

Audio Noise Reduction Using Low Pass Filters

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Abstract

The study aimed to filter and remove noise from audio, and in this study researcher followed the descriptive analytical method. The study sample consisted of an audio file and has been save Audio of on a formula (WAV), and the study used matlab 7.10.0 to read sound and design low pass filter, then insert the audio signal with the noise signal into the filter and output a signal audio without noise. The researcher has reached findings that differed according to the rank of the filter. The low pass filter has a great effect on removing noise during the registration process together with the times of implementation.

Subject Areas

Applications of Communication Systems, Artificial Intelligence

Keywords

Low Pass Filters, Noise, Audio Filtering, IIR Filters, FIR Filters

1. Introduction

With the development of communication technology, voice communication has become a major communication media for people to transmit information more convenient [1]. Audio noise reduction system is the system that is used to remove the noise from the audio signals. Audio noise reduction systems can be divided into two basic approaches. The first approach is the complementary type which involves compressing the audio signal in some well-defined manner before it is recorded (primarily on tape). On playback [2], the subsequent complementary expansion of the audio signal which restores the original dynamic range, at the same time has the effect of pushing the reproduced tape noise (added during recording) farther below the peak signal level—and hopefully below the threshold of hearing. The second approach is the single-ended or non-complementary type which utilizes techniques to reduce the noise level already present in the source material—in essence a playback only noise reduction system.

1.1. Filter

Filters are networks that process signals in a frequency-dependent manner. The basic concept of a filter can be explained by examining the frequency dependent nature of the impedance of capacitors and inductors. Consider a voltage divider where the shunt leg is reactive impedance. As the frequency is changed, the value of the reactive impedance changes, and the voltage divider ratio changes as well. This mechanism yields the frequency dependent change in the input/output transfer function that is defined as the frequency response [3]. Filters have many practical applications. A simple, single-pole, low-pass filter (the integrator) is often used to stabilize amplifiers by rolling off the gain at higher frequencies where excessive phase shift may cause oscillations. A simple, single-pole, high-pass filter can be used to block dc offset in high gain amplifiers or single supply circuits [4] (Table 1).

There are two types of filters:

- 1) Finite Impulse Response (FIR) filter.
- 2) Infinite Impulse Response (IIR) filter.

FIR filters have the following advantages over IIR filters:

- 1) They can have an exact linear phase.
- 2) They are always stable.
- 3) The design methods are generally linear.
- 4) They can be realized efficiently in hardware.
- 5) The filter start-up transients have finite duration [4].

1.2. Low Pass Filter

Low pass filter: For different low-pass filter, there is different weakening of frequency in each signal. When using it in audio applications, sometimes it is called high-cut filter or treble cut filter [5]. The application of low-pass filter in signal processing is equal to the effect of other areas. There are many types of low-pass filter; the most common one is Butterworth filter and Chebyshev filter (**Figure** 1).

Table	e 1.	Type	of filter	and	purpose.	
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S. N	Filter	Purpose
1	Low pass filter	Passes low frequency band
2	High pass filter	Passes high frequency band
3	Band pass filter	Passes selected range of frequency band
4	Band stop filter	Stop selected range of frequency band

1.3. Time-Domain Filters

1) Finite Impulse Response (FIR) filters-A finite impulse response (FIR) filter is one in which the output signal goes to zero in some finite amount of time.

2) Infinite Impulse Response (IIR) filters-An infinite impulse response (IIR) filter may run for an arbitrarily long period of time and never have the output go to zero. The difference between the two types of filters is that an IIR filter is recursive; *i.e.*, an IIR filter will take its previous output and use it as input for the next output, whereas an FIR filter will take as input the current sample in addition to some previous sample. In other words, an IIR filter has internal feedback while an FIR filter does not (**Figure 2** and **Figure 3**).

2. Problem Definition

The aim of study is to reduce the noise from the sound signal assuming that we have a useful voice signal related to a particular material and is the signal of the sound of the noise over the entire wave of the sound signal and the V is distributed with the noise or noise associated with it, the study problem is to reduce noise or The noise associated with the sound signal can be achieved using the low pass filter. This filter can predict the sound added to the main sound and will clear the noise (**Figure 4**).

Definition of the problem is shown in **Figure 4**.



Figure 1. Low pass filter specifications.







Figure 3. IIR filter.



Figure 4. Definition of the problem.

3. Result

This shows the implementation results of the dissertation work. There are a different figure that shows how the signals are processed and how the system tools works in MATLAB (Figures 5-11).

- 1) FIR low pass filter
- 2) Phase response
- 3) Magnittude response (dB)
- 4) For noisy signal sample 1
- 5) For noiseless signal sample 1
- 6) For noisy signal sample 2
- 7) For noiseless signal sample 2



Figure 5. Magnitude response filter.







Figure 7. Magnitude response (dB) filter.







Figure 9. Noiseless signal sample 1.







Figure 11. Noiseless signal sample 2.

4. Conclusion

In this paper a sound sample was taken in wav format. The sound sample was passed on a low pass filter where a new audio signal was obtained after noise reduction, the low pass filter that is used to reduce the noise from the signals with the different frequency and ripple factor. These filters perform the filtering operations by the computation of difference equations. The coefficient equation and function as the low pass filter are given. Simple design formulas for various equalizers lead to efficient implementations for time-varying filter applications.

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