

A New Expression for Rhotrix

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Received 17 March 2014; revised 17 April 2014; accepted 24 April 2014

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Abstract

This paper presents a new technique for expressing rhotrices in a generalize form. The method involves using multiple array indexes as analogous to matrix expressions, unlike the earlier method in the literature, which can only be functional in a single array computational environment. The new rhotrix look will encourage the study of rhotrix algebra and analysis from a better perspective. In addition, computing efficiency and accuracy will also be improved, particularly when the operations in rhotrix space over the new expression are algorithmatized for computing machines.

Keywords

Rhotrix, Rhotrix Space, Rhotrix Generalization, Rhotrix Operations

1. Introduction

Rhotrix theory is a relatively new area of Mathematics, whose goal is central on representing arrays of numbers in rhomboid mathematical form, unlike matrix theory dealing with representing array of numbers in rectangular form. The concept of rhotrices of size three, also well known as base rhotrices, was introduced by Ajibade [1] as an extension of ideas on matrix-tertion and matrix-noitret, suggested by Atanassov and Shannon [2].

Expressing rhotrices of size n , particularly in a generalized form, has been a difficult problem to the rhotrix theorist. This may probably be the reason, why most works in rhotrix theory are communicated using rhotrices of specific size; one can see [1] [3]-[6]. Though, some attempts were made by Sani [8] and Mohammed *et al.* [7] to overcome such problem in literature, but the two generalizations proposed by these authors are sometimes inconvenient for presenting rhotrices as two dimensional objects.

Thus, it becomes imperative to seek for a new method of generalizing expression for rhotrices in order to allow for exactness, efficiency and convenience in presentation of research results. Furthermore, better algebra and analysis of rhotrix theory can be studied using multiple array technique as proposed in this article.

2. An Overview of Initial Generalized Rhotrix Expressions

2.1. Coupled Matrix Technique for Expressing Rhotrix in a Generalized Form

In an attempt to find an answer to the problem of “finding a transformation of rhotrix to matrix and vice versa” posed by Ajibade [1] in the concluding remark of his article, Sani [8] proposed an alternative method for multiplication of rhotrices of size 3, based on their rows and columns vectors, as comparable to matrices, recorded as follows:

$$R(3) \circ Q(3) = \left\langle \begin{matrix} a \\ b & h(R) & d \\ e \end{matrix} \right\rangle \circ \left\langle \begin{matrix} f \\ g & h(Q) & j \\ k \end{matrix} \right\rangle = \left\langle \begin{matrix} af + dg \\ bf + eg & h(R)h(Q) & aj + dk \\ bj + ek \end{matrix} \right\rangle$$

This alternative multiplication approach was also used in his work to establish some relationships between rhotrices of size 3 and 2×2 dimensional matrices through an isomorphism. Thereafter, Sani [9] extend his own method for multiplication of base rhotrices to higher size rhotrices in form of generalization, recorded as follows:

$$R(n) \circ Q(n) = \left\langle a_{i1j1}, c_{l1k1} \right\rangle \circ \left\langle b_{i2j2}, d_{l2k2} \right\rangle = \left\langle \sum_{i2j1=1}^m (a_{i1j1} b_{i2j2}), \sum_{i2k1=1}^{m-1} (c_{l1k1}, d_{l2k2}) \right\rangle,$$

where $R(n) = \left\langle \begin{matrix} & & & a_{11} \\ & & a_{21} & c_{11} & a_{12} \\ \dots & \dots & \dots & \dots & \dots \\ a_{m1} & \dots & \dots & \dots & \dots & \dots & a_{mm} \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots \\ & & a_{mm-1} & c_{m-1m-1} & a_{m-1m} \\ & & & & a_{mm} \end{matrix} \right\rangle,$

a_{ij} and c_{kl} represent the a_{ij} and c_{kl} elements respectively, $m = (n+1)/2$ with $i, j = 1, 2, 3, \dots, m$ and $l, k = 1, 2, 3, \dots, m-1$. This idea of expressing rhotrix of size n , $n \in 2Z^+ + 1$, as a combination of two matrices, was later presented as an idea for conversion of a rhotrix to a special form of a matrix, termed “coupled matrix” in Sani [10]. That is, a rhotrix R of size n can be expressed as a couple of two matrices A and C of sizes $m \times m$ and $(m-1) \times (m-1)$ respectively, where $m = (n+1)/2$ and $n \in 2Z^+ + 1$.

It is noteworthy to mention that, this method presented by Sani for expressing rhotrix in a generalised form, requires some form of transformation or half transpose, in order to identify the rows and columns for any given rhotrix. Also, unique expression for the “rhotrix heart” cannot be deduced and therefore, this method of rhotrix expression is unsuitable for presenting heart-based rhotrices.

2.2. Single Array Technique for Expressing Rhotrix in a Generalized Form

Mohammed *et al.* [7] employ a single dimensional array routine for expressing real rhotrices of size n in a generalised form, recorded as follows:

$$R(n) = \left\langle \begin{matrix} & & & & r_1 \\ & & & r_2 & r_3 & r_4 & \dots \\ & & \vdots & \vdots & \vdots & \vdots & \vdots \\ & & \vdots & \vdots & \vdots & \vdots & \vdots \\ r_{\left\{\frac{t+1}{2}\right\}-n\setminus 2} & \dots & \dots & r_{\left\{\frac{t+1}{2}\right\}} & \dots & \dots & r_{\left\{\frac{t+1}{2}\right\}+n\setminus 2} \\ & & \vdots & \vdots & \vdots & \vdots & \vdots \\ & & \vdots & \vdots & \vdots & \vdots & \vdots \\ & & & r_{t-3} & r_{t-2} & r_{t-1} \\ & & & & r_t \end{matrix} \right\rangle,$$

new expression are algorithmatized for computing machines. In the future research direction, it seems interesting to think of “axiomatization of real rhotrix space”. This topic will be our next line of focus for research.

Acknowledgements

We wish to thank Ahmadu Bello University, Zaria, Nigeria for funding this relatively new area of research.

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