

# Mixture Ratio Estimators Using Multi-Auxiliary Variables and Attributes for Two-Phase Sampling

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## Abstract

In this paper, we have proposed three classes of mixture ratio estimators for estimating population mean by using information on auxiliary variables and attributes simultaneously in two-phase sampling under full, partial and no information cases and analyzed the properties of the estimators. A simulated study was carried out to compare the performance of the proposed estimators with the existing estimators of finite population mean. It has been found that the mixture ratio estimator in full information case using multiple auxiliary variables and attributes is more efficient than mean per unit, ratio estimator using one auxiliary variable and one attribute, ratio estimator using multiple auxiliary variable and multiple auxiliary attributes and mixture ratio estimators in both partial and no information case in two-phase sampling. A mixture ratio estimator in partial information case is more efficient than mixture ratio estimators in no information case.

## Keywords

Ratio Estimator, Multiple Auxiliary Variables, Multiple Auxiliary Attributes, Two-Phase Sampling, Bi-Serial Correlation Coefficient

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## 1. Introduction

The history of using auxiliary information in survey sampling is as old as history of the survey sampling. The work of Neyman [1] may be referred to as the initial works where auxiliary information has been used. Cochran [2] used auxiliary information in single-phase sampling to develop the ratio estimator for estimation of population mean. In the ratio estimator, the study variable and the auxiliary variable had a high positive correlation and the regression line was passing through the origin. Hansen and Hurwitz [3] also suggested the use of auxiliary

information in selecting the sample with varying probabilities. If regression line is still linear but does not pass through the origin the regression estimator is used. Watson [4] used the regression estimator of leaf area on leaf weight to estimate the average area of the leaves on a plant.

Olkin [5] was the first person to use information on more than one auxiliary variable, which was positively correlated with the variable under study, using a linear combination of ratio estimator based on each auxiliary variable. Raj [6] suggested a method of using multi-auxiliary information in sample survey. Singh [7] proposed a ratio-cum-product estimator and its multi-variable expression.

The concept of double sampling was first proposed by Neyman [1] in sampling human populations when the mean of auxiliary variable was unknown. It was later extended to multi-phase by Robson [8]. Ahmad [9] proposed a generalized multivariate ratio and regression estimators for multi-phase sampling while Zahoor, Muhammad and Munir [10] suggested a generalized regression-cum-ratio estimator for two-phase sampling using multiple auxiliary variables.

Jhajj, Sharma and Grover [11] proposed a family of estimators using information on auxiliary attribute. They used known information of population proportion possessing an attribute (highly correlated with study variable  $Y$ ). The attribute are normally used when the auxiliary variables are not available e.g. amount of milk produced and a particular breed of cow or amount of yield of wheat and a particular variety of wheat. Jhajj, Sharma and Grover [11] used the information on auxiliary attributes in ratio estimator in estimating population mean of the variable of interest using known attributes such as coefficient of variation, coefficient kurtosis and point bi-serial correlation coefficient. The estimator performed better than the usual sample mean and Naik and Gupta [12] estimator. Jhajj, Sharma and Grover [11] also used the auxiliary attribute in regression, product and ratio type exponential estimator following the work of Bahl and Tuteja [13].

Hanif, Haq and Shahbaz [14] proposed a general family of estimators using multiple auxiliary attribute in single- and double-phase sampling. The estimator had a smaller MSE compared to that of Jhajj, Sharma and Grover [11]. They also extended their work to ratio estimator which was generalization of Naik and Gupta [12] estimator in single- and double-phase samplings with full information, partial information and no information. Kung'u and Odongo [15] and [16] proposed ratio-cum-product estimators using multiple auxiliary attributes in single- and two-phase sampling. Moeen, Shahbaz and Hanif [17] proposed a class of mixture ratio and regression estimators for single-phase sampling for estimating population mean by using information on auxiliary variables and attributes simultaneously.

In this paper, we will extend the mixture ratio estimator proposed by Moeen, Shahbaz and Hanif [17] in single-phase sampling to two-phase sampling under full, partial and no information case strategies introduced by Samiuddin and Hanif [18] and also incorporate Arora and Bansi [19] approach in writing down the mean squared error.

## 2. Preliminaries

### 2.1. Notation and Assumption

Consider a population of  $N$  units. Let  $Y$  be the variable for which we want to estimate the population mean and  $X_1, X_2, \dots, X_k$  are  $k$  auxiliary variables. For two-phase sampling design let  $n_1$  and  $n_2$  ( $n_2 < n_1$ ) are sample sizes for first and second phase respectively.  $x_{j(1)}$  and  $x_{j(2)}$  denote the  $j^{\text{th}}$  auxiliary variables from first and second phase samples respectively and  $y_2$  denote the variable of interest from second phase.  $X_j$  and  $C_{x_j}$  denote the population means and coefficient of variation of  $j^{\text{th}}$  auxiliary variables respectively and  $\rho_{yx_j}$  denotes the population correlation coefficient of  $Y$  and  $X_j$ .

Further, let  $\theta_1 = \left( \frac{1}{n_1} - \frac{1}{N} \right)$   $\theta_2 = \left( \frac{1}{n_2} - \frac{1}{N} \right)$  ( $\theta_1 < \theta_2$ )

$$\begin{aligned} y_{(2)} &= Y + e_{y_{(2)}}, & x_{j(1)} &= X_j + e_{x_{j(1)}} \\ \text{and } x_{j(2)} &= X_j + e_{x_{j(2)}} & (j &= (1, 2, \dots, k)) \end{aligned} \quad (1.0)$$

where  $\bar{e}_{y_2}$ ,  $\bar{e}_{x_{j(1)}}$  and  $\bar{e}_{x_{j(2)}}$  are sampling error and are very small. We assume that

$$E(\bar{e}_{y_2}) = E(\bar{e}_{x_{j(1)}}) = E(\bar{e}_{x_{j(2)}}) = 0. \quad (1.1)$$

Consider a sample of size  $n$  drawn by simple random sampling without replacement from a population of size  $N$ . Let  $y_j$  and  $\tau_j$  denotes the observations on variable  $y$  and  $r$  respectively for the  $j^{th}$  unit where  $j = k+1, k+2, \dots, q$ .

In defining the attributes we assume complete dichotomy so that,

$$\tau_{ij} = \begin{cases} 1, & \text{if } i^{th} \text{ unit of population possess } j^{th} \text{ auxiliary attribute,} \\ 0, & \text{otherwise.} \end{cases} \quad (1.2)$$

