grounded by resistance. Line model is LGJ-240, their length shown in Figure 4, $r_1 = 0.1181 \Omega/km$, $L_1 = 1.2450 \text{mH}/km$; $r_0 = 0.2881 \Omega/km$, $L_0 = 2.4900 \text{mH}/km$, $C_0 = 0.0054 \mu\text{F}/km$. The line terminal transformer are 110/10.5 kV, Y/ Δ -11. The 1# and 2# transformers parameters are $S_e = 50 \text{MVA}$, $U_{d1-2} = 10.56\%$; 3# and 4# transformers parameters are $S_e = 40 \text{MVA}$, $U_{d1-2} = 10.74\%$

Analysis system the most serious condition under the possible operation mode, and making the simulation schemes are as follows:

1) The system operate in the minimum way, the one-phase grounding fault respectively happening in the head end of line(d_1) and the tail end of the longest line(d_2).

2) The system is running in the biggest way, and the one-phase grounding fault respectively happening in the d_1 and d_2 .

We can calculated that when the system is running in the minimum way, and the fault happened at d_2 , the X_1 will be the biggest 26.49 Ω . According to the type(8), we can find out the resistance which eliminate voltage sag

and swell.

$$R_0 \geq 10 X_1 = 10 \times 26.49 = 260.49 \Omega$$

Making $R_0 = 300 \Omega$, and the resistance of each main transformer is $R_N = 2R_n = 200 \Omega$.

When the $R_N = 200 \Omega$, the simulation results shown in **Table 1**.

Seen from the **Table 1**, when neutral grounding resistance is 200 Ω , the highest power frequency overvoltage is 1.78p.u, the maximum line voltage drop is 9%, So the line voltage fluctuation have not more than system allows range, and the power frequency overvoltage under 2p.u. Since the model in ATP considering the resistance of transformer and line, the simulation results have a certain error compared to the theoretical calculation value, and the simulation results may be more close to the practical situation.

6. Conclusions

This paper researches the voltage sag and power frequency overvoltage for the 110 kV neutral grounding system by the resistance, and concludes :

1) When the selected resistance meet the requirement that $R_0 / X_1 \geq 10$, the voltage sag degree less than an average 10%. It can eliminate voltage sag when most frequent one-phase fault happened in high voltage side.

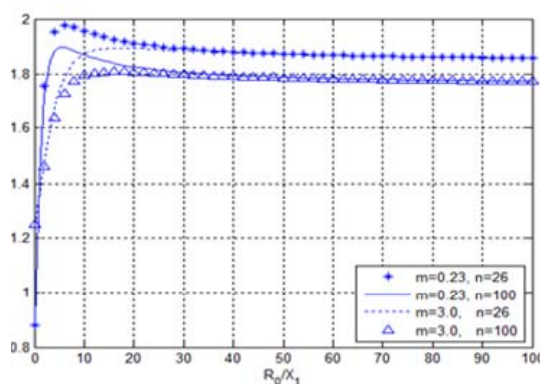


Figure 3. Phase voltage U_{C^*} with R_0/X_1 changes.

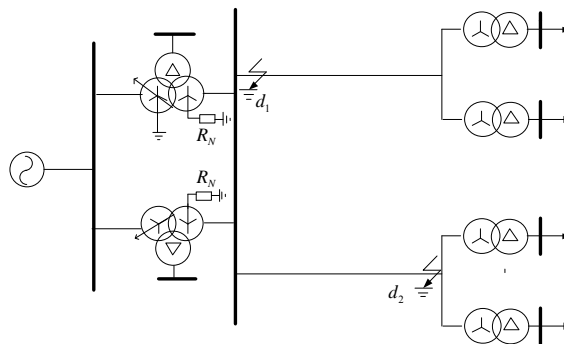


Figure 4. Substation simulation system diagram.

Table 1. Simulation results.

Simulation scheme	Running status	110 kV bus voltage		1#transformer Y side phase voltage/ Δ side line voltage					3#transformer Y side phase voltage/ Δ side line voltage				
		U_{B*}	U_{C*}	U_{B*}	U_{C*}	U_{ab*}	U_{bc*}	U_{ca*}	U_{B*}	U_{C*}	U_{ab*}	U_{bc*}	U_{ca*}
scheme 1	normal	1.0	1.0	0.99	0.99	1.0	1.0	1.0	0.96	0.96	0.99	0.99	0.99
	$d_{1A}^{(1)}$	1.64	1.78	1.64	1.76	0.96	1.04	0.99	1.63	1.73	0.94	1.02	0.98
	$d_{2A}^{(1)}$	1.37	1.76	1.36	1.75	0.96	1.03	0.97	1.47	1.65	0.91	1.02	0.91
scheme 2	normal	1.0	1.0	0.99	0.99	1.0	1.0	1.0	0.96	0.96	0.99	0.99	0.99
	$d_{1A}^{(1)}$	1.67	1.77	1.67	1.75	0.98	1.03	1.0	1.66	1.72	0.96	1.01	0.98
	$d_{2A}^{(1)}$	1.40	1.77	1.40	1.75	0.98	1.02	0.98	1.50	1.66	0.93	1.01	0.93

2) The power frequency overvoltage will increase in the neutral grounding resistance system, but the overvoltage will be not more than 2.0p.u. Since the relay protection can fast action to react the fault, so it will be not harmful to the electrical equipment.

REFERENCES

[1] Y. Li, Y. P. Duan, J. Qiu, *et al.*, Voltage Sag Analysis and Fault Position Sag Coefficient Calculation, *High Voltage Engineering*, Vol. 32, No. 7, 2006, pp. 113-115.

[2] IEEE Recommended Practice for Evaluating Electric Power System Compatibility with Electronic Process Equipment[S]. IEEE Standard, 1998, pp. 1346-1998.

[3] D. Tao and X. N. Xiao, "Voltage Sags Types under Different Grounding Modes of Neutral and Their Propagation: part II", *Transactions of China Electrotechnical Society*, Vol. 22, No. 10, 2007, pp. 156-159.

[4] G. R. Xie, "Power System Overvoltage," Wuhan Water Electrical Institute Press, China, 1985.

[5] The People's Republic of Electrical Power Industry. Overvoltage Protection and Insulation Coordination for AC Electrical Installations, Beijing, China: China Electric Power Press, 2010.

[6] Z. Y. Xu, "Digital Protection for Power Transformer and Medial-low Voltage Electric Power Net," China Water-Power Press, Beijing, China, 2004.