

Algorithms for Computing Some Invariants for Discrete Knots

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ABSTRACT

Given a cubic knot K , there exists a projection $p: \mathbb{R}^3 \rightarrow P$ of the Euclidean space \mathbb{R}^3 onto a suitable plane $P \subset \mathbb{R}^3$ such that $p(K)$ is a knot diagram and it can be described in a discrete way as a cycle permutation. Using this fact, we develop an algorithm for computing some invariants for K : its fundamental group, the genus of its Seifert surface and its Jones polynomial.

Keywords: Cubic Knots; Discrete Knots; Algorithms

1. Introduction

Considering the set $S \subset \mathbb{R}^3$ consists of the lattice \mathbb{Z}^3 and all the straight lines parallel to the coordinate axis and passing through points in \mathbb{Z}^3 , we say that a knot $K \subset \mathbb{R}^3$ is a *cubic knot* if it is contained in S . In [1] it was shown that any classical knot is isotopic to a cubic knot and by [2] we know that there exists a generic projection p of any cubic knot into a suitable plane. If we combine these two results, we have that $p(K)$ is a diagram of K and it can be described in a discrete way as a cyclic permutation of points (w_1, w_2, \dots, w_n) (with some restrictions). This allows us to develop an algorithm for computing the fundamental group of K , the genus of its Seifert surface and its Jones polynomial.

2. Discrete Knots and Some Invariants

Consider an oriented cubic knot K . In [2] it was proved that we can associate to K a unique sequence of points (v_1, v_2, \dots, v_n) such that $v_i \in \mathbb{Z}^3$, $v_i \neq v_j$, $1 \leq i, j \leq n$, v_i is joined to v_{i+1} by a unit edge, v_n is likewise joined to v_1 by a unit edge, and the numbering of the v_i 's is compatible with the orientation of K . Henceforth, we will assume that all the coordinates of the points in K are positive.

An advantage of cubic knots is that there exists a canonical generic projection p (for details see [2]). In fact, let $N = (1, \pi, \pi^2)$, where π is the well-known transcendental number. Let P be the plane through the origin

in \mathbb{R}^3 orthogonal to N and consider the orthogonal projection $p: \mathbb{R}^3 \rightarrow P$. Then $p|_{\mathbb{Z}^3}$ is injective. Let $\hat{K} = p(K)$ be its projection into the plane P . Thus \hat{K} is a polygonal curve contained in P with some self-intersections called *inessential vertices* or *crossings*. The crossings are not contained in $p(\mathbb{Z}^3) := \Lambda_p = p(K)$ and are transverse, hence p is regular. The projections of the vertices of K are contained in Λ_p , and are called *vertices*. Hence we can write \hat{K} as a *cyclic permutation of points* (w_1, w_2, \dots, w_n) where $w_i \in \Lambda_p$, $w_i \neq w_j$, $1 \leq i, j \leq n$ and w_i is joined to w_{i+1} by a straight line segment whose preimage is a unit edge and in the same way w_n is likewise joined to w_1 (for details see [2]).

Definition 2.1. A *discrete knot* \hat{K} is the equivalence class of the n cyclic permutations of n points (w_1, w_2, \dots, w_n) in $\Lambda_p \subset P$ such that the w_i 's satisfy the above assumptions.

Next we will describe the crossings of \hat{K} . Consider an orthonormal basis β of the plane $P \subset \mathbb{R}^3$, given by

$$\beta = \left\{ \frac{1}{A}(\pi, -1, 0), \frac{1}{B}(\pi^2, \pi^3, -1 - \pi^2) \right\}$$

where $A = \sqrt{\pi^2 + 1}$ and $B = \sqrt{2\pi^2 + 2\pi^4 + \pi^6 + 1}$. Consider four points $w_{i_1}, w_{i_2}, w_{i_3}$ and $w_{i_4} \in \hat{K}$ whose coordinates with respect to the basis β are $w_{i_j} = (x_j, y_j)$. The following lemma gives us a criteria to know when the line segment $w_{i_1}w_{i_2}$ intersects the line segment $w_{i_3}w_{i_4}$. Notice that for the computing algorithm purpose, we just need to consider only the quadruples of points

where $i_2 = i_1 + 1$ and $i_4 = i_3 + 1$ (see [2]).

