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# Asymptotic Behavior of a Bi-Dimensional Hybrid System

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## **Abstract**

We study the asymptotic behavior of the solutions of a Hybrid System wrapping an elliptic operator

## **Keywords**

Hybrid System, Compressible, Stabilization, Asymptotic Behavior, Decay Rate, Generator Infinitesimal, Polynomial Decay

#### 1. Introduction

In this paper, we address some issues related to the asymptotic behavior a hybrid system with two types of vibrations of different nature. The model under consideration is inspired in and introduced in [1]. However, there are some important differences between these two models. In [1] the flexible part of the boundary  $\Gamma_0$  is occupied by a flexible damped beam instead of a flexible. Most of the relevant properties see [2]. In [3] the authors are interested on the existence of periodic solutions of this system. Due to the localization of the damping term in a relatively small part of the boundary and to the effect of the hybrid structure of the system, the existence of periodic solutions holds for a restricted class of non homogeneous terms. Some resonance-type phenomena are also exhibited. Cindea, Sorin and Pazoto [4] consider the motion of a stretched string coupled with a rigid body at one end and we study the existence of periodic solution when a periodic force facts on the body. The main difficulty of the study is related to the weak dissipation that characterizes this hybrid system, which does not ensure a uniform decay rate of the energy. For more examples of hybrid systems see [5] [6]. We refer to [7] for a

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discussion on the model and references therein. In [8] the authors to discern exact controllability properties of two coupled wave equations, one of which holds on the interior of a bounded open domain  $\Omega$ , and the other on a segment  $\Gamma_0$  of the boundary  $\partial\Omega$ . Moreover, the coupling is accomplished through terms on the boundary. Because of the particular physical application involved the attenuation of acoustic waves within a chamber by means of active controllers on the chamber walls control is to be implemented on the boundary only.

We consider the bi-dimensional cavity  $\Omega = \Omega_1 \setminus \overline{\Omega}_0$  and that  $\Omega_0$  an open class  $C^2$  with limited boundary contained in  $\Omega_1$ , filled with an elastic, in viscid, compressible fluid, in which the acoustic vibrations are coupled with the mechanical vibration of a string located in the subset  $\Gamma_0 = \{(x,0); x \in (0,1)\}$  a part of the boundary of omega of  $\Omega_1$ ,  $\Gamma_1 = \partial \Omega_1 \setminus \Gamma_0$  and  $\Gamma = \partial \Omega_1 \cup \partial \Omega_0$  with  $\partial \Omega_1 \cap \partial \Omega_0 = \phi$ , is boundary of  $\Omega$ . The subset  $\Gamma_1$  is assumed to be rigid and we impose zero normal velocity of the fluids on it. The subset  $\Gamma_0$  is supposed to be flexible and occupied by a flexible string that vibrates under the pressure of the fluid on the plane where  $\Omega$  lies. The displacement of  $\Gamma_0$ , described by the scalar function w = w(x,t), obeys the one-dimensional dissipative wave equation. As  $\Omega$  is compressible fluid where the velocity field v is given by the potential  $\varphi = \varphi(x,y,t), (v = \nabla \varphi)$ . All deformations are supposed to be small enough so that linear theory applies.

The linear motion of this system is described by means of the coupled wave equations

$$\begin{cases} \rho \varphi_{tt} - c\Delta \varphi + \gamma_1 \varphi_t = 0 & \text{in } \Omega \times (0, \infty) \\ \frac{\partial \varphi}{\partial \nu} = 0 & \text{on } \Gamma_1 \times (0, \infty) \\ \frac{\partial \varphi}{\partial \nu} = -w_t & \text{on } \Gamma_0 \times (0, \infty) \\ \varphi = 0 & \text{on } \Gamma_2 \times (0, \infty) \\ w_{tt} - w_{xx} + \gamma_0 w_t + c\varphi_t = 0 & \text{on } \Gamma_0 \times (0, \infty) \\ w_x (0, t) = w_x (1, t) = 0 & \text{for } t > 0 \\ \varphi (0) = \varphi^0, \quad \varphi_t (0) = \varphi^1 & \text{in } \Omega \\ w(0) = w^0, \quad w_t (0) = w^1 & \text{on } \Gamma_0 \end{cases}$$

$$(1)$$

where  $\nu$  denote the unit outward normal to  $\Omega$ .

