# Generalized Irreducible $\alpha$-Matrices and Its Applications 

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How to cite this paper: Sun, Y., Zhang, H.B. and Li, C.Q. (2018) Generalized Irreducible $\alpha$-Matrices and Its Applications. Advances in Linear Algebra \& Matrix Theory, 8, 111-121.
https://doi.org/10.4236/alamt.2018.83010

Received: June 21, 2018
Accepted: August 6, 2018
Published: August 9, 2018

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#### Abstract

The class of generalized $\alpha$-matrices is presented by Cvetković, L. (2006), and proved to be a subclass of $H$-matrices. In this paper, we present a new class of matrices-generalized irreducible $\alpha$-matrices, and prove that a generalized irreducible $\alpha$-matrix is an $H$-matrix. Furthermore, using the generalized arith-metic-geometric mean inequality, we obtain two new classes of $H$-matrices. As applications of the obtained results, three regions including all the eigenvalues of a matrix are given.


## Keywords

Generalized Irreducible $\alpha$-Matrices, $H$-Matrices, Irreducible, Nonsingular, Eigenvalues

## 1. Introduction

$H$-matrices play a very important role in Numerical Analysis, in Optimization theory and in other Applied Sciences [1]-[7]. Here we call a matrix $A=\left(a_{i j}\right) \in C^{n \times n}$ an $H$-matrix if its comparison matrix $\operatorname{com}(A)=\left(m_{i j}\right)$ defineded by

$$
m_{i i}=\left|a_{i i}\right|, m_{i j}=-\left|a_{i j}\right|, i, j \in N=\{1,2, \cdots, n\}, j \neq i
$$

is an $M$-matrix, i.e., $(\operatorname{com}(A))^{-1} \geq 0 \quad$ [4].
One interesting problem involving on $H$-matrices is to identify whether or not a matrix is an $H$-matrix [2] [8]. But it is not easy to do this by its definition. So researchers turned to study some subclasses of $H$-matrices, which are easy to identify [1] [2] [3] [4] [5] [8] [9] [10]. One of the classical subclasses is strictly diagonally dominant matrices (see Definition 1) which was first presented by Lévy only for real matrices [11]. And Minkowski [12] and Desplanques [13] ob-
tained the general complex result.
Definition 1. A matrix $A=\left(a_{i j}\right) \in C^{n \times n}$ is called a strictly diagonally dominant matrix if for any $i \in N$,

$$
\left|a_{i i}\right|>r_{i}(A)=\sum_{i \neq j}\left|a_{i j}\right|
$$

As is well known, a strictly diagonally dominant matrix is nonsingular.
This can lead to the following famous Geršgorin's Theorem.
Theorem 1. [12] Let $A=\left(a_{i j}\right) \in C^{n \times n}$ and $\sigma(A)$ be the spectrum of $A$. Then

$$
\sigma(A) \subseteq \Gamma(A)=\bigcup_{i \in N} \Gamma_{i}(A)
$$

where $\Gamma_{i}(A)=\left\{z \in C:\left|z-a_{i i}\right| \leq r_{i}(A)\right\}$.
By considering the irreducibility of a matrix, Taussky [14] [15] extended the notion of a strictly diagonally dominant matrix, and given the following subclass of $H$-matrices (see Definition 2). A matrix $A$ is irreducible if and only if its directed graph $G(A)$ is strongly connected (for details, see [16] [17]).

Definition 2. A matrix $A=\left(a_{i j}\right) \in C^{n \times n}$ is called an irreducibly diagonally dominant matrix if $A$ is irreducible, if for any $i \in N$,

$$
\begin{equation*}
\left|a_{i i}\right| \geq r_{i}(A) \tag{1}
\end{equation*}
$$

and if strict inequality holds in (1) for at least one $i$.
Theorem 2. ([17], Theorem 1.11) For an irreducibly diagonally dominant matrix $A$, then $A$ is nonsingular.

Another one subclass of $H$-matrices is provided by Ostrowski (see [14] or Theorem 1.16 of [17]).

Theorem 3. [18] For any $A=\left(a_{i j}\right) \in C^{n \times n}$, and any $\alpha \in[0,1]$, assume that

$$
\begin{equation*}
\left|a_{i i}\right|>\left(r_{i}(A)\right)^{\alpha}\left(c_{i}(A)\right)^{1-\alpha} \text { for each } i \in N \tag{2}
\end{equation*}
$$

where $c_{i}(A)=r_{i}\left(A^{\mathrm{T}}\right)$. Then $A$, which is called $\alpha_{2}$-matrices, is nonsingular and is an $H$-matrix.

