

The Discriminance for $FLDcirc_r$ Matrices and the Fast Algorithm of Their Inverse and Generalized Inverse

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Abstract

This paper presents a new type of circulant matrices. We call it the first and the last difference r -circulant matrix ($FLDcirc_r$ matrix). We can verify that the linear operation, the matrix product and the inverse matrix of this type of matrices are still $FLDcirc_r$ matrices. By constructing the basic $FLDcirc_r$ matrix, we give the discriminance for $FLDcirc_r$ matrices and the fast algorithm of the inverse and generalized inverse of the $FLDcirc_r$ matrices.

Keywords

$FLDcirc_r$ Matrix, Discriminance, Diagonalization, Inverse, Generalized Inverse

1. Introduction

Circulant matrix plays an important role in the matrix theory, its special structure and properties have been widely used in applied mathematics, physics, modern engineering, and so on [1]-[6]. There have been many new circulant matrices come forward [7]-[12]. In this paper we will firstly put forward the concept of the $FLDcirc_r$ matrix and the basic $FLDcirc_r$ matrix. The sum, the difference, the product, the inverse and the adjoint matrix of this type of matrices are still $FLDcirc_r$ matrices. Then, we will give five discriminance for $FLDcirc_r$ matrix by constructing the basic $FLDcirc_r$ matrix. At last, we will discuss the fast algorithm of the inverse and generalized inverse of the $FLDcirc_r$ matrix and give the numerical example. In this paper, we just study the square matrices in complex field.

2. Definition of the $FLDcirc_r$ Matrix

Definition 2.1 For a square matrix A of order n , if its form is

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$$A = \begin{pmatrix} a_0 & a_1 & a_2 & \cdots & a_{n-2} & a_{n-1} \\ ra_{n-1} & a_0 - ra_{n-1} & a_1 & \cdots & a_{n-3} & a_{n-2} \\ ra_{n-2} & ra_{n-1} - ra_{n-2} & a_0 - ra_{n-1} & \cdots & a_{n-4} & a_{n-3} \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ ra_2 & ra_3 - ra_2 & ra_4 - ra_3 & \cdots & a_0 - ra_{n-1} & a_1 \\ ra_1 & ra_2 - ra_1 & ra_3 - ra_2 & \cdots & ra_{n-1} - ra_{n-2} & a_0 - ra_{n-1} \end{pmatrix},$$

We call it the $FLDcirc_r$ matrix, and denote shortly $A = FLDcirc_r(a_0, a_1, \dots, a_{n-1})$.

Definition 2.2 Let D is the basic $FLDcirc_r$ matrix of order n , that is

$$D = \begin{pmatrix} 0 & 1 & 0 & \cdots & 0 & 0 \\ 0 & 0 & 1 & \cdots & 0 & 0 \\ 0 & 0 & 0 & \cdots & 0 & 0 \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ 0 & 0 & 0 & \cdots & 0 & 1 \\ r & -r & 0 & \cdots & 0 & 0 \end{pmatrix}.$$

We obtain $g(x) = x^n + rx - r$ is the characteristic polynomial of D , $D^n = r(I_n - D)$, we specify $D^0 = I_n$.

From the definition of $FLDcirc_r$ matrix, we can prove the following proposition.

Proposition 2.3 If A and B are $FLDcirc_r$ matrices, then $A + B$, $A - B$ and kA are both $FLDcirc_r$ matrices, for any k belongs to the complex field.

Definition 2.4 Let $A \in C^{n \times n}$, the index of A is the least nonnegative integer k such that $rankA^{k+1} = rankA^k$, we note it as $Ind(A) = k$. If A is nonsingular, then $Ind(A) = 0$; if A is singular, then $Ind(A) \geq 1$.

Definition 2.5 Let $A \in C^{n \times n}$, if there is $X \in C^{n \times n}$ which satisfies $AXA = A$, $XAX = X$ at the same time, we named X as the reflexive generalize inverse of A , we note it as $A^{\{1,2\}}$.

Definition 2.6 Let $A \in C^{n \times n}$, $Ind(A) = k$, if $X \in C^{n \times n}$ satisfies

$$\begin{aligned} A^k X A &= A^k, \\ X A X &= X, \\ A X &= X A, \end{aligned}$$

Then we denote X as the Drazin inverse of A , note it as $A^{\{d\}}$.