We define the energy associated with this system. Proceeding formally, multiply the first equation by  $\varphi_t$  and then integrate over  $\Omega$ .

$$\frac{1}{2}\frac{\mathrm{d}}{\mathrm{d}t}\int_{\Omega}\left|\varphi_{t}\right|^{2}\mathrm{d}x\mathrm{d}y + \frac{c}{\rho}\int_{\Omega}\nabla\varphi\cdot\nabla\varphi_{t}\mathrm{d}x\mathrm{d}y - \frac{c}{\rho}\int_{\Gamma}\frac{\partial\varphi}{\partial\nu}\cdot\varphi_{t}\mathrm{d}\sigma + \frac{\gamma_{1}}{\rho}\int_{\Omega}\left|\varphi_{t}\right|^{2}\mathrm{d}x\mathrm{d}y = 0. \tag{2}$$

However, the integral

$$\int_{\Gamma} \frac{\partial \varphi}{\partial \nu} \cdot \varphi_t d\sigma = \int_{\Gamma_1} \underbrace{\frac{\partial \varphi}{\partial \nu}}_{=0} \cdot \varphi_t d\sigma + \int_{\Gamma_0} \underbrace{\frac{\partial \varphi}{\partial \nu}}_{-w_t} \cdot \varphi_t d\sigma - \int_{\Gamma_2} \underbrace{\frac{\partial \varphi}{\partial \nu}}_{=0} \cdot \underbrace{\varphi_t}_{=0} \sigma,$$

which leads us

$$\int_{\Gamma} \frac{\partial \varphi}{\partial \nu} \cdot \varphi_t d\sigma = \int_{\Gamma_0} \frac{\partial \varphi}{\partial \nu} \cdot \varphi_t = -\int_{\Gamma_0} w_t \varphi_t dx.$$
 (3)

Replacing (3) into (2) we obtain

$$\frac{\mathrm{d}}{\mathrm{d}t} \left[ \frac{1}{2} \int_{\Omega} |\varphi_t|^2 \, \mathrm{d}x \, \mathrm{d}y + \frac{c}{\rho} |\nabla \varphi|^2 \right] + \frac{\gamma_1}{\rho} \int_{\Omega} |\varphi_t|^2 \, \mathrm{d}x \, \mathrm{d}y - \frac{c}{\rho} \int_{\Gamma_0} w_t \varphi_t \, \mathrm{d}x = 0. \tag{4}$$

Multiplying by w in the second equation of the system (1) and then integrate over  $\Gamma_0$ 

$$\frac{1}{2\rho} \frac{d}{dt} \int_{\Gamma_0} |w_t|^2 dx - \frac{1}{\rho} \int_{\Gamma_0} w_{xx} w_t dx + \frac{\gamma_0}{\rho} \int_{\Gamma_0} |w_t|^2 dx + \frac{c}{\rho} \int_{\Gamma_0} \varphi_t w_t dx = 0.$$
 (5)

Integrating by parts

$$\int_{\Gamma_0} w_{xx} w_t dx = \underbrace{w_x}_{t} w_t \Big|_{0}^{1} - \int_{\Gamma_0} w_x w_{tx} dx = -\frac{1}{2} \frac{d}{dt} \int_{\Gamma_0} |w_x|^2 dx.$$

Replacing the above equation over (5) we obtain

$$\frac{1}{2\rho} \frac{d}{dt} \int_{\Gamma_0} |w_t|^2 dx + \frac{1}{2\rho} \frac{d}{dt} \int_{\Gamma_0} |w_x|^2 dx + \frac{\gamma_0}{\rho} \int_{\Gamma_0} |w_t|^2 dx + \frac{c}{\rho} \int_{\Gamma_0} \varphi_t w_t dx = 0, \tag{6}$$

which leads us to assert that, the energy of the system is given by

$$E(t) = E(\varphi, w; t) = \frac{1}{2} \int_{\Omega} |\varphi_{t}|^{2} + \frac{c}{\rho} |\nabla \varphi|^{2} dxdy + \frac{1}{2\rho} \int_{\Gamma_{0}} w_{x}^{2} + w_{t}^{2} dx,$$
 (7)

for each  $t \ge 0$ .