By the nonsingularity of $\alpha_{2}$-matrices, one can easily obtain the corresponding eigenvalue localization theorem as below.

Theorem 4. [17] For any $A=\left(a_{i j}\right) \in C^{n \times n}$, and any $\alpha \in[0,1]$, then

$$
\sigma(A) \subseteq\left\{z \in C:\left|z-a_{i i}\right| \leq r_{i}(A)^{\alpha} c_{i}(A)^{1-\alpha}\right\}
$$

For irreducible matrices, Hadjidimos in [19] gave extensions of Theorem 4 by the nonsingularity of the so-called irreducible $\alpha_{2}$-matrices (see Theorems 5 and 6).

Definition 3. A matrix $A=\left(a_{i j}\right) \in C^{n \times n}$ is called an irreducible $\alpha_{2}$-matrix if $A$ is irreducible, if for any $i \in N$,

$$
\begin{equation*}
\left|a_{i i}\right| \geq r_{i}(A)^{\alpha} c_{i}(A)^{1-\alpha} \tag{3}
\end{equation*}
$$

hold for some $\alpha \in[0,1]$, with at least one inequality being strict.
Theorem 5. ([19], Theorem 2.1) For an irreducible $\alpha_{2}$-matrix $A$, then $A$ is nonsingular.

Theorem 6. [19] For any $A=\left(a_{i j}\right) \in C^{n \times n}$, and any $\alpha \in[0,1]$, for which (3) holds, then

$$
\sigma(A) \subseteq \Gamma^{\alpha 1}(A) \cup \Gamma^{\alpha 2}(A)
$$

where

$$
\begin{aligned}
\Gamma^{\alpha 1}(A) & =\bigcup_{i \in N}\left\{z \in C:\left|z-a_{i i} \leq r_{i}(A)^{\alpha} c_{i}(A)^{1-\alpha}\right|\right\} \\
\Gamma^{\alpha 2}(A) & =\bigcup_{i \in N \backslash N_{1}}\left\{z \in C:\left|z-a_{i i}<r_{i}(A)^{\alpha} c_{i}(A)^{1-\alpha}\right|\right\}
\end{aligned}
$$

and $N_{1}$ is the set of indices for which strict inequality holds in (3).
We remark here that although Hadjidimos in [19] pointed out that irreducible $\alpha_{2}$-matrices is nonsingular, he didn't give the relationship between $\alpha_{2}$-matrices and $H$-matrices. In fact, the class of $\alpha_{2}$-matrices is a subclass of $H$-matrices, which is showed by the following theorem.

Theorem 7. For an irreducible $\alpha_{2}$-matrix $A$, then $A$ is an $H$-matrix.
Proof. We let $\operatorname{com}(A)=D-B$, where $D=\operatorname{diag}\left(\left|a_{11}\right|,\left|a_{22}\right|, \cdots,\left|a_{n n}\right|\right)$, and prove that the spectral radius $\rho\left(D^{-1} B\right)$ of $D^{-1} B$ is less than 1 . In fact, if there exists an eigenvalue $\lambda$ of $D^{-1} B$ such that $|\lambda| \geq 1$, then
$D\left(\lambda I-D^{-1} B\right)=\lambda D-B$, is an irreducible $\alpha_{2}$-matrix, and hence it is nonsingular. But this contradicts the fact that $\lambda$ is an eigenvalue of the matrix $D^{-1} B$. Therefore, $\rho\left(D^{-1} B\right)<1$.

According to $(\operatorname{com}(A))^{-1}=\sum_{j=0}^{\infty}\left(D^{-1} B\right)^{j} D^{-1} \geq 0$, the conclusion follows.
Recently, Cvetković in [4] presented a new subclass of $H$-matrices, which is called generalized $\alpha$-matrices defined as below, and given a new eigenvalue localization set by using the nonsingularity of generalized $\alpha$-matrices (see Theorem 9).

Theorem 8. ([4], Theorem 16) If for a matrix $A=\left(a_{i j}\right) \in C^{n \times n}$, there exists $\alpha \in[0,1]$ and $k \in N$ such that for each subset $S \subseteq N$ of cardinality $k$

$$
\begin{equation*}
\left|a_{i i}\right|>\left(r_{i}^{S}(A)\right)^{\alpha}\left(c_{i}^{S}(A)\right)^{1-\alpha}+r_{i}^{\bar{S}}(A), \bar{S}=N \backslash S \tag{4}
\end{equation*}
$$

holds, where $r_{i}^{S}(A)=\sum_{j \in S, j \neq i}\left|a_{i j}\right|$ and $c_{i}^{S}(A)=r_{i}^{S}\left(A^{\mathrm{T}}\right)$, then the matrix $A$, which is called a generalizaed $\alpha$-matrices, is nonsingular, moreover it is an $H$-matrix.

