

A Multivariate Student's *t*-Distribution

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Abstract

A multivariate Student's *t*-distribution is derived by analogy to the derivation of a multivariate normal (Gaussian) probability density function. This multivariate Student's *t*-distribution can have different shape parameters v_i for the marginal probability density functions of the multivariate distribution. Expressions for the probability density function, for the variances, and for the covariances of the multivariate *t*-distribution with arbitrary shape parameters for the marginals are given.

Keywords

Multivariate Student's t, Variance, Covariance, Arbitrary Shape Parameters

1. Introduction

An expression for a multivariate Student's *t*-distribution is presented. This expression, which is different in form than the form that is commonly used, allows the shape parameter ν for each marginal probability density function (pdf) of the multivariate pdf to be different.

The form that is typically used is [1]

$$\frac{\Gamma((\nu+n)/2)}{\Gamma(\nu/2)(\pi\nu)^{n/2}|\Sigma|} \left(1 + [x]^{\mathrm{T}} \Sigma^{-1}[x]\right)^{-(\nu+n)/2}.$$
(1)

This "typical" form attempts to generalize the univariate Student's *t*-distribution and is valid when the *n* marginal distributions have the same shape parameter ν . The shape of this multivariate *t*-distribution arises from the observation that the pdf for $[x] = [y]/\sigma$ is given by Equation (1) when [y] is distributed as a multivariate normal distribution with covariance matrix $[\Sigma]$ and σ^2 is distributed as chi-squared.

The multivariate Student's *t*-distribution put forth here is derived from a Cholesky decomposition of the scale matrix by analogy to the multivariate normal (Gaussian) pdf. The derivation of the multivariate normal pdf is

given in Section 2 to provide background. The multivariate Student's t-distribution and the variances and covariances for the multivariate t-distribution are given in Section 3. Section 4 is a conclusion.

2. Background Information

2.1. Cholesky Decomposition

A method to produce a multivariate pdf with known scale matrix $[\Sigma_s]$ is presented in this section. For normally distributed variables, the covariance matrix $[\Sigma] = [\Sigma_s]$ since the scale factor for a normal distribution is the standard deviation of the distribution. An example with n = 4 is used to provide concrete examples.

Consider the transformation [y] = [M][x] where [y] and [x] are 4×1 column matrices, [M] is 4×4 square matrix, and the elements of [x] are independent random variables. The off-diagonal elements of [M] introduce correlations between the elements of [y].

$$\begin{bmatrix} \mathbf{y}_{1} \\ \mathbf{y}_{2} \\ \mathbf{y}_{3} \\ \mathbf{y}_{4} \end{bmatrix} = \begin{bmatrix} m_{1,1} & 0 & 0 & 0 \\ m_{2,1} & m_{2,2} & 0 & 0 \\ m_{3,1} & m_{3,2} & m_{3,3} & 0 \\ m_{4,1} & m_{4,2} & m_{4,3} & m_{4,4} \end{bmatrix} \begin{bmatrix} \mathbf{x}_{1} \\ \mathbf{x}_{2} \\ \mathbf{x}_{3} \\ \mathbf{x}_{4} \end{bmatrix}$$
(2)

The scale matrix $[\Sigma_s] = [M][M]^T$. The covariance matrix $[\Sigma]$ has elements $\Sigma_{i,j} = E\{y_i y_j\}$ where $E\{y_i y_j\}$ is the expectation of $y_i y_j$ and $\Sigma_{i,j} = \Sigma_{j,i}$. If the [x] are normally distributed, then $[\Sigma] = [\Sigma_s] = [M][M]^T$, where the superscript T indicates a transpose of the matrix. If $[\Sigma_s]$ is known, then [M] is the Cholesky decomposition of the matrix $[\Sigma_s]$ [2].

