

# Overlapping Nonmatching Grid Method for the Ergodic Control Quasi Variational Inequalities

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## ABSTRACT

In this paper, we provide a maximum norm analysis of an overlapping Schwarz method on nonmatching grids for a quasi-variational inequalities related to ergodic control problems studied by M. Boulbrachène [1], where the “discount factor” (*i.e.*, the zero order term) is set to 0, we use an overlapping Schwarz method on nonmatching grid which consists in decomposing the domain in two sub domains, where the discrete alternating Schwarz sequences in sub domains converge to the solution of the ergodic control IQV for the zero order term. For  $\alpha \in ]0,1[$  and under a discrete maximum principle we show that the discretization on each sub domain converges quasi-optimally in the  $L^\infty$  norm to 0.

**Keywords:** Quasi Variational Inequalities; Ergodic Control; Schwarz Method; Finite Element Method

## 1. Introduction

The Schwarz alternating method can be used to solve elliptic boundary value problems on domains which consist of two or more overlapping sub domains.

The solution is approximated by an infinite sequence of functions which results from solving a sequence of elliptic boundary value problems in each of the sub domain.

In this paper, we are interested in the error analysis in the maximum norm for the obstacle problem in the context of overlapping nonmatching grids: we consider a domain  $\Omega$  which is the union of two overlapping subdomains where each sub domain has its own triangulation. This kind of discretizations is very interesting as they can be applied to solving many practical problems which cannot be handled by global discretizations. They are earning particular attention of computational experts and engineers as they allow the choice of different mesh sizes and different orders of approximate polynomials in different sub domains according to the different properties of the solution and different requirements of the practical problems.

We study a new approach for the finite element approximation for the ergodic problem where the obstacle is related to a solution. We consider a domain which the union of two overlapping sub-domains where each sub domain has its own generated triangulation. The grid

points on the sub-domain boundaries need not much the grid points from the other sub-domains. Under a discrete maximum principle, we show that the discretization on each sub-domain converges quasi-optimally in the  $L^\infty$  norm.

In the first section we study the Schwarz method for the ergodic control Quasi-variational inequalities; we state the continuous alternating Schwarz sequence for quasi-variational inequalities, and define their respective finite element counterparts in the context of overlapping grids.

In Section 2, we give a simple proof for the main result concerning error estimates in the  $L^\infty$  norm for the problem studied, taking into account the combination of Jinping Zeng & Shuzi Zhou [2] geometrical convergence and P. L. Lions, B. Perthame [3] quasi-variational inequalities and ergodic impulse control.

## 2. Schwarz Method for the Ergodic Control Quasi-Variational Inequalities

We begin by down a classical results related to ergodic control quasi-variational inequalities [1-18].

It is well known that impulse control problems for reflected diffusion process may be solved by considering the solution of quasi variational inequalities (QVI) (see Bensoussan [4], A. Bensoussan and J. L. Lions [5]). A typical example is the following:

$$\begin{cases} a(u_\alpha, v - u_\alpha) + (u_\alpha, v - u_\alpha) \geq (f, v - u_\alpha) \\ u_\alpha \in H^1(\Omega), u_\alpha \leq Mu_\alpha; v \in H^1(\Omega), v \leq Mu_\alpha \end{cases} \quad (1)$$

where  $\Omega$  is given bounded smooth open set in  $\square^N$ ,  $\alpha > 0$ ,  $f$  is given function, the cost function  $Mu$  represents the obstacle of impulse control defined by:

$$\begin{aligned} M\varphi(x) &= k + \inf(x + \xi); \\ \xi &\geq 0, x + \xi \in \Omega, \text{ where } k > 0 \end{aligned} \quad (2)$$

where  $k$  is a positive number,  $M$  is an operator defined on  $C(\bar{\Omega})$  and assumed to map into itself, that is,

$$M\varphi(x) \leq M\tilde{\varphi}(x) \text{ whenever } \varphi(x) \leq \tilde{\varphi}(x) \quad (3)$$

$a(u, v) = \int_{\Omega} \nabla u \cdot \nabla v dx$ ; and  $(\cdot, \cdot)$  denotes the inner product on  $\Omega$ .

