

# Note on Fully Modified Estimation for Three-Regime Threshold Cointegration Model

# **Chien-Ho Wang**

Department of Economics, National Taipei University, New Taipei City, Taiwan Email: <u>wangchi3@mail.ntpu.edu.tw</u>

Received 12 April 2014; revised 14 May 2014; accepted 22 June 2014

Copyright © 2014 by author and Scientific Research Publishing Inc. This work is licensed under the Creative Commons Attribution International License (CC BY). http://creativecommons.org/licenses/by/4.0/

© Open Access

# Abstract

In this paper we consider a three-regime threshold cointegration model. The fully modified ordinary least squares (FM-OLS) regression of Phillips and Hansen [1] is used to develop new methods for estimating cointegrating coefficients. After we remove the second-order biases of parameter estimates from the three-regime threshold cointegration model, FM-OLS estimates have a limit distribution that is mixed normal for all the nonstationary coefficients.

#### **Keywords**

Fully Modified Regression, Nonlinearity, Threshold Cointegration

# **1. Introduction**

Since the breakthrough paper by Balke and Fomby [2], nonlinear cointegration has become one of the most important research areas in time series analysis, and a strand of econometric literature has concentrated on estimating and testing for threshold cointegration. The early works in these directions include the studies by Choi and Saikkonen [3], Hansen and Seo [4], Gaul [5], Gonzalo and Pitarakis [6] [7], Kiliç [8], Li and Lee [9], and Seo [10] among others. Numerous contributions apply the threshold cointegration concept in empirical studies. Lo and Zivot [11] and Bec and Rahbek [12] have provided comprehensive reviews of the topic.

Although there are numerous research papers in the literature, only a few of those papers focus on the estimation of multi-regime threshold cointegration. Hansen and Seo [4] developed a maximum likelihood-based estimation and testing theory for a two-regime threshold cointegration model, while Seo [10], Gonzalo and Pitarakis [6], and Li and Lee [9] constructed tests for cointegration in the presence of possible threshold effects. Gaul [5] provided a Wald test against threshold effects in a three-regime threshold vector error correction model<sup>1</sup>. Moreover, all of the theories proposed before require the assumption of i.i.d. residuals. Only rare studies have discussed the efficiency of estimation when the error sequence is under weakly stationary,

The main purpose of this paper is to develop an approach estimating for cointegrated parameters in three-regime threshold models. We use the fully modified ordinary least squares (FM-OLS) regression by Phillips and Hansen [1] to provide the optimal estimates of threshold cointegration. An asymptotic theory for FM-OLS is derived. From the asymptotic theory for three-regime threshold cointegration regression, the FM-OLS principle may be used to eliminate the possible second-order biases from weakly dependent residuals. The estimates of FM-OLS for threshold cointegration are free for possible endogeneity.

The remainder of the paper is organized as follows. Section 2 introduces the basic assumptions and asymptotic distributions of fully modified threshold cointegration estimators. Section 3 provides a conclusion, and the Appendix provides all the proofs of the theorems discussed.

#### 2. Assumptions and Parameter Estimation

This study considers the following cointegrating relationship with three-regime threshold effects.

٨

$$y_{1t} = \rho_1 y_{2t} I(q_{t-1} \le c_1) + \rho_2 y_{2t} I(c_1 < q_{t-1} \le c_2) + \rho_3 y_{2t} I(c_2 < q_{t-1}) + u_{1t}$$
(1)

$$ay_{2t} = u_{2t} \tag{2}$$

where  $u_{1t}$  and  $u_{2t}$  are scalar and p vector-valued stationary disturbances,  $q_t$  is the stationary threshold variable,  $c_1$  and  $c_2$  are threshold parameters,  $I(\cdot)$  is indicator function. For convenience, we rewrite Equation (1) in matrix format as

$$Y_t = \rho_1 X_1 + \rho_2 X_2 + \rho_3 X_3 + u, \tag{3}$$

where  $Y_t$  stacks  $y_{1t}$  and  $X_i$ , i = 1, 2, 3 stacks on the regressors of Equation (1) for different indicators. Asymptotic properties of FM-OLS estimates are determined by the joint error process of  $U_t = (u_{1t} \quad u'_{2t})'$ , Throughout this paper, we will derive the limit distributions under following assumptions.