For the 4×4 example of Equation (2),

$$\left[\Sigma_{s}\right] = \begin{bmatrix} m_{1,1}^{2} & m_{1,1}m_{2,1} & m_{1,1}m_{3,1} & m_{1,1}m_{4,1} \\ m_{1,1}m_{2,1} & m_{2,1}^{2} + m_{2,2}^{2} & m_{2,1}m_{3,1} + m_{2,2}m_{3,2} & m_{2,1}m_{4,1} + m_{2,2}m_{4,2} \\ m_{1,1}m_{3,1} & m_{2,1}m_{3,1} + m_{2,2}m_{3,2} & m_{3,1}^{2} + m_{3,2}^{2} + m_{3,3}^{2} & m_{3,1}m_{4,1} + m_{3,2}m_{4,2} + m_{3,3}m_{4,3} \\ m_{1,1}m_{4,1} & m_{2,1}m_{4,1} + m_{2,2}m_{4,2} & m_{3,1}m_{4,1} + m_{3,2}m_{4,2} + m_{3,3}m_{4,3} & m_{4,1}^{2} + m_{4,2}^{2} + m_{4,3}^{2} + m_{4,4}^{2} \end{bmatrix} .$$
 (3)

From linear algebra, $\det\left(\begin{bmatrix} M \end{bmatrix} \begin{bmatrix} M^T \end{bmatrix}\right) = \det\left[M\right] \det\left[M\right]^T = \left(\det\left[M\right]\right)^2$. For $\begin{bmatrix} M \end{bmatrix}$ as defined in Equation (2), $\det\left[M\right] = m_{1,1}m_{2,2}m_{3,3}m_{4,4}$ and $\det\left[\Sigma_s\right] = m_{1,1}^2m_{2,2}^2m_{3,3}^2m_{4,4}^2 = \left(\det\left[M\right]\right)^2$ whereas $\Sigma_{i,i} = E\left\{y_i y_i\right\} = \sigma_{y_i}^2$ is the variance of the zero-mean random variable y_i and $\Sigma_{i,j} = E\left\{y_i y_j\right\} = \sigma_{y_i y_j}^2$ is the covariance of the zero-mean random variable y_i and $\Sigma_{i,j} = E\left\{y_i y_j\right\} = \sigma_{y_i y_j}^2$ is the covariance of the zero-mean random variable y_i and $\Sigma_{i,j} = E\left\{y_i y_j\right\} = \sigma_{y_i y_j}^2$ is the covariance of the zero-mean random variable y_i and $\Sigma_{i,j} = E\left\{y_i y_j\right\} = \sigma_{y_i y_j}^2$ is the covariance of the zero-mean random variables y_i and y_j .

2.2. Multivariate Normal Probability Density Function

To create a multivariate normal pdf, start with the joint pdf $f_N([x])$ for *n* unit normal, zero mean, independent random variables [x]:

$$f_{N}\left([x]\right) = \prod_{i=1}^{n} \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2}x_{i}^{2}\right) = \frac{1}{\sqrt{(2\pi)^{n}}} \exp\left(-\frac{1}{2}[x]^{T}[x]\right)$$
(4)

where [x] is an *n*-row column matrix: $[x]^{T} = [x_1, x_2, \dots, x_n]$. $f_N([x])dx_1dx_2 \dots dx_n$ gives the probability that the random variables [x] lie in the interval $[x] < [x] \le [x] + [dx]$.

The requirement for zero mean random variables is not a restriction. If $E\{x_i\} = \mu_i$, then $x'_i = x_i - \mu_i$ is a zero mean random variable with the same shape and scale parameters as x_i .

Use Equation (2) to transform the variables. The Jacobian determinant of the transformation relates the products of the infinitesimals of integration such that

$$dx_i dx_2 \cdots dx_n = \left| \frac{\partial(x_1, x_2, \cdots, x_n)}{\partial(y_1, y_2, \cdots, y_n)} \right| dy_1 dy_2 \cdots dy_n.$$
(5)

The magnitude of the Jacobian determinant of the transformation [y] = [M][x] is (Appendix)

$$\left|\frac{\partial(x_1, x_2, \cdots, x_n)}{\partial(y_1, y_2, \cdots, y_n)}\right| = \left|\frac{1}{\det[M]}\right| = \left|\frac{1}{\sqrt{\det[\Sigma_s]}}\right|$$
(6)

where the equality $det[\Sigma_s] = (det[M])^2$ has been used.