Let  $A_j = \sum_{i=1}^N \tau_{ij}$  and  $a_j = \sum_{i=1}^n \tau_{ij}$  be the total number of units in the population and sample respectively possessing attribute  $\tau_j$ . Let  $P_j = \frac{A_j}{N}$  and  $p_{j(2)} = \frac{a_j}{n}$  be the corresponding proportion of units possessing a specific attributes  $\tau_j$  and  $\bar{y}$  is the mean of the main variable at second phase. Let  $p_{j(1)}$  and  $p_{j(2)}$  denote the  $j^{th}$  auxiliary attribute form first and second phase samples respectively and  $y_2$  denote the variable of interest from second phase. The mean of main variable of interest at second phase will be denoted by  $\bar{y}_2$ . Also let us define

$$\bar{e}_{\tau_{j(1)}} = p_{j(1)} - P_j, \quad \bar{e}_{\tau_{j(2)}} = p_{j(2)} - P_j \quad (1.3)$$

where  $\bar{e}_{y_2}$ ,  $\bar{e}_{\tau_{j(1)}}$  and  $\bar{e}_{\tau_{j(2)}}$  are sampling error and are very small. We assume that

$$E(\bar{e}_{y_2}) = E(\bar{e}_{\tau_{j(1)}}) = E(\bar{e}_{\tau_{j(2)}}) = 0.$$

Let  $v_j = \frac{\bar{x}_{(2)j}}{\bar{X}_j}$ , then  $v_j - 1 = \frac{\bar{x}_{(2)j}}{\bar{X}_j} - 1 = \frac{\bar{x}_{(2)j} - \bar{X}_j}{\bar{X}_j} = \frac{\bar{e}_{x_{(2)j}}}{\bar{X}_j}$ . Therefore  $v_j = 1 + \frac{\bar{e}_{x_{(2)j}}}{\bar{X}_j}$ . Similarly,  $w_j = 1 + \frac{\bar{e}_{\tau_{(2)j}}}{P_j}$ .

Also  $z_j = \frac{\bar{x}_{(2)j}}{\bar{x}_{(1)j}}$ , then

$$v_j - 1 = \frac{\bar{x}_{(2)j} - \bar{x}_{(1)j}}{\bar{x}_{(1)j}} = \frac{\bar{e}_{x_{(2)j}} - \bar{e}_{x_{(1)j}}}{\bar{x}_{(1)j}} = \frac{\bar{e}_{x_{(2)j}} - \bar{e}_{x_{(1)j}}}{\bar{e}_{x_{(1)j}} + \bar{X}_j} = \frac{\bar{e}_{x_{(2)j}} - \bar{e}_{x_{(1)j}}}{\bar{X}_j \left( 1 + \frac{\bar{e}_{x_{(1)j}}}{\bar{X}_j} \right)} = \frac{\bar{e}_{x_{(2)j}} - \bar{e}_{x_{(1)j}}}{\bar{X}_j} \left( 1 + \frac{\bar{e}_{x_{(1)j}}}{\bar{X}_j} \right)^{-1}.$$

We shall take  $v_i - 1$  to term of order  $\frac{1}{n}$  as  $v_j - 1 = \frac{\bar{e}_{x_{(2)j}} - \bar{e}_{x_{(1)j}}}{\bar{X}_j}$  hence,

$$z_j = 1 + \frac{\bar{e}_{x_{(2)j}} - \bar{e}_{x_{(1)j}}}{\bar{X}_j} = 1 - \frac{\bar{e}_{x_{(1)j}} - \bar{e}_{x_{(2)j}}}{\bar{X}_j}.$$

Similarly,

$$u_j = 1 - \frac{\bar{e}_{\tau_{(1)j}} - \bar{e}_{\tau_{(2)j}}}{P_j}. \quad (1.4)$$

The coefficient of variation and correlation coefficient are given by

$$C_y^2 = \frac{S_{y_2}^2}{\bar{Y}^2}, \quad C_{x_1}^2 = \frac{S_{x_1}^2}{\bar{X}_1^2}, \quad C_{\tau_1}^2 = \frac{S_{\tau_1}^2}{\bar{P}_1^2}, \quad \rho_{yx} = \frac{S_{yx}}{S_y S_x}, \quad (1.5)$$

$$\rho_{yz} = \frac{S_{yz}}{S_y S_z}, \quad \rho_{Pb_1} = \frac{S_{y\tau}}{S_y S_\tau}, \quad \text{and} \quad \rho_{Pb_1} = \frac{S_{y\tau}}{S_y S_\tau}.$$

Then for simple random sampling without replacement for both first and second phases we write by using phase wise operation of expectations as:

$$\begin{aligned}
 E(\bar{e}_{y_2})^2 &= \theta_2 \bar{Y}^2 C_{y_2}^2, \quad E(\bar{e}_{\tau_{j(1)}} - \bar{e}_{\tau_{j(2)}})^2 = (\theta_2 - \theta_1) P_j^2 C_{\tau_j}^2, \quad E(\bar{e}_{x_{j(1)}} - \bar{e}_{x_{j(2)}})^2 = (\theta_2 - \theta_1) \bar{X}_j^2 C_{x_j}^2, \\
 E(\bar{e}_{y_2} \bar{e}_{x_{j(2)}})^2 &= \theta_2 \bar{Y} \bar{X}_j C_{y_2} C_{x_j} \rho_{yx_j}, \quad E(\bar{e}_{y_2} \bar{e}_{\tau_{j(2)}})^2 = \theta_2 \bar{Y} P_j C_{y_2} C_{\tau_j} \rho_{Pb\tau_j}, \\
 E(\bar{e}_{y_2} (\bar{e}_{x_{j(1)}} - \bar{e}_{x_{j(2)}})) &= (\theta_1 - \theta_2) \bar{Y} \bar{X}_j C_{y_2} C_{x_j} \rho_{yx_j}, \quad E(\bar{e}_{x_{j(2)}} (\bar{e}_{x_{j(1)}} - \bar{e}_{x_{j(2)}})) = (\theta_1 - \theta_2) \bar{X}_j^2 C_{x_j}^2, \\
 E(\bar{e}_{\tau_{j(2)}} (\bar{e}_{\tau_{j(1)}} - \bar{e}_{\tau_{j(2)}})) &= (\theta_1 - \theta_2) P_j^2 C_{\tau_j}^2, \quad E(\bar{e}_{x_{j(2)}} \bar{e}_{x_{j(2)}}) = \theta_2 \bar{X}_i \bar{X}_j C_{x_i} C_{x_j} \rho_{x_i x_j} \quad (i \neq j), \\
 E(\bar{e}_{\tau_{i(2)}} \bar{e}_{\tau_{j(2)}}) &= \theta_2 P_i P_j C_{\tau_i} C_{\tau_j} \rho_{Pb\tau_i \tau_j} \quad (i \neq j), \quad E(\bar{e}_{y_2} (\bar{e}_{x_{j(1)}} - \bar{e}_{x_{j(2)}})) = (\theta_1 - \theta_2) \bar{Y} \bar{X}_j C_{y_2} C_{x_j} \rho_{yx_j}, \\
 E((\bar{e}_{\tau_{i(1)}} - \bar{e}_{\tau_{i(2)}}) (\bar{e}_{\tau_{j(1)}} - \bar{e}_{\tau_{j(2)}})) &= (\theta_2 - \theta_1) P_i P_j C_{\tau_i} C_{\tau_j} \rho_{\tau_i \tau_j}; \quad (i \neq j) \\
 E((\bar{e}_{x_{i(1)}} - \bar{e}_{x_{i(2)}}) (\bar{e}_{x_{j(1)}} - \bar{e}_{x_{j(2)}})) &= (\theta_2 - \theta_1) \bar{X}_i \bar{X}_j C_{x_i} C_{x_j} \rho_{x_i x_j}; \quad (i \neq j) \\
 E(\bar{e}_{x_{j(2)}} (\bar{e}_{x_{i(1)}} - \bar{e}_{x_{i(2)}})) &= (\theta_1 - \theta_2) \bar{X}_i \bar{X}_j C_{x_i} C_{x_j} \rho_{x_i x_j}; \quad (i \neq j) \\
 E(\bar{e}_{\tau_{i(2)}} (\bar{e}_{\tau_{j(1)}} - \bar{e}_{\tau_{j(2)}})) &= (\theta_1 - \theta_2) P_i P_j C_{\tau_i} C_{\tau_j} \rho_{\tau_i \tau_j}; \quad (i \neq j)
 \end{aligned}
 \tag{1.6}$$

$$A^{-1} = \frac{1}{|A|} (C^T)_{ij} = \frac{Adj(A)}{|A|} \tag{1.7}$$

$$\frac{|R|_{y_{x_q}}}{|R|_{x_q}} = (1 - \rho_{y_{x_q}}^2) \text{ Arora and Lai [19]} \tag{1.8}$$

The following notations will be used in deriving the mean square errors of proposed estimators.

