

\mathcal{F} -Multiautomata on Join Spaces Induced by Differential Operators

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Abstract

In this paper, we introduce the notion of fuzzy multiautomata and we investigate the hyperstructures induced by the linear second-order differential operators which can be used for construction of fuzzy multiautomata serving as a theoretical background for modeling of processes.

Keywords

Fuzzy Systems, Differential Operators, Hyperalgebraic Structures, Multiautomata

1. Introduction

Hyperstructure theory was born in 1934 when Marty defined hypergroups as a generalization of groups. This theory has been studied in the following decades and nowadays by many mathematicians. The hypergroup theory both extends some well-known group results and introduces new topics, thus leading to a wide variety of applications, as well as to a broadening of the investigation fields. There are applications of algebraic hyperstructures to the following subjects: geometry, hypergraphs, binary relations, lattices, fuzzy sets and rough sets, automata, cryptography, combinatorics, codes, artificial intelligence, and probabilistic. A comprehensive review of the theory of hyperstructures appears in [1]-[3].

Further, since the beginning of the first decade of this century relationships between ordinary linear differential operators and the hypergroup theory have been studied [4]-[8].

Zadeh [9] introduced the theory of fuzzy sets and, soon after, Wee [10] introduced the concept of fuzzy automata. Automata have a long history both in theory and application and are the prime examples of general computational systems over discrete spaces. Fuzzy automata not only provide a systematic approach for handling

uncertainty in such systems, but also can be used in continuous spaces [11]. In this paper, we introduce \mathcal{F} -multiautomaton, without output function, where the transition function or next state function satisfies so called Fuzzy Generalized Mixed Condition (FGMC). These \mathcal{F} -multiautomata are systems that can be used for the transmission of information of certain type. Then we construct \mathcal{F} -multiautomata of commutative hypergroups and join spaces created from second order linear differential operators.

2. Preliminaries

Let J be an open interval of real numbers, and $(C(J), \cdot)$ be the group of all continuous functions from J to interval $(0, 1]$. In what follows we denote $L(p, q)y = y'' + p(x)y' + q(x)y$; $p, q \in C(J)$ that named differential operators of second order. And define $LA_2(J) = \{L(p, q); p, q \in C(J)\}$. Recall some basic notions of the hypergroup theory. A hypergroupoid is a pair (H, \cdot) , where $H \neq \emptyset$ and $\cdot: H \times H \rightarrow \mathcal{P}^*(H)$ is a binary hyperoperation on H . (Here $\mathcal{P}^*(H)$ denotes the system of all nonempty subsets of (H)). If $a \cdot (b \cdot c) = (a \cdot b) \cdot c$ holds for all $a, b, c \in H$ then (H, \cdot) is called a semihypergroup. If moreover, the reproduction axiom ($a \cdot H = H = H \cdot a$, for any element $a \in H$) is satisfied, then the pair (H, \cdot) is called a hypergroup. Join spaces are playing an important role in theories of various mathematical structures and their applications. The concept of a join space has been introduced by Prenowitz [12] and used by him and afterwards together with James Jantosciak to reconstruct several branches of geometry. In order to define a join space, we need the following notation: If a, b, x are elements of a hypergroupoid $(H, *)$ then we denote $a/b = \{x \in H \mid a \in x * b\}$ and A/B we intend the set $\bigcup_{a \in A, b \in B} a/b$.

Definition 2.1 [12] [13] A commutative hypergroup $(H, *)$ is called a join space (or commutative transposition hypergroup) if the following condition holds for all elements a, b, c, d of H :

$$\frac{a}{b} \cap \frac{c}{d} \neq \emptyset \Rightarrow a * d \cap b * c \neq \emptyset$$

By a quasi-ordered (semi)group we mean a triple (G, \cdot, \leq) , where (G, \cdot) is a (semi) group and binary relation \leq is a quasi ordering (i.e. is reflexive and transitive) on the set G such that, for any triple $x, y, z \in G$ with the property $x \leq y$ also $x \cdot z \leq y \cdot z$ and $z \cdot x \leq z \cdot y$ hold.

