

Inherent Properties of Two Dimension Green Function with Linear Boundary Condition of Free Water Surface^{*}

Xing Wang, Chao Liu, Zhenli Sun, Mingyan Wu, Shesheng Zhang[#]

Department of Statistics, Wuhan University of Technology, Wuhan, China Email: [#]sheshengz@qq.com

Received May 11, 2013; revised June 11, 2013; accepted June 18, 2013

Copyright © 2013 Xing Wang *et al.* This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

ABSTRACT

A mathematic model of Green function is build for two dimension free water surface. The analytic expression of Green function is obtained by introducing a parameter of complex number. The intrinsic properties of Green function are discussed for the special parameter values. The real and imaginary parts of H function are shown in the paper.

Keywords: Green Function; Free Surface; Hydrodynamics

1. Introduction

Researches on ship's hydrodynamics force need to work out the added mass. The near field two dimensional added mass is generally calculated by boundary integral method, in which the Green function is often used as the kernel function. Since the Green function can be represented by improper integral with several singularities and an infinite integrating range, problems of calculation errors and large mount of calculation naturally arise. However it causes scholars' interests to study on the Green function with free surface for years. Some researchers like Frank [1], Poul [2], Newman [3], Ricardo [4], Chen [5] and etc have done lots of work on the Green function. Researchers like Liu [6], Dai [7], Ma [8], Zhou [9], Zhou [10] and etc also have gotten their findings. In 2010, French scholar Ricardo [4] published his research results of the Green function, which pointed out that if using infinite series or integral to represent the two-dimensional frequency domain Green function with free surface, it has an ambiguous theory discourse, a huge mount of computation and some inconvenience in practical.

Based on the work of Ricardo [4], this paper theoretically discusses the near-field two-dimensional Green function with free surface about its inherent properties using complex function theories.

*Corresponding author.

2. Fundamental Theories

Taking Oxyz as the orthogonal coordinate system along with ship's movement, plane Oxz is placed on the horizontal plane, with y axis vertical downwards and z axis pointing the movement's direction, see **Figure 1**. If fluid is in-viscid and ir-rotational. Considering the near-field flow in z axis's cross section, suppose ϕ satisfies Laplace equation:

$$\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = \delta \left(x - \xi \right) \delta \left(y - \eta \right)$$
(2.1)

where z is the coordinate of field point P defined as z = x + jy, $y \ge 0$; complex number ζ is the coordinate of source point Q defined as $\zeta = \xi + j\eta$, $\eta \ge 0$; The right of the equation is the product of two delta functions.

The boundary condition on the free surface is:

$$\frac{\partial \phi}{\partial y} + K\phi = 0, y = 0 \tag{2.2}$$



Figure 1. Coordinate system Oxyz.

^{*}The paper is financially supported by China national natural science foundation (No. 51139005), and supported by China national natural science foundation (No. 51279149).

where K, ε are real numbers and $j = \sqrt{(-1)}$ is the unit imaginary number.

At infinite, take the radiation conditions are:

$$|\phi| < C \quad \left| \frac{\partial \phi}{\partial x} \pm j K \phi \right| < \frac{C}{|x|} \quad x \to \mp \infty$$
 (2.3)

where C is constant.

Ricardo [4] obtained the Green function with the above free surface linear boundary conditions using Fourier transform method:

$$\phi = \frac{1}{2\pi} \operatorname{Re}\left\{\ln\frac{z-\zeta}{z-\zeta}\right\} - i\cos\left[K\left(x-\zeta\right)\right] \exp\left[-K\left(y+\eta\right)\right] + \frac{1}{\pi}\int_{0,K}^{\infty} \frac{\exp\left[-t\left(y+\eta\right)\right]}{K-t} \cos\left[t\left(x-\zeta\right)\right] dt$$

It can be represented as the following patterns after simplification

$$\phi = \frac{1}{2\pi} \operatorname{Re}\left\{\ln\left(Y - 2K\eta\right)\right\} + \phi_{Y}\left(Y\right)$$
(2.4)

where

$$\phi_{Y}(Y) = \frac{1}{2\pi} \operatorname{Re}\left\{\ln Y\right\} - j \operatorname{Re}\left\{e^{-Y}\right\} + \frac{1}{\pi} \operatorname{Re}\left\{H(Y)\right\}$$

and $Y = K(y + \mu) - jK(x - \xi)$ (2.5)

H function is defined as:

$$H(Y) = e^{-Y} \left[C_E + \ln(Y) + \sum_{n=1}^{\infty} \frac{Y^n}{n!n} \right]$$
(2.6)

here *C* is the Euler's constant. The above formula has only one infinite series, whose denominator is (n!n) and as a result the convergence rate is relatively fast.