Lemma 2.7 If polynomial matrix $\begin{pmatrix} f(x) & 1 & 0 \\ g(x) & 0 & 1 \end{pmatrix}$ can transformed into $\begin{pmatrix} d(x) & u(x) & v(x) \\ 0 & s(x) & t(x) \end{pmatrix}$ after elementary row transformation, then we have $(f(x), g(x)) = d(x)$, and $u(x)f(x) + v(x)g(x) = d(x)$.

3. The Discriminance of the $FLDcirc_r$ Matrix

Theorem 3.1 A is an $FLDcirc_r$ matrix if and only if A is of the following form

$$A = f(D) = \sum_{i=0}^{n-1} a_i D^i \quad (1)$$

For some polynomial $f(x) = \sum_{i=0}^{n-1} a_i x^i$.

Proof. By the **Definition 2.1** and **Definition 2.2**, we get this result.

Theorem 3.2 A is an $FLDcirc_r$ matrix if and only if $AD = DA$, D is the basic $FLDcirc_r$ matrix.

Proof. (\Rightarrow) For A is an $FLDcirc_r$ matrix, from the definition of A and D , we obtain $AD = DA$.

(\Leftarrow) By the method of undetermined coefficients, let

$$A = \begin{pmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1,n-1} & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2,n-1} & a_{2n} \\ a_{31} & a_{32} & a_{33} & \cdots & a_{3,n-1} & a_{3n} \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ a_{n-1,1} & a_{n-1,2} & a_{n-1,3} & \cdots & a_{n-1,n-1} & a_{n-1,n} \\ a_{n1} & a_{n2} & a_{n3} & \cdots & a_{n,n-1} & a_{nn} \end{pmatrix}.$$

Due to

$$AD = DA,$$

It follows that

$$\begin{aligned} a_{21} &= ra_{1n}, a_{22} = a_{11} - ra_{1n}, a_{23} = a_{12}, \cdots, a_{2,n-1} = a_{1,n-2}, a_{2n} = a_{1,n-1}; \\ a_{31} &= ra_{2n}, a_{32} = a_{21} - ra_{2n}, a_{33} = a_{22}, \cdots, a_{3,n-1} = a_{2,n-2}, a_{3n} = a_{2,n-1}; \\ &\cdots. \end{aligned}$$

We obtain

$$A = \begin{pmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1,n-1} & a_{1n} \\ ra_{1n} & a_{11} - ra_{1n} & a_{12} & \cdots & a_{1,n-2} & a_{1,n-1} \\ ra_{1,n-1} & ra_{1n} - ra_{1,n-1} & a_{11} - ra_{1n} & \cdots & a_{1,n-3} & a_{1,n-2} \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ ra_{13} & ra_{14} - ra_{13} & ra_{15} - ra_{14} & \cdots & a_{11} - ra_{1n} & a_{12} \\ ra_{12} & ra_{13} - ra_{12} & ra_{14} - ra_{13} & \cdots & ra_{1n} - ra_{1,n-1} & a_{11} - ra_{1n} \end{pmatrix},$$

So A is an $FLDcirc_r$ matrix.

Corollary 3.3 If A and B are both $FLDcirc_r$ matrices, then AB and BA are $FLDcirc_r$ matrices. Furthermore, we get $AB = BA$.

Proof. Since A and B are $FLDcirc_r$ matrices, by the **Theorem 3.2**, we get

$$AD = DA, \quad BD = DB,$$

Hence

$$ABD = ADB = DAB, \quad BAD = BDA = DBA,$$

Then, AB and BA are both $FLDcirc_r$ matrices.

From **Theorem 3.1**, we have

$$AB = BA.$$

4. The Diagonalization of the $FLDcirc_r$ Matrix

First, we consider the diagonalization of the basic $FLDcirc_r$ matrix D .

For the characteristic polynomial $g(x) = x^n + rx - r$ of D has n different roots. So, D has n different eigenvalues:

$$\lambda_0 = \omega_0, \lambda_1 = \omega_1, \cdots, \lambda_{n-1} = \omega_{n-1}.$$

Let

$$V = \begin{pmatrix} 1 & 1 & 1 & \cdots & 1 & 1 \\ \omega_0 & \omega_1 & \omega_2 & \cdots & \omega_{n-2} & \omega_{n-1} \\ \omega_0^2 & \omega_1^2 & \omega_2^2 & \cdots & \omega_{n-2}^2 & \omega_{n-1}^2 \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ \omega_0^{n-2} & \omega_1^{n-2} & \omega_2^{n-2} & \cdots & \omega_{n-2}^{n-2} & \omega_{n-1}^{n-2} \\ \omega_0^{n-1} & \omega_1^{n-1} & \omega_2^{n-1} & \cdots & \omega_{n-2}^{n-1} & \omega_{n-1}^{n-1} \end{pmatrix},$$