It has been proved that the long run average cost for this problem solves the ergodic QVI. More precisely, denoting by:

$$\langle w \rangle = \frac{1}{|\Omega|} \int_{\Omega} w dx, w_\alpha = u_\alpha - \langle u_\alpha \rangle \text{ and } \lambda_\alpha = \alpha \langle u_\alpha \rangle.$$

P. L. Lions and B. Perthame [3] proved that the solution  $(w_\alpha, \lambda_\alpha)$  of the QVI :

$$\begin{cases} a(w_\alpha, v - w_\alpha) + (w_\alpha, v - w_\alpha) \geq (f - \lambda_\alpha, v - w_\alpha) \\ w_\alpha \in H^1(\Omega), w_\alpha \leq Mw_\alpha; v \in H^1(\Omega), v \leq Mw_\alpha, \langle w_\alpha \rangle = 0 \end{cases} \quad (4)$$

converges to the solution of the ergodic control QVI :

$$\begin{cases} a(w_0, v - w_0) + (w_0, v - w_0) \geq (f - \lambda_0, v - w_0) \\ w_0 \in H^1(\Omega), w_0 \leq Mw_0; v \in H^1(\Omega), v \leq Mw_0, \langle w_0 \rangle = 0 \end{cases} \quad (5)$$

As stated in the following theorem.

**Theorem 1 [1]:** As  $\alpha$  goes to  $0^+$ ,  $\lambda_\alpha$  converges uniformly in  $C(\bar{\Omega})$  to some constant  $\lambda_0$ , and  $w_\alpha$  converges uniformly in  $C(\bar{\Omega})$  and strongly in  $H^1(\Omega)$  to  $w_0$ . Moreover  $(\lambda_0, w_0)$  is the unique solution of the quasi variational inequality of the ergodic control problem (5).

**Problem Position**

Let  $\alpha$  be fixed in the open interval  $]0, 1[$  and set. Then, one can easily see that problem (1) is equivalent to the following QVI:

$$\begin{cases} b(u_\alpha, v - u_\alpha) \geq (f + \gamma u_\alpha, v - u_\alpha) \\ u_\alpha \in H^1(\Omega), u_\alpha \leq Mu_\alpha; \\ v \in H^1(\Omega), v \leq Mu_\alpha \end{cases} \quad (6)$$

where

$$b(u, v) = a(u, v) + (u, v), \text{ and } \gamma = 1 - \alpha \quad (7)$$

Thanks to [5], (1) or (6) has a unique solution. Also, notice that, as the bilinear form (7) is independent of  $\alpha$ , the left hand side of (6) is independent of  $\alpha$  too.

**3. The Schwarz Method for the Obstacle**

We decompose  $\Omega$  into two overlapping polygonal sub domains  $\Omega_1$  and  $\Omega_2$ , such that

$$\Omega = \Omega_1 \cup \Omega_2 \quad (8)$$

and  $u_\alpha$  satisfies the local regularity condition

$$u_\alpha / \Omega_i \in W^{2,p}(\Omega_i), 2 \leq p < \infty \quad (9)$$

We denote by  $\partial\Omega_i$  the boundary condition of  $\Omega_i$  and  $\Gamma_i = \partial\Omega_i \cap \Omega_j$  the intersection of  $\bar{\Gamma}_i$  and  $\bar{\Gamma}_j$  is assumed to be empty.

**3.1. The Schwarz Sequences for Problem (4)**

We denote by:

$$w_\alpha^{n+1} = u_\alpha^{n+1} - \langle u_\alpha^{n+1} \rangle \text{ and } \lambda_\alpha^{n+1} = \alpha^{n+1} \langle u_\alpha^{n+1} \rangle, n \geq 0 \quad (10)$$

Choosing  $w_\alpha^0 = w_0$  such that  $w_0$  the unique solution of:

$$\begin{cases} a(w_0, v - w_0) + (w_0, v - w_0) \geq (f - \lambda_0, v - w_0) \\ w_0 \in H^1(\Omega), w_0 \leq Mw_0; \\ v \in H^1(\Omega), v \leq Mw_0, \langle w_0 \rangle = 0 \end{cases} \quad (11)$$

We respectively define  $w_\alpha^{n+1}$  the alternating Schwarz sequences on  $\Omega_i$  such that:

$$\begin{cases} a(w_{ai}^{n+1}, v - w_{ai}^{n+1}) + (w_{ai}^{n+1}, v - w_{ai}^{n+1}) \geq (f_i - \lambda_{ai}^{n+1}, v - w_{ai}^{n+1}) \\ w_{ai}^{n+1} = w_{ai}^n \text{ on } \Gamma_i, w_{ai}^{n+1} \leq Mw_{ai}^n; \\ v \in H^1(\Omega), v \leq Mw_{ai}^n, \langle w_{ai}^{n+1} \rangle = 0 \end{cases} \quad (12)$$

where  $i = 1, 2$  and  $f_i = f / \Omega_i$ .