**Remark 1** The first two terms represents the energy of acoustic wave and the other terms is the energy of bungee wave.

The system has a natural dissipation. Indeed, to observe this fact multiply the first equation of (1) by  $\varphi_t$  and then the second equation of (1) by  $w_t$ , as was done in previous calculations

$$\frac{\mathrm{d}E(t)}{\mathrm{d}t} = -\frac{\gamma_1}{\rho} \int_{\Omega} \left| \varphi_t \right|^2 \mathrm{d}x \mathrm{d}y - \frac{\gamma_0}{\rho} \int_{\Gamma_0} w_t^2 \mathrm{d}x < 0, \tag{8}$$

if  $\gamma_1^2 + \gamma_0^2 \neq 0$ . Micu, S. in his doctoral thesis [7] shows non-exponential decay of the energy of the hybrid system (1).

#### 2. Mathematical Formulation

Define the face space  $\mathcal{H} = H^1(\Omega) \times L^2(\Omega) \times H^1(\Gamma_0) \times L^2(\Gamma_0)$  endowed with the Hilbertian scalar product given by

$$\langle U, V \rangle = \int_{\Omega} \frac{c}{\rho} \nabla \varphi_1 \cdot \nabla \psi_1 + \varphi_2 \psi_2 dx dy + \frac{1}{\rho} \int_{\Gamma_0} (\varphi_3)_x (\psi_3)_x + \varphi_4 \psi_4 dx, \tag{9}$$

for all  $U = (\varphi_1, \varphi_2, \varphi_3, \varphi_4), V = (\psi_1, \psi_2, \psi_3, \psi_4) \in \mathcal{H}$ . We can show that the pair  $(\mathcal{H}, \langle,\rangle)$  is a Hilbert space. Since the first and second equation of the system (1), we obtain

$$\varphi_t = \varphi_2$$
 then  $\varphi_{2t} = \frac{c}{\rho} \Delta \varphi_1 - \frac{\gamma_1}{\rho} \varphi_2$ 

$$w_t = \varphi_4$$
 then  $\varphi_{4t} = (\varphi_3)_{xx} - \gamma_0 \varphi_4 - c \varphi_2$ .

These equations lead us to define the operator  $A: \mathcal{H} \to \mathcal{H}$  by

$$\mathcal{A} := \begin{bmatrix} 0 & 1 & 0 & 0 \\ \frac{c}{\rho} \Delta & -\frac{\gamma_1}{\rho} & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & -c & (\cdot)_{xx} & -\gamma_0 \end{bmatrix},$$

in this sense for all  $U = (\varphi_1, \varphi_2, \varphi_3, \varphi_4) \in \mathcal{H}$ ,

$$\mathcal{A}U = \left(\varphi_2, \frac{c}{\rho} \Delta \varphi_1 - \frac{\gamma_1}{\rho} \varphi_2, \varphi_4, (\varphi_3)_{xx} - \gamma_0 \varphi_4 - c \varphi_2\right). \tag{10}$$

Note that  $AU \in \mathcal{H}$  if and only if

$$\begin{split} & \varphi_2 \in H^1\left(\Omega\right), \quad \frac{c}{\rho} \Delta \varphi_1 - \frac{\gamma_1}{\rho} \varphi_2 \in L^2\left(\Omega\right), \quad \frac{c}{\rho} \Delta \varphi_1 - \frac{\gamma_1}{\rho} \varphi_2, \quad \varphi_4 \in H^1\left(\Gamma_0\right) \\ & - c \varphi_2 + \left(\varphi_3\right)_{xx} - \gamma_0 \varphi_4 \in L^2\left(\Gamma_0\right). \end{split}$$

