

Solution Scheme for Time Synchronization of Current Differential Protection between Digital Substations*

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ABSTRACT

In digital substations with power transformers, the key to implementation of line differential protection is synchronization of electrical quantities at both two sides. System framework of current differential protection for lines between digital substations is analyzed briefly, as well as the necessity of demand for time synchronization. Principle of time synchronization based on GPS and IEEE1588 PTP (Precision Time Protocol) are introduced. Time synchronization of current differential protection between digital substations based on IEC61850 is discussed. This paper puts forward two solution schemes of time synchronization, analyzes their advantages and disadvantages respectively, and points out that the development direction of time synchronization of differential protection between digital substations is IEEE1588 PTP.

Keywords: Differential Protection; Time Synchronization; GPS; IEEE1588

1. Introduction

At present, synchronous clock source based on global positioning system (GPS)[1] is widely used in electric power system in China. GPS has its unique superiority and is the best candidate synchronous clock source in available clock reference sources. Second pulse statistical error of its output is 1 μ s and has no cumulative error, which can meet requirements of many application fields for synchronous clock. Substation receives a standard Second Pulse signal (Pulse per Second, PPS) from GPS, then send synchronous Pulse to total IED of all substations through special cable. This scheme can realize time tick of multiple IED clocks with ease. However, the development trend of digital substation is that secondary hardwiring in station will be replaced by serial communication line. The clock system Based on GPS has showed some limitations.

IEEE 1588[2,3] defines a precision time protocol(PTP) used in distributed measurement and control system. IEEE1588 has important significance for construction of digital substation and provides a good technical options for realization of IEC61850 [4] T5 level precision clock as a distributed network time synchronization scheme [5,6] whose accuracy can achieve submicro second level. Despite IEEE1588 is still in the test phase, its high preci-

sion network time tick has distinctive characteristics which indicate its bright application prospect.

This paper briefly introduces system architecture of current differential protection for lines between substations [7-9], and respectively analyses synchronous solutions based on GPS and IEEE1588. The aim is to provide reference for engineering application of data synchronization of current differential protection between digital substations in future.

2. The Structure of Protection System and Requirement Analysis of Data Synchronization to Current Differential Protection based on the Information Exchange between Substations

2.1. The System Architecture of Information Exchange in Substations, which Supports the Protection of Current Difference Lines

This diagram includes circuit breaker, current transformer, information collector(filter, hybrid circuit, A/D converter), emitter, receiver, remote switching system, time-delay device and protection device. First, current transformer measures current value i_A , and the current is converted into right current value which information collector can capture. Second, information collector of A collects data and converts analog signal into a digital signal. Finally through the remote exchange system, transmitter will sent the collected data of A to B, through

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a time-delay device, the collected data of B which is captured by the data acquisition unit will realize data synchronization with the data of A. Then we can get the i_D by compared the data of A with B, and if it is larger than set value meaning that line has internal fault, both A and B circuit breaker will disconnect, otherwise they will be normal operation. In the process of data acquisition and transmission, the protection device has been up to protect data without being interfered (If in the ideal case, the value of i_D will be zero).

2.2. The Demand for Data Synchronous

For line current differential protection, the most important is to compare the current of “the same moment” on both sides. As can be seen from **Figure 1**, guide lines can directly transmit secondary current of short circuit (less than 10 km) on both sides, which does not exist “different moment” problem. However, when it transfers the current of both sides through the communication channel, the system should carry digital data acquisition for current instantaneous value of each side. Sampling rate of protection commonly should be 12 - 24 points each working frequency, and phase difference is $30^\circ - 15^\circ$. So in order to work properly, protection must use the synchronous data on both sides. The “data synchronization” of both sides contains two meanings: One is the sampling time of both sides must be strictly same, which is known as synchronous sampling; The other is to use the sampling data of both sides at the same time to calculate differential current, which is called data-window synchronization. However, both ends of the line are apart from hundreds of kilometers, which are not able to use the same time to ensure time-unification and sample synchronization. The technical problem of current differential protection between digital substations must be solved to ensure unity of the clock time of two remote substations and strict synchronization of sampling instant[10].

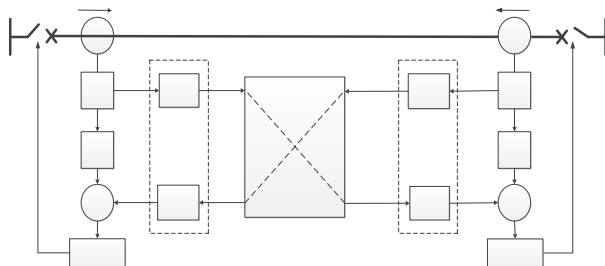


Figure 1. Current differential line protection.

