

# Data Recovering Problem Using a New KMF Algorithm for Annular Domain

**Chakir Tajani, Jaafar Abouchabaka, Otman Abdoun**

LaRIT, Faculty of Sciences, Ibn Tofail University, Kenitra, Morocco  
Email: [chakir\\_tajani@hotmail.fr](mailto:chakir_tajani@hotmail.fr), [abouchabaka3@yahoo.fr](mailto:abouchabaka3@yahoo.fr), [otman.fsk@gmail.com](mailto:otman.fsk@gmail.com)

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## ABSTRACT

This paper is interested at the Cauchy problem for Laplace's equation, which is to recover both Dirichlet and Neumann conditions on the inaccessible part of the boundary (inner part) of an annular domain from the over specified conditions on the accessible one (outer part). This work is an extension of the proposed algorithm for a unit circle [1] to annular domain, where, we describe an alternating formulation of the KMF algorithm proposed by Kozlov, Mazya and Fomin, and its relationship with the standard formulation. The new KMF algorithm ameliorates the accuracy of the solution and reduces the number of iterations required to achieve convergence. In the last part, the discussion of the error estimation of solution is presented and some numerical tests, using the software Freefem are given to show the efficiency of the proposed method.

**Keywords:** Inverse Problem; Annular Domain; Laplace Equation; Iterative Method; Freefem

## 1. Introduction

We consider an inverse problem for Laplace equation called data completion problem, which aims at recovering missing conditions on some inaccessible part of the boundary from the over specified boundary data on the remaining part. In this paper, the problem was studied to recover both Neumann and Dirichlet data on the inner part of the boundary of an annular domain, from measurements in the outer part of the domain.

This problem arises and can be encountered as challenge in several areas of engineering, especially in the detection of corrosion problem where the completed data are used to calculate the Robin coefficient that represent the coefficient damage and which is the quotient of these extended data, on the inner boundary [2-4].

This problem is ill-posed in the sense of Hadamard [5], since the existence, uniqueness and stability of the solution are not always assured [6-8]. Solving this problem by direct method is very difficult and leads to unstable solutions in the sense that the solution (if it exists) does not depend continuously on the data.

Many performing numerical methods have been developed to overcome the ill-posed nature of this kind of problem. Among them we mention the method of Quasi-reversibility introduced by Lattés [9], Thikhonov method [10] and the iterative method [11].

The group of iterative method has the advantage to allow any physical constraint to be easily taken into ac-

count directly in the scheme of the iterative algorithm, simplicity of the implementation schemes and the similarity of schemes for problems with linear and non linear operators. One possible disadvantage of this kind of method is the large number of iterations that may be required in order to achieve convergence.

Based on these reasons, we have decided in this work to consider the KMF algorithm addressed by Kozlov, Mazya and Fomin since 1991 [12] (see also [13,14]), also called alternating method since it is to solve alternately two well-posed problems: the first one permits to complete the Dirichlet condition and the second to complete the Neumann condition on the boundary.

To deal with the large number of iterations required to achieve the convergence, we propose in this paper a new KMF algorithm to overcome this problem with more precision. The main idea of the developed algorithm is to divide the boundary of missing data in two parts, and then complete the missing data in alternative way in the two sub-parts of the inaccessible boundary.

This algorithm of data completion problems has been widely studied in the case of simply connected domains, especially on the unit disk [1]. We wish to generalize here this method to annular domains.

The next section is devoted to the presentation of the Cauchy problem for Laplace's equation for annular domain. In Section 3, we present a classical KMF algorithm which enables one to find an approximate solution to that problem; we consider a New KMF algorithm and exhibit

the relationship it has with the classical KMF algorithm. Finally, Section 4 presents a numerical example showing the feasibility of the alternating formulation, its ability to find an approximate solution more accurately in less iteration.

