

# Study for System of Nonlinear Differential Equations with Riemann-Liouville Fractional Derivative

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## ABSTRACT

In this work, we study existence theorem of the initial value problem for the system of fractional differential equations  $D^\alpha \bar{x}(t) = A\bar{x}(t), t^{1-\alpha} \bar{x}(t)|_{x=0} = \bar{b}$ , where  $D^\alpha$  denotes standard Riemann-Liouville fractional derivative,  $0 < \alpha < 1$ ,  $\bar{x}(t) = [x_1(t), x_2(t), \dots, x_n(t)]^T$ ,  $\bar{b} = [b_1, b_2, \dots, b_n]^T$  and  $A$  is a square matrix. At the same time, power-type estimate for them has been given.

**Keywords:** Riemann-Liouville Fractional Derivative; Weighted Cauchy-Type Problem; Fractional Differential Equations

## 1. Introduction

Let  $M_n$  denote the  $n \times n$  matrix over real fields  $R$  or complex fields  $C$ . For  $h > 0$ ,

$$C_r^0([0, h]) := \left\{ f \in C^0([0, h]) : \lim_{t \rightarrow 0^+} t^r f(t) \text{ exists and is finite} \right\},$$

here  $C^0([0, h])$  is the usual space of continuous functions on  $(0, h]$ , which is a Banach space with the norm

$$\|f\|_r := \max_{0 < t \leq h} t^r |f(t)|.$$

The space  $C_{1-\alpha}^\alpha([0, h])$  is defined by

$$C_{1-\alpha}^\alpha([0, h]) := \left\{ f \in C_{1-\alpha}([0, h]) : \text{there exists } c \in R \text{ and } f^* \in C_{1-\alpha}^0([0, h]) \text{ s.t. } f(t) = ct^{\alpha-1} + I^\alpha f^*(t) \right\}.$$

(see [1]).

The existence of solution of initial value problems for fractional order differential equations have been studied in many literatures such as [1-4]. In this paper, we present the analysis of the system of fractional differential equations

$$\begin{cases} D^\alpha \bar{x}(t) = A\bar{x}(t), \\ t^{1-\alpha} \bar{x}(t)|_{t=0} = \bar{b}, \end{cases} \quad (*)$$

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where  $D^\alpha$  denotes standard Riemann-Liouville fractional derivative, where

$$\begin{aligned} \bar{x}(t) &= [x_1(t), x_2(t), \dots, x_n(t)]^T, \\ D^\alpha \bar{x}(t) &= [D^\alpha x_1(t), D^\alpha x_2(t), \dots, D^\alpha x_n(t)]^T, \\ 1/2 < \alpha < 1, \end{aligned}$$

$\bar{b} = [b_1, b_2, \dots, b_n]^T$  and  $A$  is a square.

To prove the main result, we begin with some definitions and lemmas. For details, see [1-5].

**Definition 1.1** Let  $f$  be a continuous function defined on  $[a, b]$  and  $n-1 \leq \alpha < n, n \in N$ . Then the expression

$$D_{a+}^\alpha f(x) = \frac{1}{\Gamma(n-\alpha)} \frac{d^n}{dx^n} \int_a^x \frac{f(t)}{(x-t)^{\alpha-n+1}} dt, x > a$$

is called left-sided fractional derivatives of order  $\alpha$ .

**Definition 1.2** Let  $f$  be a continuous function defined on  $[a, b]$  and  $\alpha > 0$ . Then the expression

$$I_{a+}^\alpha f(x) = \frac{1}{\Gamma(\alpha)} \int_a^x \frac{f(t)}{(x-t)^{-\alpha+1}} dt, x > a$$

is called left-sided fractional integral of order  $\alpha$ .

**Lemma 1.3** Given  $A \in M_n$  with eigenvalues  $\lambda_1, \lambda_2, \dots, \lambda_n$  in any prescribed order, there is a unitary

matrix  $U \in M_n$  such that  $U^*AU = T = [t_{ij}]$  is upper triangular with diagonal entries  $t_{ii} = \lambda_i, i = 1, \dots, n$ . That is, every square matrix  $A$  is unitarily equivalent to triangular matrix whose entries are the eigenvalues of  $A$  in a prescribed order. Further more, if  $A \in M_n(R)$  and if all the eigenvalues of  $A$  are real, then  $U$  may be chosen to be real and orthogonal.