3. Introduction to Two Synchronous Technologies

The existing main synchronization technology: one is based on the global positioning synchronous (GPS) and the other is based on IEEE1588 network time synchronization technology[11,12].

3.1. GPS Time Synchronization

GPS is a new generation of space satellite navigation and positioning system developed in the 1970s, 24 GPS satellites covered up to 98% of the globe has successfully launched and emplaced by 1994. One of its functions is to provide people with high precision time information. GPS synchronization method is based on this characteristic. GPS can provide the whole power system with long-term stable wireless clock source, so far, has been widely used in PMU, fault location, etc.

Principle of GPS synchronization is that the special receiver receives the time information from GPS. The receiver is made up of the receiving module and receiving antenna. GPS receiver receive time information, then decode it and make corresponding treatment, which can get two kinds of information, one is the second pulse signal (1PPS), Its synchronous error is less than $1 \mu s$ between rising edge and UTC, as shown in **Figure 2**. The other is UTC time code (year, month, day, minutes and seconds). Its corresponding serial port output signal to differential protection device. So it can provide sample data with time tag. In order to make pulse rising edge of the sampling signal synchronization with UTC, what it need is a stability high crystal oscillator sampling clock which can produces corresponding sampling pulse. IPPS synchronize the sampling pulse once per second. When two ends of line are equipped with this kind of synchronous receptors, they can respectively provide their differential protection devices with highly synchronous sampling pulse (error less than two microseconds).

In the power system, we don't use precise positioning technology of GPS, but use its accurate timing information to choose the GPS receiver. GPS receiver receive, decode and process satellite signal, then provide 1PPS signal, which is international standard signal, and can be reliably received in around the global. Then these signal synchronize clocks in power system as the standard clock source, which ensures that substation clocks will synchronously operate.

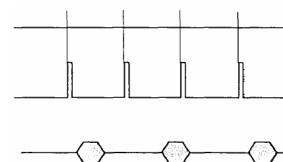


Figure 2. GPS receiver clock signal.

3.2. IEEE 1588 Time Synchronization Technology

The full name of IEEE 1588 is “Standard for a Precision Clock Synchronization Protocol for Networked Measurement and Control Systems” (PTP for short). Synchronization of PTP system is achieved by exchanging messages across the communication medium. PTP uses the following multicast message types: Sync, Delay-Req, Follow-Up and Delay-Resp. The Principle of IEEE 1588 is as shown in below.

As shown in **Figure 3**, the master clock sends a Sync message to all the clocks in the domain at time T_{a1} , the slave clock receives this message at time T_{b1} , the master may subsequently send a follow-Up message with accurate T_{a1} timestamp to the slave, the slave send Delay-Req message to the master at time T_{a1} after received the accurate T_{a1} timestamp from Follow-up, the master shall receive Delay-Req at T_{a2} and take note of the accurate time T_{a2} into Delay-Resq, which then be sent to the slave. Once the slave receive the Delay-Resp message, the time offset $T_{off-delay}$ and path delay T_{delay} can be calculated, formulas are listed below:

$$T_{off-delay} = \frac{(T_{b1} - T_{a1}) + (T_{b2} - T_{a2})}{2} \quad (1)$$

$$T_{delay} = \frac{(T_{b1} - T_{a1}) - (T_{b2} - T_{a2}) - 2T_{Q-delay}}{2} \quad (2)$$

($T_{Q-delay}$ stands for forwarding delay quantity.)

If the slave time is assumed to be T_{sOld} right now, then the new time T_{sNew} can be worked out:

$$T_{sNew} = T_{sOld} - T_{off-delay} - T_{Delay} \quad (3)$$

Accordingly, in the next synchronization period, the synchronization of the slave clock and the master clock can be realized by adjusting time offset and the amount of path delay online. Further more, each clock node link to power communication network, the synchronization of all substations in the network can be achieved.

4. Solutions for Time Synchronization of Differential Protection between Digital Substations

4.1. Two Solutions to Time Synchronization of Differential Protection between Digital Substations

Solution 1: time synchronization between substations is implemented by GPS, as shown in **Figure 4**. Each substation is equipped with GPS receiver, which can output absolute time serial data and second pulse signal into the GC within substation, *i.e.*, GPS ensure time synchronization between each substation GC. The substation 1-N stands for station-level system in **Figure 4**.

Advantages and disadvantages of solution 1: time synchronization of the network between substations is implemented by GPS, IEEE 1588 is adopted for time synchronization within substation, solution 1 needs hardware that support IEEE 1588, so the investment would increase, the total time synchronization error is larger than the way of single-GPS due to the two-class time synchronization structure formed by GPS and IEEE 1588. The advantages of this solution are as follows: the time synchronization structure is clear and simple; it can save serial bus and hard wire that need to be connected to related devices when single-GPS way is used[13].