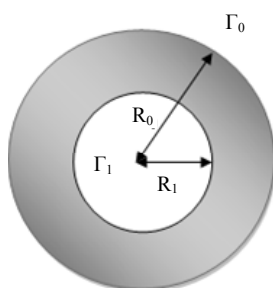
## 2. Mathematical Formulation

### 2.1. Robin Inverse Problem

Let  $\Omega = \{(x, y) \in \mathbb{R}^2 / R_1^2 \leq x^2 + y^2 \leq R_0^2\}$  be a doubly connected domain with smooth boundary  $\partial\Omega = \Gamma_0 \cup \Gamma_1$  made of two Jordan closed curves  $\Gamma_0$  and  $\Gamma_1$  such that  $\Gamma_0 \cap \Gamma_1 = \emptyset$  and

$$\Gamma_0 = \{(x, y) \in \mathbb{R}^2 / x^2 + y^2 = R_0^2\}$$

$$\Gamma_1 = \{(x, y) \in \mathbb{R}^2 / x^2 + y^2 = R_1^2\}$$



We assume that the corrosion only happened on the interior boundary of the domain  $\Omega$  and the corrosion can be described by a non-negative function  $\gamma$ , called coefficient of Robin, in the boundary condition on the interior boundary.

The determination of the coefficient of Robin is an inverse problem that consists to:

Given two functions  $f$  and  $g$  defined on  $\Gamma_0$  or a number of their pointwise measurements, with  $g \neq 0$ , find a function  $\gamma$ , such that a solution  $u$  to:

$$\begin{cases} \Delta u = 0 & \text{on } \Omega \\ u = f & \text{in } \Gamma_0 \\ \partial_n u = g & \text{in } \Gamma_0 \end{cases} \quad (1)$$

also satisfies

$$\partial_n u + \gamma u = 0 \quad \text{in } \Gamma_1 \quad (2)$$

where  $\partial_n u$  is the normal derivative of  $u$ . And  $\gamma \geq 0$  is the coefficient of Robin that represents the corrosion damage.

In the thermal framework,  $f$  corresponds to the measured temperature and  $g$  to the imposed heat flux on the outer boundary of a domain, while  $\gamma$  is the Robin exchange coefficient to be recovered on the associated inner boundary from the extended data.

This inverse problem consists to find the unknown coefficient  $\gamma$  from the Cauchy data  $f$  and  $g$  on  $\Gamma_0$ . That

can be treated by the following steps:

**Step 1:** Get the Cauchy data on the interior circle by solving the Cauchy problem for Laplace's equations (1).

**Step 2:** Get the impedance  $\gamma$  from the Cauchy data on the interior circle.

From the boundary condition  $\partial_n u + \gamma u = 0$  in  $\Gamma_1$ ,  $\gamma$  can be obtained by  $\gamma = -\frac{\partial_n u}{u} / \Gamma_1$  if  $u / \Gamma_1 \neq 0$ .

### 2.2. Reconstruction Problem

In this paper, we consider the problem of the *Step 1* to complete the missing data which consist to recover both Dirichlet and Newman conditions in the inner part of the annular domain.

This problem has a unique solution for compatible data  $f$  and  $g$  which means that the over specified data is indeed the trace and normal derivative of the solution of a single harmonic function. *i.e.*

For  $f \in H^{\frac{1}{2}}(\Gamma_0)$  and  $g \in H^{-\frac{1}{2}}(\Gamma_0)$ , where

$H^{-\frac{1}{2}}(\Gamma_0)$  is defined as dual space of  $H^{\frac{1}{2}}(\Gamma_0)$  and

$$H^{\frac{1}{2}}_0(\Gamma_0) = \{v \in L^2(\Gamma_0) / \exists w \in H^1(\Omega), w / \Gamma_0 = v, w / \Gamma_1 = 0\}$$

the problem (1) has a unique solution.

