# Some Symmetry Results for the A-Laplacian Equation via the Moving Planes Method* 

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Received July 3, 2012; revised September 1, 2012; accepted September 8, 2012


#### Abstract

In this paper, we are concerned with a positive solution of the non-homogeneous A-Laplacian equation in an open bounded connected domain. We use moving planes method to prove that the domain is a ball and the solution is radially symmetric.


Keywords: Symmetry; A-Laplacian; Moving Planes Method; Overdetermined Boundary Value Problem

## 1. Introduction

In this paper, we are going to study the symmetry results for the overdetermined problem

$$
\begin{gather*}
\operatorname{div}(A(|\nabla u|) \nabla u)+f(u,|\nabla u|)=0, \text { in } \Omega \backslash\{P\} .  \tag{1.1}\\
u=0, \text { on } \partial \Omega .  \tag{1.2}\\
\frac{\partial u}{\partial v}=c, \text { on } \partial \Omega . \tag{1.3}
\end{gather*}
$$

Here $\Omega$ is a bounded connected open subset of $R^{n}$ with $C^{2}$ boundary and $P$ is a point in $\Omega$. The function $A:(0, \infty) \rightarrow[0, \infty)$ satisfies the regularity requirement

$$
\begin{equation*}
A \in C^{2}(0, \infty) \tag{1.4}
\end{equation*}
$$

and the (possibly degenerate) elliptic condition

$$
\begin{equation*}
\lim _{t \rightarrow 0^{+}} t A(t)=0,(t A(t))^{\prime}>0 \text { for } t>0 \tag{1.5}
\end{equation*}
$$

$f$ is a continuously differentiable function. $c$ is a constant and $v$ denotes the inner normal to $\partial \Omega$.
J. Serrin proved the radial symmetry for positive solutions of the equation $\Delta u=-1$ in $\Omega$ with the same overdetermined boundary conditions as the above problem, see [1]. N. Garofalo and J. Lewis extended Serrin's result to a larger class of elliptic equations possibly degenerate, including the following p-Laplacian equation $\operatorname{div}\left(|\nabla u|^{p-2} \nabla u\right)=-1$ with the same boundary conditions, see [2]. For the overdetermined elliptic boundary value

[^0]problem $\operatorname{div}(A(|\nabla u|))=-1$ in $\Omega$ with the same overdetermined boundary conditions as above, I. Fragala, I. F. Gazzaola and B. Kawohl used the geometric approach which relies on a maximum principle for a suitable P function, combined with some geometric arguments involving the mean curvature of $\partial \Omega$ to prove that if the above problem admits a solution in a suitable weak sense, then $\Omega$ is a ball, see [3]. A. Farina and B. Kawohl obtained the same result under removing the strong ellipticity assumption in [4] and a growth assumption in [2] on the diffusion coefficient $A$, as well as a starshapedness assumption on $\Omega$ in [3], see [5]. A. Firenze considered the positive solution of problem (1.1)-(1.3) when it is a p-Laplacian equation in an open bounded connected subset $\Omega$ of $R^{n}$ with $C^{2}$ boundary, see [6]. All of the above motivated us to extend the symmetry result to the non-homogeneous A-Laplacian equation.

Our main result is that for the problem (1.1)-(1.3), if $u$ has only one critical point in $\Omega$, then $\Omega$ is a ball and $u$ is radially symmetric.

Section 2 of this paper is devoted to the main result and a more general version of this theorem. In Section 3, we will present the proof of the main theorem.

Some components, such as multi-leveled equations, graphics, and tables are not prescribed, although the various table text styles are provided. The formatter will need to create these components, incorporating the applicable criteria that follow.

## 2. Preliminaries and Statement of Results

In this section we give some lemma that we shall use and present our main result.

Lemma 2.1. (The boundary lemma at corner) (Lemma 2 in [1]) Let $\Omega$ be a domain with $C^{2}$ boundary and $T$ be a hyperplane containing the normal to $\partial \Omega$ at some point $Q$. Let $\Omega^{*}$ denote the portion of $\Omega$ lying on some particular side of $T$.