**Assumption 1.** The sequence  $\{u_{1t}, u_{2t}\}$  is weakly stationary, ergodic and strong mixing with mixing coefficients  $\kappa_n$  satisfying

$$\sum_{n=1}^{\infty} \kappa_n^{\frac{1}{2} - \frac{1}{r}} < \infty$$

for some r > 2.

Assumption 2.  $E(U_t) = 0$  and  $E|U_t|^{2+m} < \infty$  for some m > 0. Assumption 3.

$$\frac{1}{\sqrt{T}}\sum_{t=1}^{[T_r]} U_t \xrightarrow{d} B(r) = \begin{pmatrix} B_1(r) \\ B_2(r) \end{pmatrix}$$

where B(r) is a p-dimensional Brownian motion with a long-run covariance matrix given by

$$\Omega = \begin{pmatrix} \Omega_{11} & \Omega_{12} \\ \Omega_{21} & \Omega_{22} \end{pmatrix}$$

with  $\Omega_{11} = E(u_{1t}^2)$ ,  $\Omega_{12} = \Sigma_{12} + \Lambda_{12} + \Lambda'_{21}$ ,  $\Omega_{21} = \Sigma_{21} + \Lambda_{21} + \Lambda'_{12}$  and  $\Omega_{22} = \Sigma_{22} + \Lambda_{22} + \Lambda'_{22}$ , where  $\Sigma_{12} = E[u_{1t}u'_{2t}]$ ,  $\Sigma_{22} = E[u_{2t}u'_{2t}]$ ,  $\Lambda_{12} = \sum_{k=1}^{\infty} E[u_{1k}u'_{20}]$ ,  $\Lambda_{21} = \sum_{k=1}^{\infty} E[u_{2k}u'_{10}]$ ,  $\Sigma_{22} = E(u_{2t}u'_{2t})$  and  $\Lambda_{22} = \sum_{k=1}^{\infty} E[u_{20}u'_{2k}]$ .

**Assumption 4.** The threshold variable  $q_t$  is strictly stationary and independent of the process  $\{u_{1t}, u_{2t}\}$ , and has a distribution function  $F(\cdot)$  that is continuous and strictly increasing.

**Assumption 5.** The threshold parameter  $c_1$  and  $c_2$  are such that  $c_1$  and  $c_2 \in \Xi = [\gamma_L, \gamma_H]$  a closed and bounded subset of the sample space of the threshold variable.

**Assumption 6.**  $\Omega_{22}$  is nonsingular, i.e. the p-dimensional I (1) vector  $y_{21}$  are not cointegrated each other.

<sup>&</sup>lt;sup>1</sup>Hansen and Seo [4] and Gonzalo and Pitarakis [6] consider MLE methods, but they need normality for residuals.

Assumption 1 is fairly general and covers a variety of weakly stationary posses. It also allows for the endogeneity of  $y_{2t}$  and the serial correlation in  $u_{1t}$  in Equation (1). This treatment of the serial correlation in  $u_{1t}$ , like that in the study by de Jong [13] and Gonzalo and Pitarakis [7], a more general assumption in threshold cointegration regression. Assumption 2 provides some moment conditions imposed on  $\{u_{1t}\}$  and  $\{u_{2t}\}$ . Assumption 3 is a multivariate invariance principle for the partial sum process. Assumption 1 - 3 are used for establishing the limit theory for partial sum process like  $\sum_{t=1}^{T} y_{2t} u_{1t} I(q_{t-1} \le c_t)$ . Assumption 4 and 5 are standard assumptions for threshold literatures. Assumption 4 excluded the possibility that that the threshold variable  $q_t$ is correlated with  $u_{1t}$ . Assumption 5 ensures that there are enough observations in each regime. Assumption 6 rules out the possibility that the components of  $y_{2t}$  will themselves be cointegrated.