## 3. Description of the Algorithm

### 3.1. KMF Standard Algorithm

Consider the Cauchy problem (1) with  $f \in H^{\frac{1}{2}}(\Gamma_0)$

and  $g \in H^{-\frac{1}{2}}(\Gamma_0)$ . The iterative algorithm proposed by Kozlov, Mazya and Fomin (KMF standard Algorithm) [12] investigated is based on reducing this ill-posed problem to a sequence of mixed well-posed boundary value problems and consists of the following steps:

**Step 1.** Specify an initial guess  $u_0 \in H^{\frac{1}{2}}(\Gamma_1)$

**Step 2.** Solve the following mixed well-posed boundary value problem:

$$\begin{cases} \Delta u^{(0)} = 0 & \text{on } \Omega \\ u^{(0)} = u_0 & \text{in } \Gamma_1 \\ \partial_n u^{(0)} = g & \text{in } \Gamma_0 \end{cases} \quad (3)$$

To obtain

$$v_0 = \partial_n u^{(0)} / \Gamma_1 \quad (4)$$

**Step 3.** For  $n \geq 1$ , solve alternatively the two mixed well-posed boundary value problems:

$$\begin{cases} \Delta u^{(2n-1)} = 0 & \text{on } \Omega \\ \partial_n u^{(2n-1)} = v_{n-1} & \text{in } \Gamma_1 \\ u^{(2n-1)} = f & \text{in } \Gamma_0 \end{cases} \quad (5)$$

To obtain

$$u_n = u^{(2n-1)} / \Gamma_1 \tag{6}$$

$$\begin{cases} \Delta u^{(2n)} = 0 & \text{on } \Omega \\ u^{(2n)} = u_n & \text{in } \Gamma_1 \\ \partial_n u^{(2n)} = g & \text{in } \Gamma_0 \end{cases} \tag{7}$$

To obtain

$$v_n = \partial_n u^{(2n)} / \Gamma_1 \tag{8}$$

**Step 4.** Repeat Step 3 from  $n \geq 1$  until a prescribed stopping criterion is satisfied.

**3.2. Observation**

- If the sequence  $(u_n)_{n \geq 0}$  defined in Equation (6) converges in  $H^{1/2}(\Gamma_1)$ , then the sequence  $(u^{(n)})_{n \geq 0}$  converges in  $H^1(\Omega)$  to the solution  $u \in H^1(\Omega)$  of the Cauchy problem (1).
- The same conclusion is obtained if at the Step 1, we specify an initial guess  $v_0 \in H^{-1/2}(\Gamma_1)$  instead of an initial guess for  $u_0 \in H^{1/2}(\Gamma_1)$ , and we modify accordingly the Steps 2 and 3 of the algorithm.
- This algorithm provides an approximate solution to exact solution in a large number of iterations
- In order to accelerate the convergence of the iterative algorithm, schemes have been developed [15] by introducing a relaxation parameter in the Neumann condition obtained after the third step and replacing (8) by:

$$v_n = \theta^{(n)} \partial_n u^{(2n)} / \Gamma_1 + (1 - \theta^{(n)}) v_{n-1}, \quad n \geq 1 \tag{9}$$

where  $\theta^{(n)}, n \geq 1$  is a positive relaxation factor

Or in the Dirichlet condition obtained after the third step and replacing (6) by:

$$u_n = \delta^{(n)} \partial_n u^{(2n-1)} / \Gamma_1 + (1 - \delta^{(n)}) u_{n-1}, \quad n \geq 1 \tag{10}$$

where  $\delta^{(n)}, n \geq 1$  is a positive relaxation factor.

Or in both Dirichlet and Neumann conditions obtained after the third step and replacing (6) and (8) by:

$$\begin{aligned} u_n &= \beta^{(n)} \partial_n u^{(2n-1)} / \Gamma_1 + (1 - \beta^{(n)}) u_{n-1}, \quad n \geq 1 \\ v_n &= \alpha^{(n)} \partial_n u^{(2n)} / \Gamma_1 + (1 - \alpha^{(n)}) v_{n-1}, \quad n \geq 1 \end{aligned} \tag{11}$$

where  $\beta^{(n)}$  and  $\alpha^{(n)}, n \geq 1$  are two positives relaxation factor.