Lemma 2.2. Let $w_{i_1}, w_{i_2}, w_{i_3}$ and $w_{i_4} \in \hat{K}$, whose coordinates are $w_{i_j} = (x_j, y_j)$. Let $u_{r,s} = w_{i_r} - w_{i_s}$ and consider the 2×2 matrices, $A = \begin{bmatrix} u_{2,3} & u_{4,3} \end{bmatrix}$,

$B = \begin{bmatrix} u_{1,3} & u_{4,3} \end{bmatrix}$, $C = \begin{bmatrix} u_{3,1} & u_{2,1} \end{bmatrix}$ and $D = \begin{bmatrix} u_{4,1} & u_{2,1} \end{bmatrix}$.

Then the line segment $w_{i_1}w_{i_2}$ intersects the line segment $w_{i_3}w_{i_4}$ if and only if $\det(A)\det(B) < 0$ and $\det(C)\det(D) < 0$.

Algorithm 1. Projection and crossings

Require: List of points at \mathbb{R}^3 , $L[v_1, v_2, \dots, v_n]$, where $v_i = (a_i, b_i, c_i)$, list of points at P , $L_1[w_1, w_2, \dots, w_n]$, an empty set I , the constant numbers A and B given above.

for all $v_s \in L$ **do**

$$w_s \leftarrow \left(\frac{a_s \pi - b_s}{A}, \frac{a_s \pi^2 + b_s \pi^3 - c_s - c_s \pi^2}{B} \right)$$

for all $w_i, w_k \in L_1$ **do**

Create matrices

$$M = \begin{bmatrix} (w_{i+1} - w_k) & (w_{k+1} - w_k) \end{bmatrix},$$

$$N = \begin{bmatrix} (w_k - w_j) & (w_{k+1} - w_k) \end{bmatrix},$$

$$O = \begin{bmatrix} (w_k - w_i) & (w_{i+1} - w_k) \end{bmatrix},$$

$$P = \begin{bmatrix} (w_{k+1} - w_k) & (w_{i+1} - w_k) \end{bmatrix}$$

where $w_s = (x_s, y_s)$ and $w_s - w_r = (x_s - x_r, y_s - y_r)$

if $(\det(M)\det(N) < 0)$ and $(\det(O)\det(P) < 0)$

then

if $(i, j) \notin I$ and $(j, i) \notin I$ **then add** (i, j) **to** I

Suppose that the line segment $l_i = w_{i+1}w_i$ intersects the line segment $l_k = w_{k+1}w_k$. We will determine which crosses ‘‘over’’ the other. Since, the line segments l_i and l_k are the image under the projection p of two segments whose endpoints are v_{i+1}, v_i and v_{k+1}, v_k , respectively, we have that these both segments are parallel to two different canonical coordinate vectors. Let

$$u_i = v_{i+1} - v_i = (x_i, y_i, z_i) \quad y \quad u_k = v_{k+1} - v_k = (x_k, y_k, z_k).$$

If $x_i = x_k$, then we compare the first coordinate of the vectors $v_i = (a_i, b_i, c_i)$ and $v_k = (a_k, b_k, c_k)$, i.e., we compare a_i and a_k . Thus,

- If $a_i < a_k$ we say that l_k crosses over l_i (over crossing).
- If $a_k < a_i$ we say that l_k crosses under l_i (under crossing).

If $y_i = y_k$, then we compare the second coordinate of the vectors v_i y v_k , and we have the same criteria of the previous case changing a by b . The last case $z_i = z_k$ is analogous to the previous one.

Let c be a crossing point of the segment l_k over the segment l_i . Consider the vectors $u_i = w_{i+1} - w_i$, $u_k = w_{k+1} - w_k$ and construct the 2×2 -matrix $M = \begin{bmatrix} u_k & u_i \end{bmatrix}$. Thus we have two possible configurations: If $\det(M) > 0$, we say that c is a *positive crossing*; If $\det(M) < 0$, then c is a *negative crossing*.