Now, we consider the problem with Neumann boundary conditions

$$\begin{cases}
\frac{c}{\rho} \Delta \varphi_{1} = \frac{\gamma_{1}}{\rho} \varphi_{2} + h \in L^{2}(\Omega), & h \in L^{2}(\Omega) \\
\frac{\partial}{\partial \nu} \varphi_{1} = 0 & \text{on } \Gamma_{1} \\
\frac{\partial}{\partial \nu} \varphi_{1} = \varphi_{4} & \text{on } \Gamma_{0} \\
\varphi_{1} = 0 & \text{on } \Gamma_{2},
\end{cases} \tag{11}$$

where we can say that  $\varphi_1 \in H^2(\Omega)$  see [9]. Similarly, consider the problem

$$\begin{cases} \left(\varphi_{2}\right)_{xx} = c\varphi_{2} + \gamma_{0}\varphi_{4} \in L^{2}\left(\Gamma_{0}\right) \\ \left(\varphi_{3}\right)_{x}\left(0\right) = \left(\varphi_{3}\right)_{x}\left(1\right) = 0. \end{cases}$$

$$(12)$$

We can say that  $\varphi_2 \in H^2\left(\Gamma_0\right)$ . In this sense we can define the domain of the operator  $\mathcal{A}$  which we denote  $\mathcal{D}\left(\mathcal{A}\right)$ , as the set of  $U=\left(\varphi_1,\varphi_2,\varphi_3,\varphi_4\right)\in\mathcal{H}$  such that  $\varphi_1\in H^2\left(\Omega\right),\ \varphi_2\in H^1\left(\Omega\right),\ \varphi_3\in H^2\left(\Gamma_0\right),$   $\varphi_4\in H^1\left(\Gamma_0\right)$  satisfying

$$\frac{\partial \varphi_1}{\partial \nu} = 0 \quad \text{on } \Gamma_1$$

$$\frac{\partial \varphi_1}{\partial \nu} = \varphi_4 \quad \text{on } \Gamma_0$$

$$\varphi_1 = 0 \quad \text{on } \Gamma_2$$

$$(\varphi_3)_{\nu}(0) = (\varphi_3)_{\nu}(1) = 0.$$

**Remark 2** By previous observations we can say that the hybrid system (1) is equivalent to the Cauchy problem

$$\begin{cases}
U_t(t) = \mathcal{A}U(t), t > 0 \\
U(0) = U_0,
\end{cases}$$
(13)

 $\text{where} \quad U_0 = \left(\varphi^0, \varphi^1, \omega^0, \omega^1\right) \in \mathcal{D}\left(\mathcal{A}\right) \quad \text{and} \quad U\left(t\right) = \left(\varphi_1, \varphi_2, \varphi_3, \varphi_4\right) \in \mathcal{D}\left(\mathcal{A}\right), \ t \geq 0.$ 

#### 3. Solution Existence

We want to show that  $\mathcal{A}$  is a dissipative operator and  $0 \in \rho(\mathcal{A})$  (The resolvent set of  $\mathcal{A}$ ). **Remark 3** The operator  $\mathcal{A}$  is dissipative, ie  $\langle \mathcal{A}U, U \rangle < 0$  for all  $U = (\varphi_1, \varphi_2, \varphi_3, \varphi_4) \in \mathcal{D}(\mathcal{A})$ . Applying (9), we get

$$\langle \mathcal{A}U, U \rangle = -\frac{\gamma_1}{\rho} \int_{\Omega} \varphi_2^2 dx dy - \frac{\gamma_0}{\rho} \int_{\Gamma_0} \varphi_4^2 dx < 0.$$

## **Resolvent Equation:**

Given  $F \in \mathcal{H}$ , we find  $U \in \mathcal{D}(A)$ 

$$(\lambda I - A)U = F, \quad \lambda \in \mathbb{C}. \tag{14}$$

In particular,  $0 \in \rho(A)$ , if and only if, there is

$$U \in \mathcal{D}(\mathcal{A}); -\mathcal{A}U = F,$$

that is,

$$-\varphi_2 = F_1$$

$$-\frac{c}{\rho}\Delta\varphi_1 + \frac{\gamma_1}{\rho}\varphi_2 = F_2$$

$$-\varphi_4 = F_3$$

$$-(\varphi_3)_{xx} + \gamma_0\varphi_4 + c\varphi_2 = F_4,$$

where  $F = (F_1, F_2, F_3, F_4)$ . By previous observations that there have  $U \in \mathcal{D}(\mathcal{A})$ . Using the application of Lummer Phillips Theorem [10] [11], we have the following result.