**3.3. New KMF Algorithm**

As first work [16], we are studied the influence of data problems, particularly; the relationship between the measure of the inaccessible part of the boundary and the rate of convergence has shown that:

- The convergence is always guaranteed and it is very

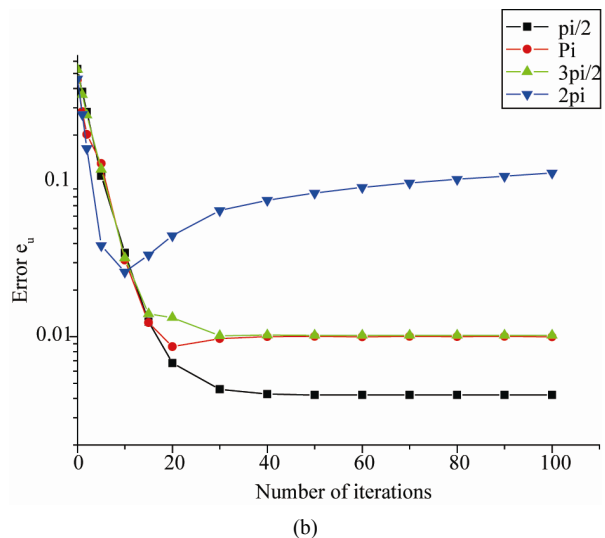
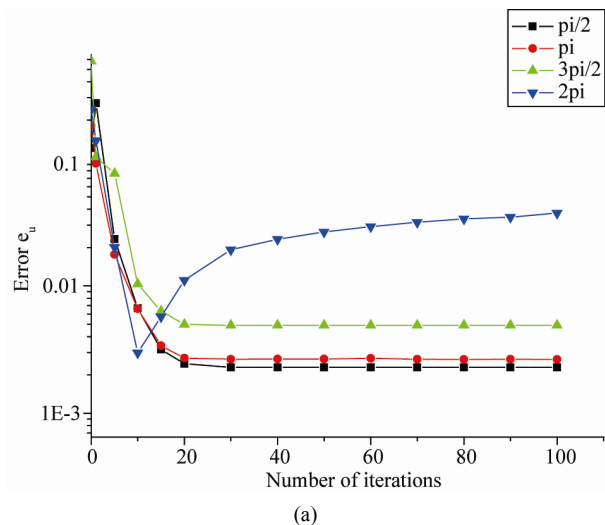
fast if the measure of the part of the boundary to be completed is small (**Figure 1**).

- The convergence requires much more iterations if the inaccessible part is greater.

In this study we extend to the annular domain, the New KMF algorithm in order to improve the rate of convergence of the iterative algorithm described.

The main idea of the proposed algorithm proposed is based on the use of the previous results and the KMF standard algorithm by completing the missing data in alternative way to the two sub-parts of the inaccessible boundary. The inaccessible part is subdivided in two parts, and the KMF standard algorithm is used to complete the data in the first part, then to complete the data in the second part in an alternative way.

For this, we consider  $\Gamma_1 = \Gamma_{1,1} \cup \Gamma_{1,2}$  such that  $\Gamma_{1,1} \cap \Gamma_{1,2} = \emptyset$  and  $mes(\Gamma_{1,1}) = mes(\Gamma_{1,2})$



**Figure 1.** The numerical results obtained for  $e_u$  (a) and  $e_v$  (b) for different choice of  $\theta$ .

The algorithm consists of the following steps:

**Step 1.** Specify an initial guess  $u_0 \in H^{\frac{1}{2}}(\Gamma_1)$

**Step 2.** Solve the well-posed problem

$$\begin{cases} \Delta u^{(0)} = 0 & \text{on } \Omega \\ u^{(0)} = u_0 & \text{in } \Gamma_1 = \Gamma_{1,1} \cup \Gamma_{1,2} \\ \partial_n u^{(0)} = g & \text{in } \Gamma_0 \end{cases} \quad (12)$$

To obtain

$$v_{1,0} = \partial_n u^{(0)} / \Gamma_{1,1} \quad \text{and} \quad v_{2,0} = \partial_n u^{(0)} / \Gamma_{1,2} \quad (13)$$

**Step 3.** For  $n \geq 1$  solve the two well-posed problems

$$\begin{cases} \Delta u^{(2n-1)} = 0 & \text{on } \Omega \\ \partial_n u^{(2n-1)} = v_{1,n-1} & \text{in } \Gamma_{1,1} \\ \partial_n u^{(2n-1)} = v_{2,n-1} & \text{in } \Gamma_{1,2} \\ u^{(2n-1)} = f & \text{in } \Gamma_0 \end{cases} \quad (14)$$

