

New VD-DIBA-Based Single-Resistance-Controlled Sinusoidal Oscillator

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Abstract

A new Single-Resistance-Controlled (SRC) sinusoidal oscillator using single Voltage Differencing-Differential Input Buffered Amplifier (VD-DIBA), only four passive components (two capacitors and two resistors), is presented. The proposed structure provides the following advantageous features: 1) independent control of oscillation frequency and condition of oscillation and 2) low active and passive sensitivities. The effects of non-idealities of the VD-DIBA on the proposed oscillator have also been investigated. The proposed SRC sinusoidal oscillator has been checked for robustness using Monte-Carlo simulation. SPICE simulation results have been included using 0.35 μm MIETEC technology to confirm the validity of the proposed SRC sinusoidal oscillator.

Keywords

Voltage Differencing-Differential Input Buffered Amplifier, Voltage-Mode Circuit, Sinusoidal Oscillator

1. Introduction

Numerous applications in control systems, signal processing, communications and instrumentation-measurement have been reported [1] [2] [3]. Recently, Biolek, Senani, Biolkova, and Kolka have introduced various modern active building blocks [4]. VD-DIBA is one of them which is emerging as a very flexible and versatile building block for analog signal processing/signal generation and has been used earlier for realizing a number of functions. Realization of oscillators, simulation of inductors and active filters has become important research areas in analog circuit design. Single Resistance

Controlled Sinusoidal Oscillators (SRCOs) employing different active building blocks have attracted considerable attention of the researchers due to their several advantages over traditional op-amp-based SRCOs, see [5]-[16] and the references cited therein.

The applications, advantages and usefulness of VD-DIBA have now been recognized in the technical literature. Biolek and Biolkova [17] have presented a first order Voltage-Mode (VM) all-pass filter using one VD-DIBA and a grounded capacitor. A high input impedance VM biquad filter employing two VD-DIBAs and two grounded capacitors has been presented by Jaikla, Biolek, Siripongdee and Bajer [18]. In [19] Pushkar, Bhaskar and Prasad proposed a new MISO-type VM universal biquad using single VD-DIBA, two capacitors and one resistor. The same authors [20] proposed another VM MISO-type universal biquad employing one VD-DIBA, two capacitors and a resistor. The uses of VD-DIBA in sinusoidal oscillator have been described in [21] [22] [23] [24]. In [21] Pushkar, Bhaskar and Prasad presented a SRCO using single VD-DIBA, two resistors and grounded capacitors offering independent control of condition of oscillation and frequency of oscillation. In [22] Bajer, Vavra and Biolek presented a VM quadrature oscillator using two VD-DIBAs and two grounded capacitors. Prasad, Bhaskar and Pushkar [23] proposed an electronically controllable oscillator employing two VD-DIBAs, two grounded capacitors and a grounded resistor, and oscillator offered independent control of condition of oscillation and frequency of oscillation. Bhaskar, Prasad and Pushkar [24] presented a fully uncoupled and electronically controllable sinusoidal oscillator using two VD-DIBAs, two grounded capacitors and two resistors, which offers totally uncoupled and independent control of condition of oscillation and frequency of oscillation. In [25] Prasad, Bhaskar and Pushkar presented new electronically controllable grounded and floating simulated inductance circuits. The grounded simulated inductance circuit uses two VD-DIBAs and a single grounded capacitor where as the floating simulated inductance circuit uses three VD-DIBAs and a grounded capacitor. Bhaskar, Prasad and Pushkar [26] proposed another electronically controllable grounded capacitor based grounded and floating simulated inductance circuit using VD-DIBAs. The grounded simulated inductance circuit employs single VD-DIBA, floating resistor and a grounded capacitor while the floating simulated inductance circuit employs two VD-DIBAs with one floating resistance and a grounded capacitor. The object of this paper is to present a new SRCO using a single VD-DIBA along with a bare minimum number of four passive components. The proposed structure offers: 1) independent control of Condition of Oscillation (CO) and Frequency of Oscillation (FO) and 2) low active and passive sensitivities. The validity of the proposed SRC sinusoidal oscillator has been confirmed by SPICE simulations using 0.35 μm MIETEC technology.