3. The Truncation Error of Series

Suppose *a* and δ is *Y*'s modulus and argument respectively, When δ is zero, *H*(*Y*) proposed above is

$$H(Y = a) = e^{-a} \left[C_E + \ln(a) + \sum_{n=1}^{\infty} \frac{a^n}{n!n} \right]$$
 (3.1)

or written as

$$H(a) = e^{-a} [C_{E} + \ln(a)] + H_{M-1}(a) + E_{M}(a)$$
 (3.2)

where

$$H_{M-1}(a) = e^{-a} \sum_{n=1}^{M-1} \frac{a^n}{n!n} \quad E_M(a) = e^{-a} \sum_{n=M}^{\infty} \frac{a^n}{n!n}$$
(3.3)

Let the relative error noted as

$$Er_{M}(a) = \frac{H_{M-1}(a)}{E_{M}(a)}$$
 (3.4)

thus we have

Copyright © 2013 SciRes.

$$Er_{M}\left(a\right) = \frac{\sum_{n=M}^{\infty} \frac{a^{n}}{n!n}}{\sum_{n=1}^{M-1} \frac{a^{n}}{n!n}}$$
(3.5)

Since constant a > 0, note q = a/M, then here's the estimating formula for error

$$\sum_{n=M} \frac{a^{n}}{n!n}$$

$$= \frac{a^{M-1}}{M!} \left[\frac{a}{M} + \left(\frac{a}{M+1} \right)^{2} + \frac{a^{3}}{(M+1)(M+2)(M+2)} + \cdots \right]$$

$$\leq \frac{a^{M-1}}{M!} \left[q + q^{2} + q^{3} + \cdots \right] = \frac{a^{M-1}}{M!} \frac{q}{1-q} = \frac{a^{M-1}}{M!} \frac{a}{M-a}$$

So we get

$$Er_{M}(a) < \frac{1}{\sum_{n=1}^{M-1} \frac{a^{n}}{n!n}} \frac{a^{M-1}}{M!} \frac{a}{M-a}$$
 (3.6)

This is the estimating formula for error. Once the positive integer M is given, we can work out the estimated error. On the contrary, if the bound on error is given, we can get the value of M. Assuming the bound on error is 0.01, here's the relationship of M and a. See details in **Table 1**.

4. Numerical Calculation

As long as the number of terms in series M is known, we can calculate the values of H(Y) and the Green function based on the proposed formula before. The specific calculation steps are:

- 1) Give the bound on error;
- 2) Work out the number of terms in series M;
- 3) Calculate H(Y) using the following formula

$$H(Y) = e^{-Y} \left[C_E + \ln(Y) + \sum_{n=1}^{\infty} \frac{Y^n}{n!n} \right];$$

4) Calculate the Green function using the following formula

$$\phi = \frac{1}{2\pi} \operatorname{Re}\left\{\ln\left(Y - 2K\eta\right)\right\} + \phi_{Y}\left(Y\right)$$
$$\phi_{Y}\left(Y\right) = \frac{1}{2\pi} \operatorname{Re}\left\{\ln Y\right\} - j \operatorname{Re}\left\{e^{-Y}\right\} + \frac{1}{\pi} \operatorname{Re}\left\{H\left(Y\right)\right\}$$

According to these steps, we obtain the real and imaginary part of H(Y). See details in **Figure 2**, where the pa-

Table 1. Relationship of M (number of terms in series) and a (bound on error).

а	1	4	7	10	13	16	19
M	6	10	14	18	22	26	29



Figure 2. The imaginary part of function *H* varying with the real part.

rameters' values are: $a = 0.1k, k = 1, 2, \dots, 9$; $\delta = 0.1\pi s$, $s = -4, -3, \dots, 3, 4$.