Algorithm 2. Crossing criteria

Require: The list of indexes of intersection points $I[(i_1, k_1), (i_2, k_2), \dots, (i_r, k_r)]$ and the list of points in \mathbb{R}^3 $L[v_1, v_2, \dots, v_n]$, where $v_i = (a_i, b_i, c_i)$ and $L_1 = [w_1, w_2, \dots, w_n]$.

for all $(i, j) \in I$ **do**

where $u_s = v_{s+1} - v_s = (x_s, y_s, z_s)$

$$u_i \leftarrow v_{i+1} - v_i$$

$$u_k \leftarrow v_{k+1} - v_k$$

if $x_i = x_k$ **then**

if $a_i < a_k$ **then**

print $w_{i+1}w_i$ crosses under

else

print $w_{k+1}w_k$ crosses under

if $y_i = y_k$ **then**

if $b_i < b_k$ **then**

print $w_{i+1}w_i$ crosses under

else

print $w_{k+1}w_k$ crosses under

if $z_i = z_k$ **then**

if $c_i < c_k$ **then**

print $w_{i+1}w_i$ crosses under

else

print $w_{k+1}w_k$ crosses under

2.1. Fundamental Group

Let $\hat{K} = (w_1, w_2, \dots, w_n)$ be an oriented discrete knot and c_1, c_2, \dots, c_r be its crossings. We will compute the fundamental group K denoted by $\Pi_1(K)$, using the Wirtinger presentation (see [3,4]). We will start describing the set of generators of $\Pi_1(K)$ (see [2]).

Suppose that c_j is the crossing point of the linear segment $l_{k_j} = w_{k_j+1}w_{k_j}$ over the linear segment

$l_{i_j} = w_{i_j+1}w_{i_j}$. Now we are going to rearrange the crossings c_j in such a way that $i_1 < i_2 < \dots < i_r$. Let γ_i be the segment of \hat{K} whose endpoints are c_i and c_{i+1} (where $c_{r+1} = c_1$). Thus $\gamma_1 = (i_1 + 1, i_1 + 2, \dots, i_2)$,

$\gamma_2 = (i_2 + 1, i_2 + 2, \dots, i_3), \dots, \gamma_r = (i_r + 1, i_r + 2, \dots, i_1)$,

where each index i_j is considered mod n . We know by Wirtinger presentation that there exists a bijection between the set of segments $\gamma_i, i = 1, \dots, r$ and the set of generators of $\Pi_1(K)$, so the set of generators of $\Pi_1(K)$ is $\{\alpha_1, \dots, \alpha_r\}$.

Again, by the Wirtinger presentation we know that for each $c_j = l_{i_j} \cap l_{k_j}$ corresponds a relation among the generators $\alpha_{i_j}, \alpha_{i_j+1}$ and α_s , where the indexes s and l satisfy that $k_j \in \gamma_s$ and $i_j \in \gamma_l$. So

- If $\det \left[\begin{bmatrix} (w_{i_j+1} - w_{i_j}) & (w_{k_j+1} - w_{k_j}) \end{bmatrix} \right] > 0$, then we have the relation R_l given by $\alpha_l \alpha_s = \alpha_s \alpha_{l+1}$.
- If $\det \left[\begin{bmatrix} (w_{i_j+1} - w_{i_j}) & (w_{k_j+1} - w_{k_j}) \end{bmatrix} \right] < 0$, then we write the relation R_l given by $\alpha_s \alpha_l = \alpha_{l+1} \alpha_s$.

Therefore $\Pi_1(K) = \{\alpha_1, \dots, \alpha_r \mid R_1, \dots, R_r\}$.

Algorithm 3. Fundamental group

Require: The list of indexes of intersection points $I[(i_1, k_1), (i_2, k_2), \dots, (i_r, k_r)]$.

Create lists

$$\begin{aligned} \gamma_1 &= (i_1 + 1, i_1 + 2, \dots, i_2) \\ \gamma_2 &= (i_2 + 1, i_2 + 2, \dots, i_3) \\ &\vdots \\ \gamma_r &= (i_r + 1, i_r + 2, \dots, i_1) \end{aligned}$$

for all $i_j, k_j \in L$ **do**

Search r and l such that $k_j \in \gamma_s$ and $i_j \in \gamma_l$.

Create a matrix,

$$A = \left[\begin{pmatrix} w_{i_j+1} - w_{i_j} \\ w_{k_j+1} - w_{k_j} \end{pmatrix} \right]$$

if $\det(A) < 0$ **then**

print $\alpha_s \alpha_l = \alpha_{l+1} \alpha_s$

else

print $\alpha_l \alpha_s = \alpha_s \alpha_{l+1}$

2.2. Seifert Surface

Given a knot K there exists an algorithm to construct its Seifert surface via an oriented diagram of it (for details see [3,4]). Roughly speaking, suppose that the corresponding diagram has r crossings, then the crossings are replaced by two disjoint arcs respecting the orientation. At the end, we obtain a collection of s simple closed curves called *Seifert curves*. We construct a *Seifert surface* F for K considering each Seifert curve as the boundary of a disk. The disks are connected at each crossing by a twisted band (so we need r bands). The genus of F is $\frac{1-s+r}{2}$. The *Seifert genus* of a knot is the minimal ge-

nus possible for a Seifert surface of that knot.