2. The Proposed New Oscillator Configuration

The circuit symbol and equivalent circuit model of the VD-DIBA are shown in **Figure 1(a)** and **Figure 1(b)** respectively. The model includes two controlled sources: the current source controlled by differential voltage $(V_+ - V_-)$ with the transconductance g_m

and the voltage source controlled by differential voltage $(V_z - V_v)$ with the unity voltage gain. The voltage-current relationship of input-output terminals of VD-DIBA can be described by the following matrix:

$$\begin{pmatrix} I_+ \\ I_- \\ I_z \\ I_v \\ V_w \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ g_m & -g_m & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 \end{pmatrix} \begin{pmatrix} V_+ \\ V_- \\ V_z \\ V_v \\ I_w \end{pmatrix} \tag{1}$$

The circuit analysis of proposed structure shown in **Figure 2** yields the following characteristic equation (CE):

CE:

$$s^2 + s \left\{ \left(\frac{1}{C_1} + \frac{1}{C_2} \right) \frac{1}{R_1} - \frac{g_m}{C_1} \right\} + \frac{1}{R_1 R_2 C_1 C_2} = 0 \tag{2}$$

From Equation (2), the CO and FO can be given by:

CO:

$$\left\{ \left(\frac{1}{C_1} + \frac{1}{C_2} \right) \frac{1}{R_1} - \frac{g_m}{C_1} \right\} \leq 0 \tag{3}$$

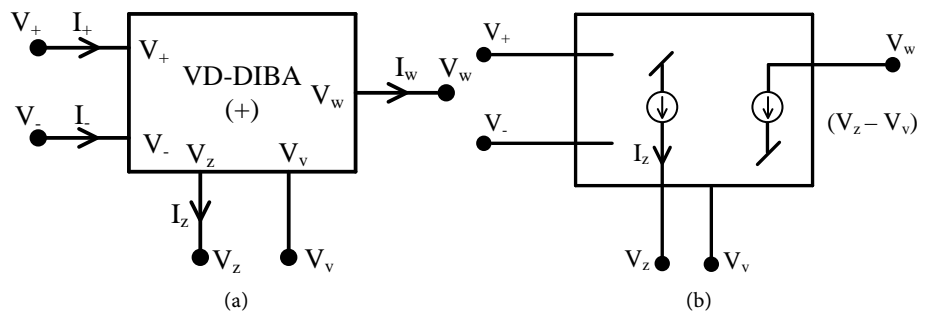


Figure 1. (a) Circuit symbol of VD-DIBA, (b) Equivalent circuit model of VD-DIBA.

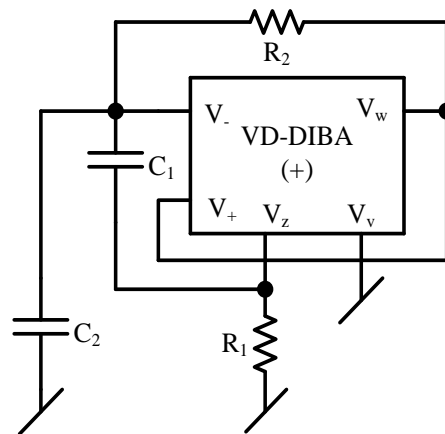


Figure 2. The proposed voltage-mode SRC sinusoidal oscillator configuration.

FO:

$$f_0 = \frac{1}{2\pi} \sqrt{\frac{1}{R_1 R_2 C_1 C_2}} \tag{4}$$

Therefore, the CO is electronically controllable independently by g_m while FO is independently controlled by resistor R_2 .