Solution2: time synchronization between substations is implemented by IEEE 1588, as shown in **Figure 5**. BC in substation 1-N needs to synchronize with the master station's time. As can be seen from **Figure 5**, this solution requires support of the overall communication network. According to this solution, only one master station is used to synchronize with the highest class clock of other substations, in order to complete the redundant configuration. And P2P transparent clock between adjacent substations is used to receive, regenerate and transmit time message as a reapter, which can decrease asymmetry error.

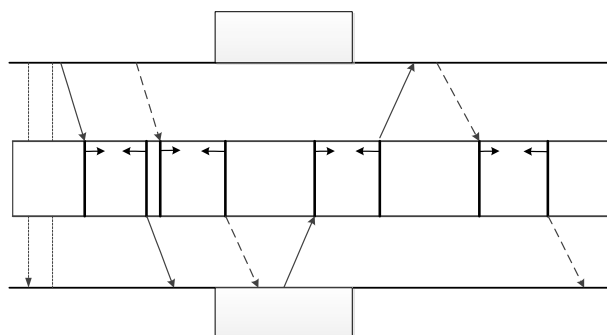


Figure 3. IEEE1588 synchronization process.

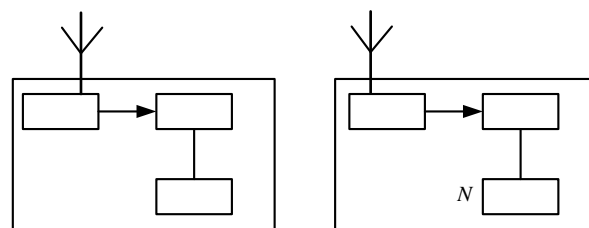


Figure 4. GPS synchronous scheme.

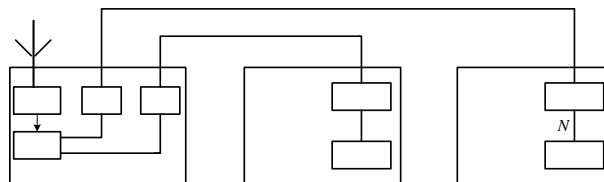


Figure 5. IEEE1588 synchronization scheme.

Advantages and disadvantages of solution 2: IEEE 1588 completes time synchronization between and within substations, so GPS can be left out. In the perspective of the whole network, GPS in the master station is nothing but to provide the absolute reference time. If the satellite communication network encounter damage or interference, the time synchronization system can still keep going, though the time is no more corresponding to the standard world's. IEEE1588 PTP holds a great capability of fault tolerance and allows exist of time isolated island. For instance, substation1 loses time message exchange with the master station, then IEEE 1588 clock in substation1 would generate a new substation-master-clock to synchronize other clocks within the substation by the means of comparing with the best master clock algorithm, which can meet requirement of synchronization precision for a short time. If synchronization message can't be received for long, clock skewing would occur, the internal time would disaccord with standard time, but all internal devices of substation shall keep a high precision synchronization. The disadvantages are as follows: hardware equipments that support IEEE 1588 make higher investment, time synchronization network would enlarge and need more nodes, the precision of clock must be strictly tested[14,15]. Meanwhile this solution need support from long distance communication network, when the size of cascading substations get larger, the problem that the time synchronization precision can meet requirement needs to be verified by practice in future.

4.2. The Necessity and Feasibility of the Solution

At present the main mode is as follows: every substation has a GPS receiver or other precise clock source to fulfil synchronization with each substation. However, the synchronization precision between substations is not high enough, it may cause errors in some cases. For example, line differential protection is based on both ends' electrical parameters, which must be high-precision synchronization with the unified time scale, if the independent synchronous timing information in each substation isn't unified and one end loses synchronous clock, synchronization error would increase, which lead to incorrect action of protector. With development of measurement and control technology, time synchronization between substations is more important. IEEE1588 has been mainly used in local network system, but as the substation communication network constantly improves, it will be applied in larger area network system.

5. Conclusions

GPS synchronization scheme is simple, so it is the first choice. The application of synchronization scheme based on IEEE1588 will depend on clock precision of whole

network and wide area communication network which can support IEEE1588. The key to the normal operation of transformer substation is precision of time synchronization. IEEE1588PTP can provide high precision and unified time information for substation. Scheme based on IEEE1588 can simplify the method of synchronization used in the current substation, improve the reliability, has a good applied foreground, will be dominant mode of clock synchronization for differential protection in digital substation in the future.

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