Since $[\Sigma_s] = [M][M]^T$, $[\Sigma_s]^{-1} = ([M]^T)^{-1}[M]^{-1}$, and since $[x] = [M]^{-1}[y]$, the multivariate "z-score" $[x]^T[x]$ becomes $[y]^T([M]^T)^{-1}[M]^{-1}[y] = [y]^T[\Sigma_s]^{-1}[y]$, which equals $[y]^T[\Sigma]^{-1}[y]$ since $[\Sigma_s] = [\Sigma]$ for normally distributed variables

normally distributed variables.

The result is that the unit normal, independent, multivariate pdf, Equation (4), becomes under the transformation Equation (2)

$$f_{N}\left(\left[y\right]\right) = \frac{1}{\sqrt{\left(2\pi\right)^{n} \left|\det\left[\Sigma_{s}\right]\right|}} \exp\left(-\frac{1}{2}\left[y\right]^{\mathrm{T}}\left[\Sigma_{s}\right]^{-1}\left[y\right]\right)$$
(7)

where [y] is a *n*-row column matrix: $[y]^{T} = [y_1, y_2, \dots, y_n]$ and $[\Sigma_s] = [\Sigma]$. For the 4×4 example,

$$\left[M\right]^{-1} = \begin{bmatrix} \frac{1}{m_{1,1}} & 0 & 0 & 0\\ -\frac{m_{2,1}}{m_{1,1}m_{2,2}} & \frac{1}{m_{2,2}} & 0 & 0\\ \frac{m_{3,2}m_{2,1} - m_{3,1}m_{2,2}}{m_{1,1}m_{2,2}m_{3,3}} & -\frac{m_{3,2}}{m_{2,2}m_{3,3}} & \frac{1}{m_{3,3}} & 0\\ \frac{m_{1,4}^{-1}}{m_{1,4}} & \frac{m_{4,3}m_{3,2} - m_{4,2}m_{3,3}}{m_{2,2}m_{3,3}m_{4,4}} & -\frac{m_{4,3}}{m_{3,3}m_{4,4}} & \frac{1}{m_{4,4}} \end{bmatrix},$$
(8)

from which $\left[\Sigma_{s}\right]^{-1} = \left(\left[M\right]^{T}\right)^{-1}\left[M\right]^{-1}$ can be calculated. In Equation (8),

$$m_{1,4}^{-1} = -\frac{m_{2,1}m_{3,2}m_{4,3} - m_{4,2}m_{2,1}m_{3,3} - m_{2,2}m_{3,1}m_{4,3} + m_{4,1}m_{2,2}m_{3,3}}{m_{1,1}m_{2,2}m_{3,3}m_{4,4}}.$$
(9)

The denominator in the expression for $m_{1,4}^{-1}$ is det [M].

3. Multivariate Student's t Probability Density Function

A similar approach can be used to create a multivariate Student's *t* pdf. Assume truncated or effectively truncated *t*-distributions, so that moments exist [3] [4]. For simplicity, assume that support is $[\mu - b\beta, \mu + b\beta]$ where *b* is a positive, large number, β is the scale factor for the distribution, and μ is the location parameter for the distribution. If *b* is a large number, then a significant portion of the tails of the distribution are included. If $b = \infty$ then all of the tails are included.