To obtain

$$u_{1,n} = u^{(2n-1)} / \Gamma_{1,1} \quad (15)$$

and

$$\begin{cases} \Delta v^{(2n-1)} = 0 & \text{on } \Omega \\ v^{(2n-1)} = u_{1,n} & \text{in } \Gamma_{1,1} \\ \partial_n v^{(2n-1)} = v_{2,n-1} & \text{in } \Gamma_{1,2} \\ v^{(2n-1)} = f & \text{in } \Gamma_0 \end{cases} \quad (16)$$

To obtain

$$u_{2,n} = v^{(2n-1)} / \Gamma_{1,2} \quad (17)$$

**Step 4.** Solve the two well-posed problems

$$\begin{cases} \Delta u^{(2n)} = 0 & \text{on } \Omega \\ u^{(2n)} = u_{1,n} & \text{in } \Gamma_{1,1} \\ u^{(2n)} = u_{2,n} & \text{in } \Gamma_{1,2} \\ \partial_n u^{(2n)} = g & \text{in } \Gamma_0 \end{cases} \quad (18)$$

To obtain

$$v_{1,n} = \partial_n u^{(2n)} / \Gamma_{1,1} \quad (19)$$

And

$$\begin{cases} \Delta v^{(2n)} = 0 & \text{on } \Omega \\ \partial_n v^{(2n)} = v_{1,n} & \text{in } \Gamma_{1,1} \\ v^{(2n)} = u_{2,n} & \text{in } \Gamma_{1,2} \\ \partial_n v^{(2n)} = g & \text{in } \Gamma_0 \end{cases} \quad (20)$$

To obtain

$$v_{2,n} = \partial_n v^{(2n)} / \Gamma_{1,2} \quad (21)$$

**Step 5.** Repeat Steps 3 and 4. From  $n \geq 1$  until a prescribed stopping criterion is satisfied.

### 3.4. Remarks

- If we consider every iteration to consist of solving the four mixed well-posed problems from the Step 3 and 4 of the algorithm, then for every  $n \geq 1$  the following approximations are obtained at the iteration number  $n$ :

- $u_{1,n}$  for the Dirichlet condition on the  $\Gamma_{1,1}$ .
- $u_{2,n}$  for the Dirichlet condition on the  $\Gamma_{1,2}$ .
- $v_{1,n}$  for the Neumann condition on the boundary  $\Gamma_{1,1}$ .
- $v_{2,n}$  for the Neumann condition on the boundary  $\Gamma_{1,2}$ .

It should be noted that:

- The KMF developed algorithm can be seen as two parallel problems of KMF standard algorithm. These two problems are initialized with the same initial data. Each problem allows to obtain approximation in each subpart  $\Gamma_{i,n}$   $i=1,2$  (for the approximation in  $\Gamma_{1,1}$  the two well-posed problems (14) and (18), for the approximation in  $\Gamma_{1,2}$  the two well-posed problems (16) and (20)).
- Each solved problem allows an approximation in one of the inaccessible subparts that can be introduced in the other well-posed problems.
- The missing Dirichlet condition in the part  $\Gamma_1$  can be obtained from the problem (16) since the condition  $u_{1,n} = u^{(2n-1)} / \Gamma_{1,1}$  obtained from (14) is introduced in (16) which also provides  $u_{2,n} = v^{(2n-1)} / \Gamma_{1,2}$ .
- The missing Neumann condition in the part  $\Gamma_1$  can be obtained from the problem (20), since the condition  $v_{1,n} = \partial_n u^{(2n)} / \Gamma_{1,1}$  obtained from (18) is introduced in (20) which also provides  $v_{2,n} = \partial_n v^{(2n)} / \Gamma_{1,2}$ .

### 4. Numerical Results

In order to present the performance of the numerical method proposed, we solve the Cauchy problem for Laplace equation for annular domain with  $R_1 = 0.5$  and  $R_0 = 1$ .