Theorem 9. ([5], Theorem 17) For any $A=\left(a_{i j}\right) \in C^{n \times n}$, and any $\alpha \in[0,1]$, then

$$
\sigma(A) \subseteq \bigcap_{k \in N / S} \bigcup_{|S|=k} \bigcup_{i \in N} \Gamma_{i}^{\alpha, k, S}
$$

where

$$
\Gamma_{i}^{\alpha, k, S}=\left\{z \in C:\left|z-a_{i i}\right| \leq\left(r_{i}^{S}(A)\right)^{\alpha}\left(c_{i}^{S}(A)\right)^{1-\alpha}+r_{i}^{\bar{S}}(A)\right\}
$$

We now present a new class of matrices-generalized irreducible $\alpha$-matrix, which is different from the class of generalized $\alpha$-matrices and will be proved to be an $H$-matrix in Section 2.

Definition 4. A matrix $A=\left(a_{i j}\right) \in C^{n \times n}$ is called a generalized irreducible $\alpha$-matrix if $A$ is irreducible and if there exists $\alpha \in[0,1]$ and $k \in N$ such that for each subset $S \subseteq N$ of cardinality $k$

$$
\begin{equation*}
\left|a_{i i}\right| \geq\left(r_{i}^{S}(A)\right)^{\alpha}\left(c_{i}^{S}(A)\right)^{1-\alpha}+r_{i}^{\bar{S}}(A) \tag{5}
\end{equation*}
$$

holds, with at least one inequality in (5) being strict.
The outline of this paper is given as follows. In Section 2, we prove that a generalized irreducible $\alpha$-matrix is nonsingular, and is an $H$-matrix. By using its nonsingularity, we also obtain a new eigenvalue localization set. Combining with the generalized arithmetic-geometric mean inequality, we in Section 3 obtain two other subclasses of H -matrices, consequently, two corresponding eigenvalue localization set. And then the simplifications of the obtained eigenvalue localization sets are given in Section 4.

## 2. Nonsingularity of Generalized Irreducible $\alpha$-Matrices

In this section, we prove that a generalized irreducible $\alpha$-matrix is nonsingular, and obtain a new eigenvalue localization set by using its nonsingularity.

Theorem 10. If a matrix $A=\left(a_{i j}\right) \in C^{n \times n}$ is a generalized irreducible $\alpha$-matrix, then it is nonsingular, moreover it is an $H$-matrix.

Proof. First, Apparent we remark that the case $k=1$ represents the class of irreducibly diagonally dominant matrices, while $k=n$ represents irreducible $\alpha_{2}$-matrices, so in both cases the nonsingularity has already been shown in Theorem 2 and Theorem 5, respectively. So, from now on, we suppose that $1<k$ < $n$.

Suppose on the contrary that $A$ is singular. Then there exists a nonzero vector $x=\left(x_{1}, x_{2}, \cdots, x_{n}\right)^{\mathrm{T}}$ such that $A x=0$, that is,

$$
-a_{i i} x_{i}=\sum_{i \neq j, j=1}^{n} a_{i j} x_{j}, \text { for each } i \in N
$$

Taking absolute values in the above equation and using the triangle inequality gives

$$
\left|a_{i i}\right|\left|x_{i}\right| \leq \sum_{i \neq j, j=1}^{n}\left|a_{i j}\right|\left|x_{j}\right|=\sum_{i \neq j, j \in S}\left|a_{i j}\right|\left|x_{j}\right|+\sum_{i \neq j, j \in \bar{S}}\left|a_{i j}\right|\left|x_{j}\right| \text { for each } i \in N
$$

Note that for the nonzero vector $x=\left(x_{1}, x_{2}, \cdots, x_{n}\right)^{\mathrm{T}}$ there always exists a subset $S \subset N$ of cardinality $k$ such that $\left|x_{i}\right| \geq\left|x_{j}\right|$ and $\left|x_{i}\right|>0$ for each $i \in S$ and each $j \in \bar{S}$. Hence, for each $i \in S$.