Next, we apply the above algorithm to our case. As in the previous section, $\hat{K} = (w_1, w_2, \dots, w_n)$ denotes an oriented discrete knot and c_1, c_2, \dots, c_r are its crossings, where c_j is as above. Let $A = (i_1, \dots, i_r)$ and $B = (k_1, \dots, k_r)$. In [2] it was defined the bijective map $\sigma : (w_1, w_2, \dots, w_n) \rightarrow (w_1, w_2, \dots, w_n)$, given by $\sigma(w_l) = w_{l+1}$ if $l \notin A$ and $l \notin B$, $\sigma(w_l) = w_{k_s+1}$ if $l = i_s$, or $\sigma(w_l) = w_{i_s+1}$ if $l = k_s$.

This permutation can be expressed as a product of s disjoint cycles, where each cycle represents a Seifert curve. Hence we can compute the Seifert genus g .

Algorithm 4. Seifert surface

Require: The set or indexes $A = (i_1, \dots, i_r)$ and $B = (k_1, \dots, k_r)$ such that $w_{i_j+1} w_{i_j}$ crosses under $w_{k_j+1} w_{k_j}$. The empty sets L_1, L_2, \dots, L_n , and $r \leftarrow 1$ and the genus of the knot $g \leftarrow 0$.

Create a function $\sigma \in \mathbb{Z}$ where l is an index

$$\sigma(w_l) = w_{l+1} \text{ if } l \notin A \text{ and } l \notin B$$

If $l \in A \Rightarrow l = i_s$ so that $\sigma(w_l) = w_{k_s+1}$

If $l \in B \Rightarrow l = k_s$ so that $\sigma(w_l) = w_{i_s+1}$

Now we will form cycles

for $i_s \notin L_r \cup L_{r-1} \cup \dots \cup L_1$ **do**

Add i_s to L_r and $m \leftarrow i_s$

while $i_s \neq \sigma(m)$ **do**

Add $\sigma(m)$ to L_r and $m \leftarrow \sigma(m)$

$r++$

print $(L_1)(L_2) \dots (L_r)$

$$g \leftarrow \frac{1-s+r}{2}$$

print g

2.3. Jones Polynomial

The Jones polynomial is a very important invariant of an oriented knot K . We compute the Jones polynomial of a cubic knot K using the method described on ‘‘The knot atlas website’’ ([5]) applied to our case.

Let $\hat{K} = (w_1, w_2, \dots, w_n)$ be as above. Let (i_j, k_j) be pairs of indexes such that l_{k_j} crosses over l_{i_j} , $j = 1, \dots, r$. Consider the sequence

$c = (i_1, i_1 + 1, k_1, k_1 + 1, \dots, i_r, i_r + 1, k_r, k_r + 1)$ and up to re-arrangement, we can assume that

$C = (l_1, l_1 + 1, l_2, l_2 + 1, \dots, l_{2k}, l_{2k} + 1)$ is an increasing sequence. Consider the segments of curves

$C_1 = (l_1 + 1, l_1 + 2, \dots, l_2)$, $C_2 = (l_2 + 1, l_2 + 2, \dots, l_3)$, \dots , $C_{2k} = (l_{2k} + 1, l_{2k} + 2, \dots, l_1)$, where the index $n + 1$ is equal to 1.