3. Non-Ideal Analysis and Sensitivity Performance

Assuming, Z-terminal of the VD-DIBA have R_z and C_z as its parasitic resistance and parasitic capacitance respectively. Taking the non-idealities into account, namely the voltage of W-terminal $V_W = (\beta^+ V_Z - \beta^- V_V)$ where $\beta^+ = 1 - \varepsilon_p$ ($\varepsilon_p \ll 1$) and $\beta^- = 1 - \varepsilon_n$ ($\varepsilon_n \ll 1$) denote the voltage tracking errors of Z-terminal and V-terminal of the VD-DIBA respectively, then the expressions for CE, CO and FO becomes:

CE:

$$s^2 (C_1 C_2 + C_1 C_z + C_2 C_z) + s \left\{ (C_1 + C_2) \left(\frac{1}{R_1} + \frac{1}{R_z} \right) + (C_1 + C_z) \frac{1}{R_2} + g_m C_1 - \beta^+ \left(g_m (C_1 + C_2) + \frac{C_1}{R_2} \right) \right\} + \left(\frac{1}{R_z R_2} + \frac{1}{R_1 R_2} \right) = 0 \tag{5}$$

CO:

$$\left\{ (C_1 + C_2) \left(\frac{1}{R_1} + \frac{1}{R_z} \right) + (C_1 + C_z) \frac{1}{R_2} + g_m C_1 - \beta^+ \left(g_m (C_1 + C_2) + \frac{C_1}{R_2} \right) \right\} \leq 0 \tag{6}$$

FO:

$$\omega_0 = \sqrt{\frac{R_1 + R_z}{R_1 R_2 R_z (C_1 C_2 + C_1 C_z + C_2 C_z)}} \tag{7}$$

The left hand side of Equation (3) with the component values shown in this section turns out to be -0.060477 which is in accordance with Equation (3) (<0). On the other hand, the left hand side of Equation (6) using the components and parasitic values turns out to be -2.2588 . It is, therefore, seen that both values are negative and satisfy the Equation (3) and Equation (6).

The active and passive sensitivities can be calculated as:

$$S_{R_z}^{\omega_0} = -\frac{1}{2} \left(\frac{R_1}{R_1 + R_z} \right), S_{R_1}^{\omega_0} = -\frac{1}{2} \left(\frac{R_z}{R_1 + R_z} \right), S_{R_2}^{\omega_0} = -\frac{1}{2}, S_{C_1}^{\omega_0} = -\frac{1}{2} \frac{1}{1 + \frac{C_2 C_z}{C_1 (C_z + C_2)}} \tag{8}$$

$$S_{C_z}^{\omega_0} = -\frac{1}{2} \frac{1}{1 + \left(\frac{C_1 C_2}{C_z (C_1 + C_2)} \right)}, S_{C_2}^{\omega_0} = -\frac{1}{2} \frac{1}{1 + \left(\frac{C_1 C_z}{C_2 (C_z + C_1)} \right)} \tag{9}$$

In the ideal case, the various sensitivities of ω_0 with respect to R_1, R_2, C_1, C_2, C_z and R_z are found to be

$$S_{R_1}^{\omega_0} = S_{R_2}^{\omega_0} = S_{C_1}^{\omega_0} = S_{C_2}^{\omega_0} = -\frac{1}{2}, S_{C_z}^{\omega_0} = S_{R_z}^{\omega_0} = 0 \tag{10}$$

Considering the typical values of various parasitic e.g. $C_z = 0.81$ pF, $R_z = 53$ k Ω , $\beta^* = \beta = 1$ along with $C_1 = C_2 = 100$ pF, $R_1 = R_2 = 8$ k Ω , the various sensitivities are found to be $S_{C_1}^{e_0} = -0.49$, $S_{C_2}^{e_0} = -0.49$, $S_{C_z}^{e_0} = -0.01$, $S_{R_1}^{e_0} = -0.43$, $S_{R_2}^{e_0} = -0.5$ and $S_{R_z}^{e_0} = -0.06$ which are all quite low.