Our estimation of threshold estimators of  $\hat{c}_1$  and  $\hat{c}_2$  for Equation (1) is based on the nonlinear least squares regression. Let

$$u_{it}(c_i) = y_{1t} - \rho_1 y_{2t} I(q_{t-1} \le c_1) - \rho_2 y_{2t} I(c_1 < q_{t-1} \le c_2) - \rho_3 y_{2t} I(c_2 < q_{t-1}).$$

The authors consider

$$\hat{c}_i = \arg\min_{c_i \in \Xi} \sum_{t=1}^T u_{1t}^2(c_i), \tag{4}$$

where i = 1, 2. Once  $\hat{c}_i$  is obtained, the  $y_{2t}$  can be separated by indictors. Because the regressors of Equation (1) are orthogonal each other. For given threshold value  $c_1$  and  $c_2$ , it can be estimated by using OLS procedure

$$\hat{\rho}_{1}(c_{1}) = (X_{1}'X_{1})^{-1} X_{1}'Y_{1}$$
(5)

$$\hat{\rho}_2(c_1, c_2) = (X_2' X_2)^{-1} X_2' Y_1$$
(6)

$$\hat{\rho}_3(c_2) = (X_3'X_3)^{-1} X_3'Y_1.$$
<sup>(7)</sup>

Although NLS procedure may be consistent, the limits of estimated parameters may contain second-order bias. Phillips and Hansen [1] propose a fully modified estimation methods which can eliminate these bias effects. Following the spirit of Phillips and Hansen [1], we suggest the FM-OLS principle for threshold cointegrating regression. From the cointegration model of Equation (3), the residuals  $\{u_{1t}\}$  are weakly dependent.  $\{u_{1t}\}$ may be correlated with  $y_{2t}$ . It will cause efficiency loss.

Consider  $y_{1t}^- = y_{1t} - \Omega_{12}\Omega_{22}^- u_{2t} = y_{1t} - \Omega_{12}\Omega_{22}^- \Delta y_{2t}$  and  $u_{1t}^- = u_{1t} - \Omega_{12}\Omega_{22}^{-1} u_{2t} = u_{1t} - \Omega_{12}\Omega_{22}^{-1} \Delta y_{2t}$ . Redefine

$$y_{1t}^{-} = y_{1t} - \Omega_{12}\Omega_{22}^{-1}\Delta y_{2t} = \rho_1 y_{2t} I(q_{t-1} \le c_1) + \rho_2 y_{2t} I(c_1 < q_{t-1} \le c_2) + \rho_3 y_{2t} I(c_2 < q_{t-1}) + u_{1t}^{-}$$
(8)

Define a transformation matrix:

$$H = \begin{pmatrix} 1 & -\Omega_{12}\Omega_{22}^{-1} \\ 0 & I_p \end{pmatrix} = \begin{pmatrix} H_1 \\ H_2 \end{pmatrix}.$$
(9)

The vector  $\begin{pmatrix} u_{1t}^- & u_{2t} \end{pmatrix}'$  can be written as

$$H\Omega H' = \begin{pmatrix} \Omega_{11} - \Omega_{22}^{-1} \Omega_{21} \Omega_{12} & 0\\ 0 & \Omega_{22} \end{pmatrix} = \begin{pmatrix} M_{11} & 0\\ 0 & M_{22} \end{pmatrix}.$$
 (10)