Start with the joint pdf for *n* independent, zero-mean (location parameters $[\mu] = 0$) Student's *t* pdfs with shape parameters $[\nu]$, and scale parameters $[\beta] = 1$:

$$f_t\left([x];[\nu]\right) = \prod_{i=1}^n \frac{\Gamma\left((\nu_i+1)/2\right)}{\Gamma\left(\nu_i/2\right)\sqrt{\pi\nu_i}} \left(1 + \frac{x_i^2}{\nu_i}\right)^{-(\nu_i+1)/2} = \prod_{i=1}^n g_i\left(x_i;\nu_i\right)$$
(10)

with $-\infty \le x_i \le +\infty$. $f_t([x]; [v]) dx_1 dx_2 \cdots dx_n$ gives the probability that a random draw of the column matrix [x] from the joint Student's *t*-distribution lies in the interval $[x] < [x] \le [x] + [dx]$. The pdf $g_i(x_i; v_i)$ is a function of only x_i and the shape parameter v_i , and thus is independent of any other $g_j(x_j; v_j)$, $j \ne i$.

Use the transformation of Equation (2) to create a multivariate pdf

$$f_t\left([y];[v]\right) = \frac{1}{\left|\det[M]\right|} \prod_{i=1}^n \frac{\Gamma\left((v_i+1)/2\right)}{\Gamma\left(v_i/2\right)\sqrt{\pi v_i}} \left(1 + \frac{\left(\sum_{j=1}^i m_{i,j}^{-1} y_j\right)^2}{v_i}\right)^{-(v_i+1)/2}.$$
(11)

The solution $x_i = \sum_{j=1}^{i} m_{i,j}^{-1} y_j$ of the transformation Equation (2) was used. The elements of the inverse matrix $[M]^{-1}$, $m_{i,j}^{-1}$, $m_{i,j}^{-1}$, are given in terms of the $m_{i,j}$ by Equation (8) for the n = 4 example. Note that the shape parameters v_i of the constituent distributions need not be the same in the multivariate *t*-distribution given by $f_t([y];[v])$. $f_t([y];[v]) dy_1 dy_2 \cdots dy_n$ gives the probability that a random draw of the column matrix [y] from the

 $f_t([y];[v])dy_1dy_2\cdots dy_n$ gives the probability that a random draw of the column matrix [y] from the multivariate Student's *t*-distribution with shape parameters [v] lies in the interval $[y] \le [y] \le [y] + [dy]$.

From the definition of the exponential function $e^x = \lim_{n \to \infty} (1 + x/n)^n$ where $e = 2.718281828\cdots$ is Euler's number, then

$$\lim_{v \to \infty} \left(1 + \frac{t^2}{v} \right)^{-(v+1)/2} = \exp\left(-t^2/2 \right)$$
(12)

and

$$\lim_{\nu \to \infty} f_t \left([y]; [\nu] \right) = \frac{1}{\left| \det[M] \right|} \prod_{i=1}^n \frac{1}{\sqrt{2\pi}} \exp\left(-0.5 \left(\sum_{j=1}^i m_{i,j}^{-1} y_j \right)^2 \right) \right)$$

$$= \frac{1}{\left| \det[M] \right| \sqrt{(2\pi)^n}} \exp\left(-0.5 \left(\sum_{i=1}^n \sum_{j=1}^i m_{i,j}^{-1} y_j \right)^2 \right) \right)$$

$$= \frac{1}{\sqrt{(2\pi)^n \left| \det[\Sigma_s] \right|}} \exp\left(-\frac{1}{2} [y]^T [\Sigma_s]^{-1} [y] \right)$$

$$= f_N \left([y] \right).$$
 (13)

In the limit as $[\nu \to \infty]$, the multivariate Student's *t*-distribution $f_t([y]; [\nu])$, Equation (11), becomes a multivariate normal distribution.

3.1. Some $\Sigma_{i,i}$ for the n = 4 Example

In this subsection some examples for the variances and covariances of a multivariate Student's *t*-distribution using the n = 4 example of Equation (2) are given.