$|R|_{y_{x_q}}$  : Determinant of population correlation matrix of variables  $y, x_1, x_2, \dots, x_{q-1}$  and  $x_q$ .

$|R|_{y_{x_i}}|_{y_{x_q}}$  : Determinant of  $i^{th}$  minor of  $|R|_{y_{x_q}}$  corresponding to the  $i^{th}$  element of  $\rho_{yx_i}$ .

$\rho_{yx_r}^2$  : Denotes the multiple coefficient of determination of  $y$  on  $x_1, x_2, \dots, x_{r-1}$  and  $x_r$ .

$\rho_{y_{x_q}}^2$  : Denotes the multiple coefficient of determination of  $y$  on  $y, x_1, x_2, \dots, x_{q-1}$  and  $x_q$ .

$|R|_{x_r}$  : Determinant of population correlation matrix of variables  $x_1, x_2, \dots, x_{r-1}$  and  $x_r$ .

$|R|_{x_q}$  : Determinant of population correlation matrix of variables  $x_1, x_2, \dots, x_{q-1}$  and  $x_q$ .

$|R|_{y_i x_r}$  : Determinant of the correlation matrix of  $y_i, x_1, x_2, \dots, x_{r-1}$  and  $x_r$ .

$|R|_{y_i \cdot x_q}$  : Determinant of the correlation matrix of  $y_i, x_1, x_2, \dots, x_{q-1}$  and  $x_q$ .

$|R|_{y_i \cdot y_j \cdot x_r}$  : Determinant of the minor corresponding to  $\rho_{y_i y_j}$  of the correlation matrix of

$y_i, y_j, x_1, x_2, \dots, x_{r-1}$  and  $x_r$  ( $i \neq j$ ).

$|R|_{y_i \cdot y_j \cdot x_q}$  : Determinant of the minor corresponding to  $\rho_{y_i y_j}$  of the correlation matrix of

$y_i, y_j, x_1, x_2, \dots, x_{q-1}$  and  $x_q$  ( $i \neq j$ ). (1.9)

## 2.2. Mean per Unit in Two-Phase Sampling

The sample mean  $\bar{y}_2$  using simple random sampling without replacement in two-phase sampling is given by is given by,

$$\bar{y}_2 = \frac{1}{n_2} \sum_{i=1}^{n_2} y_i \tag{2.0}$$

while its variance is given,

$$\text{Var}(\bar{y}_2) = \theta_2 \bar{Y}^2 C_y^2. \tag{2.1}$$

### 2.3. Ratio Estimator Using Auxiliary Variable in Two-Phase Sampling

Let  $\bar{x}_2 = \frac{1}{n_2} \sum_{i=1}^{n_2} x_i$  be the sample mean of the auxiliary variable in two-phase sampling. The ratio estimator when information on one auxiliary variables is available for population (*full information case*) is:

$$t_{RV} = \bar{y}_2 \left( \frac{\bar{X}_1}{\bar{x}_2} \right)^{\alpha_1}. \tag{2.2}$$

The mean square error of  $t_{RV}$  can be written as:

$$\text{MSE}(t_{RV}) = \theta_2 \bar{Y}^2 \left( C_{y_2}^2 + \alpha_1^2 C_x^2 - 2\alpha_1 C_x C_y \rho_{yx} \right) \tag{2.3}$$

where  $\alpha_1 = \frac{C_y \rho_{yx}}{C_x}$  and  $\rho_{yx}$  are the optimum value and the correlation coefficient respectively.

### 2.4. Ratio Estimator Using Multiple Auxiliary Variables in Two-Phase Sampling

The ratio estimator by Haq [9] when information on  $k$  auxiliary variables is available for population (*full information case*) is:

$$t_{RMV} = \bar{y}_2 \left( \frac{\bar{X}_1}{\bar{x}_{(2)1}} \right)^{\beta_1} \left( \frac{\bar{X}_2}{\bar{x}_{(2)2}} \right)^{\beta_2} \dots \left( \frac{\bar{X}_k}{\bar{x}_{(2)k}} \right)^{\beta_k}. \tag{2.4}$$

The optimum values of unknown constants are,

$$\beta_j = (-1)^{j+1} \frac{C_y \left| R_{yx_j} \right|_{yx_k}}{C_{x_j} \left| R \right|_{x_k}}. \tag{2.5}$$

The mean square error of  $t_{RMV}$  can be written as:

$$\text{MSE}(t_{RMV}) = \theta_2 \bar{Y}^2 C_y^2 \left( 1 - \rho_{yx_k}^2 \right). \tag{2.6}$$

### 2.5. Ratio Estimator Using Auxiliary Attribute in Two-Phase Sampling

In order to have an estimate of the population mean  $\bar{Y}$  of the study variable  $y$ , assuming the knowledge of the population proportion  $P$ , Naik and Gupta [12] defined ratio estimator of population mean when the prior information of population proportion of units possessing the same attribute is variable. Naik and Gupta [12] proposed the following estimator:

$$t_{RA} = \bar{y}_2 \left( \frac{P}{p_2} \right)^{\alpha_1}. \tag{2.7}$$

The MSE of  $t_{RA}$  up to the first order of approximation are given respectively by,

$$\text{MSE}(t_{RA}) = \theta_2 \bar{Y}^2 \left( C_y^2 + \alpha_1^2 C_p^2 - 2\alpha_1 C_p C_y \rho_{pb\tau_j} \right) \tag{2.8}$$

where  $\alpha_1 = \frac{C_y \rho_{yx}}{C_x}$  and  $\rho_{pb\tau}$  are the optimum value and the bi-serial correlation coefficient respectively.

### 2.6. Ratio Estimator Using Multiple Auxiliary Attributes in Two-Phase Sampling

The ratio estimators by Hanif, Haq and Shahbaz [14] for two-phase sampling using information on multiple

auxiliary attributes is given by,

$$t_{MRA} = \bar{y}_2 \left( \frac{P_1}{P_{(2)1}} \right)^{\gamma_1} \left( \frac{P_2}{P_{(2)2}} \right)^{\gamma_2} \dots \left( \frac{P_q}{P_{(2)q}} \right)^{\gamma_q}. \tag{2.9}$$

The optimum values of unknown constants are,

$$\gamma_j = (-1)^{j+1} \frac{C_y}{C_{\tau_j}} \frac{|R_{y\tau_j}|_{y\tau_j}}{|R|_{\tau_j}}. \tag{2.10}$$

The MSE of the  $t_{MRA}$  up to the first order of approximation is given by,

$$MSE(t_{MRA}) = \theta_2 \bar{Y}^2 C_{y_2}^2 (1 - \rho_{Pb\tau_q}^2). \tag{2.11}$$

In general these estimators have a bias of order  $\frac{1}{n}$ . Since the standard error of the estimates is of order  $\frac{1}{\sqrt{n}}$ ,

the quantity  $\text{bias}/s.e$  is of order  $\frac{1}{\sqrt{n}}$  and becomes negligible as  $n$  becomes large.