The following lemma is called Ends-Lemma that is proved on [14] [15].

Lemma 2.2 Let (G, \cdot, \leq) be a quasi-ordered semigroup. Define a hyperoperation

$$*: G \times G \rightarrow \mathcal{P}^*(G) \quad \text{by } a * b = [a \cdot b]_{\leq} = \{x \in G; a \cdot b \leq x\}$$

For all pairs of elements $a, b \in G$. Then $(G, *)$ is a semihypergroup which is commutative if the semigroup (G, \cdot) is commutative. If moreover, (G, \cdot) is a group, then $(G, *)$ is a transposition hypergroup. Therefore, if (G, \cdot) is a commutative group, then $(G, *)$ is a join space.

Proposition 2.3 For any pair of differential operators $L(p_1, q_1), L(p_2, q_2) \in LA_2(J)$ define a binary operation as below:

$$L(p_1, q_1) \cdot L(p_2, q_2) = L(p_1 \cdot p_2, q_1 \cdot q_2)$$

and define a quasi-ordered relation as following:

$$L(p_1, q_1) \leq L(p_2, q_2) \quad \text{if } p_1(x) = p_2(x), q_1(x) \leq q_2(x), \text{ for all } x \in J.$$

Then $(LA_2(J), \cdot, \leq)$ is a commutative ordered group with the unit element $L(1, 1)$. □

Now we apply the simple construction of a hypergroup from Lemma 2.2 into this considered concrete case of differential operators:

For arbitrary pair of operators $L(p_1, q_1), L(p_2, q_2) \in LA_2(J)$ we put:

$$\begin{aligned} L(p_1, q_1) * L(p_2, q_2) &= \{L(p, q) \in LA_2(J) \mid L(p_1, q_1) \cdot L(p_2, q_2) \leq L(p, q)\} \\ &= \{L(p_1 \cdot p_2, \varphi) \mid q_1 \cdot q_2 \leq \varphi; \varphi \in C(J)\} \end{aligned}$$

Then we obtain the following Corollary from Lemma 2. 2 immediately:

Corollary 2.4 For each $L(p_1, q_1), L(p_2, q_2) \in LA_2(J)$, if

$$L(p_1, q_1) * L(p_2, q_2) = \{L(p_1 \cdot p_2, \varphi) \mid q_1 \cdot q_2 \leq \varphi, \varphi \in C(J)\}$$

Then $(LA_2(J), *)$ is a commutative hypergroup and a join space.

Definition 2.5 [16] Let X be a non-empty set, $(H, *)$ be a (semi) hypergroup and $\delta: X \times H \rightarrow X$ be a mapping such that, for all $x \in X$, and $s, t \in H$:

$$\delta(\delta(x, t), s) \in \delta(x, t * s), \text{ where } \delta(x, t * s) = \{\delta(x, u); u \in t * s\} \quad (2.1)$$

Then (X, H, δ) is called a discrete transformation (semi)hypergroup or an action of the (semi)hypergroup H on the set X . The mapping δ is usually said to be simply an action.

Remark 2.6 The condition (2.1) used above is called *Generalized Mixed Associativity Condition*, shortly **GMAC**.

Definition 2.7 [6] [7] (Quasi)multiautomaton without output is a triad $M = (H, S, \delta)$, where $(H, *)$ is a (semi)hypergroup, S is a non-empty set, and $\delta: H \times S \rightarrow S$ is a transition map satisfying **GMAC** condition. The set S is called the state set of the (quasi)multiautomaton M , the structure $(H, *)$ is called an input (semi)-hypergroup of the (quasi)multiautomaton M and δ is called a transition function. Elements of the set S are called states and the elements of the set H are called input symbols.

3. \mathcal{F} -Multi Automata

Definition 3.1 A fuzzy transformation (semi)hypergroup (or a fuzzy action) of (semi)hypergroup H on S is a triple (S, H, μ) , where S is a non-empty set, $(H, *)$ is a (semi)hypergroup, and μ is a fuzzy subset of $S \times H \times S$ such that, for all $u, v \in H$ and $p, q \in S$:

$$\vee \{\mu(q, u, r) \wedge \mu(r, v, p) \mid r \in S\} \in \mu(q, u * v, p) \text{ where } \mu(q, u * v, p) = \{\mu(q, x, p) \mid x \in u * v\} \quad (3.2)$$

Remark 3.2 The condition (3.2) used above is called *Fuzzy Generalized Mixed Condition*, shortly **FGMC**.