5. Inherent Properties of the Green Function

We have already got the expression of the Green function, namely

$$\phi = \frac{1}{2\pi} \operatorname{Re} \left\{ \ln \left(Y - 2K\eta \right) \right\} + \phi_Y \left(Y \right)$$
$$\phi_Y \left(Y \right) = \frac{1}{2\pi} \operatorname{Re} \left\{ \ln Y \right\} - j \operatorname{Re} \left\{ e^{-Y} \right\} + \frac{1}{\pi} \operatorname{Re} \left\{ H \left(Y \right) \right\}$$
$$Y = K \left(y + \mu \right) - j K \left(x - \xi \right)$$

It's easy to compute the Green function's first item for its simple logarithmic form. And as a function of complex parameter Y, $\phi_Y(Y)$ can be pre-computation shown by a graph or a table. When Y takes different values, we get these inherent properties.

Property 1: when the argument equals zero, Y = a, and the calculation equation is:

$$\phi = \frac{1}{2\pi} \ln \left(a - 2K\eta \right) + \frac{1}{2\pi} \ln a - j e^{-a} + \frac{1}{\pi} H(a)$$

Property 2: when the argument equals 0.5 π , Y = ja, and the calculation equation is:

$$\phi = \frac{1}{2\pi} \operatorname{Re}\left\{\ln\left(ja - 2K\eta\right)\right\} + \phi_Y\left(Y\right)$$
$$\phi_Y\left(Y\right) = \frac{1}{2\pi} \ln a - j \times \cos\left(a\right) + \frac{1}{\pi} \operatorname{Re}\left\{H\left(Y\right)\right\}$$

Property 3: When the modulus of *Y* tends to infinite, the Green function tends to zero.

This paper works out the explicit formulation of the Green function, estimates the formulation's error and gives the relationship between the number of terms in series M and the bound on error a. Then, inherent properties of the Green function are concluded.

7. Acknowledgements

The paper is financially supported by China national natural science foundation (No. 51139005), and (No. 51279149) and JWSL [2011] 1568).

REFERENCES

- W. Frank, "Oscillation of Cylinders in or below the Free Surface of Deep Fluids," Report, No. 2375, Naval Ship Researcher and Development Center, 1967.
- [2] A. Poul and W. Z. He, "On the Calculation of Two-Dimensional Added Mass and Damping Coefficients by Simple Green's Function Technique," *Ocean Engineering*, Vol. 12, No. 5, 1985, pp. 425-451. doi:10.1016/0029-8018(85)90003-4
- [3] J. N. Newman, "Algorithm for the Free-Surface Green Function," *Journal of Engineering Mathematics*, Vol. 19, No. 1, 1985, pp. 57-67. doi:10.1007/BF00055041
- [4] R. Hein, M. Duran and J.-C. Nedelec, "Explicit Representation for the Infinite-Depth Two-Dimensional Free-Surface Green's Function in Linear Water-Wave Theory," *AIAN: Journal on Applied Mathematics*, Vol. 70, No. 7, 2010, pp. 2353-2372.
- [5] Z. M. Chen, "Harmonic Function Expansion for Translating Green Functions and Dissipative Free-Surface Waves," *Wave Motion*, Vol. 50, No. 2, 2013, pp. 282-294. doi:10.1016/j.wavemoti.2012.09.005
- [6] A. Poul and W. Z. He, "On the Calculation of Two-Dimensional Added Mass and Damping Coefficients by Simple Green's Function Technique," *Ocean Engineering*, Vol. 12, No. 5, 1985, pp. 425-451. doi:10.1016/0029-8018(85)90003-4
- J. V. Wehausen and E. V. Latoine, "Surface Waves," In: S. Flügge, Ed., *Encyclopedia of Physics*, Vol. IX, Springer, Berlin, 1960, pp. 446-778.
- [8] A. H. Clement, "An Ordinary Differential Equation for the Green Function of Time-Domain Free-Surface Hydrodynamics," *Journal of Engineering Mathematics*, Vol. 33, No. 2, 1998, pp. 201-217. doi:10.1023/A:1004376504969
- [9] R. Hein, M. Duran and J.-C. Nedelec, "Explicit Representation for the Infinite-Depth Two-Dimensional Free-Surface Green's Function in Linear Water-Wave Theory," *AIAN: Journal on Applied Mathematics*, Vol. 70, No. 7, 2010, pp. 2353-2372.
- [10] J. N. Newman, "Algorithm for the Free-Surface Green Function," *Journal of Engineering Mathematics*, Vol. 19, No. 1, 1985, pp. 57-67. doi:10.1007/BF00055041