### 3. Methodology

#### 3.1. Mixture Ratio Estimators Using Multi-Auxiliary Variable and Attributes for Two-Phase Sampling (Full Information Case)

If we estimate a study variable when information on all auxiliary variables is available from population, it is utilized in the form of their means. By taking the advantage of mixture ratio estimators technique for two-phase sampling, a generalized estimator for estimating population mean of study variable  $Y$  with the use of multi auxiliary variables and attributes are suggested as:

$$t_{MRVAF(3.0)} = \bar{y}_2 \left( \frac{\bar{X}_1}{\bar{X}_{(2)1}} \right)^{\alpha_1} \left( \frac{\bar{X}_2}{\bar{X}_{(2)2}} \right)^{\alpha_2} \dots \left( \frac{\bar{X}_k}{\bar{X}_{(2)k}} \right)^{\alpha_k} \left( \frac{P_{k+1}}{P_{(2)k+1}} \right)^{\beta_{k+1}} \left( \frac{P_{k+2}}{P_{(2)k+2}} \right)^{\beta_{k+2}} \dots \left( \frac{P_t}{P_{(2)t}} \right)^{\beta_t}. \tag{3.0}$$

Using (1.0), (1.3) and (1.4) in (3.0) and ignoring the second and higher terms for each expansion of product and after simplification, we write,

$$t_{MRVAF(3.0)} = \bar{e}_{y_2} + \bar{Y} - \sum_{j=1}^k \alpha_j \bar{Y} \frac{\bar{e}_{x(2)j}}{\bar{X}_j} - \sum_{j=k+1}^{h+k=t} \beta_j \bar{Y} \frac{\bar{e}_{\tau(2)j}}{P_j}. \tag{3.1}$$

The mean squared error of  $t_{MRVAF(3.0)}$  is given by,

$$MSE(t_{MRVAF(3.0)}) = E(t_{MRVAF(3.0)} - \bar{Y})^2 = E \left( \bar{e}_{y_2} - \sum_{j=1}^k \alpha_j \bar{Y} \frac{\bar{e}_{x(2)j}}{\bar{X}_j} - \sum_{j=k+1}^{h+k=t} \beta_j \bar{Y} \frac{\bar{e}_{\tau(2)j}}{P_j} \right)^2. \tag{3.2}$$

We differentiate the Equation (3.2) partially with respect to  $\alpha_j$  ( $i = 1, 2, \dots, k$ ) and  $\beta_j$  ( $i = k + 1, k + 2, \dots, t$ ) then equate to zero, using (1.6), (1.7) and (1.9), we get

$$\alpha_j = (-1)^{j+1} \frac{C_y}{C_{x_j}} \frac{|R_{yx_j}|_{x_j}}{|R|_{x_j}} \tag{3.3}$$

$$\beta_j = (-1)^{j+1} \frac{C_y}{C_{\tau_j}} \frac{|R_{y\tau_j}|_{\tau_j}}{|R|_{\tau_j}}. \tag{3.4}$$

Using normal equation that is used to find the optimum values given (3.2) we can write,

$$\text{MSE}(t_{\text{MRVAF}(3.0)}) = E \left( \bar{e}_{y_2} \left( \bar{e}_{y_2} - \sum_{j=1}^k \alpha_j \bar{Y} \frac{\bar{e}_{x(2)j}}{\bar{X}_j} - \sum_{j=k+1}^{h+k=t} \beta_j \bar{Y} \frac{\bar{e}_{\tau(2)j}}{P_j} \right) \right). \tag{3.5}$$

Taking expectation and using (1.6) in (3.5), we get,

$$\text{MSE}(t_{\text{MRVAF}(3.0)}) = \theta_2 \bar{Y}^2 \left( C_y^2 - \sum_{j=1}^k \alpha_j \frac{\bar{Y}}{\bar{X}_j} \bar{X}_j C_y C_{x_j} \rho_{yx_j} - \sum_{j=k+1}^{k+h=t} \frac{\bar{Y}}{P_j} P_j \beta_j C_y C_{\tau_j} \rho_{Pb_j} \right). \tag{3.6}$$

Substituting the optimum (3.3) and (3.4) in (3.6), we get,

$$\text{MSE}(t_{\text{MRVAF}(3.0)}) = \theta_2 \bar{Y}^2 \left( C_y^2 + \sum_{j=1}^k (-1)^j \frac{C_y}{C_{x_j}} \frac{|R_{yx_j}|_{x_j}}{|R_{x_j}|} C_y C_{x_j} \rho_{yx_j} + \sum_{j=1}^{k+h=t} (-1)^j \frac{C_y}{C_{\tau_j}} \frac{|R_{y\tau_j}|_{\tau_j}}{|R_{\tau_j}|} C_y C_{\tau_j} \rho_{Pb_j} \right). \tag{3.7}$$

Or

$$\text{MSE}(t_{\text{MRVAF}(3.0)}) = \theta_2 \bar{Y}^2 C_y^2 \left( 1 + \left( \sum_{j=1}^k (-1)^j \frac{|R_{yx_j}|_{x_j}}{|R_{x_j}|} \rho_{yx_j} + \sum_{j=k+1}^{k+h=t} (-1)^j \frac{|R_{y\tau_j}|_{\tau_j}}{|R_{\tau_j}|} \rho_{Pb_j} \right) \right). \tag{3.8}$$

Or

$$\text{MSE}(t_{\text{MRVAF}(3.0)}) = \theta_2 \bar{Y}^2 C_y^2 \frac{|R|_{y(x,\tau)_t}}{|R|_{(x,\tau)_t}}. \tag{3.9}$$

Using (1.8), we get,

$$\text{MSE}(t_{\text{MRVA}(3.0)}) = \theta_2 \bar{Y}^2 C_y^2 (1 - \rho_{y.(x,\tau)_t}^2). \tag{3.10}$$

### 3.2. Mixture Ratio Estimator Using Multi-Auxiliary Variable and Attributes in Two-Phase Sampling (Partial Information Case)