Obviously, $V = V(\omega_0, \omega_1, \dots, \omega_{n-1})$ is a nonsingular *Vandermonde* matrix about $\omega_0, \omega_1, \dots, \omega_{n-1}$, and

$$D = V \text{diag}(\omega_0, \omega_1, \dots, \omega_{n-1}) V^{-1}. \quad (2)$$

Next, we study the diagonalization of general *FLDcirc_r* matrix A .
From **Theorem 3.1** and Equation (2), we obtain

$$\begin{aligned} A &= \sum_{i=0}^{n-1} a_i D^i = \sum_{i=0}^{n-1} a_i \left(V \text{diag}(\omega_0, \omega_1, \dots, \omega_{n-1}) V^{-1} \right)^i \\ &= \sum_{i=0}^{n-1} V \text{diag}(a_i \omega_0^i, a_i \omega_1^i, \dots, a_i \omega_{n-1}^i) V^{-1} \\ &= V \text{diag}(f(\omega_0), f(\omega_1), \dots, f(\omega_{n-1})) V^{-1}, \end{aligned}$$

The eigenvalues of A are

$$f(\omega_j) = \sum_{i=0}^{n-1} a_i \omega_j^i.$$

Theorem 4.1 A is an *FLDcirc_r* matrix if and only if $V^{-1}AV$ is a diagonal matrix.

Proof. (\Rightarrow) If A is an *FLDcirc_r* matrix, from the above discussion, we have

$$V^{-1}AV = \text{diag}(f(\omega_0), f(\omega_1), \dots, f(\omega_{n-1})).$$

(\Leftarrow) Let $V^{-1}AV = P_1$, P_1 is a diagonal matrix, then

$$A = VP_1V^{-1}.$$

Let $P_2 = \text{diag}(\omega_0, \omega_1, \dots, \omega_{n-1})$, from Equation (2) we have

$$D = VP_2V^{-1},$$

Thus

$$\begin{aligned} AD &= VP_1V^{-1}VP_2V^{-1} = VP_1P_2V^{-1}, \\ DA &= VP_2V^{-1}VP_1V^{-1} = VP_2P_1V^{-1}. \end{aligned}$$

For P_1 and P_2 are both diagonal matrix, so

$$AD = DA,$$

hence, A is an *FLDcirc_r* matrix.

Theorem 4.2 A is a nonsingular *FLDcirc_r* matrix if and only if the eigenvalues $f(\omega_i) \neq 0 (i = 0, 1, \dots, n-1)$, where $\omega_i (i = 0, 1, \dots, n-1)$ are eigenvalues of the basic *FLDcirc_r* matrix.

Proof. (\Rightarrow) For A is a nonsingular *FLDcirc_r* matrix, from the above discussion, we have

$$A = V \text{diag}(f(\omega_0), f(\omega_1), \dots, f(\omega_{n-1})) V^{-1},$$

where $f(\omega_i) \neq 0 (i = 0, 1, \dots, n-1)$ are eigenvalues of A .

So

$$|A| = |V| \prod_{i=0}^{n-1} f(\omega_i) \frac{1}{|V|} = \prod_{i=0}^{n-1} f(\omega_i).$$

Hence, if A is a nonsingular *FLDcirc_r* matrix, we have $f(\omega_i) \neq 0 (i = 0, 1, \dots, n-1)$.

(\Leftarrow) Due to $f(\omega_i) \neq 0 (i = 0, 1, \dots, n-1)$,

Then

$$|A| = |V| \prod_{i=0}^{n-1} f(\omega_i) \frac{1}{|V|} = \prod_{i=0}^{n-1} f(\omega_i) \neq 0,$$

So A is nonsingular.

5. The Fast Algorithm of the Inverse and Generalized Inverse of the *FLDcirc_r* Matrix

Theorem 5.1 If A is a nonsingular matrix, then A is an *FLDcirc_r* matrix if and only if A^{-1} is an *FLDcirc_r* matrix.

Proof. (\Rightarrow) From A is nonsingular and **Theorem 3.2**, we obtain

$$AD = DA,$$

Hence

$$DA^{-1} = A^{-1}D,$$

That is to say A^{-1} is an *FLDcirc_r* matrix.