**3.2. The Continuous Schwarz Sequences for Principal Problem**

We consider the following problem:

$$\begin{cases} b(u_\alpha, v - u_\alpha) \geq (f + \gamma u_\alpha, v - u_\alpha) \\ u_\alpha \in H^1(\Omega), u_\alpha \leq Mu_\alpha; v \in H^1(\Omega), v \leq Mu_\alpha \end{cases} \quad (13)$$

Choosing  $u_\alpha^0 = u_0$ , solution of:

$$\begin{cases} a(u_0, v - u_0) \geq (f, v - u_0) \\ u_0 \in H^1(\Omega), u_0 \leq Mu_0; \\ v \in H^1(\Omega), v \leq Mu_0 \end{cases} \quad (14)$$

We respectively define the alternating Schwarz sequences  $(u_{ai}^{n+1})$  on  $\Omega_1$  such that:  $\Omega = \Omega_1 \cup \Omega_2$  and;

$$\begin{cases} b(u_{\alpha 1}^{n+1}, v - u_{\alpha 1}^{n+1}) \geq (f + \gamma u_{\alpha 1}^{n+1}, v - u_{\alpha 1}^{n+1}), \forall v \in H^1(\Omega) \\ u_{\alpha 1}^{n+1} \leq Mu_{\alpha 1}^n, Mu_{\alpha 1}^n > 0 \\ u_{\alpha 1}^{n+1} = u_{\alpha 2}^n \text{ on } \Gamma_1, v = u_{\alpha 2}^n \text{ on } \Gamma_1 \end{cases} \quad (15)$$

$$\begin{cases} b(u_{\alpha 2}^{n+1}, v - u_{\alpha 2}^{n+1}) \geq (f + \gamma u_{\alpha 2}^{n+1}, v - u_{\alpha 2}^{n+1}), \forall v \in H^1(\Omega) \\ u_{\alpha 2}^{n+1} \leq Mu_{\alpha 2}^n, Mu_{\alpha 2}^n > 0 \\ u_{\alpha 2}^{n+1} = u_{\alpha 1}^{n+1} \text{ on } \Gamma_2, v = u_{\alpha 1}^{n+1} \text{ on } \Gamma_2 \end{cases} \quad (16)$$

$$\begin{aligned} b_i(u_\alpha, v) \\ = a(u_\alpha, v) + \gamma \int_{\Omega_i} u_\alpha \cdot v dx, i = 1, 2 \end{aligned} \quad (17)$$

**Lemma 1 [3]:** for each  $n \geq 0$ ;

$$Mu_{\alpha 1}^{n+1} \text{ (respec } Mu_{\alpha 2}^{n+1}) \in C(\bar{\Omega})$$

### 4. The Discret Problem

We suppose for simplicity that  $\Omega$  is polyhedral. Let  $r_h$  be a regular, quasi uniform triangulation of  $\Omega$  into  $n$ -simplexes of diameter less than  $h$ .

We denote by  $V_h$  the standard piecewise linear finite element space, we consider the discrete variational inequality:

$$\begin{cases} a(u_{\alpha h}, v_h - u_{\alpha h}) + (u_{\alpha h}, v_h - u_{\alpha h}) \geq (f, v_h - u_{\alpha h}) \\ u_{\alpha h} \in V_h, u_{\alpha h} \leq r_h Mu_{\alpha h}; v_h \in V_h, v_h \leq r_h Mu_{\alpha h} \end{cases} \quad (18)$$

Thanks to ([6]), QVI (18) has a unique solution.