In this case suppose we have no information on all  $s$  and  $t$  auxiliary variables but only for  $r$  and  $g$  auxiliary variables from population. Considering mixture ratio technique of estimating technique, the population mean of study variable  $Y$  can be estimated for two-phase sampling using multi-auxiliary variables and attributes as:

$$t_{\text{MRVAP}(3.1)} = \bar{y}_2 \left( \frac{\bar{x}_{(1)1}}{\bar{x}_{(2)1}} \right)^{\alpha_1} \left( \frac{\bar{X}_1}{\bar{x}_{(2)1}} \right)^{\beta_1} \left( \frac{\bar{x}_{(1)2}}{\bar{x}_{(2)2}} \right)^{\alpha_2} \left( \frac{\bar{X}_2}{\bar{x}_{(2)2}} \right)^{\beta_2} \dots \left( \frac{\bar{x}_{(1)r}}{\bar{x}_{(2)r}} \right)^{\alpha_s} \left( \frac{\bar{X}_r}{\bar{x}_{(2)r}} \right)^{\beta_s} \left( \frac{\bar{x}_{(1)s+1}}{\bar{x}_{(2)s+1}} \right)^{\alpha_{r+1}} \left( \frac{\bar{x}_{(1)s+2}}{\bar{x}_{(2)s+2}} \right)^{\alpha_{r+2}} \dots \left( \frac{\bar{x}_{(1)k}}{\bar{x}_{(2)k}} \right)^{\alpha_k} \left( \frac{P_{(1)k+1}}{P_{(2)k+1}} \right)^{\gamma_{k+1}} \left( \frac{P_{k+1}}{P_{(2)k+1}} \right)^{\lambda_{k+1}} \left( \frac{P_{(1)k+2}}{P_{(2)k+2}} \right)^{\gamma_{k+2}} \left( \frac{P_{k+2}}{P_{(2)k+2}} \right)^{\lambda_{k+2}} \dots \left( \frac{P_{(1)h}}{P_{(2)h}} \right)^{\gamma_h} \left( \frac{P_h}{P_{(2)h}} \right)^{\lambda_h} \left( \frac{P_{(1)h+1}}{P_{(2)h+1}} \right)^{\gamma_{h+1}} \left( \frac{P_{(1)h+2}}{P_{(2)h+2}} \right)^{\gamma_{h+2}} \dots \left( \frac{P_{(1)t}}{P_{(2)t}} \right)^{\gamma_q}. \tag{3.11}$$

Using (1.0), (1.3) and (1.4) in (3.1) and ignoring the second and higher terms for each expansion of product and after simplification, we write,

$$t_{\text{MRVAP}(3.1)} = \bar{y}_2 + \sum_{j=1}^r \bar{Y} \alpha_j \frac{\bar{e}_{x(1)j} - \bar{e}_{x(2)j}}{\bar{X}_j} - \sum_{j=1}^r \bar{Y} \beta_j \frac{\bar{e}_{x(2)j}}{\bar{X}_j} + \sum_{j=1}^{s+r=k} \bar{Y} \alpha_j \frac{\bar{e}_{x(1)j} - \bar{e}_{x(2)j}}{\bar{X}_j} + \sum_{i=1}^{k+t=h} \bar{Y} \gamma_i \frac{\bar{e}_{\tau(1)i} - \bar{e}_{\tau(2)i}}{P_i} - \sum_{j=1}^{k+t=h} \bar{Y} \lambda_j \frac{\bar{e}_{\tau(2)j}}{P_j} + \sum_{j=h+1}^{h+q=q} \bar{Y} \gamma_j \frac{\bar{e}_{\tau(1)j} - \bar{e}_{\tau(2)j}}{P_j}. \tag{3.12}$$

Mean squared error of  $t_{\text{MRVAP}(3.1)}$  estimator is given by,

$$\begin{aligned}
 & t_{MRVAP(3.1)} \\
 &= E_1 E_{2/l} \left( \bar{e}_{y_2} + \sum_{j=1}^r \bar{Y} \alpha_j \frac{\bar{e}_{x(1)j} - \bar{e}_{x(2)j}}{\bar{X}_j} - \sum_{j=1}^r \bar{Y} \beta_j \frac{\bar{e}_{x(2)j}}{\bar{X}_j} + \sum_{j=1}^{s+r=k} \bar{Y} \alpha_j \frac{\bar{e}_{x(1)j} - \bar{e}_{x(2)j}}{\bar{X}_j} + \sum_{i=1}^{k+t=h} \bar{Y} \gamma_i \frac{\bar{e}_{\tau(1)j} - \bar{e}_{\tau(2)j}}{P_i} \right. \\
 & \quad \left. - \sum_{j=1}^{k+t=h} \bar{Y} \lambda_j \frac{\bar{e}_{\tau(2)j}}{P_j} + \sum_{j=h+1}^{h+q=q} \bar{Y} \gamma_j \frac{\bar{e}_{\tau(1)j} - \bar{e}_{\tau(2)j}}{P_j} \right)^2. \tag{3.13}
 \end{aligned}$$

We differentiate the Equation (3.13) with respect to  $\alpha_i (i = 1, 2, \dots, r)$ ,  $\beta_i (i = 1, 2, \dots, r)$ ,  $\alpha_i (i = r + 1, r + 2, \dots, k)$ ,  $\gamma_i (i = k + 1, k + 2, \dots, h)$ ,  $\lambda_i (i = k + 1, k + 2, \dots, h)$ ,  $\gamma_i (i = h + 1, h + 2, \dots, q)$  and equate to zero and use (1.6), (1.7) and (1.9). The optimum values are as follows,

$$\begin{aligned}
 \alpha_j &= (-1)^{j+1} \frac{C_y}{C_{x_j}} \left( \frac{|R_{yx_j}|_{\Delta_m}}{|R|_{\Delta_m}} - \frac{|R_{yx_j}|_{\Delta_v}}{|R_{yx_j}|_{\Delta_v}} \right) & (j = 1, 2, \dots, r); \\
 \gamma_j &= (-1)^{j+1} \frac{C_y}{C_{\tau_j}} \left( \frac{|R_{y\tau_j}|_{\Delta_p}}{|R|_{\Delta_m}} - \frac{|R_{y\tau_j}|_{\Delta_w}}{|R_{\tau_w}|} \right) & j = k + 1, k + 2, \dots, h; \\
 \beta_j &= (-1)^{j+1} \frac{C_y}{C_{x_j}} \frac{|R_{yx_j}|_{\Delta_r}}{|R_{\Delta_w}|} & (j = 1, 2, \dots, r); \\
 \lambda_j &= \frac{C_y}{|R_{\tau_w}|} \frac{1}{C_{\tau_j}} \left( (-1)^{j+1} |R_{y\tau_j}|_{\Delta_w} \right) & j = k + 1, k + 2, \dots, h; \\
 \alpha_j &= (-1)^{j+1} \frac{C_y}{C_{x_j}} \frac{|R_{yx_{ji}}|_{\Delta_s}}{|R|_{\Delta_s}} & j = r + 1, r + 2, \dots, k; \\
 \gamma_j &= (-1)^{j+1} \frac{C_y}{|R|_{\Delta_p} C_{\tau_j}} |R_{y\tau_j}|_{\Delta_w} & j = h + 1, h + 2, \dots, q.
 \end{aligned} \tag{3.14}$$

Using normal equation that are used to find the optimum values given (3.13) we can write

$$\begin{aligned}
 & MSE(t_{MRVAP(3.1)}) \\
 &= E_1 E_{2/l} \left( \bar{e}_y \left( \bar{e}_{y_2} + \sum_{j=1}^r \bar{Y} \alpha_j \frac{\bar{e}_{x(1)j} - \bar{e}_{x(2)j}}{\bar{X}_j} - \sum_{j=1}^r \bar{Y} \beta_j \frac{\bar{e}_{x(2)j}}{\bar{X}_j} + \sum_{j=1}^{s+r=k} \bar{Y} \alpha_j \frac{\bar{e}_{x(1)j} - \bar{e}_{x(2)j}}{\bar{X}_j} \right. \right. \\
 & \quad \left. \left. + \sum_{i=1}^{k+t=h} \bar{Y} \gamma_i \frac{\bar{e}_{\tau(1)j} - \bar{e}_{\tau(2)j}}{P_i} - \sum_{j=1}^{k+t=h} \bar{Y} \lambda_j \frac{\bar{e}_{\tau(2)j}}{P_j} + \sum_{j=h+1}^{h+q=m} \bar{Y} \gamma_j \frac{\bar{e}_{\tau(1)j} - \bar{e}_{\tau(2)j}}{P_j} \right) \right). \tag{3.15}
 \end{aligned}$$