Lemma 1. Under Assumption 1 - 3, for Equation (8) we have

$$\frac{1}{T} \sum_{t=1}^{T} y_{2t} I\left(q_{t-1} \le c_1\right) u_{1t}^{-} \xrightarrow{p} M_{11}^{1/2} \int_0^1 W_2\left(r, F\left(c_1\right)\right) \mathrm{d}W_{1/2}\left(r\right) + \chi.$$
(11)

$$\frac{1}{T} \sum_{t=1}^{T} y_{2t} I(c_1 < q_{t-1} \le c_2) u_{1t}^{-} \xrightarrow{p} \mathcal{M}_{11}^{1/2} \int_0^1 W_2(r, F(c_2) - F(c_1)) dW_{1/2}(r) + \chi.$$
(12)

$$\frac{1}{T} \sum_{t=1}^{T} y_{2t} I(c_2 < q_{t-1}) u_{1t}^{-} \xrightarrow{p} M_{11}^{1/2} \int_0^1 W_2(r, 1 - F(c_2)) dW_{1/2}(r) + \chi.$$
(13)

where W(s,r) denotes a Brownian sheet,  $W_i(r)$ , i = 1, 2, is a p-dimensional standard Brownian motion,  $W_{1/2} = W_1(r) - \Omega_{12}\Omega_{22}^{-1}W_2(r)$  and  $\chi = \sum_{\nu=0}^{\infty} E(u_{2\tau}u_{1\tau+\nu})$ . **Lemma 2.** Under Assumption 1 - 3, for Equation (8) we have

$$\frac{1}{T^2} \sum_{t=1}^{T} y_{2t}^2 I(q_{1t} \le c_1) \xrightarrow{p} F(c_1) M_{22} \int_0^1 W_2(r)^2 dr$$
(14)

$$\frac{1}{T^{2}} \sum_{t=1}^{T} y_{2t}^{2} I(q_{1t} \le c_{1}) \xrightarrow{p} (F(c_{2}) - F(c_{1})) M_{22} \int_{0}^{1} W_{2}(r)^{2} dr$$
(15)

$$\frac{1}{T^2} \sum_{t=1}^{T} y_{2t}^2 I(q_{1t} \le c_1) \xrightarrow{p} F(c_2) M_{22} \int_0^1 W_2(r)^2 dr$$
(16)

The following theorem shows the limit distribution of FM-OLS estimators.

**Theorem 1.** Under Assumption 1 - 3, for Equation (8) we have

$$T\left(\hat{\rho}_{1}-\rho_{1}\right)-TH_{1}\left(\hat{\Omega}_{21}+\hat{\Lambda}_{21}\right)\longrightarrow\Upsilon\left(F\left(c_{1}\right)\int_{0}^{1}W_{2}\left(r\right)^{2}\mathrm{d}r\right)^{-1}\times\left(\int_{0}^{1}W_{2}\left(r,F\left(c_{1}\right)\right)\mathrm{d}W_{1/2}\left(r\right)\right)$$
(17)

$$T(\hat{\rho}_{2} - \rho_{2}) - TH_{1}(\hat{\Omega}_{21} + \hat{\Lambda}_{21})$$

$$= \sum_{\mu} \sum_{i=1}^{p} \sum_{j=1}^{p} \sum_{i=1}^{p} \left( E(x_{i}) - E(x_{i}) \right) \int_{0}^{1} W_{i}(x_{i})^{2} dx_{i}^{-1} \cdots \int_{0}^{1} \int_{0}^{1} W_{i}(x_{i}) E(x_{i}) dW_{i}(x_{i})$$

$$(18)$$

$$\xrightarrow{p} \Upsilon((F(c_2) - F(c_1)) \int_0^1 W_2(r)^2 dr) \times (\int_0^1 W_2(r, F(c_2) - F(c_1)) dW_{1/2}(r))$$

$$T(\hat{\rho}_{3}-\rho_{3})-TH_{1}(\hat{\Omega}_{21}+\hat{\Lambda}_{21}) \xrightarrow{p} \Upsilon\left(1-(F(c_{2}))\int_{0}^{1}W_{2}(r)^{2} dr\right)^{-1} \times \left(\int_{0}^{1}W_{2}(r,1-F(c_{2}))dW_{1/2}(r)\right)$$
(19)

where  $\Upsilon = M_{11}^{1/2} / M_{22}$ .