The variance of the random variable y_3 is

$$E\left\{\mathbf{y}_{3}^{2}\right\} = \iiint \left\{\mathbf{y}_{3}^{2} f_{t}\left(\left[M\right]^{-1}\left[y\right];\left[\nu\right]\right) dy_{4} dy_{3} dy_{2} dy_{1}\right]$$
(14)

with the limits of the integrations equal to $\mu_i - b\beta_i$ and $\mu_i + b\beta_i$, i = 1, 2, 3, 4.

Perform the integrations as listed. The integral over dy_4 is unity since only x_4 depends on y_4 (c.f. Equation (2)) and $f_t([x];[v])$ factors into a product $g_1(x_1)g_2(x_2)g_3(x_3)g_4(x_4)$ —see Equation (10). Write

$$x_4 = m_{4,4}^{-1} y_4 + m_{4,3}^{-1} y_3 + m_{4,2}^{-1} y_2 + m_{4,1}^{-1} y_1$$
(15)

$$= m_{4,4}^{-1} y_4 - \mu_4 \tag{16}$$

where the $m_{i,j}^{-1}$ are the elements of the inverse of matrix [M] and are as given by $[M]^{-1}$, Equation (8), and μ_4 is a constant as far as the integral over y_4 is concerned.

Repeat the procedure for the integrals for dy_3 , dy_2 , and dy_1 . These integrals are not equal to unity owing to the presence of the y_3^2 term.

The variance of the random variable y_i for the multivariate Student's *t*-distribution with support $[-\infty,\infty]$ and with $v_i = v$ for all *i* is given by

$$E\left\{\mathbf{y}_{i}^{2}\right\} = \sigma_{\mathbf{y}_{i}}^{2} = \sum_{j=1}^{i} m_{j,j}^{2} \frac{\nu}{\nu - 2}$$
(17)

The expression for $\sigma_{y_i}^2$ is valid only for v > 2. The expression would be valid for $v \ge 1$ if the region of support was $[\mu_i - b\beta_i, \mu_i + b\beta_i]$ rather than $[-\infty, \infty]$ where β_i is a scale factor and $b < \infty$ [3]-[5]. Note that the scale factors for the multivariate *t*-distribution are $\beta_i = |m_{i,i}|$.

Truncation or effective truncation of the pdf keeps the moments finite [3]-[5]. For example, the second central moment for a v = 1 Student's *t*-distribution with scale factor β and support $[\mu - b\beta, \mu + b\beta]$ is

$$\mu_2(\nu = 1, \beta, b) = \beta^2 \times \frac{(b - \arctan(b))}{\arctan(b)},$$
(18)

which is finite provided that $b < \infty$.

In the interest of brevity, only variances and covariances that were calculated for support of $[-\infty,\infty]$ will be discussed. The requirement that $v_i > 2$ will be understood to be waived if the pdf is truncated or effectively truncated. It is also to be understood that the variances and covariances as calculated for support of $[-\infty,\infty]$ provide upper limits for variances and covariances calculated for truncation or effective truncation of the pdf.

If the v_i are not equal, then for the n = 4 example of Equation (2)

$$E\left\{\mathbf{y}_{3}^{2}\right\} = \frac{v_{1}}{v_{1}-2} \times m_{3,1}^{2} + \frac{v_{2}}{v_{2}-2} \times m_{3,2}^{2} + \frac{v_{3}}{v_{3}-2} \times m_{3,3}^{2}.$$
(19)

The covariance $E\{y_2, y_3\}$ for the $v_i = v$ for all *i* is given by

$$E\{\mathbf{y}_{2}\,\mathbf{y}_{3}\} = \left(m_{2,1}\,m_{3,1} + m_{2,2}\,m_{3,2}\right)\frac{\nu}{\nu - 2}.$$
(20)

If the v_i are not equal, then the covariance $E\{y_2, y_3\}$

$$\mathbf{E}\left\{\mathbf{y}_{2}\,\mathbf{y}_{3}\right\} = \frac{\nu_{1}}{\nu_{1}-2} \times m_{2,1}m_{3,1} + \frac{\nu_{2}}{\nu_{2}-2} \times m_{2,2}m_{3,2}.$$
(21)