Taking expectation and using (1.6) in (3.15), we get,

$$\begin{aligned}
 & MSE(t_{MRVAP(3.1)}) \\
 &= \theta_2 \bar{Y}^2 C_y^2 + (\theta_1 - \theta_2) \sum_{j=1}^r \frac{\bar{Y}^2}{\bar{X}_j} \alpha_j \bar{X}_j C_y C_{x_j} \rho_{yx_j} - \theta_2 \sum_{j=1}^r \frac{\bar{Y}^2}{\bar{X}_j} \beta_j \bar{X}_j C_y C_{x_j} \rho_{yx_j} + (\theta_1 - \theta_2) \sum_{j=r+1}^{r+s=k} \frac{\bar{Y}^2}{\bar{X}_j} \alpha_j \bar{X}_j C_y C_{x_j} \rho_{yx_j} \\
 & \quad + (\theta_1 - \theta_2) \sum_{i=k+1}^{k+t=h} \frac{\bar{Y}^2}{P_j} \gamma_j P_j C_y C_{\tau_j} \rho_{p\tau_j} - \theta_2 \sum_{i=k+1}^{k+t=h} \frac{\bar{Y}^2}{P_j} \lambda_j P_j C_y C_{\tau_j} \rho_{p\tau_j} + (\theta_1 - \theta_2) \sum_{i=h+1}^q \frac{\bar{Y}^2}{P_j} \gamma_j P_j C_y C_{\tau_j} \rho_{p\tau_j}. \tag{3.16}
 \end{aligned}$$

Using the optimum value (3.14) in (3.16), we get,

$$\begin{aligned}
 & \text{MSE}\left(t_{\text{MRVAP}(3.1)}\right) \\
 &= \bar{Y}^2 C_y^2 \left( \theta_2 + (\theta_1 - \theta_2) \sum_{j=1}^r (-1)^{j+1} \left( \frac{|R_{yx_j}|_{y, \underline{x}_q}}{|R|_{\underline{x}_q}} - \frac{|R_{yx_j}|_{y, \underline{x}_w}}{|R|_{\underline{x}_w}} \right) \rho_{yx_j} - \theta_2 \sum_{j=1}^r (-1)^{j+1} \frac{|R_{yx_j}|_{y, \underline{x}_w}}{|R|_{\underline{x}_w}} \rho_{yx_j} \right. \\
 & \quad + (\theta_1 - \theta_2) \sum_{j=r+1}^{r+s=k} (-1)^{j+1} \frac{|R_{yx_j}|_{y, \underline{x}_q}}{|R|_{\underline{x}_q}} \rho_{yx_j} + (\theta_1 - \theta_2) \sum_{j=k+1}^{t+k=h} (-1)^{j+1} \left( \frac{|R_{y\tau_j}|_{y, \underline{x}_q}}{|R|_{\underline{x}_q}} - \frac{|R_{y\tau_j}|_{y, \underline{x}_w}}{|R|_{\underline{x}_w}} \right) \rho_{Pb_j} \\
 & \quad \left. - \theta_2 \sum_{j=k+1}^{t+k=h} (-1)^{j+1} \frac{|R_{y\tau_j}|_{y, \underline{x}_w}}{|R|_{\underline{x}_w}} \rho_{Pb_j} + (\theta_1 - \theta_2) \sum_{j=h+1}^q (-1)^{j+1} \frac{|R_{y\tau_j}|_{y, \underline{x}_q}}{|R|_{\underline{x}_q}} \gamma_j \rho_{Pb_j} \right). \tag{3.17}
 \end{aligned}$$

Or

$$\begin{aligned}
 & \text{MSE}\left(t_{\text{MRVAP}(3.1)}\right) = \bar{Y}^2 C_y^2 \left( \theta_2 + (\theta_1 - \theta_2) \sum_{j=1}^r (-1)^{j+1} \frac{|R_{yx_j}|_{y, \underline{x}_q}}{|R|_{\underline{x}_q}} \rho_{yx_j} - \theta_1 \sum_{j=1}^r (-1)^{j+1} \frac{|R_{yx_j}|_{y, \underline{x}_w}}{|R|_{\underline{x}_w}} \rho_{yx_j} \right. \\
 & \quad + (\theta_1 - \theta_2) \sum_{j=r+1}^{r+s=k} (-1)^{j+1} \frac{|R_{yx_j}|_{y, \underline{x}_q}}{|R|_{\underline{x}_q}} \rho_{yx_j} + (\theta_1 - \theta_2) \sum_{j=k+1}^{t+k=h} (-1)^{j+1} \frac{|R_{y\tau_j}|_{y, \underline{x}_q}}{|R|_{\underline{x}_q}} \rho_{Pb_j} \\
 & \quad \left. - \theta_1 \sum_{j=k+1}^{t+k=h} (-1)^{j+1} \frac{|R_{y\tau_j}|_{y, \underline{x}_w}}{|R|_{\underline{x}_w}} \rho_{Pb_j} + (\theta_1 - \theta_2) \sum_{j=h+1}^q (-1)^{j+1} \frac{|R_{y\tau_j}|_{y, \underline{x}_q}}{|R|_{\underline{x}_q}} \gamma_j \rho_{Pb_j} \right). \tag{3.18}
 \end{aligned}$$

Or

$$\begin{aligned}
 & \text{MSE}\left(t_{\text{MRVAP}(3.1)}\right) \\
 &= \bar{Y}^2 C_y^2 \left( (\theta_2 - \theta_1) \left( 1 + \left( \sum_{j=1}^r (-1)^j \frac{|R_{yx_j}|_{\underline{x}_q}}{|R|_{\underline{x}_q}} \rho_{yx_j} + \sum_{j=r+1}^{r+s=k} (-1)^j \frac{|R_{yx_j}|_{y, \underline{x}_q}}{|R|_{\underline{x}_q}} \rho_{yx_j} + \sum_{j=k+1}^{t+k=h} (-1)^j \frac{|R_{y\tau_j}|_{y, \underline{x}_q}}{|R|_{\underline{x}_q}} \rho_{Pb_j} \right) \right. \tag{3.19} \\
 & \quad \left. + \sum_{j=h+1}^q (-1)^j \frac{|R_{y\tau_j}|_{y, \underline{x}_q}}{|R|_{\underline{x}_q}} \gamma_j \rho_{Pb_j} \right) + \theta_1 \left( 1 + \left( \sum_{j=1}^r (-1)^j \frac{|R_{yx_j}|_{y, \underline{x}_w}}{|R|_{\underline{x}_w}} \rho_{yx_j} + \sum_{j=k+1}^{t+k=h} (-1)^j \frac{|R_{y\tau_j}|_{y, \underline{x}_w}}{|R|_{\underline{x}_w}} \rho_{Pb_j} \right) \right) \Bigg).
 \end{aligned}$$