Suppose that $W$ is of class $C^{2}$ in the closure of $\Omega^{*}$ and satisfies the elliptic inequality

$$
L w=\sum_{i, j=1}^{n} a_{i j}(x) w_{i j}+\sum_{i=1}^{n} b_{i}(x) w_{i} \leq 0, \quad x \in \Omega^{*}
$$

where the coefficients are uniformly bounded. We assume that the matrix $a_{i j}$ is uniformly definite

$$
\sum_{i, j=1}^{n} a_{i j}(x) \xi_{i} \xi_{j} \geq k|\xi|^{2}, \quad k=\text { const }>0
$$

and that

$$
\sum_{i, j=1}^{n}\left|a_{i j} \xi_{i} \eta_{j}\right| \leq K(|\xi \cdot \eta|+|\xi| \cdot|\mathrm{d}|), \quad K=\text { const }>0
$$

where $\xi=\left(\xi_{1}, \cdots, \xi_{n}\right)$ is an arbitrary real vector, $\eta=\left(\eta_{1}, \cdots, \eta_{n}\right)$ is the unit normal to the plane $T$, and d is the distance from $T$. Suppose also $w \geq 0$ in $\Omega^{*}$ and $w=0$ at $Q$. Let $s$ be any direction at $Q$ which enters $\Omega^{*}$ nontangentially. Then

$$
\frac{\partial w}{\partial s}>0 \text { or } \frac{\partial^{2} w}{\partial s^{2}}>0 \text { at } Q,
$$

unless $w \equiv 0$.
Our main results are as follows:
Theorem 2.2. Let $\Omega$ be a bounded connected open subset of $R^{n}$ with $C^{2}$ boundary and let $P$ be a point in $\Omega$. Let $u \in C^{2}(\bar{\Omega} \backslash\{P\}) \cap C^{1+\alpha}(\bar{\Omega}), \quad 0<\alpha<1$, be a strictly positive solution of the following overdetermined boundary value problem

$$
\begin{gather*}
\operatorname{div}(A(|\nabla u|) \nabla u)+f(u,|\nabla u|)=0, \text { in } \Omega \backslash\{P\} .  \tag{2.1}\\
u=0, \text { on } \partial \Omega .  \tag{2.2}\\
\frac{\partial u}{\partial v}=c, \text { on } \partial \Omega . \tag{2.3}
\end{gather*}
$$

Here $f$ is a continuously differentiable function, $A \in C^{2}(0, \infty)$ and

$$
\begin{equation*}
\lim _{t \rightarrow 0^{+}} t A(t)=0,(t A(t))^{\prime}>0 \text { for } t>0 \tag{2.4}
\end{equation*}
$$

$c$ is a constant and $v$ denotes the inner normal to $\partial \Omega$. Assume

$$
\begin{equation*}
|\nabla u|>0 \text { in } \Omega \backslash\{P\}, \tag{2.5}
\end{equation*}
$$

then $\Omega$ is a ball and $u$ is radially symmetric.
The following remark is a general version of the theorem. It can be viewed as an extension result of p-Laplacian too. As the proof is similar to Theorem 2.2, we omit
it.
Remark 2.3. Let $\Omega$ be as in Theorem 2.2 and $D$ be a subset of $\Omega$. Let $u \in C^{2}(\bar{\Omega} \backslash D) \cap C^{1+\alpha}(\bar{\Omega})$ be a strictly positive solution of Equation (2.1) in $\Omega \backslash D$ and verify the boundary conditions; Assume that $D$ is the critical set of $u$, then if $\hat{D}$ denotes the convex hull of $D$,

1) the normal line to $\partial \Omega$ at an arbitrary point of $\partial \Omega$ intersects $\hat{D}$;
2) if $\pi$ is a support plane to $\hat{D}$ through $A \in \partial \hat{D} \cap \Omega$ and $\gamma$ is a ray from $A$ orthogonal to $\pi$ which lies in the half-space determined by $\pi$ not containing $\hat{D}$, then $\gamma$ intersects $\partial \Omega$ exactly in one point.

In what follows we assume that the origin $O$ of the coordinates system is an interior point of $\Omega$, and we denote with $B_{\varepsilon}$ the closure of the ball centered in $O$ with radius $\varepsilon$.

Theorem 2.4. Assume that the hypotheses of Theorem 2.2 hold and furthermore assume that

$$
D \subset B_{\varepsilon} \subset \Omega
$$

for some positive $\varepsilon$. Then

1) $\Omega$ is starshaped with respect to $O$;
2) if

$$
\begin{aligned}
& d=\inf \{\|P-O\|: P \in \partial \Omega\} \\
& l=\sup \{\|P-O\|: P \in \partial \Omega\}
\end{aligned}
$$

then

$$
l-d \leq \frac{\pi d \varepsilon}{\sqrt{d^{2}-\varepsilon^{2}}}
$$

## 3. Proof of Theorem 2.1

The technique we are going to use is the moving planes method. For the detailed description about moving planes method, see [1].

Proof. Step 1: To prove $\Omega$ is a ball.
If we can demonstrate that for any point $Q$ on $\partial \Omega, P$ lies on the normal line to $\partial \Omega$ at $Q$, then $\Omega$ is a ball with centre $P$. To do this, we argue by contradiction.