4. Simulation Results

The proposed SRC sinusoidal oscillator is simulated using CMOS VD-DIBA (as shown in **Figure 3**) to verify its theoretical analysis. The passive elements were selected as $C_1 = C_2 = 100$ pF, $R_1 = R_2 = 8$ k Ω . The transconductance of VD-DIBA was controlled by bias voltage V_{B1} . The transient response of the proposed SRCO showing the buildup of oscillations for above component values is shown in **Figure 4(a)**. A typical steady state

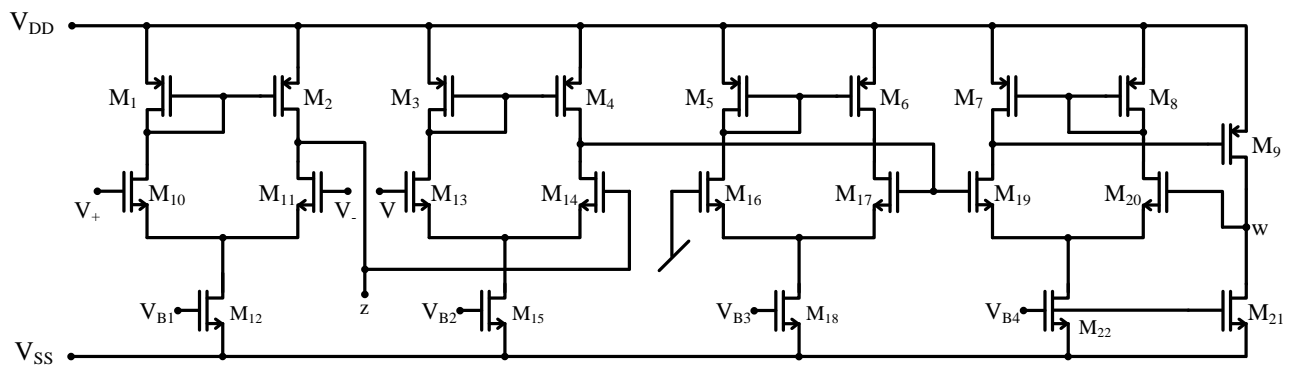
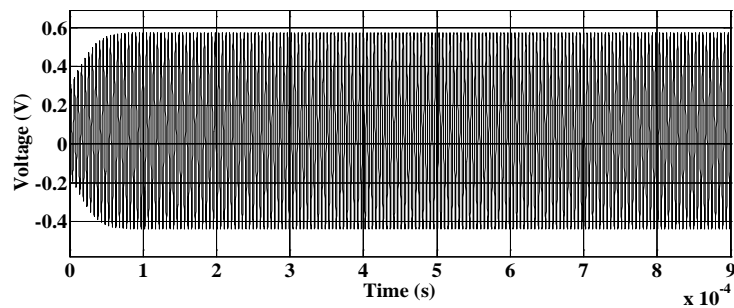
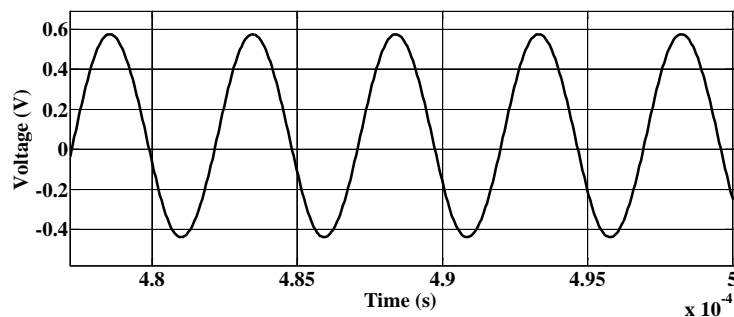


Figure 3. A CMOS Implementation of VD-DIBA, $V_{DD} = -V_{SS} = 2$ V, $V_{B1} = -0.46$ V, $V_{B2} = V_{B3} = -0.22$ V and $V_{B4} = -0.9$ V.