**Lemma 1.4** Assume that  $f \in C^0(R_0^+) \cap \text{Loc}^1(R_0^+)$  with fractional derivative of order  $0 < \alpha < 1$  that belongs to  $C^0(R_0^+) \cap \text{Loc}^1(R_0^+)$ . Then

$$I^\alpha D^\alpha f(x) = f(x) + Cx^{\alpha-1}$$

for some  $c \in R$ . When the function  $f \in C^0(R^+)$ , then  $c = 0$ , where

$$R_0^+ = \{x \in R, x > 0\} \text{ and } R^+ = \{x \in R, x \geq 0\}.$$

**Lemma 1.5** (Schauder's fixed theorem) Assume  $\Omega$  is a relative subset of a convex set  $K$  in a normed space  $X$ . Let  $A: \bar{\Omega} \rightarrow K$  be a compact map with  $0 \in \Omega$ . Then either

- (A<sub>1</sub>)  $A$  has a fixed point in  $\bar{\Omega}$ , or
- (A<sub>2</sub>) there is a  $x \in \partial\Omega$  and a  $\lambda < 1$  such that  $x = \lambda Ax$ .

Now, let's us give some hypotheses:

**H1:**  $f(t, x)$  is continuous on  $R^+ \times R$  and is such that

$$|f(t, x)| \leq t^\mu \varphi(t) e^{-\sigma t} |x|^m, \mu \geq 0, m > 1, \sigma > 0, \quad (1)$$

where  $\varphi(t)$  is a continuous function on  $R^+$ .

**H2:**  $f(t, x)$  is continuous on  $R^+ \times R$  and is such that

$$|f(t, x)| \leq t^\mu \varphi(t) |x|^m, \mu \geq 0, m > 1, \quad (2)$$

where  $\varphi(t)$  is a continuous function on  $R^+$ .

**Lemma 1.6** Let  $1/2 < \alpha < 1$ . If we assume that  $0 < q < 1/1 - \alpha$ , then the initial value problem

$$\begin{cases} D^\alpha x(t) = x^q(t) + y(t), \\ t^{1-\alpha} x(t)|_{t=0} = b, \end{cases} \quad (3)$$

where

$$y(t) \in C_{1-\alpha}^0([0, h]) \cap L^1((0, h)),$$

$$x^q(t) \in C_{1-\alpha}^0([0, h]) \cap L^1((0, h)),$$

has at least a solution  $x(t) \in C_{1-\alpha}^0([0, h]) \cap L^1((0, h))$  for  $h > 0$  sufficiently small.

**Proof.** If

$$x^q(t) \in C_{1-\alpha}^0([0, h]) \cap L^1((0, h)),$$

then  $q(\alpha - 1) > -1$ , by Lemma 1.4, We are therefore reduced the initial problem to the nonlinear integral equation

$$x(t) = bt^{\alpha-1} + \frac{1}{\Gamma(\alpha)} \left( \int_0^t (t-s)^{\alpha-1} x^q(s) ds + \int_0^t (t-s)^{\alpha-1} y(s) ds \right). \quad (4)$$

The existence of a solution to Problem (3) can be formulated as a fixed point equation  $Tx = x$ , where

$$(Tx)(t) = bt^{\alpha-1} + \frac{1}{\Gamma(\alpha)} \left( \int_0^t (t-s)^{\alpha-1} x^q(s) ds + \int_0^t (t-s)^{\alpha-1} y(s) ds \right) \quad (5)$$

in the space  $C_{1-\alpha}^0([0, h]) \cap L^1((0, h))$ .

Define

$$S = \left\{ x \in C_{1-\alpha}^0([0, h]) : \|x - bt^{\alpha-1}\|_{1-\alpha} \leq r + \frac{1}{\alpha} h^{2\alpha-1} \|y\|_{1-\alpha} \right\}.$$

Clearly, it is closed, convex and nonempty.