In this section, we illustrate the numerical results obtained using the alternating KMF algorithm described in Section 3. In addition, we investigate the convergence and the accuracy of the solution with respect the number of iterations.

We assume that the boundary  $\Gamma_1$  of the solution domain is divided into two disjointed parts  $\Gamma_{1,1}$  and  $\Gamma_{1,2}$ , namely;

$$\Gamma_{1,1} = \{(x, y) \in \square^2 / x = R_1 \cos(t), y = R_1 \sin(t), 0 \leq t \leq \pi\}$$

$$\Gamma_{1,2} = \{(x, y) \in \square^2 / x = R_1 \cos(t), y = R_1 \sin(t), \pi < t \leq 2\pi\}$$

The analytical function to be retrieved is given by:

$$u(x, y) = e^x \cos y \quad (22)$$

For the implementation of the iterative algorithm we use the software FreeFem, and solve the well-posed problems in the algorithm by the finite element method. In this example, we use a finite element method with continuous piecewise linear polynomials to provide simultaneously the unspecified boundaries Dirichlet and Neumann.

The following stopping criterion was adopted

$$E = \|u_n - u_{n+1}\|_{0,\Gamma_1} \leq \varepsilon \tag{23}$$

where  $\varepsilon$  is a small positive number.

The convergence of the algorithm may be investigated by evaluating at every iteration the error:

$$e_u = \|u_n - u_{ex}\|_{0,\Gamma_1} \text{ and } e_v = \|v_n - \partial_n u_{ex}\|_{0,\Gamma_1} \tag{24}$$

where the approximation  $u_n$  is obtained for the function on the boundary  $\Gamma_1$  after  $n$  iterations and  $u_{ex}$  is the exact solution of the problem of the problem (1). However, in practical applications the error  $e_u$  cannot be evaluated since the analytical solution is not known and therefore the error  $E$  has to be used.

The **Figure 2** presents the function  $u$  obtained after convergence ( $u_{iter\ final}$ ), the function  $u$  with the initial guess considered ( $u_{iter\ 0}$ ) and the exact solution ( $u_{exact}$ ). You can see that; from a given initial data not very close to exact solution, we obtained a very satisfactory approximation of the solution of problems in an acceptable number of iterations.

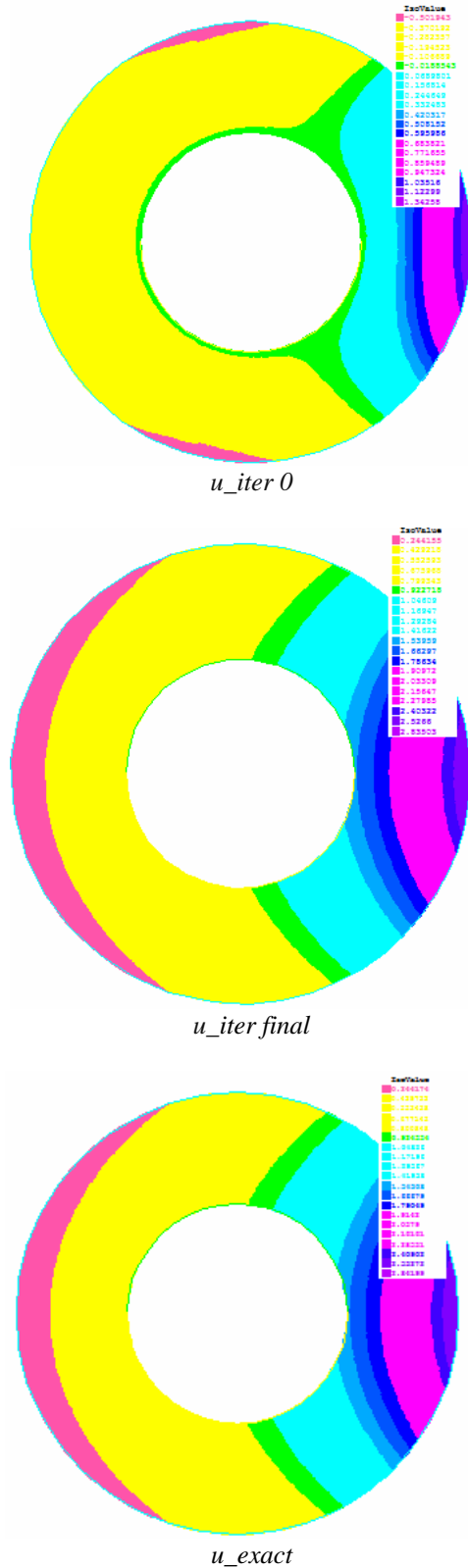
**Figure 3** presents the error  $e_u$  and  $e_v$  obtained for different number of boundary elements used for discretising the inner part of the boundary  $\Gamma_1$ .