#### 4.1. The Discrete Maximum Principle [7]

We assume that the matrix  $A$  with generic coefficient is a  $M$ -matrix.

$$B_{ij}(\varphi_i, \varphi_j), 1 \leq i, j \leq m(h) \quad (19)$$

As for the continuous problem, it is easy to see that  $u_{\alpha h}$ , the solution of (18), is also solution to the following (QVI):

$$\begin{cases} b(u_{\alpha h}, v_h - u_{\alpha h}) \geq (f + \gamma u_{\alpha h}, v_h - u_{\alpha h}) \\ u_{\alpha h} \in V_h, u_{\alpha h} \leq r_h Mu_{\alpha h}; v_h \in V_h, v_h \leq r_h Mu_{\alpha h} \end{cases} \quad (20)$$

**Theorem 2 [1]:** Let  $u_\alpha$  and  $u_{\alpha h}$  (the discrete solution). Then, there exists a constant independent of  $\alpha$  the both and  $h$  such that

$$\|u_\alpha - u_{\alpha h}\|_\infty \leq C \cdot \alpha^{-2} h^2 |\log h|^3$$

**Theorem 3 [1]:** Under conditions of theorem 1 and 2, we have

$$\begin{aligned} \lim_{h \rightarrow 0} \|w_{\alpha h} - w_0\|_\infty &= 0 \\ \lim_{h \rightarrow 0} |\lambda_{\alpha h} - \lambda_0| &= 0 \end{aligned}$$

Note that  $w_{\alpha h}$  and  $\lambda_{\alpha h}$  is the finite element approximation of  $w_\alpha$  and  $\lambda_\alpha$  respectively.

### 4.2. The Discrete Schwarz Sequences

Let  $V_{hi} = V_h(\Omega_i)$  be the space of continuous piecewise linear function on  $\tau_{hi}$  which vanish on  $\partial\Omega \cap \partial\Omega_i$ .

For  $w \in C(\Gamma_i)$ , we define

$$\begin{aligned} V_{hi}^{(w)} = \\ \{v \in V_h / v = 0 \text{ on } \partial\Omega \cap \partial\Omega_i, v = \pi_{hi}(w) \text{ on } \Gamma_i\} \end{aligned}$$

where  $\pi_{hi}$  denotes the interpolation operator on  $\Gamma_i$ .

For  $i = 1, 2$ . Let  $\tau_{hi}$  be a standard regular finite element triangulation in  $\Omega_i$ ,  $h_i$  being the mesh size.

We suppose that the two triangulations are mutually independent on  $\Omega_1 \cup \Omega_2$  a triangle belonging to one triangulation does not necessarily belong to the other.

Choosing  $u_{\alpha h}^0 = u_{0h}$ , such that  $u_{0h}$  is a solution of the following inequation:

$$\begin{cases} a(u_{0h}, v_h - u_{0h}) \geq (f, v_h - u_{0h}) \\ u_{0h} \in V_h, u_{0h} \leq r_h Mu_{0h}; v_h \in V_h, v_h \leq r_h Mu_{0h} \end{cases} \quad (21)$$

We define the alternating Schwarz sequences  $(u_{\alpha 1h}^{n+1})$  on  $\Omega_1$  such that:

$$\begin{cases} b_1(u_{\alpha 1h}^{n+1}, v_h - u_{\alpha 1h}^{n+1}) \geq (f_1 + \gamma u_{\alpha 1h}^{n+1}, v_h - u_{\alpha 1h}^{n+1}), v_h \in V_h \\ u_{\alpha 1h}^{n+1} \leq r_h Mu_{\alpha 1h}^n, Mu_{\alpha 1h}^n > 0 \\ u_{\alpha 1h}^{n+1} = u_{\alpha 2h}^n \text{ on } \Gamma_1, v_h = u_{\alpha 2h}^n \text{ on } \Gamma_1 \end{cases} \quad (22)$$

And  $(u_{\alpha 2h}^{n+1})$  on  $\Omega_2$  such that:

$$\begin{cases} b_2(u_{\alpha 2h}^{n+1}, v_h - u_{\alpha 2h}^{n+1}) \geq (f_2 + \gamma u_{\alpha 2h}^{n+1}, v_h - u_{\alpha 2h}^{n+1}), \\ v_h \in V_h, u_{\alpha 2h}^{n+1} \leq r_h Mu_{\alpha 2h}^n, Mu_{\alpha 2h}^n > 0 \\ u_{\alpha 1h}^{n+1} = u_{\alpha 1h}^{n+1} \text{ on } \Gamma_2, v_h = u_{\alpha 1h}^{n+1} \text{ on } \Gamma_2 \end{cases} \quad (23)$$