Step I. We shall prove that we note that  $TS \subseteq S$ .

We note that

$$\begin{aligned} \|Tx - bt^{\alpha-1}\|_{1-\alpha} &= \max_{t \in [0, h]} \frac{t^{1-\alpha}}{\Gamma(\alpha)} \\ &\cdot \left\{ \int_0^t (t-s)^{\alpha-1} x^q(s) ds + \int_0^t (t-s)^{\alpha-1} y(s) ds \right\} \\ &\leq \max_{t \in [0, h]} \frac{t^{1-\alpha}}{\Gamma(\alpha)} \left\{ \int_0^t (t-s)^{\alpha-1} s^{q(\alpha-1)} s^{q(1-\alpha)} x^q(s) ds \right. \\ &\quad \left. + \int_0^t (t-s)^{\alpha-1} s^{\alpha-1} s^{1-\alpha} y(s) ds \right\} \\ &= \max_{t \in [0, h]} \frac{t^{1-\alpha}}{\Gamma(\alpha)} \left\{ \int_0^t (t-s)^{\alpha-1} s^{q(\alpha-1)} s^{q(1-\alpha)} x^q(s) ds \right\} \\ &\quad + \max_{t \in [0, h]} \frac{t^{1-\alpha}}{\Gamma(\alpha)} \left\{ \int_0^t (t-s)^{\alpha-1} s^{\alpha-1} s^{1-\alpha} y(s) ds \right\} \\ &\leq \frac{\Gamma(q(\alpha-1)+1)}{\Gamma(q(\alpha-1)+1+\alpha)\Gamma(\alpha)} h^{q(\alpha-1)+1} \|x\|_{1-\alpha}^q + \frac{1}{\alpha} h^{2\alpha-1} \|y\|_{1-\alpha}. \end{aligned}$$

Since  $\|x\|_{1-\alpha} \leq r + |b| + \frac{1}{\alpha} h^{2\alpha-1} \|y\|_{1-\alpha}$ , it will be sufficient to impose

$$\begin{aligned} &\|x - bt^{\alpha-1}\|_{1-\alpha} \\ &\leq \text{const} \cdot h^{q(\alpha-1)+1} \left( r + |b| + \frac{1}{\alpha} h^{2\alpha-1} \|y\|_{1-\alpha} \right)^q \leq r. \end{aligned}$$

In view of the assumption  $q(\alpha - 1) + 1 > 0$ , the second estimate is satisfied if say  $r = |b|$  and  $h$  is chosen sufficiently small.

Step II. We shall prove that the operator  $T$  is compact. To prove the compactness of

$$T : C_{1-\alpha}^0([0, h]) \rightarrow C_{1-\alpha}^0([0, h])$$

defined by (5), it will be sufficient to argue on the operator

$$T_* : C^0([0, h]) \rightarrow C^0([0, h])$$

defined in this way:

$$(T_*x)(t) = t^{1-\alpha}T(t^{\alpha-1}x(t)).$$

We have  $T_*x = b + T^*x$  where the operator

$$(T^*x)(t) = \frac{t^{1-\alpha}}{\Gamma(\alpha)} \left( \int_0^t (t-s)^{\alpha-1} s^{q(\alpha-1)} x^q(s) ds + \int_0^t (t-s)^{\alpha-1} s^{\alpha-1} y(s) ds \right).$$

Turn out to be compact from classical sufficient conditions, since  $q(\alpha-1) > -1, \alpha-1 > -1$ . By Lemma 1.5, we have that Problem (3) has least a solution.

The proof is complete.

**Lemma 1.7** Suppose that  $f(t, x)$  satisfies H1,  $\mu - (m-1)(1-\alpha) > 0$  and  $\alpha > 1/2$ . If  $\|\varphi\|_q < L$  for some  $q > 1/\alpha$ , then the problem

$$\begin{cases} D^\alpha x(t) = f(t, x), \\ t^{1-\alpha} x(t)|_{t=0} = b, \end{cases} \quad (6)$$

exists a positive constant  $C$  such that  $|x(t)| \leq Ct^{\alpha-1}, t > 0$ .