The expression for $E\{y_1, y_3\}$, which is valid for the v_i not equal, is

$$E\{\mathbf{y}_{1}\,\mathbf{y}_{3}\} = \frac{V_{1}}{V_{1}-2} \times m_{1,1}m_{3,1}.$$
(22)

The expressions for $E\{y_3y_3\}$, $E\{y_2y_3\}$, and $E\{y_1y_3\}$ show a simple pattern for the relationship between the covariance matrix Σ , the scale matrix $[\Sigma_s]$ Equation (3), and the matrix [M] Equation (2).

3.2. General Expressions for $\Sigma_{i,i}$

Given a matrix [M] that is an $n \times n$ square matrix with elements $m_{i,j}$, an expression for the variance (assuming support $[-\infty,\infty]$, $v_i > 2$ for all *i*, and $i \le n$) for the multivariate Student's *t*-distribution $f_t([y];[v])$ is

$$E\left\{y_{i}^{2}\right\} = \sum_{j=1}^{i} \frac{v_{j}}{v_{j}-2} \times m_{j,j}^{2}.$$
(23)

A general expression for the covariance (assuming support $[-\infty,\infty]$, $v_i > 2$ for all *i*, and $i \le n, j \le n$) for the multivariate Student's *t*-distribution $f_t([y]; [v])$ is

$$E\left\{\boldsymbol{y}_{i}\,\boldsymbol{y}_{j}\right\} = \sum_{k=1}^{\min(i,j)} \frac{\boldsymbol{v}_{k}}{\boldsymbol{v}_{k}-2} \times m_{i,k}\,m_{j,k}.$$
(24)

If support is $[\mu - b\beta, \mu + b\beta]$, then the general expressions need to be multiplied by functions that depend on *b* and ν . Truncation or effective truncation keeps the moments finite and defined for all $\nu \ge 1$ [3]-[5]. The general expressions for the covariance, Equation (24), yields, when i = j, the general expression for the variance, Equation (23). The general expression for the variance, Equation (23), is given to emphasize the $m_{i,i}^2$ nature of the variance.

Unlike normally distributed random variables, the correlation matrix $[\Sigma]$ for random variables that are distributed as Student's *t* is not equal to $[M][M]^T$. For normally distributed variables, the scale parameter β equals the standard deviation σ . For Student's *t* distributed variables, the standard deviation σ does not equal the scale parameter β . For a Student's *t* distribution with shape parameter ν , scale parameter β , and support $[-\infty,\infty]$, $\sigma^2 = \beta^2 \times \nu/(\nu-2)$. If the region of support for the Student's *t* distribution is truncated to $[\mu - b\beta, \mu + b\beta]$ then the variance $\sigma^2 < \beta^2 \times \nu/(\nu-2)$ for all $\nu \ge 2$ and is finite for all $\nu \ge 1$ [3]-[5].

Given a matrix of the variances and the covariances, $[\Sigma]$, and a column matrix of the shape parameters $[\nu]$ associated with each variable, the scale matrix $[\Sigma_s] = [M][M]^T$ would in principle be determined sequentially, starting with $m_{1,1}$ and $m_{1,2}$. The shape parameters $[\nu]$ would be obtained from the marginal distributions or from other knowledge.

4. Conclusion

A multivariate Student's *t*-distribution is derived by analogy to the derivation for a multivariate normal (or Gaussian) pdf. The variances and covariances for the multivariate *t*-distribution are given. It is noteworthy that the shape parameters [v] of the constituent Student's *t*-distributions of the *multivariate t*-distribution, Equation (11), need not be the same.

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Appendix: The Jacobian

The Jacobian determinant is used in physics, mathematics, and statistics. Many of these uses can be traced to the Jacobian determinate as a measure of the volume of an infinitesimially small, *n*-dimensional parallelepiped.