**Notation:** We will adapt the following notations:

$$\begin{aligned} |\cdot|_i &= \|\cdot\|_{L^\infty(\Gamma_i)}, i = 1, 2 \\ \|\cdot\|_i &= \|\cdot\|_{L^\infty(\Omega_i)}, i = 1, 2 \end{aligned} \quad (24)$$

### 5. $L^\infty$ -Error Analysis

**Lemma 2 [8]:**  $B = (b_{ij})_{i,j=\{1,\dots,N\}}$  is  $M$ -matrix such that

$$(b_{ij}) = b_{ij}(\varphi_i, \varphi_j)$$

then exists constants  $k_1, k_2$  such that

$$k_1 = \sup\{w_h(x), x \in \eta_1\} \in (0, 1)$$

and  $k_2 = \sup\{w_h(x), x \in \eta_2\} \in (0, 1)$

$$\begin{aligned} \sup_{\eta_1} |u_{\alpha 1h} - u_{\alpha 1h}^{n+1}| &\leq k_1 \sup_{\eta_1} |u_{\alpha 1h} - u_{01h}^0| \\ \sup_{\eta_2} |u_{\alpha 2h} - u_{\alpha 2h}^{n+1}| &\leq k_2 \sup_{\eta_2} |u_{\alpha 2h} - u_{02h}^0| \end{aligned} \quad (25)$$

**Theorem 4 [8]:**  $(u_{\alpha 1h}^{n+1}), (u_{\alpha 2h}^{n+1}); n \geq 0$  produced by Schwarz alternating method converges geometrically to  $u_\alpha$  the solution of obstacle problem, more precisely, there exist  $k_1, k_2 \in (0, 1)$  which depend only respectively of  $(\Omega_1, \eta_1)$  and  $(\Omega_2, \eta_2)$ , such that

$$\begin{aligned} \sup_{\bar{\Omega}_1} |u_{\alpha 1h} - u_{\alpha 1h}^{n+1}| &\leq k_1^{n+1} k_2^{n+1} \sup_{\eta_1} |u_{\alpha 1h} - u_{01h}^0| \\ \sup_{\bar{\Omega}_2} |u_{\alpha 2h} - u_{\alpha 2h}^{n+1}| &\leq k_1^{n+1} k_2^n \sup_{\eta_2} |u_{\alpha 2h} - u_{02h}^0| \end{aligned} \quad (26)$$

**Theorem 5:** Let  $h = \max(h_1, h_2)$ . Then, there exist two constants  $C$  and  $k, 0 < k < 1$ , independent of both  $h$  and  $n$  such that:

$$\|u_{\alpha 1} - u_{\alpha 1h}^{n+1}\|_\infty \leq C \cdot \alpha^{-2} h^2 |\log h|^4$$

and

$$\|u_{\alpha 2} - u_{\alpha 2h}^{n+1}\|_\infty \leq C \cdot \alpha^{-2} h^2 |\log h|^4.$$

**Proof:**

$$\begin{aligned} &\|u_{\alpha 1} - u_{\alpha 1h}^{n+1}\|_\infty \\ &\leq \|u_{\alpha 1} - u_{\alpha 1h}\|_\infty + \|u_{\alpha 1h} - u_{\alpha 1h}^{n+1}\|_\infty \\ &\leq C \cdot \alpha^{-2} h^2 |\log h|^3 + k_1^{n+1} \|u_{\alpha 1h} - u_{01h}^0\| \end{aligned}$$

$$\begin{aligned} &\|u_{\alpha 1} - u_{\alpha 1h}^{n+1}\|_\infty \\ &\leq C_1 \cdot \alpha^{-2} h^2 |\log h|^3 + k_1^{n+1} [\|u_{\alpha 1} - u_{\alpha 1h}\|_1 + \|u_{\alpha 1} - u_{01h}^0\|_1] \\ &\leq C_1 \cdot \alpha^{-2} h^2 |\log h|^3 + k_1^{n+1} \|u_{\alpha 1} - u_{\alpha 1h}\|_1 + k_1^{n+1} \|u_{\alpha 1} - u_{01h}^0\|_1 \\ &\leq C_1 \cdot \alpha^{-2} h^2 |\log h|^3 + (k_1^{n+1}) C_2 \cdot \alpha^{-2} h^2 |\log h|^3. \end{aligned}$$

We obtain

$$\|u_{\alpha 1} - u_{\alpha 1h}^{n+1}\|_\infty \leq C \cdot \alpha^{-2} h^2 |\log h|^4.$$

The case  $i = 2$  is similar.