In the formulae for the bias correction terms in Equation (17)-(19),  $\hat{\Omega}_{21}$  and  $\hat{\Lambda}_{21}$  are the kernel estimates of long run covariance matrices, which can be found in Phillips [14]. From the Theorem 1, the limit distribution is free of second order bias.

# **3.** Conclusions

In this paper, we have established the asymptotics of fully modified ordinary least squares cointegrating estimators for three-regime threshold cointegration regression. Our results may be used under the condition that residuals with weakly dependency exist. These results improve the estimation methods available in threshold cointegration literatures.

There are a variety of potential topics for future research related to this study. First, it is possible to extend our results to more than one cointegrating relationship, although a single threshold cointegrating relationship is often used in economics and international finance. Second, testing for threshold cointegration based on the FM-OLS principle is not yet available. The authors hope to further study these issues in the future.

#### Acknowledgements

The author thanks financial support from Ministry of Science and Technology of Taiwan under grant NSC 95-2415-H-305-010 and Shu-Yu Lin and Yi-Ting Tsai for excellent research assistants.

#### References

- [1] Phillips, P. and Hansen, B. (1990) Statistical Inference in Instrumental Variables Regression with I(1) Processes. Review of Economic Studies, 57, 99-125. http://dx.doi.org/10.2307/2297545
- [2] Balke, N. and Fomby, T. (1997) Threshold Cointegration. International Economic Review, 38, 627-645. http://dx.doi.org/10.2307/2527284
- [3] Choi, I. and Saikkonen, P. (2004) Testing Linearity in Cointegrating Smooth Transition Regressions. The Econometrics Journal, 7, 341-365. http://dx.doi.org/10.1111/j.1368-423X.2004.00134.x
- Hansen, B. and Seo, B. (2002) Testing for Two-Regime Threshold Cointegration in Vector Error Correction Models. [4] Journal of Econometrics, 110, 293-318. http://dx.doi.org/10.1016/S0304-4076(02)00097-0

- [5] Gaul, J. (2006) Estimation and Testing in a Three Regime Vector Error Correction Model. University of Bonn, Bonn.
- [6] Gonzalo, J. and Pitarakis, J.-Y. (2006) Threshold Effects in Multivariate Error Correction Models. In: Mills, T. and Patterson, K., Eds., *Palgrave Handbook of Econometrics: Econometric Theory Volume* 1, Palgrave MacMillan, New York, 578-609.
- [7] Gonzalo, J. and Pitarakis, J.-Y. (2006) Threshold Effects in Cointegration Relationships. Oxford Bulletin of Economics and Statistics, 68, 813-833. <u>http://dx.doi.org/10.1111/j.1468-0084.2006.00458.x</u>
- [8] Kiliç, R. (2011) Testing for Co-Integration and Nonlinear Adjustment in a Smooth Transition Error Correction Model. Journal of Time Series Analysis, 32, 647-660. <u>http://dx.doi.org/10.1111/j.1467-9892.2011.00722.x</u>
- [9] Li, J. and Lee, J. (2010) ADL Tests for Threshold Cointegration. Journal of Time Series Analysis, 31, 241-254.
- [10] Seo, M. (2006) Bootstrap Testing for the Null of No Cointegration in a Threshold Vector Error Correction Models. *Journal of Econometrics*, **134**, 129-150. <u>http://dx.doi.org/10.1016/j.jeconom.2005.06.018</u>
- [11] Lo, M. and Zivot, E. (2001) Threshold Cointegration and Nonlinear Adjustment to the Law of One Price. Macroeconomic Dynamics, 5, 533-576.
- [12] Bec, F. and Rahbek, A. (2004) Vector Equilibrium Correction Models with Non-Linear Discontinuous Adjustments. *The Econometrics Journal*, 7, 628-651. <u>http://dx.doi.org/10.1111/j.1368-423X.2004.00147.x</u>
- [13] De Jong, R. (2002) Nonlinear Minimization Estimators in the Presence of Cointegrating Relationships. *Journal of Econometrics*, **110**, 241-259. <u>http://dx.doi.org/10.1016/S0304-4076(02)00093-3</u>
- Phillips, P. (1995) Fully Modified Least Squares and Vector Autoregression. *Econometrica*, 63, 1023-1078. http://dx.doi.org/10.2307/2171721