1. Volume of a Parallelepiped

The volume of an *n*-dimensional parallelepiped is given by the absolute value of the determinant of the components of the edge vectors that form the parallelepiped.

The area of a parallelogram with edge vectors \boldsymbol{a} and \boldsymbol{b} is $|\boldsymbol{a} \times \boldsymbol{b}|$.

The volume of a parallelepiped with edge vectors $\boldsymbol{a} = (a_1, a_2, a_3)$, $\boldsymbol{b} = (b_1, b_2, b_3)$, and $\boldsymbol{c} = (c_1, c_2, c_3)$ is given by the determinant

$$\boldsymbol{c} \cdot \left(\boldsymbol{a} \times \boldsymbol{b} \right) = \begin{vmatrix} c_1 & c_2 & c_3 \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}.$$
(25)

2. Inversion Exists

Assume that there are *n* functions $x_i = f_i(q_1, q_2, \dots, q_n)$. The necessary and sufficient condition that the functions can be inverted to find $q_i = f_i^{-1}(x_1, x_2, \dots, x_n)$ is that the Jacobian determinant is nonzero, *i.e.*,

$$\frac{\partial(x_1, x_2, \cdots, x_n)}{\partial(q_1, q_2, \cdots, q_n)} \neq 0$$
(26)

where

$$\frac{\partial (x_1, x_2, \cdots, x_n)}{\partial (q_1, q_2, \cdots, q_n)} \equiv \begin{vmatrix} \frac{\partial x_1}{\partial q_1} & \frac{\partial x_1}{\partial q_2} & \cdots & \frac{\partial x_1}{\partial q_n} \\ \frac{\partial x_2}{\partial q_1} & \frac{\partial x_2}{\partial q_2} & \cdots & \frac{\partial x_2}{\partial q_n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \end{vmatrix}$$
(27)

To simplify the notation, assume that n = 3 so that $x_i = f_i(q_1, q_2, q_3)$, $i = 1, \dots, 3$. The total differential is

$$dx_i = \frac{\partial f_i}{\partial q_1} dq_1 + \frac{\partial f_i}{\partial q_2} dq_2 + \frac{\partial f_i}{\partial q_3} dq_3.$$
(28)

These equations can be put in matrix form

$$\begin{bmatrix} dx_1 \\ dx_2 \\ dx_3 \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1}{\partial q_1} & \frac{\partial f_1}{\partial q_2} & \frac{\partial f_1}{\partial q_3} \\ \frac{\partial f_2}{\partial q_1} & \frac{\partial f_2}{\partial q_2} & \frac{\partial f_2}{\partial q_3} \\ \frac{\partial f_3}{\partial q_1} & \frac{\partial f_3}{\partial q_2} & \frac{\partial f_3}{\partial q_3} \end{bmatrix} \begin{bmatrix} dq_1 \\ dq_2 \\ dq_3 \end{bmatrix}.$$
(29)

These three equations can be solved for the dq_i if the determinant of the 3×3 matrix is non-zero. This is a standard result from linear algebra. The determinant of the 3×3 matrix is called the Jacobian determinant of the transformation.

3. Change of Variables

The Jacobian determinant of the transformation is used in change of variables in integration:

$$\iiint dV = \iiint dx_1 dx_2 dx_3 = \iiint \left| \frac{\partial(x_1, x_2, x_3)}{\partial(q_1, q_2, q_3)} \right| dq_1 dq_2 dq_3.$$
(30)