(\Leftarrow) Clearly, the nonsingular matrix A is an *FLDcirc_r* matrix.

Corollary 5.2 If A is a nonsingular *FLDcirc_r* matrix, then A^* is a nonsingular *FLDcirc_r* matrix.

Proof. For A is an *FLDcirc_r* matrix, we have $AD = DA$, so

$$D^*A^* = A^*D^*.$$

Due to

$$DD^* = |D|I, D^* = |D|D^{-1},$$

Thus

$$|D|D^{-1}A^* = |D|A^*D^{-1},$$

Hence

$$A^*D = DA^*.$$

Then A^* is an *FLDcirc_r* matrix.

Theorem 5.3 If A is an *FLDcirc_r* matrix, then A is nonsingular if and only if $(f(x), g(x)) = 1$.

Proof. If A is a nonsingular *FLDcirc_r* matrix, from **Theorem 4.2**, we have $f(\omega_i) \neq 0 (i = 0, 1, \dots, n-1)$, so $f(x)$ and $g(x)$ don't have the same solutions, thus $(f(x), g(x)) = 1$.

Otherwise, if $(f(x), g(x)) = 1$, there exist $u(x), v(x)$ such that $u(x)f(x) + v(x)g(x) = 1$, $u(D)f(D) + v(D)g(D) = E$. For $g(D) = 0$, $f(D) = A$, we have $u(D)A = E$. So, A is nonsingular and $A^{-1} = u(D)$. From **Theorem 3.1**, we have A^{-1} is an *FLDcirc_r* matrix.

Corollary 5.4 If A is a nonsingular *FLDcirc_r* matrix, there exists $A^{-1} = u(D)$.

Corollary 5.5 A is a singular *FLDcirc_r* matrix, there exists an *FLDcirc_r* matrix H that satisfies $A^{\{1,2\}} = A^{\{d\}} = H$.

Proof. For A is singular, we get $(f(x), g(x)) \neq 1$. Suppose $(f(x), g(x)) = d(x)$, $g(x) = d(x)g_1(x)$, $f(x) = d(x)f_1(x)$, then $(f_1(x), g_1(x)) = 1$. Furthermore, $g(x)$ doesn't have repeated root, thus,

$(d(x), g_1(x)) = 1$, $(d(x)f_1(x), g_1(x)) = 1$, $(d(x)d(x)f_1(x), g_1(x)) = 1$. So, $(d(x)f(x), g_1(x)) = 1$.

Hence, there exist $u(x), v(x)$ such that

$$u(x)d(x)f(x) + v(x)g_1(x) = 1. \quad (3)$$

Equation (3) both sides multiplied by $f(x)$, then

$$f(x)u(x)d(x)f(x) + f_1(x)v(x)g(x) = f(x).$$

For $g(D) = 0$, $f(D) = A$, we have

$$Au(D)d(D)A = A. \quad (4)$$

Equation (3) both sides multiplied by $u(x)d(x)$. Similarly, we get

$$u(D)d(D)Au(D)d(D) = u(D)d(D). \quad (5)$$

If $H = u(D)d(D)$, then H is the polynomial of D , from **Theorem 3.1**, we get H is an *FLDcirc_r* matrix, and from Equation (4), Equation (5) we have $H = A^{\{1,2\}}$.

Due to

$$A^k HA = A^{k-1} (AHA) = A^{k-1} A = A^k,$$

$$AH = Au(D)d(D) = f(D)u(D)d(D) = u(D)d(D)f(D) = HA,$$

Hence $H = A^{\{d\}}$.

From **Lemma 2.7** and the proof of **Theorem 5.3, Corollary 5.5**, we can get the fast algorithm of the inverse and generalized inverse of the *FLDcirc* matrix. The general steps are as follows:

Step 1 get the greatest common factor $d(x)$ of $f(x)$, $g(x)$;

Step 2 If $d(x) = 1$, the polynomial matrix $\begin{pmatrix} f(x) & 1 \\ g(x) & 0 \end{pmatrix}$ can transformed into $\begin{pmatrix} 1 & u(x) \\ 0 & s(x) \end{pmatrix}$ after elementary row transformation, then $A^{-1} = u(D)$;

Step 3 If $d(x) \neq 1$, divide $g(x)$ by $d(x)$, get $g_1(x)$, then the polynomial matrix $\begin{pmatrix} f(x)d(x) & 1 \\ g_1(x) & 0 \end{pmatrix}$ can transformed into $\begin{pmatrix} 1 & u(x) \\ 0 & s(x) \end{pmatrix}$ after elementary row transformation, hence $A^{\{1,2\}} = A^{\{d\}} = u(D)d(D)$.