For each pair (i_s, k_s) , consider the segments C_{as} , C_{bs} , C_{cs} and C_{ds} such that $i_s \in C_{cs}$, $i_s + 1 \in C_{as}$, $k_s \in C_{ds}$ and $k_s + 1 \in C_{bs}$. Now we take the following expressions

- If $\det \left[\begin{pmatrix} w_{i_s+1} - w_{i_s} \\ w_{k_s+1} - w_{k_s} \end{pmatrix} \right] < 0$, then we consider $A[as, ds][bs, cs] + A^{-1}[as, bs][cs, ds]$,

- if $\det \left[\begin{pmatrix} w_{i_s+1} - w_{i_s} \\ w_{k_s+1} - w_{k_s} \end{pmatrix} \right] > 0$, then we consider $A[as, ds][cs, ds] + A^{-1}[as, ds][bs, cs]$,

as formal sums, where A denotes a variable and $s = 1, \dots, r$. Notice that in the above expressions the order does not matter; for instance, the expressions $[as, ds]$ and $[ds, as]$ are equal. Now, we compute the formal product of all the above expressions to obtain a new expression Q .

We calculate the *Kauffman bracket*, denoted by $t(A)$ from Q replacing first $[as, bs][bs, cs]$ by $[as, cs]$ and afterward replace $[as, as]$ by $-A^2 - A^{-2}$. Next we compute the *writhe number* denoted by w , which is equal to the number of positive crossings minus the number of negative crossings.

Finally, the Jones polynomial $J(q)$ is equal to

$$J(q) = \frac{\left(-q^{\frac{1}{4}}\right)^{3w} t\left(q^{\frac{1}{4}}\right)}{-q^{\frac{1}{2}} - q^{-\frac{1}{2}}}$$

where q denotes a variable, $t\left(q^{\frac{1}{4}}\right)$ is the Kauffman bracket evaluated at $q^{\frac{1}{4}}$ and w is the writhe number.

Algorithm 5. Jones polynomial

Require: The list of indexes of intersection points $I[(i_1, k_1), (i_2, k_2), \dots, (i_r, k_r)]$, *bracketKauffman*, *polynomJones* and *writhe* $\leftarrow 0$.

Create array

$$c = (i_1, i_1 + 1, k_1, k_1 + 1, \dots, i_r, i_r + 1, k_r, k_r + 1)$$

Sort C and produces $C[l_1, l_2, \dots, l_n]$ where

$$l_1 \leq l_2 \leq \dots \leq l_n$$

Take curve segments

$$C_1 = [l_1 + 1, l_1 + 2, \dots, l_2]$$

$$C_2 = [l_2 + 1, l_2 + 2, \dots, l_3]$$

⋮

$$C_n = [l_n + 1, l_n + 2, \dots, l_1]$$

for all $i_s, k_s \in L$ **do**

Take $i_s \in C_l, k_s \in C_m, i_{s+1} \in C_n, k_{s+1} \in C_p$

such that l, m, n, p are the labels of the edges around that crossing, starting from the incoming lower edge l and proceeding counterclockwise direction.

Example:

$[l, m, n, p]$ such that m is next to l in counterclockwise direction, n is next to m in counterclockwise direction, etc.

Save $[l, m, n, p]$

Replace each $[l, m, n, p] \rightarrow A[l, p][m, n] + A^{-1}[l, m][n, p]$

bracketKauffman \leftarrow Multiply all replacements

bracketKauffman \leftarrow Replace $[as, bs][bs, cs] \rightarrow [as, cs]$

and $[as, bs]^2 \rightarrow [as, as]$

bracketKauffman \rightarrow Replace and simplify

$$[as, as] \rightarrow -A^2 - A^{-2}$$

print $t(A) = \textit{bracketKauffman}$

for all $i_s, k_s \in L$ **do**

Create matrix $U = \begin{bmatrix} (w_{i_s+1} - w_{i_s}) & (w_{k_s+1} - w_{k_s}) \end{bmatrix}$

if $\det(U) < 0$ **then**

writhe++

else

writhe--

$$\textit{PolynomJones} \leftarrow \frac{(-A)^{3\textit{writhe}} t(A)}{-A^2 - A^{-2}}$$

PolynomJones \leftarrow replace and simplify $A \rightarrow q^{\frac{1}{4}}$

print $J(q) = \textit{PolynomJones}$

3. Examples

3.1. Left-Handed Trefoil Knot

Considering the left-handed trefoil knot as a cubic knot, see **Figure 1**, where you can see the corresponding vectors v_i^j ; $i = 1, \dots, 24$.

Now, we apply our program to compute its fundamental group, genus Seifert and Jones polynomial. See **Figure 2**. In this case, its fundamental group has 3 generators a_1, a_2, a_3 ; and relations: $a_3a_2 = a_2a_1, a_1a_3 = a_3a_2, a_2a_1 = a_1a_3$. Its genus surface is one and its Jones polynomial is $J(q) = -q^4 + q^3 + q$.