$$
\begin{equation*}
\left|a_{i i}\right|\left|x_{i}\right| \leq \sum_{i \neq j, j=1}^{n}\left|a_{i j}\right|\left|x_{j}\right| \leq \sum_{i \neq j, j \in S}\left|a_{i j}\right|\left|x_{j}\right|+r_{i}^{\bar{S}}(A)\left|x_{i}\right| \tag{6}
\end{equation*}
$$

equivalently,

$$
\left(\left|a_{i i}\right|-r_{i}^{\bar{s}}(A)\right)\left|x_{i}\right| \leq \sum_{i \neq j, j=1}^{n}\left|a_{i j}\right|\left|x_{j}\right|
$$

Furthermore, by (5) in Definition 4, we have

$$
\begin{equation*}
\left(r_{i}^{S}(A)\right)^{\alpha}\left(c_{i}^{S}(A)\right)^{1-\alpha}\left|x_{i}\right| \leq\left(\left|a_{i i}\right|-r_{i}^{\bar{S}}(A)\right)\left|x_{i}\right| \leq \sum_{j \in S, j \neq i}\left|a_{i j}\right|\left|x_{j}\right|, i \in S \tag{7}
\end{equation*}
$$

with at least one strict inequality holds above. Using Höder's inequality (see Lemma 2.1 in [19]) we get

$$
\left(r_{i}^{S}(A)\right)^{\alpha}\left(c_{i}^{S}(A)\right)^{1-\alpha}\left|x_{i}\right| \leq\left(\sum_{j \in S, j \neq i}\left|a_{i j}\right|\right)^{\alpha}\left(\sum_{j \in S, j \neq i}\left|a_{i j}\right|\left|x_{j}\right|^{\frac{1}{1-\alpha}}\right)^{1-\alpha}, i \in S
$$

that is

$$
\begin{equation*}
\left(r_{i}^{S}(A)\right)^{\alpha}\left(c_{i}^{S}(A)\right)^{1-\alpha}\left|x_{i}\right| \leq\left(r_{i}^{S}(A)\right)^{\alpha}\left(\sum_{j \in S, j \neq i}\left|a_{i j}\right|\left|x_{j}\right|^{\frac{1}{1-\alpha}}\right)^{1-\alpha}, i \in S \tag{8}
\end{equation*}
$$

without loss of generality, suppose that for any $i \in S, r_{i}^{S}(A) \neq 0$. In fact, if there exists $i_{0} \in S$ such that $r_{i_{0}}^{S}(A)=0$, i.e., $a_{i_{0} k}=0$ for each $k \in S, k \neq i_{0}$, then from (7), we have

$$
\left(\left|a_{i_{0} i_{0}}\right|-r_{i_{0}}^{\bar{S}}(A)\right)\left|x_{i_{0}}\right| \leq 0
$$

Note that $\left|x_{i}\right| \neq 0$ for each $i \in S$. then

$$
\left|a_{i_{0} i_{0}}\right| \leq r_{i_{0}}^{\bar{S}}(A)=r_{i_{0}}(A) .
$$

Since $A$ is a generalized irreducible $\alpha$-matrix, we have

$$
\left|a_{i_{0} i_{0}}\right| \geq\left(r_{i_{0}}^{S}(A)\right)^{\alpha}\left(c_{i_{0}}^{S}(A)\right)^{1-\alpha}+r_{i_{0}}^{\bar{S}}(A)=r_{i_{0}}^{\bar{S}}(A)
$$

hence,

$$
\begin{equation*}
\left|a_{i 0_{0} i_{0}}\right|=r_{i_{0}}^{\bar{S}}(A), \quad i_{0} \in S \tag{9}
\end{equation*}
$$

Furthermore, by (6) and (9), we get that

$$
\left|a_{i_{0} i_{0}}\right|\left|x_{i_{0}}\right|=\sum_{j \in S}\left|a_{i_{0} j}\right|\left|x_{j}\right|=r_{i_{0}}^{\bar{S}}(A)
$$

which implies that there is $j_{0} \in \bar{S}$ such that $a_{i_{0} j_{0}} \neq 0$ and $\left|x_{i_{0}}\right|=\left|x_{j_{0}}\right| \neq 0$.
Because $A$ is irreducible. Let $S_{1}=\left(S \backslash\left\{i_{1}\right\}\right) \cup\left\{j_{0}\right\}$, for $i_{1} \in S, i_{1} \neq i_{0}$. Note that