(a)



(b)

Figure 4. Waveforms of proposed SRCO: (a) Transient output, (b) Steady state output.

waveform generated by the oscillator for the frequency 203.01 kHz (for the same component values) is shown in **Figure 4(b)**. **Figure 5** shows the frequency response of the output, where the Total Harmonic Distortion (THD) is found to be 1.72%. The oscillator circuit of **Figure 2** has been checked for robustness using Monte-Carlo simulation, the sample results have been shown in **Figure 6** which confirm that, for $\pm 5\%$ variation in the value of R_1 , the value of oscillation frequency remains close to its normal value of 204.459 kHz and hence almost unaffected by change in R_1 . **Figure 7** shows the variability

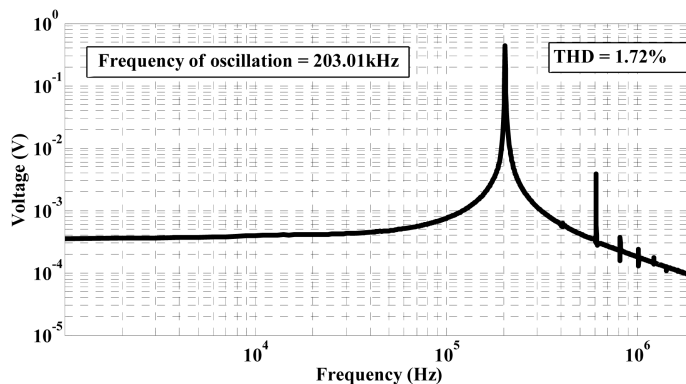


Figure 5. Frequency response of the output.

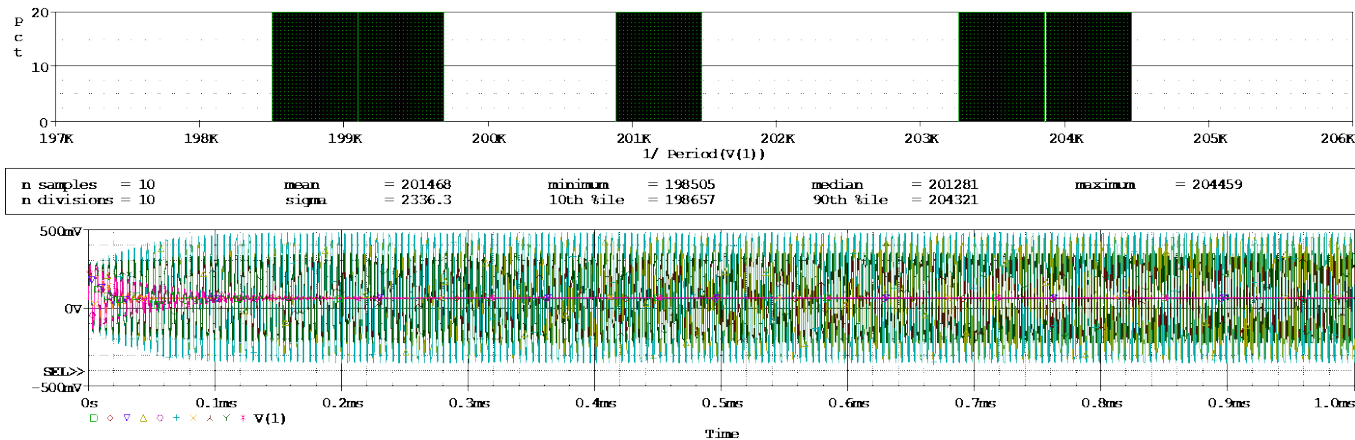


Figure 6. Monte Carlo analysis of proposed SRCO.

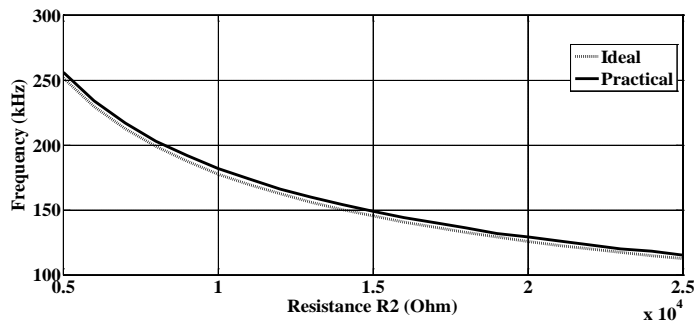


Figure 7. Variation of the oscillation frequency of the proposed SRCO with resistance R_2 .

of the frequency with resistance R_2 varied from 5 k Ω to 25 k Ω . These results, thus, confirm the validity of the proposed structure. A comparison with other previously known SRCOs using different active building blocks has been given in **Table 1**.