**Theorem 1** The operator A set to (10) is the infinitesimal generator of a contraction semigroup  $C_0$ .

**Theorem 2** The A is the infinitesimal generator of a semigroup  $C_0$  and verifies  $U_0 \in \mathcal{D}(A^3)$  then the solution of (13) satisfies

$$U \in C^{1}(0,\infty;\mathcal{H}) \cap C^{2}(0,\infty;\mathcal{D}(\mathcal{A})). \tag{15}$$

# 4. Asymptotic Behavior

We now show that the energy associated with the system decays exponentially. Multiplying by  $\varphi$  the first equation in (1) and integrating over  $\Omega$  yields

$$\int_{\Omega} \varphi_{tt} \varphi dx dy - \frac{c}{\rho} \int_{\Omega} \Delta \varphi \varphi dx dy + \frac{\gamma_{1}}{\rho} \int_{\Omega} \varphi_{t} \varphi dx dy = 0,$$

equivalently

$$\frac{\mathrm{d}}{\mathrm{d}t} \int_{\Omega} \varphi_{t} \varphi \mathrm{d}x \mathrm{d}y - \int_{\Omega} \left| \varphi_{t} \right|^{2} \mathrm{d}x \mathrm{d}y + \frac{c}{\rho} \int_{\Omega} \left| \nabla \varphi \right|^{2} \mathrm{d}x \mathrm{d}y - \frac{c}{\rho} \int_{\Gamma_{0}} \frac{\partial \varphi}{\partial \nu} \varphi \sigma + \frac{\gamma_{1}}{\rho} \int_{\Omega} \varphi_{t} \varphi \mathrm{d}x \mathrm{d}y = 0.$$
 (16)

Observe that

$$-\frac{c}{\rho} \int_{\Gamma_0} \frac{\partial \varphi}{\partial \nu} \varphi \sigma = \frac{c}{\rho} \frac{d}{dt} \int_{\Gamma_0} \omega \varphi dx - \frac{c}{\rho} \int_{\Gamma_0} \omega \varphi_t dx. \tag{17}$$

From the second equation in (1), we obtain

$$-\frac{c}{\rho} \int_{\Gamma_0} \omega \varphi_t dx = -\frac{1}{\rho} \int_{\Gamma_0} \omega \left( -\omega_{tt} + \omega_{xx} - \gamma_0 \omega \right) dx. \tag{18}$$

On the other hand,

$$\frac{1}{\rho} \int_{\Gamma_0} \omega \omega_{tt} dx = \frac{1}{\rho} \frac{d}{dt} \int_{\Gamma_0} \omega \omega_{t} dx - \frac{1}{\rho} \int_{\Gamma_0} \omega_{t}^2 dx.$$
 (19)

From (17)-(19), we obtain

$$-\frac{c}{\rho}\int_{\Gamma_0} \frac{\partial \varphi}{\partial \nu} \varphi \sigma = \frac{d}{dt} \left[ \frac{1}{\rho} \int_{\Gamma_0} \omega \omega_t dx + \frac{c}{\rho} \int_{\Gamma_0} \omega \varphi dx \right] + \frac{1}{\rho} \int_{\Gamma_0} \omega_x^2 dx - \frac{1}{\rho} \int_{\Gamma_0} \omega_t^2 dx + \frac{\gamma_0}{\rho} \int_{\Gamma_0} \omega \omega_t dx.$$
 (20)

Replacing (20) into (16)

$$\frac{\mathrm{d}}{\mathrm{d}t} \int_{\Omega} \varphi_{t} \varphi \mathrm{d}x \mathrm{d}y - \int_{\Omega} \left| \varphi_{t} \right|^{2} \mathrm{d}x \mathrm{d}y + \frac{c}{\rho} \int_{\Omega} \left| \nabla \varphi \right|^{2} \mathrm{d}x \mathrm{d}y + \frac{\mathrm{d}}{\mathrm{d}t} \left[ \frac{1}{\rho} \int_{\Gamma_{0}} \omega \omega_{t} \mathrm{d}x + \frac{c}{\rho} \int_{\Gamma_{0}} \omega \varphi \mathrm{d}x \right] 
+ \frac{1}{\rho} \int_{\Gamma_{0}} \omega_{x}^{2} \mathrm{d}x - \frac{1}{\rho} \int_{\Gamma_{0}} \omega_{t}^{2} \mathrm{d}x + \frac{\gamma_{0}}{\rho} \int_{\Gamma_{0}} \omega \omega_{t} \mathrm{d}x + \frac{\gamma_{1}}{\rho} \int_{\Omega} \varphi_{t} \varphi \mathrm{d}x \mathrm{d}y = 0,$$
(21)