# **Mathematical Appendix**

# **Proof of Lemma 1**

Let  $U_t = (u_{1t} \quad u'_{2t})$  and  $U^- = HU_t = \begin{pmatrix} u_{1t} - \sum_{12} \sum_{22}^{-1} u_{2t} \\ u_{2t} \end{pmatrix} = \begin{pmatrix} u_{1t} \\ u_{2t} \end{pmatrix}$ . The asymptotic distribution follows directly from Phillips [14] and Gonzalo and Pitarakis [6]

$$\frac{1}{T} \sum_{t=1}^{T} y_{2t} I(q_{t-1} \le c_1) u_{1t}^{-} \xrightarrow{p} M_{11}^{1/2} \int_0^1 W_{1/2}(r) dW_2(r) + \chi$$

$$\frac{1}{T} \sum_{t=1}^{T} y_{2t} I(c_1 < q_{t-1} \le c_2) u_{1t}^{-} \xrightarrow{p} M_{11}^{1/2} \int_0^1 W_2(r, F(c_2) - F(c_1)) dW_{1/2}(r) + \chi$$

$$\frac{1}{T} \sum_{t=1}^{T} y_{2t} I(c_2 < q_{t-1}) u_{1t}^{-} \xrightarrow{p} M_{11}^{1/2} \int_0^1 W_2(r, 1 - F(c_2)) dW_{1/2}(r) + \chi.$$

#### **Proof of Lemma 2**

From the Proposition 2 in Gonzalo and Pitarakis [7], Lemma A3 in Gonzalo and Pitarakis [7] and the continuous mapping theorem give

$$\frac{1}{T^{2}} \sum_{t=1}^{T} y_{2t}^{2} I(q_{1t} \leq c_{1}) \xrightarrow{p} F(c_{1}) M_{22} \int_{0}^{1} W_{2}(r)^{2} dr$$

$$\frac{1}{T^{2}} \sum_{t=1}^{T} y_{2t}^{2} I(q_{1t} \leq c_{1}) \xrightarrow{p} (F(c_{2}) - F(c_{1})) M_{22} \int_{0}^{1} W_{2}(r)^{2} dr$$

$$\frac{1}{T^{2}} \sum_{t=1}^{T} y_{2t}^{2} I(q_{1t} \leq c_{1}) \xrightarrow{p} F(c_{2}) M_{22} \int_{0}^{1} W_{2}(r)^{2} dr.$$

## **Proof of Theorem 1**

Consider fully modified estimator  $\hat{\rho}_j j = 1, 2, 3$ .

$$\begin{pmatrix} T(\hat{\rho}_{1}-\rho_{1}) \\ T(\hat{\rho}_{2}-\rho_{2}) \\ T(\hat{\rho}_{3}-\rho_{3}) \end{pmatrix} = \begin{pmatrix} \left( (1/T^{2}) \sum_{t=1}^{T} y_{2t}^{2} I(q_{t-1} \le c_{1}) \right)^{-1} (1/T^{2}) \sum_{t=1}^{T} y_{2t} I(q_{t-1} \le c_{1}) u_{1t}^{-1} \\ \left( (1/T^{2}) \sum_{t=1}^{T} y_{2t}^{2} I(c_{1} < q_{t-1} \le c_{2}) \right)^{-1} (1/T^{2}) \sum_{t=1}^{T} y_{2t} I(c_{1} < q_{t-1} \le c_{2}) u_{1t}^{-1} \\ \left( (1/T^{2}) \sum_{t=1}^{T} y_{2t}^{2} I(q_{t-1} < c_{2}) \right)^{-1} (1/T^{2}) \sum_{t=1}^{T} y_{2t} I(q_{t-1} < c_{2}) u_{1t}^{-1} \end{pmatrix}$$