**Theorem 6:** Let  $(w_{\alpha ih}^{n+1})$  and  $(\lambda_{\alpha ih}^{n+1})$ , the discretized alternating Schwarz sequences, we have:

$$\begin{aligned} \lim_{h \rightarrow 0} \|w_{\alpha ih}^{n+1} - w_{0i}\|_\infty &= 0, i = 1, 2 \\ \lim_{h \rightarrow 0} |\lambda_{\alpha ih}^{n+1} - \lambda_{0i}| &= 0, i = 1, 2. \end{aligned}$$

**Proof:**

1)

$$\begin{aligned} \|w_{\alpha 1h}^{n+1} - w_{01}\|_1 &\leq \|w_{\alpha 1h}^{n+1} - w_{\alpha 1h}\|_1 + \|w_{\alpha 1h} - w_{01}\|_1 \\ &\leq \|w_{\alpha 1h}^{n+1} - w_{\alpha 1h}\|_1 + \|w_{\alpha 1h} - w_{01h}\|_1 + \|w_{01h} - w_{01}\|_1 \\ \lim_{\alpha \rightarrow 0} \|w_{\alpha 1h} - w_{01h}\|_1 &\rightarrow 0 \end{aligned}$$

$$\begin{aligned} \|w_{\alpha 1h}^{n+1} - w_{01}\|_1 &\leq \|w_{\alpha 1h}^{n+1} - w_{\alpha 1h}\|_1 + \|w_{01h} - w_{01}\|_1 \\ &\leq \|u_{\alpha 1h}^{n+1} - \langle u_{\alpha 1h}^{n+1} \rangle - u_{\alpha 1h} + \langle u_{\alpha 1h} \rangle\|_1 \\ &\quad + \|u_{01h} - \langle u_{01h} \rangle - u_{01} + \langle u_{01} \rangle\|_1 \\ &\leq \|u_{\alpha 1h}^{n+1} - u_{\alpha 1h}\|_1 + \text{meas}(\Omega)^{-1} \|u_{\alpha 1h}^{n+1} - u_{\alpha 1h}\|_1 \\ &\quad + \|u_{01h} - u_{01}\|_1 + \text{meas}(\Omega)^{-1} \|u_{01h} - u_{01}\|_1 \\ &\leq 4C \cdot \alpha^{-2} h^2 |\log h|^4 \end{aligned}$$

For:  $\alpha = \sqrt{h}$  and  $h \rightarrow 0$ .

The case  $i = 2$  is similar.

$\lim_{h \rightarrow 0} \|w_{\alpha ih}^{n+1} - w_{0i}\|_i = 0, i = 1, 2$ .

$$\begin{aligned} &|\lambda_{\alpha 1h}^{n+1} - \lambda_{01}| \\ &\leq |\lambda_{\alpha 1h}^{n+1} - \lambda_{\alpha 1}| + |\lambda_{\alpha 1} - \lambda_{01}| \\ &\leq |\alpha^{n+1} \langle u_{\alpha 1h}^{n+1} \rangle - \alpha \langle u_{\alpha 1} \rangle| + |\lambda_{1\alpha} - \lambda_{01}|. \end{aligned}$$

Hence  $|\alpha^{n+1}| \leq |\alpha|$ : for  $\alpha \in ]0, 1[$

$$\begin{aligned} &|\lambda_{\alpha 1h}^{n+1} - \lambda_{01}| \\ &\leq \alpha \|u_{\alpha 1h}^{n+1} - u_{\alpha 1}\|_1 + |\lambda_{1\alpha} - \lambda_{01}| \\ &\leq \alpha \cdot C \cdot \alpha^{-2} h^2 |\log h|^4 + |\lambda_{1\alpha} - \lambda_{01}| \\ &\leq C \cdot \alpha^{-1} h^2 |\log h|^4 + |\lambda_{1\alpha} - \lambda_{01}| \end{aligned}$$

$\lim_{\alpha \rightarrow 0} |\lambda_{1\alpha} - \lambda_{01}| \rightarrow 0$ , For:  $\alpha = \sqrt{h}$  and  $h \rightarrow 0$ .

The case  $i = 2$  is similar.

$$\lim_{h \rightarrow 0} |\lambda_{\alpha ih}^{n+1} - \lambda_{0i}| = 0, i = 1, 2.$$

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