3.2. Figure Eight Knot

Considering the figure eight knot as a cubic knot, in this case, we have 40 vertices. See **Figure 3**.

We now compute its fundamental group, its genus surface and its Jones polynomial. Thus, its fundamental group has 4 generators a_1, a_2, a_3, a_4 ; and relations: $a_2a_4 = a_1a_2, a_1a_3 = a_3a_2, a_4a_2 = a_3a_4, a_3a_1 = a_1a_4$. Its genus surface is one and its Jones polynomial is $J(q) = q^2 - q + 1 - q^{-1} + q^{-2}$. See **Figure 4**.

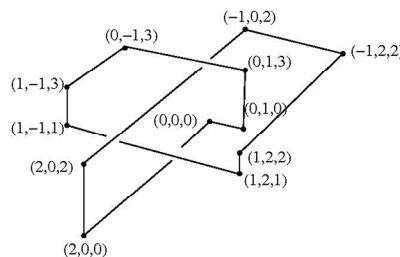


Figure 1. Cubic left-handed trefoil knot.

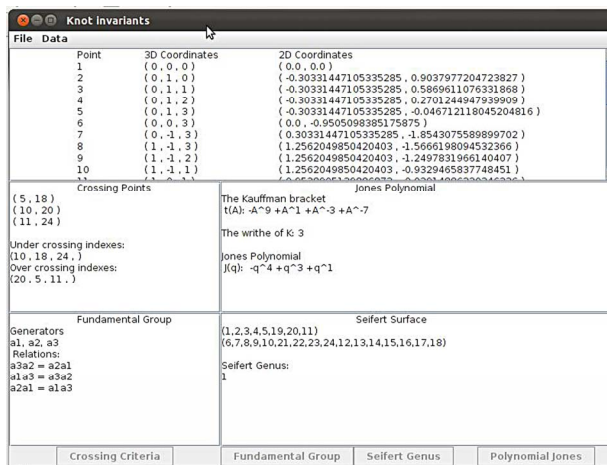


Figure 2. Left-handed trefoil knot invariants.

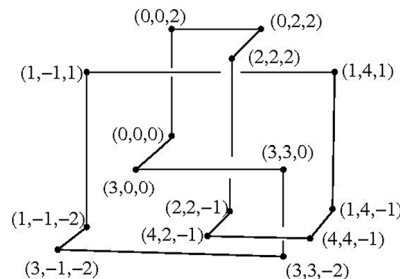


Figure 3. Cubic eight knot.

Point	3D Coordinates	2D Coordinates
1	(1, 2, 3)	(0.34622615718819816, 1.1447733519639114)
2	(2, 2, 3)	(1.2991520858706689, 1.432461101500645)
3	(3, 2, 3)	(2.2520425998593563, 1.7201488510373788)
4	(4, 2, 3)	(3.2049331138480435, 2.007839600574112)
5	(4, 3, 3)	(2.901818642794691, 2.9116343210464954)
6	(4, 4, 3)	(2.5983041717413378, 3.815432041518878)
7	(4, 5, 3)	(2.294989700687985, 4.71922976199126)
8	(4, 5, 2)	(2.294989700687985, 5.0390663748304555)
9	(4, 5, 1)	(2.294989700687985, 5.35290298766951)
10	(4, 4, 1)	(2.5983041717413378, 4.449105267197269)

Crossing Points	The Kauffman bracket	Jones Polynomial
(1, 19)	$\langle A \rangle$	
(6, 31)		
(10, 30)		
(20, 35)		

Under crossing indexes:	Jones Polynomial
(1, 10, 20, 31,)	$J(q) = +q^2 - 2q^{-1} + 1 - q^{-1} + q^{-2}$
Over crossing indexes:	
(19, 30, 35, 6,)	

Fundamental Group	Seifert Surface
Generators a1, a2, a3, a4	(1, 20, 36, 37, 38, 39, 40)
Relations:	(2, 3, 4, 5, 6, 32, 33, 34, 35, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 11, 12, 13, 14, 15, 16, 17, 18, 19, 7, 8, 9, 10, 31)
a2a4 = a1a2	Seifert Genus:
a1a3 = a3a2	1
a4a2 = a3a4	
a3a1 = a1a4	

Figure 4. Figure eight knot invariants.

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