Definition 3.3 \mathcal{F} -(quasi) multiautomaton without outputs is a triad $\mathcal{F} = (H, S, \mu)$, where $(H, *)$ is a (semi)hyper-group, S is a non-empty set and $\mu: S \times H \times S \rightarrow [0, 1]$ is a fuzzy transition map satisfying **FGMC** condition.

Set S is called the state set and the hyperstructure $(H, *)$ is called the input (semi)hypergroup of the \mathcal{F} -(quasi)multiautomaton \mathcal{F} and μ is called fuzzy transition function. Elements of the set S are called states and the elements of the set H are called input symbols.

Definition 3.4 \mathcal{F} -(quasi)multiautomaton $\mathcal{F} = (H, S, \mu)$ is said to be *abelian* (or commutative) if

$$\mu(s, x * y, t) = \mu(s, y * x, t), \text{ for all } s, x, y, t \in S \times H \times H \times S$$

Example 3.5 Suppose that $H = \{a, b\}$, $S = \{q_1, q_2, q_3\}$. Let hyperoperation $*$ on H and fuzzy transition function $\delta: S \times H \times S \rightarrow [0, 1]$ are defined as follows:

$*$	a	b
a	$\{a\}$	$\{a, b\}$
b	$\{a, b\}$	$\{b\}$

$$\delta(q_1, a, q_1) = \frac{1}{3} \quad \delta(q_2, a, q_2) = \frac{1}{3} \quad \delta(q_1, a, q_2) = \frac{1}{3} \quad \delta(q_2, a, q_3) = \frac{1}{3}$$

$$\delta(q_1, b, q_2) = \frac{2}{3} \quad \delta(q_2, b, q_2) = \frac{2}{3} \quad \delta(q_2, a, q_1) = \frac{1}{3} \quad \delta(q_1, a, q_3) = \frac{1}{3}$$

And for all other ordered triples (q, h, p) we define $\delta(q, h, p) = 0$. Then (h, S, δ) is a commutative \mathcal{F} -multiautomaton (**Figure 1**).

4. \mathcal{F} -Multi Automata on Join Spaces Induced by Differential Operators

Proposition 4.1: Let $\mathcal{F}_1 = ((C(J), \odot), LA_2(J), \mu_1)$ where, for all $f, g \in C(J)$:

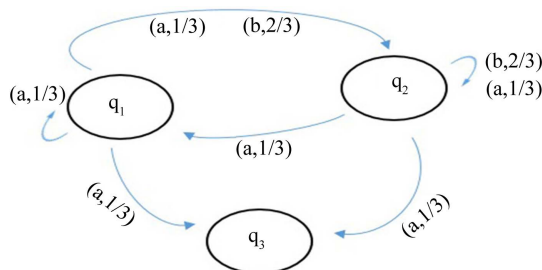


Figure 1. The \mathcal{F} -multiautomaton of Example 3.5.

$$f \odot g = [f \cdot g]_{\leq} = \{h \in C(J) \mid f(x) \cdot g(x) \leq h(x), \forall x \in J\}$$

And define:

$$\mu_1 : LA_2(J) \times C(J) \times LA_2(J) \rightarrow [0, 1]$$

$$\mu_1(L(p_1, q_1), f, L(p_2, q_2)) = \vee(q_1 \cdot f \cdot q_2)$$

$$\text{where } \vee(q_1 \cdot f \cdot q_2) = \bigvee_{\forall x, y, z \in J} (q_1(x) \cdot f(y) \cdot q_2(z))$$

Then \mathcal{F}_1 is a commutative \mathcal{F} -multiautomaton.