$$
r_{i_{0}}^{S_{1}}(A) \geq\left|a_{i_{0} j_{0}}\right|>0
$$

then we only consider $S_{1}$ instead of $S$.
For every $i \in S, \quad r_{i_{0}}^{S}(A)>0$, By canceling $\left(r_{i}^{S}(A)\right)^{\alpha}$ on both sides of (8)and raising both sides of $(8)$ to the power $\frac{1}{1-\alpha}$, we have

$$
\sum_{i \in S}\left(c_{i}^{S}(A)\right)\left|x_{i}\right|^{\frac{1}{1-\alpha}} \leq\left(\sum_{j \in S, j \neq i}\left|a_{i j}\right|\left|x_{j}\right|^{\frac{1}{1-\alpha}}\right) i \in S
$$

where strict inequality holds above for at least one $i \in S$. Summing on all $i$ in $S$ in the above inequalities gives

$$
\sum_{i \in S}\left(c_{i}^{S}(A)\right)\left|x_{i}\right|^{\frac{1}{1-\alpha}}<\sum_{i \in S}\left(\sum_{j \in S, j \neq i}\left|a_{i j}\right|\left|x_{j}\right|^{\frac{1}{1-\alpha}}\right)
$$

equivalently

$$
\sum_{i \in S}\left(c_{i}^{S}(A)\right)\left|x_{i}\right|^{\frac{1}{1-\alpha}}<\sum_{i \in S}\left(\sum_{j \in S, j \neq i}\left|a_{i j}\right|\left|x_{j}\right|^{\frac{1}{1-\alpha}}\right)=\sum_{j \in S}\left(c_{i}^{S}(A)\right)\left|x_{j}\right|^{\frac{1}{1-\alpha}} .
$$

This is a contradiction. Therefore, $A$ is nonsingular.
Moreover, similar to the proof of Theorem 7, we can easily prove that $A$ is an $H$-matrix.

From Theorem 10, we easily get the corresponding eigenvalue localization set as below.

Corollary 1. For any $A=\left(a_{i j}\right) \in C^{n \times n}$, and any $\alpha \in[0,1]$, then

$$
\sigma(A) \subseteq \bigcap_{k \in N / S} \bigcup_{|S|=k}\left(\left(\bigcup_{i \in S_{1}} \Gamma_{i}^{\alpha, k, S_{1}}\right) \bigcup\left(\bigcup_{i \in S_{2}} \Gamma_{i}^{\alpha, k, S_{2}}\right)\right)
$$

where

$$
\begin{aligned}
& \Gamma_{i}^{\alpha, k, S_{1}}=\left\{z \in C:\left|z-a_{i i}\right| \leq\left(r_{i}^{S}(A)\right)^{\alpha}\left(c_{i}^{S_{1}}(A)\right)^{1-\alpha}+r_{i}^{\bar{S}}(A)\right\} ; \\
& \Gamma_{i}^{\alpha, k, S_{2}}=\left\{z \in C:\left|z-a_{i i}\right|<\left(r_{i}^{S}(A)\right)^{\alpha}\left(c_{i}^{S_{2}}(A)\right)^{1-\alpha}+r_{i}^{\bar{S}}(A)\right\} .
\end{aligned}
$$

and $S_{2}=S \backslash S_{1}$ with $S_{1}$ is the set of indices for which strict inequality holds in (5).

## 3. Applications

Combining the nonsingularity of generalized (irreducible) $\alpha$-matrices with the generalized arithmetic-geometric mean inequality:

$$
\alpha a+(1-\alpha) b \geq a^{\alpha} b^{1-\alpha}
$$

where $a, b \geq 0$ and $\alpha \in[0,1]$.
We obtain two other subclasses of $H$-matrices, consequently, two new eigenvalue localization set.

Theorem 11. If for a matrix $A=\left(a_{i j}\right) \in C^{n \times n}$, there exists $\alpha \in[0,1]$ and
$k \in N$ such that for each subset $S \subseteq N$ of cardinality $k$

$$
\begin{equation*}
\left|a_{i i}\right|>\alpha r_{i}^{S}(A)+(1-\alpha) c_{i}^{S}(A)+r_{i}^{\bar{S}}(A) \tag{10}
\end{equation*}
$$

holds, then $A$, which is called a generalized sum $\alpha$-matrix, is nonsingular, moreover it is an $H$-matrix.