Assume that there exists a point $Q \in \partial \Omega$ such that the normal line $r$ to $\partial \Omega$ at $Q$ does not contain $P$. We choose a coordinate system in $R^{n}$ such that $P \equiv(-\theta, 0, \cdots, 0), \quad \theta>0$, and the $x_{n}$ axis coincides with $r$.

When we use the moving planes method, we choose a family of hyperplanes normal to the $x_{1}$ axis. Define hyperplan $T(\lambda) \equiv\left\{x_{1}=\lambda\right\}$ for any positive $\lambda$; Let $\lambda_{0}$ be the infimum of $\lambda^{\prime}$ s such that $T(\lambda) \cap \bar{\Omega}=\phi$; Define $\Sigma(\lambda)=\Omega \bigcap\left\{x_{1}>\lambda\right\}$ for $\lambda<\lambda_{0}$ and we denote by $\Sigma^{\prime}(\lambda)$ the reflection $\Sigma(\lambda)$ in $T(\lambda)$. Since $\partial \Omega$ is $C^{2}$, for some $\lambda$ close to $\lambda_{0}, v$, we have

$$
\begin{equation*}
\Sigma^{\prime}(\lambda) \subset \Omega \tag{3.1}
\end{equation*}
$$

As $\lambda$ decreases, condition (3.1) holds until one of
the following facts happens:

1) $\partial \Sigma^{\prime}(\lambda)$ is internally tangent to $\partial \Omega$ at some point of $\partial \Sigma^{\prime}(\lambda) \backslash T(\lambda)$;
2) $T(\lambda)$ intersects $\partial \Omega$ at some point of $\partial \Omega$.

Let $\lambda^{\prime}$ be the greatest value of $\lambda, \lambda<\lambda_{0}$, such that either condition a) or b) is true. Since $T_{0}$ is orthogonal to $\partial \Omega$ at $Q$, we have $\lambda^{\prime} \geq 0$ and then $P \notin T(\lambda)$ for any $\lambda$ in $\left[\lambda^{\prime}, \lambda_{0}\right]$. This is the crucial point of our proof. We have found a direction such that as the moving plane $T(\lambda)$ moves from $T\left(\lambda_{0}\right)$ to the critical position $T\left(\lambda^{\prime}\right)$, it never intersects $P$, so that the moving planes method may be applied.

Let $x^{\lambda}$ be the reflected point of $x$ in $T(\lambda)$. We defined

$$
\begin{gathered}
v(x)=u\left(x^{\lambda}\right) \text { for } x \in \Sigma(\lambda), \lambda \in\left[\lambda^{\prime}, \lambda_{0}\right] \\
w(x)=v(x)-u(x)
\end{gathered}
$$

From Equation (2.1) we have for $\lambda^{\prime} \leq \lambda \leq \lambda_{0}$,

$$
\begin{align*}
& A(|\nabla u|) \Delta u+\frac{A^{\prime}(|\nabla u|)}{|\nabla u|} \sum_{i, j=1}^{n} u_{i} u_{j} u_{i j}+f(u,|\nabla u|)  \tag{3.2}\\
& =0 \text { in } \Sigma(\lambda) .
\end{align*}
$$

By the definition of $v$, we obtain

$$
\begin{aligned}
& A(|\nabla v|) \Delta v+\frac{A^{\prime}(|\nabla v|)}{|\nabla v|} \sum_{i, j=1}^{n} v_{i} v_{j} v_{i j}+f(v,|\nabla v|) \\
& =0 \text { in } \Sigma(\lambda) \backslash\left\{P^{\lambda}\right\} .
\end{aligned}
$$

Differencing Equations (3.2) and (3.3) yields

$$
\begin{align*}
& A(|\nabla v|) \Delta v+\frac{A^{\prime}(|\nabla v|)}{|\nabla v|} \sum_{i, j=1}^{n} v_{i} v_{j} v_{i j}+f(v,|\nabla v|)  \tag{3.4}\\
& -A(|\nabla u|) \Delta u-\frac{A^{\prime}(|\nabla u|)}{|\nabla u|} \sum_{i, j=1}^{n} u_{i} u_{j} u_{i j}-f(u,|\nabla u|)=0 .
\end{align*}
$$

Meanwhile, (3.4) can also be rewritten into

$$
\begin{aligned}
& \{A(|\nabla v|)+A(|\nabla u|)\} \Delta(v-u) \\
& +\sum_{i, j=1}^{n}\left(\frac{A^{\prime}(|\nabla v|)}{|\nabla v|}+\frac{A^{\prime}(|\nabla u|)}{|\nabla u|}\right)(v-u)_{i j} \\
& +\{A(|\nabla v|)-A(|\nabla u|)\} \Delta(v+u) \\
& +\sum_{i, j=1}^{n}\left(\frac{A^{\prime}(|\nabla v|)}{|\nabla v|}-\frac{A^{\prime}(|\nabla u|)}{|\nabla u|}\right)(v+u)_{i j} \\
& =2\{f(u,|\nabla u|)-f(v,|\nabla v|)\} .
\end{aligned}
$$