Or

$$\begin{aligned}
 & \text{MSE}\left(t_{\text{MRVAP}(3.1)}\right) = \bar{Y}^2 C_y^2 \left( \frac{(\theta_2 - \theta_1)}{|R|_{(\underline{x}, \underline{\tau})_q}} \left( |R|_{(\underline{x}, \underline{\tau})_q} + \sum_{j=1}^q (-1)^j \frac{|R_{y \cdot x_j \cdot \tau_j}|_{(\underline{x}, \underline{\tau})_q}}{|R|_{(\underline{x}, \underline{\tau})_q}} \rho_{y(x_j, \tau_j)} \right) \right. \\
 & \quad \left. + \frac{\theta_1}{|R|_{(\underline{x}, \underline{\tau})_w}} \left( 1 + \left( \sum_{j=1}^r (-1)^j \frac{|R_{yx_j}|_{\underline{x}_w}}{|R|_{(\underline{x}, \underline{\tau})_w}} \rho_{yx_j} + \sum_{j=k+1}^{t+k=h} (-1)^j \frac{|R_{yx_j}|_{\underline{x}_w}}{|R|_{(\underline{x}, \underline{\tau})_w}} \rho_{Pb_j} \right) \right) \right). \tag{3.20}
 \end{aligned}$$

Or

$$MSE(t_{MRVAP(3.1)}) = \bar{Y}^2 C_y^2 \left( (\theta_2 - \theta_1) \frac{|R|_{y:(z,\varepsilon)_q}}{|R|_{(z,\varepsilon)_q}} + \theta_1 \frac{|R|_{y:(z,\varepsilon)_w}}{|R|_{(z,\varepsilon)_w}} \right). \tag{3.21}$$

Using (1.8) in (3.21), we get,

$$MSE(t_{MRVAP(3.1)}) = \bar{Y}^2 C_y^2 \left( (\theta_2 - \theta_1) (1 - \rho_{y(z,\varepsilon)_q}^2) + \theta_1 (1 - \rho_{y(z,\varepsilon)_w}^2) \right). \tag{3.22}$$

Simplifying (3.22) we get,

$$MSE(t_{MRVAP(3.1)}) = \bar{Y}^2 C_y^2 \left( \theta_2 (1 - \rho_{y(z,\varepsilon)_q}^2) + \theta_1 (\rho_{y(z,\varepsilon)_q}^2 - \rho_{y(z,\varepsilon)_w}^2) \right). \tag{3.23}$$

### 3.3. Mixture Ratio Estimator Using Multi-Auxiliary Variable and Attributes in Two-Phase Sampling (No Information Case)

If we estimate a study variable when information on all auxiliary variables is unavailable from population, it is utilized in the form of their means. By taking the advantage of mixture ratio technique for two-phase sampling, a generalized estimator for estimating population mean of study variable  $Y$  with the use of multi auxiliary variables and attributes are suggested as:

$$t_{MRVAN(3.2)} = \bar{y}_2 \left( \frac{\bar{X}_{(1)1}}{\bar{X}_{(2)1}} \right)^{\alpha_1} \left( \frac{\bar{X}_{(1)2}}{\bar{X}_{(2)2}} \right)^{\alpha_2} \dots \left( \frac{\bar{X}_{(1)k}}{\bar{X}_{(2)k}} \right)^{\alpha_k} \left( \frac{P_{(1)k+1}}{P_{(2)k+1}} \right)^{\gamma_{k+1}} \left( \frac{P_{(1)k+2}}{P_{(2)k+2}} \right)^{\gamma_{k+2}} \dots \left( \frac{P_{(1)t}}{P_{(2)t}} \right)^{\gamma_t}. \tag{3.24}$$

Using (1.0), (1.3) and (1.4) in (3.24) and ignoring the second and higher terms for each expansion of product and after simplification, we write,

$$t_{MRVAN(3.2)} = \bar{y}_2 + \sum_{j=1}^k \bar{Y} \alpha_j \frac{\bar{e}_{x_{j(1)}} - \bar{e}_{x_{j(2)}}}{\bar{X}_j} + \sum_{j=1}^{k+h=t} \bar{Y} \gamma_j \frac{\bar{e}_{\tau_{j(1)}} - \bar{e}_{\tau_{j(2)}}}{P_j}. \tag{3.25}$$

Mean squared error of  $t_{MRVAN(3.2)}$  estimator is given by

$$MSE(t_{MRVAN(3.2)}) = E \left( \bar{e}_{y_2} + \sum_{j=1}^k \bar{Y} \alpha_j \frac{\bar{e}_{x_{j(1)}} - \bar{e}_{x_{j(2)}}}{\bar{X}_j} + \sum_{j=1}^{k+h=t} \bar{Y} \gamma_j \frac{\bar{e}_{\tau_{j(1)}} - \bar{e}_{\tau_{j(2)}}}{P_j} \right)^2. \tag{3.26}$$

We differentiate the Equation (3.27) partially with respect to  $\alpha_i$  ( $i = 1, 2, \dots, k$ ) and  $\beta_i$  ( $i = k + 1, k + 2, \dots, t$ ) then equate to zero, using (1.6), (1.7) and (1.9), we get

$$\alpha_j = (-1)^{j+1} \frac{C_y}{C_{x_j}} \frac{|R_{yx_j}|_{x_k}}{|R_{x_j}|} \tag{3.27}$$

$$\beta_j = (-1)^{j+1} \frac{C_y}{C_{\tau_j}} \frac{|R_{y\tau_j}|_{\tau_j}}{|R_{\tau_j}|}. \tag{3.28}$$

Using normal equation that are used to find the optimum values given (3.26) we can write,

$$MSE(t_{MRVAN(3.2)}) = E \left( \bar{e}_{y_2} \left( \bar{e}_{y_2} + \sum_{j=1}^k \bar{Y} \alpha_j \frac{\bar{e}_{x_{(1)j}} - \bar{e}_{x_{(2)j}}}{\bar{X}_j} + \sum_{j=k+1}^{k+h=t} \bar{Y} \gamma_j \frac{\bar{e}_{x_{(1)j}} - \bar{e}_{x_{(2)j}}}{P_j} \right) \right). \tag{3.29}$$

Taking expectation and using (1.6) in (3.29), we get

$$MSE(t_{MRVAN(3.2)}) = \bar{Y}^2 C_y^2 \left( \theta_2 + (\theta_1 - \theta_2) \sum_{j=1}^k \alpha_j C_y C_{x_j} \rho_{yx_j} + (\theta_1 - \theta_2) \sum_{j=k+1}^{k+h=t} \beta_j C_y C_{\tau_j} \rho_{Pb_j} \right). \tag{3.30}$$

Or

$$\text{MSE}\left(t_{\text{MRVAN}(3.2)}\right) = \theta_2 \bar{Y}^2 C_y^2 \left( \theta_2 + (\theta_2 - \theta_1) \sum_{j=1}^k (-1)^j \frac{|R_{yx_j}|_{y, \bar{x}_q}}{|R|_{(\bar{x}, \bar{\tau})_q}} \rho_{yx_j} + (\theta_2 - \theta_1) \sum_{j=1}^{k+h-t} (-1)^j \frac{|R_{y\tau_j}|_{y, \bar{x}_q}}{|R|_{(\bar{x}, \bar{\tau})_q}} \rho_{Pb_j} \right). \quad (3.31)$$