Proof. By the generalized arithmetic-geometric mean inequality, we have

$$
\left|a_{i i}\right|>\alpha r_{i}^{S}(A)+(1-\alpha) c_{i}^{S}(A)+r_{i}^{\bar{S}}(A) \geq\left(r_{i}^{S}(A)\right)^{\alpha}\left(c_{i}^{S}(A)\right)^{1-\alpha}+r_{i}^{\bar{S}}(A)
$$

This implies that $A$ is generalized $\alpha$-matrix. Hence $A$ is nonsingular. Furthermore, similar to the proof of Theorem 7, we can obtain easily that $A$ is an $H$-matrix.

From Theorem 11, we also get a corresponding eigenvalue localization set.
Corollary 2. For any $A=\left(a_{i j}\right) \in C^{n \times n}$, and any $\alpha \in[0,1]$, then

$$
\sigma(A) \subseteq \bigcap_{k \in N / S|S|=k} \bigcup_{i \in S} \gamma_{i}^{\alpha, k, S}
$$

where

$$
\gamma_{i}^{\alpha, k, S}=\left\{z \in C:\left|z-a_{i i}\right| \leq \alpha r_{i}^{S}(A)+(1-\alpha) c_{i}^{S}(A)+r_{i}^{\bar{S}}(A)\right\}
$$

According to Theorem 10 and the generalized arithmetic-geometric mean inequality, we can obtain easily the following subclass of $H$-matrices and the corresponding eigenvalue localization set.

Theorem 12. If for an irreducible matrix $A=\left(a_{i j}\right) \in C^{n \times n}$, there exists $\alpha \in[0,1]$ and $k \in N$ such that for each subset $S \subset N$ of cardinality $k$.

$$
\begin{equation*}
\left|a_{i i}\right| \geq \alpha r_{i}^{S}(A)+(1-\alpha) c_{i}^{S}(A)+r_{i}^{\bar{S}}(A) \tag{11}
\end{equation*}
$$

holds, with at least one inequality in (11) being strict, then $A$ is nonsingular, moreover it is an $H$-matrix.

Corollary 3. For any $A=\left(a_{i j}\right) \in C^{n \times n}$, and any $\alpha \in[0,1]$, then

$$
\sigma(A) \subseteq \bigcap_{k \in N / S|S|=k} \bigcup\left(\left(\bigcup_{i \in S_{1}} \gamma_{i}^{\alpha, k, S_{1}}\right) \cup\left(\bigcup_{i \in S_{2}} \gamma_{i}^{\alpha, k, S_{2}}\right)\right)
$$

where

$$
\begin{aligned}
& \gamma_{i}^{\alpha, k, S_{1}}=\left\{z \in C:\left|z-a_{i i}\right| \leq \alpha r_{i}^{S}(A)+(1-\alpha) c_{i}^{S}(A)+r_{i}^{\bar{S}}(A)\right\} \\
& \gamma_{i}^{\alpha, k, S_{2}}=\left\{z \in C:\left|z-a_{i i}\right|<\alpha r_{i}^{S}(A)+(1-\alpha) c_{i}^{S}(A)+r_{i}^{\bar{S}}(A)\right\}
\end{aligned}
$$

and $S_{2}=S \backslash S_{1}$ with $S_{1}$ is the set of indices for which strict inequality holds in (11).

## 4. Simplifications of Eigenvalue Localization Sets

The eigenvalue localization sets in Theorem 9 and Corollary 2 are not of much practical use because of the restriction of $\alpha$. To solve this problem, we in this section use the method provided in [5] [6], and obtain more convenient forms of the two eigenvalue localization sets. First, the sufficient and necessary conditions of generalized $\alpha$-matrices and generalized sum $\alpha$-matrices are given.

For a matrix $A=\left(a_{i j}\right) \in C^{n \times n}$ with $n \geq 2$, and for $S \subseteq N$ of cardinality $k \in N$, we partition the set of indices S into three sets:

$$
\begin{aligned}
& R=\left\{i \in S: r_{i}^{S}(A)>c_{i}^{S}(A)\right\} \\
& C=\left\{i \in S: r_{i}^{S}(A)<c_{i}^{S}(A)\right\} \\
& L=\left\{i \in S: r_{i}^{S}(A)=c_{i}^{S}(A)\right\}
\end{aligned}
$$

where $r_{i}^{S}(A)=c_{i}^{S}(A)=0$.
Consequently, $R=C=0$ if $k=1$. Obviously, $S=R \bigcup C \bigcup L$.
Lemma 13. A matrix $A=\left(a_{i j}\right) \in C^{n \times n}$ with $n \geq 2$, is a generalized $\alpha$-matrix if and only if there exists $k \in N$, such that for each subset $S \subseteq N$ of cardinality $k$ the following two conditions hold:

1) $\left|a_{i i}\right|>\min \left\{r_{i}^{S}(A), c_{i}^{S}(A)\right\}+r_{i}^{\bar{S}}(A), i \in S$;
2) $\log _{\frac{r_{i}^{S}(A)}{c_{i}^{S}(A)}} \frac{\left|a_{i i}\right|-r_{i}^{S}(A)}{c_{i}^{S}(A)}>\log _{\frac{r_{j}^{S}(A)}{c_{j}^{S}(A)}} \frac{c_{j}^{S}(A)}{\left|a_{i i}\right|-r_{i}^{S}(A)}$,
for each $i \in R$, for which $c_{i}^{S}(A) \neq 0$, and for each $j \in C$, for which $r_{j}^{S}(A) \neq 0$.

Proof. The case $k=1$ : The class of generalized $\alpha$-matrices reduces to strictly diagonally dominant matrices. And note that the condition (1) changes to

$$
\left|a_{i i}\right|>r_{i}^{\bar{S}}(A)=r_{i}(A), i \in S
$$

This also holds for each $S \subseteq N$ of cardinality $k=1$, that is, for any $i \in N$, $\left|a_{i i}\right|>r_{i}(A)$, which implies that $A$ is strictly diagonally dominant.

The case $k=\mathrm{n}$ : The class of generalized $\alpha$-matrices reduces to $\alpha_{2}$-matrices. On the other hand, the condition (1) changes to

$$
\left|a_{i i}\right|>\min \left\{r_{i}^{S}(A), c_{i}^{S}(A)\right\}=\min \left\{r_{i}(A), c_{i}(A)\right\} .
$$

And the condition (2) changes to

$$
\log _{\frac{r_{i}^{s}(A)}{c_{i}^{S}(A)}} \frac{\left|a_{i i}\right|}{c_{i}(A)}>\log _{\frac{c_{j}^{s}(A)}{r_{j}^{S}(A)}} \frac{c_{j}(A)}{\left|a_{i i}\right|}, i \in S
$$

Hence by Theorem 5 in [5], $A$ in this case is an $\alpha_{2}$-matrix.
The case $1<k<n$ : Similar to the proof of Theorem 5 in [5], the conclusion in this case follows easily.

Similar to the proof of Lemma 13, for generalized sum $\alpha$-matrices we also obtain easily its sufficient and necessary condition by Theorem 4 in [5].

Lemma 14. A matrix $A=\left(a_{i j}\right) \in C^{n \times n}$ with $n \geq 2$, is a generalized sum $\alpha$-matrix if and only if there exists $k \in N$ such that for each subset $S \subseteq N$ of cardinality $k$ the following two conditions hold:

1) $\left|a_{i i}\right|>\min \left\{r_{i}^{S}(A), c_{i}^{S}(A)\right\}+r_{i}^{\bar{S}}(A), i \in S$;
2) $\frac{\left|a_{i i}\right|-r_{i}^{S}(A)-c_{i}^{S}(A)}{r_{i}^{S}(A)-c_{i}^{S}(A)}>\frac{c_{i}^{S}(A)-\left(\left|a_{i i}\right|-r_{i}^{\bar{S}}(A)\right)}{c_{i}^{S}(A)-r_{i}^{S}(A)}$
for each $i \in R$ and each $j \in C$.
We now establish two eigenvalue localization sets by Lemmas 13 and 14, which are the equivalent forms of the sets in Theorem 9 and Corollary 2 respectively.

Corollary 4. For any $A=\left(a_{i j}\right) \in C^{n \times n}$, then

$$
\sigma(A) \subseteq \bar{\Gamma}^{k, S}(A) \cup \hat{\Gamma}^{k, S}(A)
$$

where

$$
\begin{gathered}
\bar{\Gamma}^{k, S}(A)=\bigcap_{k \in N / S} \bigcup_{|S|=k} \bigcup_{i \in S}\left\{z \in C:\left|z-a_{i i}\right| \leq \min \left(r_{i}^{S}(A), c_{i}^{S}(A)\right)+r_{i}^{\bar{S}}(A)\right\} ; \\
\hat{\Gamma}^{k, S}(A)=\bigcap_{k \in N \backslash S} \bigcup_{|S|=k} \bigcup_{\substack{ \\
i \in R \subseteq S, c_{i}^{S}(A) \neq 0 \\
j \in C \subseteq S, r_{i}^{S}(A) \neq 0}} \hat{\Gamma}_{i j}^{k, S}(A) ;
\end{gathered}
$$

and

$$
\hat{\Gamma}_{i j}^{k, S}(A)=\left\{z \in C: \frac{\left|z-a_{i i}\right|-r_{i}^{\bar{S}}(A)}{c_{i}^{S}(A)}\left(\frac{\left|z-a_{i j}\right|-r_{j}^{\bar{S}}(A)}{c_{j}^{S}(A)}\right)^{\log _{i}^{\log _{i}^{S}(A)} \bar{c}_{i}^{r_{i}^{S}(A)}} c_{c_{i}^{S}(A)}^{r^{S}} \leq 1\right\} .
$$