or equivalently

$$\frac{\mathrm{d}}{\mathrm{d}t} \left[ \int_{\Omega} \varphi_{t} \varphi \mathrm{d}x \mathrm{d}y + \frac{1}{\rho} \int_{\Gamma_{0}} \omega \omega_{t} \mathrm{d}x + \frac{c}{\rho} \int_{\Gamma_{0}} \omega \varphi \mathrm{d}x \right] - \int_{\Omega} \left| \varphi_{t} \right|^{2} \mathrm{d}x \mathrm{d}y + \frac{c}{\rho} \int_{\Omega} \left| \nabla \varphi \right|^{2} \mathrm{d}x \mathrm{d}y \\
+ \frac{1}{\rho} \int_{\Gamma_{0}} \omega_{x}^{2} \mathrm{d}x - \frac{1}{\rho} \int_{\Gamma_{0}} \omega_{t}^{2} \mathrm{d}x + \frac{\gamma_{0}}{\rho} \int_{\Gamma_{0}} \omega \omega_{t} \mathrm{d}x + \frac{\gamma_{1}}{\rho} \int_{\Omega} \varphi_{t} \varphi \mathrm{d}x \mathrm{d}y = 0. \tag{22}$$

Now, since Poincaré inequality we have

$$\left| \frac{\gamma_0}{\rho} \int_{\Gamma_0} \omega \omega_t \right| \le \frac{\gamma_0 \lambda_1}{\rho} \left[ \int_{\Gamma_0} \omega_x^2 \right]^{1/2} \left[ \int_{\Gamma_0} \omega_t^2 dx \right]^{1/2} \le \frac{\alpha}{2\rho} \int_{\Gamma_0} \omega_x^2 dx + \frac{\gamma_0 \lambda_1}{2\alpha} \int_{\Gamma_0} \omega_t^2, \tag{23}$$

where  $\lambda_1$  is the Poincaré constant. In a similar way,

$$\left| \frac{\gamma_1}{\rho} \int_{\Omega} \varphi \varphi_t dx dy \right| \le \frac{\theta}{2\rho} \int_{\Omega} \left| \nabla \varphi \right|^2 dx dy + \frac{\gamma_1 \lambda_1}{2\theta \rho} \int_{\Omega} \left| \varphi_t \right|^2 dx dy. \tag{24}$$

From (22), (23) and (24) we have

$$\frac{\mathrm{d}}{\mathrm{d}t} \left[ \int_{\Omega} \varphi_{t} \varphi \mathrm{d}x \mathrm{d}y + \frac{1}{\rho} \int_{\Gamma_{0}} \omega \omega_{t} \mathrm{d}x + \frac{c}{\rho} \int_{\Gamma_{0}} \omega \varphi \mathrm{d}x \right] \\
\leq \left( 1 + \frac{\gamma_{1} \lambda_{1}}{2c\rho} \right) \int_{\Omega} \left| \varphi_{t} \right|^{2} \mathrm{d}x \mathrm{d}y - \frac{3c}{4\rho} \int_{\Omega} \left| \nabla \varphi \right|^{2} \mathrm{d}x \mathrm{d}y + \frac{1}{\rho} \int_{\Gamma_{0}} \omega_{t}^{2} \mathrm{d}x - \frac{1}{2} \int_{\Gamma_{0}} \omega_{x}^{2} \mathrm{d}x. \tag{25}$$

We define the operator

$$\mathcal{L}(t) := nE(t) + \int_{\Omega} \varphi_{t} \varphi dx dy + \frac{1}{\rho} \int_{\Gamma_{0}} \omega \omega_{t} dx + \frac{c}{\rho} \int_{\Gamma_{0}} \omega \varphi dx, \quad n \in \mathbb{N}.$$
 (26)