Proof: By Lemma 2.2 the hypergroupoid $(C(J), \odot)$ is a join space. Now, we prove this structure is satisfying FGMC property. Let

$$\vee\{\mu_1(L(p_1, q_1), u, L(t, r)) \wedge \mu_1(L(t, r), v, L(p_2, q_2)) \mid L(t, r) \in LA_2(J)\} = i$$

and

$$\mu_1(L(p_1, q_1), u \odot v, L(p_2, q_2)) = \mathcal{A}, \text{ for all } u, v \in C(J) \text{ and } L(p_1, q_1), L(p_2, q_2) \in LA_2(J).$$

Then

$$i = \bigvee_{r \in C(J)} ((\vee(q_1 \cdot u \cdot r)) \wedge (\vee(r \cdot v \cdot q_2))) = (\vee(q_1 \cdot u)) \wedge (\vee(v \cdot q_2))$$

$$\mathcal{A} = \{\vee(q_1 \cdot t \cdot q_2) \mid t(x) \geq u(x) \cdot v(x)\}$$

Clearly $i \in \mathcal{A}$ (since we can take $t(x) = \frac{u(x)}{q_2(x)}$ or $t(x) = \frac{v(x)}{q_1(x)}$ for each $x \in J$). Then **FGMC** property

holds. Hence \mathcal{F}_1 is a \mathcal{F} -multiautomaton. In addition, since $f \odot g = g \odot f$, for all $f, g \in C(J)$ then \mathcal{F}_1 is commutative. \square

Proposition 4.2: Let $\mathcal{F}_2 = ((C(J), \odot), LA_2(J), \mu_2)$ where hyperoperation \odot was defined in proposition 4.1.

And define:

$$\mu_2 : LA_2(J) \times C(J) \times LA_2(J) \rightarrow [0, 1]$$

$$\mu_2(L(p_1, q_1), f, L(p_2, q_2)) = \vee(q_1 \wedge f \wedge q_2)$$

$$\text{where } \vee(q_1 \wedge f \wedge q_2) = \bigvee_{\forall x, y, z \in J} (q_1(x) \wedge f(y) \wedge q_2(z))$$

Then \mathcal{F}_2 is a commutative \mathcal{F} -multiautomaton.

Proof: By Lemma 2.2 the hypergroupoid $(C(J), \odot)$ is a join space. Now, we prove this structure is satisfying FGMC property. Let

$$\vee\{\mu_2(L(p_1, q_1), u, L(t, r)) \wedge \mu_2(L(t, r), v, L(p_2, q_2)) \mid L(t, r) \in LA_2(J)\} = j$$

and

$$\mu_2(L(p_1, q_1), u \odot v, L(p_2, q_2)) = \mathcal{B}$$

for all, $u, v \in C(J)$ and $L(p_1, q_1), L(p_2, q_2) \in LA_2(J)$.

Then

$$j = \bigvee_{r \in C(J)} ((\vee(q_1 \wedge u \wedge r)) \wedge (\vee(r \wedge v \wedge q_2))) = \vee(q_1 \wedge u \wedge v \wedge q_2)$$

$$\mathcal{B} = \{ \vee(q_1 \wedge t \wedge q_2) \mid u(x) \cdot v(x) \leq t(x), x \in J \}$$

Since $u(x) \cdot v(x) \leq u(x) \wedge v(x)$, for all $x \in J$ then $j \in \mathcal{B}$. Hence **FGMC** property holds. Therefore \mathcal{F}_2 is a \mathcal{F} -multiautomaton. In addition, It is clear that \mathcal{F}_2 is commutative.

Proposition 4.3: Let $\mathcal{F}_3 = ((LA_2(J), *), C(J), \mu_3)$ where, for all $L(p_1, q_1), L(p_2, q_2) \in LA_2(J)$:

$$L(p_1, q_1) * L(p_2, q_2) = \{ L(p_1 \cdot p_2, \varphi) \mid q_1(x) \cdot q_2(x) \leq \varphi(x), \varphi \in C(J) \}$$

And define:

$$\mu_3 : C(J) \times LA_2(J) \times C(J) \rightarrow [0, 1]$$

$$\mu_3(f, L(p, q), g) = \vee(f \wedge q \wedge g)$$

where $\vee(f \wedge q \wedge g) = \bigvee_{\forall x, y, z \in J} (f(x) \wedge q(y) \wedge g(z))$

Then \mathcal{F}_3 is a commutative \mathcal{F} -multiautomaton.