The absolute value sign is required since the determinant could be negative (*i.e.*, the volume could decrease). The Jacobian determinant for the inverse transformation (to obtain [x] as functions of [y]) given by Equation (8) is

$$\frac{\partial x_{1}}{\partial y_{1}} = 0 = 0 = 0$$

$$\frac{\partial x_{2}}{\partial y_{1}} = \frac{\partial x_{2}}{\partial y_{2}} = 0 = 0$$

$$\frac{\partial x_{3}}{\partial y_{1}} = \frac{\partial x_{3}}{\partial y_{2}} = \frac{\partial x_{3}}{\partial y_{3}} = 0$$

$$\frac{\partial x_{4}}{\partial y_{1}} = \frac{\partial x_{4}}{\partial y_{2}} = \frac{\partial x_{4}}{\partial y_{3}} = \frac{\partial x_{4}}{\partial y_{4}}$$

$$\frac{\partial x_{4}}{\partial y_{1}} = \frac{\partial x_{4}}{\partial y_{2}} = \frac{\partial x_{4}}{\partial y_{3}} = \frac{\partial x_{4}}{\partial y_{4}}$$

$$\frac{\partial x_{4}}{\partial y_{1}} = \frac{\partial x_{4}}{\partial y_{2}} = \frac{\partial x_{4}}{\partial y_{3}} = \frac{\partial x_{4}}{\partial y_{4}}$$

$$\frac{\partial x_{4}}{\partial y_{1}} = \frac{\partial x_{4}}{\partial y_{2}} = \frac{\partial x_{4}}{\partial y_{3}} = \frac{\partial x_{4}}{\partial y_{4}}$$

$$\frac{\partial x_{4}}{\partial y_{1}} = \frac{\partial x_{4}}{\partial y_{2}} = \frac{\partial x_{4}}{\partial y_{3}} = \frac{\partial x_{4}}{\partial y_{4}}$$

$$\frac{\partial x_{4}}{\partial y_{1}} = \frac{\partial x_{4}}{\partial y_{2}} = \frac{\partial x_{4}}{\partial y_{3}} = \frac{\partial x_{4}}{\partial y_{4}}$$

$$\frac{\partial x_{4}}{\partial y_{1}} = \frac{\partial x_{4}}{\partial y_{2}} = \frac{\partial x_{4}}{\partial y_{3}} = \frac{\partial x_{4}}{\partial y_{4}}$$

$$\frac{\partial x_{4}}{\partial y_{1}} = \frac{\partial x_{4}}{\partial y_{2}} = \frac{\partial x_{4}}{\partial y_{3}} = \frac{\partial x_{4}}{\partial y_{4}}$$

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$$\frac{\partial x_{4}}{\partial y_{1}} = \frac{\partial x_{4}}{\partial y_{2}} = \frac{\partial x_{4}}{\partial y_{3}} = \frac{\partial x_{4}}{\partial y_{4}}$$

$$\frac{\partial x_{4}}{\partial y_{1}} = \frac{\partial x_{4}}{\partial y_{2}} = \frac{\partial x_{4}}{\partial y_{3}} = \frac{\partial x_{4}}{\partial y_{4}}$$

$$\frac{\partial x_{4}}{\partial y_{1}} = \frac{\partial x_{4}}{\partial y_{2}} = \frac{\partial x_{4}}{\partial y_{3}} = \frac{\partial x_{4}}{\partial y_{4}}$$

$$\frac{\partial x_{4}}{\partial y_{1}} = \frac{\partial x_{4}}{\partial y_{3}} = \frac{\partial x_{4}}{\partial y_{4}}$$

$$\frac{\partial x_{4}}{\partial y_{4}} = \frac{\partial x_{4}}{\partial y_{4}} = \frac{\partial x_{4}}{\partial y_{4}}$$

$$\frac{\partial x_{4}}{\partial y_{4}} = \frac{\partial x_{4}}{\partial y_{4}} = \frac{\partial x_{4}}{\partial y_{4}}$$

$$\frac{\partial x_{4}}{\partial x_{4}} = \frac{\partial x_{4}}{\partial y_{4}}$$

which equals

$$\frac{1}{m_{1,1}} \times \frac{1}{m_{2,2}} \times \frac{1}{m_{3,3}} \times \frac{1}{m_{4,4}} = \frac{1}{\det[M]}.$$
(32)