Differentiating (26) and using (8) we obtain

$$\frac{\mathrm{d}}{\mathrm{d}t}\mathcal{L}(t) = n\frac{\mathrm{d}}{\mathrm{d}t}E(t) + \frac{\mathrm{d}}{\mathrm{d}t}\left[\int_{\Omega}\varphi_{t}\varphi\mathrm{d}x\mathrm{d}y + \frac{1}{\rho}\int_{\Gamma_{0}}\omega\omega_{t}\mathrm{d}x + \frac{c}{\rho}\int_{\Gamma_{0}}\omega\varphi\mathrm{d}x\right]$$

$$\leq \left[n\frac{\gamma_{1}}{\rho} - \left(1 + \frac{\gamma_{1}\lambda_{1}}{2c\rho}\right)\right]\int_{\Omega}\left|\varphi_{t}\right|^{2}\mathrm{d}x\mathrm{d}y - \frac{3c}{4\rho}\int_{\Omega}\left|\nabla\varphi\right|^{2}\mathrm{d}x\mathrm{d}y$$

$$- \left[n\frac{\gamma_{0}}{\rho} - \left(1 + \frac{\gamma_{0}\lambda_{1}}{2\rho}\right)\right]\int_{\Gamma_{0}}\omega_{t}^{2}\mathrm{d}x - \frac{1}{2}\int_{\Gamma_{0}}\omega_{x}^{2},$$
(27)

Considering n large enough, we can obtain a constant C such that

$$\frac{\mathrm{d}}{\mathrm{d}t}\mathcal{L}(t) \le -CE(t). \tag{28}$$

On the other hand, using Poincaré, we can obtain

$$\left| \int_{\Omega} \varphi \varphi_{t} dx dy \right| \leq \frac{c_{0} \delta \lambda_{1}}{2} \int_{\Omega} \left| \nabla \varphi \right|^{2} dx dy + \frac{1}{2 \delta} \int_{\Omega} \left| \varphi_{t} \right|^{2} dx dy. \tag{29}$$

In a similar way

$$\left| \frac{c}{\rho} \int_{\Gamma_0} \omega \varphi dx \right| \le \frac{c\lambda_1}{\rho} \left( \int_{\Gamma_0} \omega_x^2 \right)^{1/2} \left( \int_{\Gamma_0} \left| \varphi \right|^2 dx \right)^{1/2} \le \frac{c\lambda_1}{2\rho} \left( \theta \int_{\Gamma_0} \omega_x^2 dx + \frac{1}{\theta} \int_{\Gamma_0} \left| \varphi \right|^2 dx \right)$$
(30)

Moreover, from trace

$$\int_{\Gamma_0} \varphi^2 dx \le \int_{\Gamma} \varphi^2 dx \le c_3 \int_{\Omega} \left| \nabla \varphi \right|^2 dx dy. \tag{31}$$

Replacing (31) into (30) we have

$$\left| \frac{c}{\rho} \int_{\Gamma_0} \omega \varphi \right| \le \frac{c \lambda_1 \theta}{2\rho} \int_{\Gamma_0} \omega_x^2 dx + \frac{c \lambda_1 c_3}{2\rho \theta} \int_{\Omega} \left| \nabla \varphi \right|^2 dx dy. \tag{32}$$

From (23), (29), (32) and (26) we can to claim that there is a constant  $\kappa_0$  and  $\kappa_1$  such that

$$\kappa_0 E(t) \le \mathcal{L}(t) \le \kappa_1 E(t),$$
(33)

leading to decay exponentially energy

$$E(t) \le c_2 E(0) e^{-\kappa t}, \quad \forall \ t > 0. \tag{34}$$

where  $\kappa = C\kappa_0$ . The result follows.

**Remark 4** In the case of  $\gamma_1 = 0$  can be also said that a power decays exponentially.

The above results support the conclusion.

**Theorem 3** If  $(\varphi_0, \varphi_1, \omega_0, \omega_1) \in \mathcal{D}(\mathcal{A})$  and  $\gamma_0 \neq 0$  then the solution  $(\varphi, \omega)$  of the hybrid system (1) decays exponentially over time.

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