**Figure 4** presents a comparison between the numerical results  $e_u$  and  $e_v$  obtained with the KMF standard algorithm and the New KMF algorithm. It can be seen that the algorithm proposed decreases considerably the number of iteration necessary to achieve the convergence that can be reduced, and present a more accurate approximations for both Dirichlet and Neumann missing data. In addition, we can notice that after the number of iterations is sufficiently increased, the error become small for the new algorithm; this shows that the numerical solution is accurate and consistent with the number of iterations.

**Figure 5** shows the numerical results obtained in approximating the function  $u$  in the part of the boundary  $\Gamma_1$ , indicating that from a choice of an initial data, we obtain satisfying results for both algorithms (stand and New). However, the New KMF algorithm requires less iteration to achieve more accurate convergence.

**5. Conclusions**

In this paper, we have presented a fast data completion algorithm solving the Cauchy problem for the Laplace



**Figure 2.** The reconstruction function  $u$  with the new algorithm ( $u_{iter\ final}$ ) in comparison with ( $u_{exact}$ ) and  $u$  obtained with the initial guess ( $u_{iter\ 0}$ ) for  $R_1 = 0.5$  and  $R_0 = 1$  and  $N_0 = N_1 = 40$ .

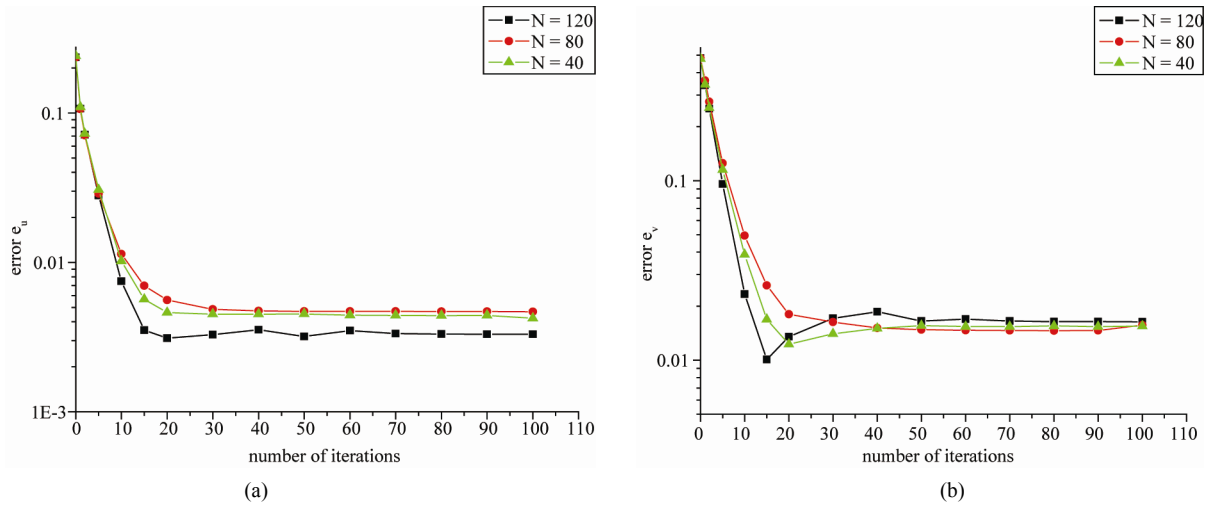


Figure 3. The error  $e_u$  and  $e_v$  as a function of the number of iterations obtained for KMF developed algorithm with  $N = 40, 80, 120$ .