**Lemma 1.8** Let  $x \in C_{1-\alpha}^0([0, h])$  with  $\alpha > 1/2$ . Suppose further that  $\mu - (m-1)(1-\alpha) > 0$ . Then Problem (6) and its associated integral equation

$$x(t) = bt^{\alpha-1} + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} f(s, x(s)) ds \quad (7)$$

are equivalent.

**Lemma 1.9** Assume that  $\alpha > 1/2$ .  $f(t, x)$  satisfies H2, and  $\|\varphi\|_q < K$  for some  $q > 1/2$ . Suppose further that  $\mu + 1/p < m(1-\alpha)$ , then there exists  $C > 0$  and  $0 < \delta < 1-\alpha$  such that any solution of (6) exists globally and satisfies

$$|x(t)| \leq Ct^{-\delta}, t \geq a > 0. \quad (8)$$

## 2. Main Results

**Theorem 2.1** Let  $A \in M_n$  then initial problem (\*) has a solution  $\bar{x}(t) \in R^n$ , where

$$\bar{x}(t) = [x_1(t), x_2(t), \dots, x_n(t)]^T,$$

$$x_i(t) \in C_{1-\alpha}^0([0, h]) \cap L^1((0, h))$$

for all  $i = 1, 2, \dots, n$  and sufficiently small  $h > 0$ .

**Proof.** Given  $A \in M_n$  with eigenvalues  $\lambda_1, \lambda_2, \dots, \lambda_n$

by Lemma 1.3, there is a unitary matrix  $U \in M_n$  such that

$$U^*AU = T = [t_{ij}]$$

is upper triangular with diagonal entries  $t_{ii} = \lambda_i, i = 1, \dots, n$ .

Let  $\bar{y}(t) = U^*\bar{x}(t)$ , we have

$$\begin{aligned} D^\alpha \bar{y}(t) &= U^*D^\alpha \bar{x}(t) = U^*A\bar{x}(t) \\ &= U^*AU\bar{y}(t) = T\bar{y}(t). \end{aligned}$$

At the same time, the initial problem (\*) changed into

$$\begin{cases} D^\alpha \bar{y}(t) = T\bar{y}(t), \\ t^{1-\alpha} \bar{y}(t)|_{t=0} = U^*\bar{b}. \end{cases} \quad (**)$$

Now, let's consider the problem (\*\*).

Clearly, the problem (\*\*) is equivalent to the following  $n$  problems

$$\begin{cases} D^\alpha y_i(t) = \sum_{j=i}^n t_{ij} y_j(t), \\ t^{1-\alpha} y_i(t)|_{t=0} = b_i, \end{cases}$$

for  $i, j = 1, 2, \dots, n$ . where  $b_i$  is the  $i$ th entries of the vector  $U^*\bar{b}$ .

Consider the weighed Cauchy-type problem

$$\begin{cases} D^\alpha y_n(t) = t_{nn} y_n(t), \\ t^{1-\alpha} y_n(t)|_{t=0} = b_n. \end{cases}$$

In Lemma 1.6, take  $q = 1, y(t) = 0$ . Then by lemma 1.6,  $\exists h > 0$ , s.t. the above problem has at least a solution

$$y_n(t) \in C_{1-\alpha}^0([0, h]) \cap L^1((0, h)).$$

Consider the following weighed Cauchy-type problem

$$\begin{cases} D^\alpha y_{n-1}(t) = t_{n-1, n-1} y_{n-1}(t) + t_{n-1, n} y_n(t), \\ t^{1-\alpha} y_{n-1}(t)|_{t=0} = b_{n-1}. \end{cases}$$

In Lemma 1.6, take  $q = 1, y(t) = t_{n-1, n} y_n(t)$ . Then by Lemma 1.6,  $\exists h > 0$ , s.t. the above problem has at least a solution  $y_{n-1}(t) \in C_{1-\alpha}^0([0, h]) \cap L^1((0, h))$ .