Proof. For any $\lambda \in \sigma(A), \quad \lambda I-A$ is singular. Note that the moduli of every off-diagonal entry of $\lambda I-A$ is the same as $A$. Hence, for each $S \subseteq N$, the sets $R \subseteq N$ and $C \subseteq N$ for the matrix $\lambda I-A$ remain the same. If $\lambda \neq \bar{\Gamma}^{k, S}(A) \cup \hat{\Gamma}^{k, S}(A)$, then $\lambda I-A$ satisfies the conditions (1) and (2) of Lemma 13, hence $\lambda I-A$ is a generalized $\alpha$-matrix, which implies that $\lambda I-A$ is nonsingular. This is a contradiction. Hence, $\lambda=\bar{\Gamma}^{k, S}(A) \cup \hat{\Gamma}^{k, S}(A)$.

Combining with Lemma 14 and similar to the proof of Corollary 4, we have the following result.

Corollary 5. For any $A=\left(a_{i j}\right) \in C^{n \times n}$, then

$$
\sigma(A) \subseteq \bar{\Gamma}^{k, S}(A) \cup \hat{\gamma}^{k, S}(A)
$$

where $\bar{\Gamma}^{k, S}(A)$ is defined as Corollary 4,

$$
\hat{\gamma}^{k, S}(A)=\bigcap_{k \in N / S} \bigcup_{|S|=k} \bigcup_{\substack{i \in R \subseteq S \\ j \in C \subseteq S}} \hat{\gamma}_{i j}^{k, S}(A)
$$

and

$$
\begin{aligned}
\hat{\gamma}^{k, S}(A)= & \left\{z \in C:\left(\left|z-a_{i i}\right|-r_{i}^{\bar{S}}(A)\right)\left(c_{j}^{S}(A)-r_{j}^{S}(A)\right)\right. \\
& +\left(\left|z-a_{j j}\right|-r_{j}^{\bar{S}}(A)\right)\left(r_{i}^{S}(A)-c_{i}^{S}(A)\right) \\
& \left.\leq c_{j}^{S}(A) r_{i}^{S}(A)-c_{i}^{S}(A) r_{j}^{S}(A)\right\}
\end{aligned}
$$

Remark 1. Obviously, the forms of the sets in Corollaries 4 and 5, which are without the restriction of $\alpha$, are easier to be determined than those in Theorem 9 and Corollary 2. In addition, similar to the proof of Lemma 3.5 in [6], we can prove that the set in Corollary 4 is tighter than that in Corollary 5, i.e.,

$$
\left(\bar{\Gamma}^{k, S}(A) \cup \hat{\Gamma}^{k, S}(A)\right) \subseteq\left(\bar{\Gamma}^{k, S}(A) \cup \hat{\gamma}^{k, S}(A)\right)
$$

However, $\bar{\Gamma}^{k, S}(A) \cup \hat{\Gamma}^{k, S}(A)$ is determined more difficultly than
$\bar{\Gamma}^{k, S}(A) \bigcup \hat{\gamma}^{k, S}(A)$. because it is difficult to compute exactly $\log _{\frac{c_{j}^{S}(A)}{r_{j}^{S}(A)}} \frac{r_{i}^{S}(A)}{c_{i}^{S}(A)}$ in some cases.

## 5. Conclusion

In this paper, we present a new class of matrices-generalized irreducible $\alpha$-matrices, and prove that a generalized irreducible $\alpha$-matrix is an $H$-matrix. Furthermore, using the generalized arithmetic-geometric mean inequality, we obtain two new classes of $H$-matrices. As applications of the obtained results, three regions including all the eigenvalues of a matrix are given.

## Acknowledgements

This work is supported by Applied Basic Research Project of Yunnan Province
(No. 2018FB001), CAS "Light of West China" Program and Program for Excellent Young Talents, Yunnan University.

## Conflicts of Interest

The authors declare no conflicts of interest regarding the publication of this paper.

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