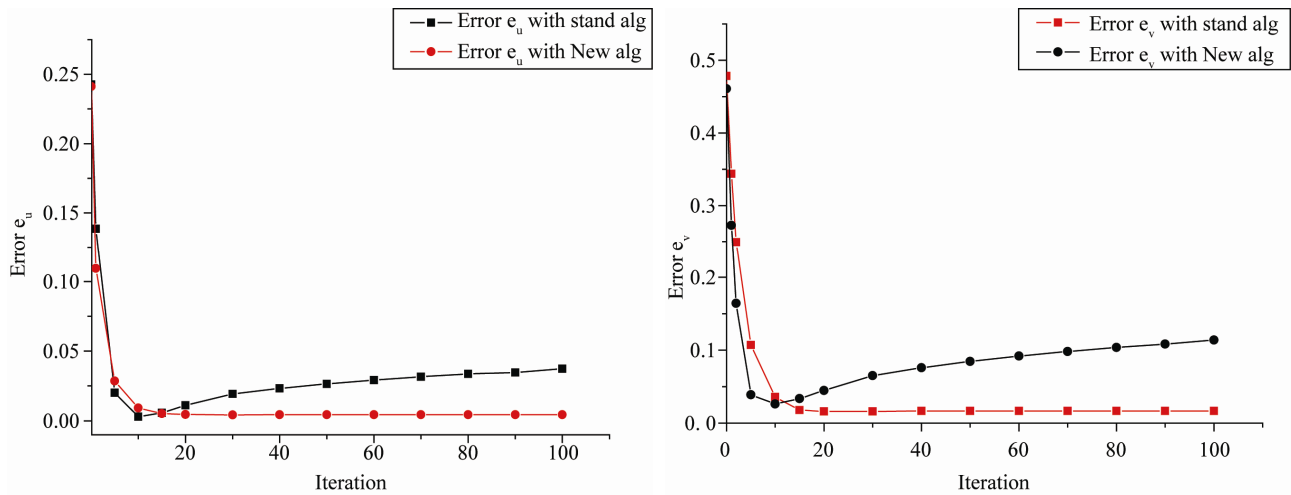


Figure 4. The error  $e_u$  and  $e_v$  as a function of the number of iterations obtained for KMF developed algorithm (New) in comparison with classical algorithm (Stand).

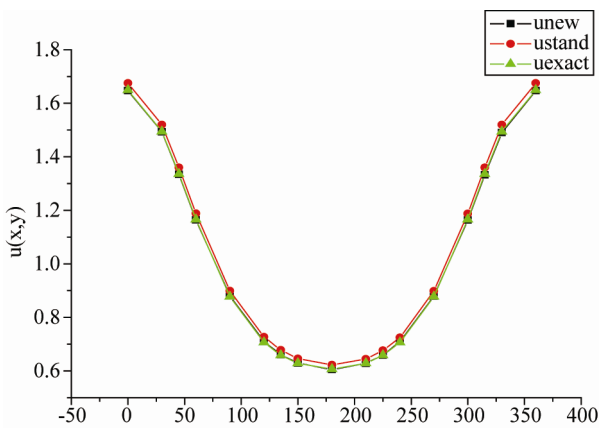


Figure 5. The numerical results for the function  $u$  on the boundary  $\Gamma_1$  obtained with KMF developed algorithm (unew) in comparison with the analytical solution (uexact) and the solution with KMF standard algorithm (uexact).

equation in an annular domain. The main goal was to compute accurately the extended data on the inaccessible inner part from the over specified data in the accessible outer part. These data can be used to calculate the coefficient data representing the corrosion damage on the inner part of the boundary.

The comparison of numerical results with those obtained by the KMF standard algorithm show that the proposed algorithm significantly reduces the number of iterations needed to achieve the convergence and produces more accurate results. In addition, it can be concluded that the proposed algorithm is very efficient to reduce the rate of convergence. When perturbations are introduced into the given data problem the results are stable. Overall, it can be concluded that the new iterative algorithm proposed produces a convergent, stable and accurate numerical solution.

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