Example 5.1 If the 3 order matrix $A = \begin{pmatrix} 1 & -1 & 1 \\ 2 & -1 & -1 \\ -2 & 4 & -1 \end{pmatrix}$, then whether A is a nonsingular matrix? If A is non-singular, solving A^{-1} .

From **Definition 2.1** we get $A = \text{FLDcirc}_2(1, -1, 1)$, $f(x) = 1 - x + x^2$, $g(x) = x^3 + 2x - 2$, $D = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 2 & -2 & 0 \end{pmatrix}$. Because of $(f(x), g(x)) = 1$, so A is nonsingular.

After a series of elementary row transformation of the following polynomial matrix, we obtain

$$\begin{pmatrix} x^2 - x + 1 & 1 \\ x^3 + 2x - 2 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} x^2 - x + 1 & 1 \\ x^2 + x - 2 & -x \end{pmatrix} \rightarrow \begin{pmatrix} -2x + 3 & x + 1 \\ x^2 + x - 2 & -x \end{pmatrix} \\ \rightarrow \begin{pmatrix} -2x + 3 & x + 1 \\ 7 & 2x^2 + 3x + 5 \end{pmatrix} \rightarrow \begin{pmatrix} 0 & x^3 + 2x - 2 \\ 1 & \frac{2}{7}x^2 + \frac{3}{7}x + \frac{5}{7} \end{pmatrix}.$$

So

$$u(x) = \frac{2}{7}x^2 + \frac{3}{7}x + \frac{5}{7}.$$

Therefore

$$A^{-1} = u(D) = \frac{2}{7}D^2 + \frac{3}{7}D + \frac{5}{7}E = \begin{pmatrix} \frac{5}{7} & \frac{3}{7} & \frac{2}{7} \\ \frac{4}{7} & \frac{1}{7} & \frac{3}{7} \\ \frac{6}{7} & -\frac{2}{7} & \frac{1}{7} \end{pmatrix},$$

That is

$$A^{-1} = \text{FLDcirc}_2\left(\frac{5}{7}, \frac{3}{7}, \frac{2}{7}\right).$$

Example 5.2 If the 3 order matrix $A = \begin{pmatrix} 1+\sqrt{3} & 1 \\ 2 & \sqrt{3}-1 \end{pmatrix}$, solving $A^{\{1,2\}}$.

From **Definition 2.1** we have $A = FLDCirc_2(1+\sqrt{3},1)$, $f(x) = x+1+\sqrt{3}$, $g(x) = x^2 + 2x - 2$,
 $D = \begin{pmatrix} 0 & 1 \\ 2 & -2 \end{pmatrix}$.

Then $d(x) = (f(x), g(x)) = x+1+\sqrt{3}$, so, A is singular and $g_1(x) = x+1-\sqrt{3}$.
 From Step 3, we get

$$\begin{aligned} & \begin{pmatrix} x^2 + 2(1+\sqrt{3})x + 4 + 2\sqrt{3} & 1 \\ x+1-\sqrt{3} & 0 \end{pmatrix} \rightarrow \begin{pmatrix} (1+3\sqrt{3})x + 4 + 2\sqrt{3} & 1 \\ x+1-\sqrt{3} & 0 \end{pmatrix} \\ & \rightarrow \begin{pmatrix} 1 & \frac{1}{12} \\ x+1-\sqrt{3} & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & \frac{1}{12} \\ 0 & x+1-\sqrt{3} \end{pmatrix}. \end{aligned}$$

Then

$$u(x) = \frac{1}{12},$$

So

$$A^{\{1,2\}} = A^{\{d\}} = u(D)d(D) = \frac{1}{12} [D + (1+\sqrt{3})E] = \begin{pmatrix} \frac{1+\sqrt{3}}{12} & \frac{1}{12} \\ \frac{1}{6} & \frac{\sqrt{3}-1}{12} \end{pmatrix},$$

That is

$$A^{\{1,2\}} = A^{\{d\}} = FLDCirc_2\left(\frac{1+\sqrt{3}}{12}, \frac{1}{12}\right).$$

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