Similarly, there has at least a solution in

$$C_{1-\alpha}^0([0, h]) \cap L^1((0, h))$$

for the rest  $n-2$  initial problem in (\*\*), denote by  $y_{n-2}(t), y_{n-3}(t), \dots, y_1(t)$  respectively. And therefore, there has at least a solution

$$\bar{y}(t) = [y_1(t), y_2(t), \dots, y_n(t)]^T$$

of the problem (\*\*). Let  $\bar{x}(t) = U\bar{y}(t)$ , it is required for us.

The proof is completed.

Since the problem (\*\*\*) is equivalent to the following  $n$  problems

$$\begin{cases} D^\alpha y_i(t) = \sum_{j=i}^n t_{ij} y_j(t), \\ t^{1-\alpha} y_i(t)|_{t=0} = b_i, \end{cases} \quad (9)$$

for  $i, j = 1, 2, \dots, n$ . where  $b_i$  is the  $i$ th entries of the vector  $U^* \bar{b}$ . Next, we shall discuss these equations in (9).

**Theorem 2.2** Assume that the right hand of these equations in (9) satisfied H1,  $\mu - (m-1)(1-\alpha) > 0$ ,  $\alpha > 1/2$  and  $\|\varphi\|_q < L$  for some  $q > 1/\alpha$ , If the solution of the problems (\*\*\*) denoted by

$$\bar{x}(t) = [x_1(t), x_2(t), \dots, x_n(t)]^T,$$

then there exists some constant  $C > 0$  such that

$$|x_i(t)| \leq \|U\|_\infty C t^{\alpha-1}, t > 0 \text{ for all } i = 1, 2, \dots, n.$$

**Proof.** Similar to the proof of Theorem 2.1, now consider the following weighted Cauchy-type problem

$$\begin{cases} D^\alpha y_n(t) = t_m y_n(t), \\ t^{1-\alpha} y_n(t)|_{t=0} = b_n. \end{cases}$$

Then by Lemma 1.7, there exists some constant  $C_n > 0$  such that  $|y_n(t)| \leq C_n t^{\alpha-1}, t > 0$ .

Consider the following problem

$$\begin{cases} D^\alpha y_{n-1}(t) = t_{n-1,n-1} y_{n-1}(t) + t_{n-1,n} y_n(t), \\ t^{1-\alpha} y_{n-1}(t)|_{t=0} = b_{n-1}. \end{cases}$$

Then by Lemma 1.7, there exists some constant  $C_{n-1} > 0$  such that  $|y_{n-1}(t)| \leq C_{n-1} t^{\alpha-1}, t > 0$ .

Similarly, there exist some positive constants  $C_{n-2}, C_{n-3}, \dots, C_1$  such that

$$|y_i(t)| \leq C_i t^{\alpha-1}, t > 0.$$

for all  $i = n-2, n-3, \dots, 1$ .

Let  $\bar{x}(t) = U \bar{y}(t), C = \max_{1 \leq i \leq n} \{C_i\}$ . Then we have

$$|x_i(t)| \leq \|U\|_\infty C t^{\alpha-1}, t > 0,$$

for all  $i = 1, 2, \dots, n$ .

The proof is completed.

**Theorem 2.3** Assume that  $\alpha > 1/2$ , the right-hand of these equations in (9) satisfied H2, and  $\|\varphi\|_q < K$  For some  $q > 1/2$ . Suppose further that

$$\mu + 1/p < m(1-\alpha).$$

If denote solution of the problems (\*\*\*)  $\bar{x}(t)$  by

$$\bar{x}(t) = [x_1(t), x_2(t), \dots, x_n(t)]^T.$$

Then there exists some constant  $C > 0$  and  $0 < \delta < 1-\alpha$ , such that

$$|x_i(t)| \leq \|U\|_\infty C t^{-\delta}, t \geq a > 0,$$

for all  $i = 1, 2, \dots, n$ .

Using Lemmas 1.3 and 1.9, the proof is similar to Theorem 2.2. Therefore, it is omitted.

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