Or

$$\text{MSE}\left(t_{\text{MRVAN}(3.2)}\right) = \theta_2 \bar{Y}^2 C_y^2 \left( (\theta_2 - \theta_1) \left( 1 + \sum_{j=1}^q (-1)^j \frac{|R_{y \cdot x_j \cdot \tau_j}|_{y, (\bar{x}, \bar{\tau})_q}}{|R|_{(\bar{x}, \bar{\tau})_q}} \rho_{y \cdot (x_j \cdot \tau_j)} + \theta_1 \right) + \theta_1 \right). \quad (3.32)$$

Or

$$\text{MSE}\left(t_{\text{MRVAN}(3.2)}\right) = \bar{Y}^2 C_y^2 \left( \frac{(\theta_2 - \theta_1)}{|R|_{(\bar{x}, \bar{\tau})_q}} \left( |R|_{(\bar{x}, \bar{\tau})_q} + \sum_{i=1}^t (-1)^i |R_{y \cdot x_i \cdot \tau_i}|_{y, (\bar{x}, \bar{\tau})_q} \rho_{y \cdot (x_i \cdot \tau_i)} + \theta_1 \right) \right). \quad (3.33)$$

Or

$$\text{MSE}\left(t_{\text{MRVAN}(3.2)}\right) = \bar{Y}^2 C_y^2 \left( (\theta_2 - \theta_1) \frac{|R|_{y \cdot (\bar{x}, \bar{\tau})_q}}{|R|_{(\bar{x}, \bar{\tau})_q}} + \theta_1 \right). \quad (3.34)$$

Using (1.8) in (3.34), we get,

$$\text{MSE}\left(t_{\text{MRVAN}(3.2)}\right) = \bar{Y}^2 C_y^2 \left( (\theta_2 - \theta_1) (1 - \rho_{y(\bar{x}, \bar{\tau})}^2) + \theta_1 \right). \quad (3.35)$$

Simplifying (3.35), we get,

$$\text{MSE}\left(t_{\text{MRVAN}(3.2)}\right) = \bar{Y}^2 C_y^2 \left( \theta_2 (1 - \rho_{y(\bar{x}, \bar{\tau})}^2) + \theta_1 \rho_{y(\bar{x}, \bar{\tau})}^2 \right). \quad (3.36)$$

### 3.4. Bias and Consistency of Mixture Ratio Estimators

These mixture ratio estimators using multiple auxiliary variables and attributes in two-phase sampling are biased. However, these biases are negligible for large samples that is  $(n \geq 30)$ . It's easily shown that the mixture ratio estimators are consistent estimators using multiple auxiliary variables since they are linear combinations of consistent estimators it follows that they are also consistent.

## 4. Simulation, Result and Discussion

We carried out data simulation experiments to compare the performance of mixture ratio estimators using multiple auxiliary variables and attributes in two-phase sampling with ratio estimator using one auxiliary variable and one auxiliary attribute or ratio estimator using multiple auxiliary variable or multiple auxiliary attributes in two-phase sampling estimators for finite population.

All the results were obtained after carrying out two hundred simulations and taking their average.

1) Study variable  $N = 800, n = 96, n_2 = 34, \text{mean} = 50, \text{standard deviation} = 6$ .

2) For ratio estimator the auxiliary variable is positively correlated with the study variable and the line passes through the origin.

$$N = 500, n = 96, n_2 = 34, \text{mean} = 29, \text{standard deviation} = 6.712.$$

$$N = 500, n = 96, n_2 = 34, \text{mean} = 38, \text{standard deviation} = 8.612.$$

Correlation coefficients  $\rho_{yx_1} = 0.6820, \rho_{yx_2} = 0.5788$ .

3) For ratio estimator the auxiliary attributes is positively correlated with the study variable and the line passes through the origin.

$$N = 500, n = 96, n_2 = 34, \text{mean} = 0.5612.$$

$N = 500, n = 96, \text{mean} = 0.4826.$

Correlation coefficients  $\rho_{yT_2} = 0.7031, \rho_{yT_1} = 0.6614.$

In order to evaluate the efficiency gain we could achieve by using the proposed estimators, we have calculated the variance of mean per unit and the mean squared error of all estimators we have considered. We have then calculated percent relative efficiency of each estimator in relation to variance of mean per unit. We have then compared the percent relative efficiency of each estimator, the estimator with the highest percent relative efficiency is considered to be the more efficient than the other estimators. The percent relative efficiency is calculated using the following formulae.

$$\text{eff}(\hat{Y}) = \frac{\text{Var}(\hat{y})}{\text{MSE}(\hat{Y})} * 100 \tag{4.0}$$

**Table 1** shows percent relative efficiency of proposed estimator with respect to mean per unit estimator for single-phase sampling. It is very clear from **Table 1** that our proposed mixture ratio estimator using multiple auxiliary variables and multiple auxiliary attributes simultaneously is the most efficient compared to ratio estimator using one auxiliary variable and one auxiliary attribute or ratio estimator using multiple auxiliary variable or multiple auxiliary attributes in two-phase sampling.

**Table 2** compares the efficiency of full information case and partial case to no information case and full to partial information case of proposed mixture ratio estimators. It is observed that the full information case and partial information case are more efficient than no information case because they have higher percent relative efficiency than no information case. In addition, the full information case is more efficient than the partial information case because it has a higher percent relative efficiency than partial information case.

### 5. Conclusion

The proposed mixture ratio estimator under full information case is recommended for estimating the finite population mean since it is the most efficient estimator compared to mean per unit, ratio estimator using one auxiliary variable, ratio estimator using one auxiliary attribute, ratio estimator using multiple auxiliary variable and ratio estimator using multiple auxiliary attributes in two-phase sampling. In case some auxiliary variables or attributes are unknown, we recommend mixture ratio estimator under partial information case since it is more

**Table 1.** Relative efficiency of existing and proposed estimator with respect to mean per unit estimator for two-phase sampling.

| Estimator                   | Relative percent efficiency with respect to mean per unit in two-phase sampling |
|-----------------------------|---|
| $\text{var}(\bar{y})$       | 100   |
| $t_{RV}$                    | 146   |
| $t_{RA}$                    | 185   |
| $t_{MRV}$                   | 212   |
| $t_{MRA}$                   | 233   |
| $t_{MRVAF(3,0)}$ (proposed) | 285   |

**Table 2.** Comparisons of full, partial and no information cases for proposed ratio-cum-product estimator using multiple auxiliary variables.

| Population                  | Percent relative efficiency of full and partial to no information |                  | Percent relative efficiency of full to partial in formation case |                  |                  |
|-----------------------------|---|------------------|--|------------------|------------------|
| Estimator                   | $t_{MRVAN(3,2)}$  | $t_{MRVAP(3,1)}$ | $t_{MRVAF(3,0)}$   | $t_{MRVAP(3,1)}$ | $t_{MRVAF(3,0)}$ |
| Relative percent efficiency | 100   | 139              | 172  | 100              | 127              |

efficient than the mixture ratio estimator under no information case and if all are unknown, we recommend the mixture ratio estimator under no information case to estimate finite population mean.

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