For denominator,

$$\frac{1}{T^{2}} \sum_{t=1}^{T} y_{2t}^{2} I(q_{1t} \le c_{1}) \xrightarrow{p} F(c_{1}) \int_{0}^{1} W_{2}(r)^{2} dr$$

$$\frac{1}{T} \sum_{t=1}^{T} y_{2t} I(c_{1} < q_{t-1} \le c_{2}) u_{1t}^{-} p \xrightarrow{p} M_{11}^{1/2} \int_{0}^{1} W_{2}(r, F(c_{2}) - F(c_{1})) dW_{1/2}(r) + \chi$$

$$\frac{1}{T} \sum_{t=1}^{T} y_{2t} I(c_{2} < q_{t-1}) u_{1t}^{-} \xrightarrow{p} M_{11}^{1/2} \int_{0}^{1} W_{2}(r, 1 - F(c_{2})) dW_{1/2}(r) + \chi.$$

by Lemma 2 For numerator, by virtue of Lemma 1

$$\frac{1}{T}\sum_{t=1}^{T} y_{2t}I(q_{t-1} \le c_1)u_{1t}^{-} - H_1(\hat{\Omega}_{21} + \hat{\Lambda}_{21}) \xrightarrow{p} \int_0^1 W_{1/2}(r)dW_2(r)$$

$$\frac{1}{T}\sum_{t=1}^{T} y_{2t}I(c_1 < q_{t-1} \le c_2)u_{1t}^{-} \xrightarrow{p} M_{11}^{1/2}\int_0^1 W_2(r, F(c_2) - F(c_1))dW_{1/2}(r) + \chi$$

$$\frac{1}{T}\sum_{t=1}^{T} y_{2t}I(c_2 < q_{t-1})u_{1t}^{-} \xrightarrow{p} M_{11}^{1/2}\int_0^1 W_2(r, 1 - F(c_2))dW_{1/2}(r) + \chi.$$

According to the continuous mapping theorem and functional central limit theorem, it follows that

$$T(\hat{\rho}_{1}-\rho_{1})-TH_{1}(\hat{\Omega}_{21}+\hat{\Lambda}_{21}) \xrightarrow{p} \Upsilon\left(F(c_{1})\int_{0}^{1}W_{2}(r)^{2} dr\right)^{-1} \times \left(\int_{0}^{1}W_{2}(r,F(c_{1}))dW_{1/2}(r)\right)$$

$$T(\hat{\rho}_{2}-\rho_{2})-TH_{1}(\hat{\Omega}_{21}+\hat{\Lambda}_{21}) \xrightarrow{p} \Upsilon\left(F(c_{2})-F(c_{1})\int_{0}^{1}W_{2}(r)^{2} dr\right)^{-1} \times \left(\int_{0}^{1}W_{2}(r,F(c_{2})-F(c_{1}))dW_{1/2}(r)\right)$$

$$T(\hat{\rho}_{2}-\rho_{2})-TH_{1}(\hat{\Omega}_{21}+\hat{\Lambda}_{21}) \xrightarrow{p} \Upsilon\left(F(c_{2})\int_{0}^{1}W_{2}(r)^{2} dr\right)^{-1} \times \left(\int_{0}^{1}W_{2}(r,F(c_{2}))dW_{1/2}(r)\right).$$
where  $\Upsilon = M_{11}^{1/2}/M_{22}$ .