Proof: According to Corollary 2.4 $(LA_2(J), *)$ is a join space. Now we check the FGMC property for this structure. Let

$$\vee \{ \mu_3(f, L(p_1, q_1), r) \wedge \mu_3(r, L(p_2, q_2), g) \mid r \in C(J) \} = \ell$$

And

$$\mu_3(f, L(p_1, q_1) * L(p_2, q_2), g) = \mathcal{C}, \text{ for all } f, g \in C(J) \text{ and } L(p_1, q_1), L(p_2, q_2) \in LA_2(J).$$

Then

$$\ell = \bigvee_{r \in C(J)} ((\vee(f \wedge q_1 \wedge r)) \wedge (\vee(r \wedge q_2 \wedge g))) = \vee(f \wedge q_1 \wedge q_2 \wedge g)$$

$$\begin{aligned} \mathcal{C} &= \{ \mu_3(f, L(p_1 \cdot p_2, \varphi), g) \mid q_1(x) \cdot q_2(x) \leq \varphi(x), x \in J \} \\ &= \{ \vee(f \wedge \varphi \wedge g) \mid q_1(x) \cdot q_2(x) \leq \varphi(x), x \in J \} \end{aligned}$$

Since $q_1(x) \wedge q_2(x) \geq q_1(x) \cdot q_2(x)$, for all $x \in J$ then $\ell \in \mathcal{C}$. Hence \mathcal{F}_3 is a \mathcal{F} -multiautomaton. It is clear that \mathcal{F}_3 is commutative. \square

Proposition 4.4: Let $\mathcal{F}_4 = ((LA_2(J), *), C(J), \mu_4)$, where hyperoperation $*$ was defined in proposition 3.4.

And define:

$$\mu_4 : C(J) \times LA_2(J) \times C(J) \rightarrow [0, 1]$$

$$\mu_4(f, L(p, q), g) = \vee(f \cdot q \cdot g)$$

where: $\vee(f \cdot q \cdot g) = \bigvee_{\forall x, y, z \in J} (f(x) \cdot q(y) \cdot g(z))$

Then \mathcal{F}_4 is a commutative \mathcal{F} -multiautomaton.

Proof: According to Corollary 2.4 $(LA_2(J), *)$ is a join space. Now, we prove this structure is satisfying FGMC property. Let

$$\vee \left\{ \mu_4(f, L(p_1, q_1), r) \wedge \mu_4(r, L(p_2, q_2), g) \mid r \in C(J) \right\} = m$$

$$\mu_4(f, L(p_1, q_1) * L(p_2, q_2), g) = \mathcal{M}$$

for all $f, g \in C(J)$ and $L(p_1, q_1), L(p_2, q_2) \in LA_2(J)$.

Then

$$m = \bigvee_{r \in C(J)} ((\vee(f \cdot q_1 \cdot r)) \wedge (\vee(r \cdot q_2 \cdot g))) = (\vee(f \cdot q_1)) \wedge (\vee(q_2 \cdot g))$$

$$\mathcal{M} = \{ \vee(f \cdot t \cdot g) \mid q_1(x) \cdot q_2(x) \leq t(x) \}$$

Since $\frac{q_1(x)}{g(x)} \geq q_1(x) \cdot q_2(x)$ and $\frac{q_2(x)}{f(x)} \geq q_1(x) \cdot q_2(x)$, for all $x \in J$ then $m \in \mathcal{M}$. Hence \mathcal{F}_4 is a \mathcal{F} -

multiautomaton. It is clear that \mathcal{F}_4 is commutative.

5. Conclusion

In this research, we introduced \mathcal{F} -multistructures which can be used for construction of \mathcal{F} -multiautomata serving as a theoretical background for modeling of processes. Then we obtain some \mathcal{F} -multiautomata of linear second-order differential operators. In future work, we can introduce \mathcal{F} -multiautomaton with output and concrete interpretations of these structures can be studied.

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