The CMOS VD-DIBA is implemented using 0.35 μm MIETEC technology. The various transistor model parameters used are listed in **Table 2** and W/L ratios (aspect ratios) of the MOSFETs used in **Figure 3** are given in **Table 3**.

5. Conclusions

A new application of VD-DIBA has been proposed in the realization of SRCO. The proposed structure employs a minimum possible number of passive elements (namely,

Table 1. A comparison with other previously known SRCOs using different active building blocks.

Reference	Active Component(s)	Grounded Capacitors	Floating Capacitors	Resistors	CO and FO Independently Controllable
[5]	1	1	1	3	YES
[6]	2	2	0	3	YES
[7]	1	1	1	3	YES
[8]	1	1	1	3	YES
[9]	2	2	0	3	YES
[10]	1	2	0	4	NO
[11]	1	2	0	3/2	YES
[12]	1	2	0	3	YES
[13]	1	1 (virtually grounded)	1	3	YES (only in second topology of Table 2)
[14]	1	1 (virtually grounded)	1	3	NO
[15]	1	2	0	2	YES
[16]	1	1	1	2	YES
[21]	1	2	0	2	YES
[22]	3	2	0	0	YES
[23]	2	2	0	1	YES
[24]	2	2	0	2	YES (fully uncoupled)
Proposed	1	1	1	2	YES

Table 2. The transistor model parameters.

.MODEL N NMOS (LEVEL = 3 TOX = 7.9E-9 NSUB = 1E17 GAMMA = 0.5827871 PHI = 0.7 VTO = 0.5445549 DELTA = 0 UO = 436.256147 ETA = 0 THETA = 0.1749684 KP = 2.055786E-4 VMAX = 8.309444E4 KAPPA = 0.2574081 RSH = 0.0559398 NFS = 1E12 TPG = 1 XJ = 3E-7 LD = 3.162278E-11 WD = 7.046724E-8 CGDO = 2.82E-10 CGSO = 2.82E-10 CGBO = 1E-10 CJ = 1E-3 PB = 0.9758533 MJ = 0.3448504 CJSW = 3.777852E-10 MJSW = 0.3508721)

.MODEL P PMOS (LEVEL = 3 TOX = 7.9E-9 NSUB = 1E17 GAMMA = 0.4083894 PHI = 0.7 VTO = -0.7140674 DELTA = 0 UO = 212.2319801 ETA = 9.999762E-4 THETA = 0.2020774 KP = 6.733755E-5 VMAX = 1.181551E5 KAPPA = 1.5 RSH = 30.0712458 NFS = 1E12 TPG = -1 XJ = 2E-7 LD = 5.000001E-13 WD = 1.249872E-7 CGDO = 3.09E-10 CGSO = 3.09E-10 CGBO = 1E-10 CJ = 1.419508E-3 PB = 0.8152753 MJ = 0.5 CJSW = 4.813504E-10 MJSW = 0.5)

Table 3. Aspect ratios of the MOSFETs.

Transistor	W/L (μm)
M1-M6	14/1
M7-M9	14/0.35
M10-M18	4/1
M19-M22	7/0.35

two resistors and two capacitors) and offers independent control of FO through the resistor R_2 and CO through the transconductance g_m . The proposed structure has low active and passive sensitivities. The robustness of the proposed SRCO circuit has been confirmed by the Monte-Carlo analysis. The workability of proposed structure has been confirmed by SPICE simulation with 0.35 μm MIETEC technology. However, any SRCO employing single VD-DIBA with both grounded capacitors and offering independent electronic control of FO is open to investigation.

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