Denote $f[u] \equiv f(u,|\nabla u|), \quad A[u] \equiv A(|\nabla u|)$,

$$
A^{\prime}[u] \equiv \frac{A^{\prime}(|\nabla u|)}{|\nabla u|} .
$$

## Let

$$
a_{i j}(x)=\{A[v]+A[u]\} \delta_{i j}+\left\{A^{\prime}[v] v_{i} v_{j}+A^{\prime}[u] u_{i} u_{j}\right\}
$$

By the mean value theorem, it follows from (3.5) that

$$
\begin{equation*}
\sum_{i, j=1}^{n} a_{i j} w_{i j}+\sum_{k=1}^{n} b_{k} w_{k}+c w=0 \tag{3.6}
\end{equation*}
$$

where $a_{i j}, b_{k}$ and $c$ are certain functions depending on $u$ and $f$. Here the matrix $a_{i j}$ is uniformly positive definite, since both expressions $A[u] \delta_{i j}+A^{\prime}[u] u_{i} u_{j}$ and $A[v] \delta_{i j}+A^{\prime}[v] v_{i} v_{j}$ have this property (recall that Equation (2.1) is elliptic). So (3.6) is uniformly elliptic with bounded coefficients far from $P^{\lambda}$, i.e. in $\Sigma(\lambda) \backslash B_{\varepsilon}^{\lambda}$ where $B_{\varepsilon}^{\lambda}$ is a ball centered in with radius $\varepsilon$, for any positive $\varepsilon$.

From the boundary condition (2.3) on the normal derivative of $u$, it follows that

$$
\begin{equation*}
w(x, \lambda)>0 \text { in } \Sigma(\lambda) \tag{3.7}
\end{equation*}
$$

for some $\lambda<\lambda_{0}$ sufficiently close to $\lambda_{0}$. Let
$\lambda^{*}=\inf \left\{\lambda \in\left[\lambda^{\prime}, \lambda_{0}\right]:(3.7)\right.$ holds $\}$. We prove $\lambda^{*}=\lambda^{\prime}$. Assume $\lambda^{*}=\lambda^{\prime}$, by continuity, $w\left(x, \lambda^{*}\right) \geq 0$ in $\Sigma\left(\lambda^{*}\right)$. On the other hand, since $\Omega$ is not symmetric with respect to $T\left(\lambda^{*}\right), w \neq 0$ in $\Sigma\left(\lambda^{*}\right)$. By the strong version of the maximum principle, we obtain $w>0$ in $\Sigma\left(\lambda^{*}\right) \backslash B_{\varepsilon}^{\lambda^{*}}$. Next we observe that $P^{\lambda^{*}}$ can not be a critical point for $w$ since $\nabla v\left(P^{\lambda^{*}}\right)=0$ while $\nabla u\left(P^{\lambda^{*}}\right) \neq 0$. So as $\varepsilon$ is arbitrarily small, it is $w>0$ in $\Sigma\left(\lambda^{*}\right)$. Since $P^{\lambda^{*}} \notin T\left(\lambda^{*}\right)$, we may apply the Hopf lemma to $w$ at each point of $\Omega \cap T\left(\lambda^{*}\right)$, we get

$$
\begin{equation*}
\frac{\partial w}{\partial x_{1}}>0 \quad \text { on } T\left(\lambda^{*}\right) \cap \Omega \tag{3.8}
\end{equation*}
$$

The plane $T\left(\lambda^{*}\right)$ is not normal to $\partial \Omega$ at any point, then from inequality (3.8) and the boundary condition (2.3) on the normal derivative of $u$, we get

$$
\begin{equation*}
\frac{\partial u}{\partial x_{1}}<0 \tag{3.9}
\end{equation*}
$$

By the definition of $\lambda^{*}$, there exists a sequence $x_{n}$ such that $x_{n} \in \Sigma\left(\lambda^{*}-\frac{1}{n}\right)$ and

$$
\begin{equation*}
w\left(x_{n}, \lambda^{*}-\frac{1}{n}\right) \leq 0 \tag{3.10}
\end{equation*}
$$

Let $\bar{x}$ be a limit point for $x_{n}$ in the closure of $\Sigma\left(\lambda^{*}\right)$, by continuity $w\left(\bar{x}, \lambda^{*}\right)=0$, thus $\bar{x} \in \partial \Sigma\left(\lambda^{*}\right) \cap T\left(\lambda^{*}\right)$. But from inequality (3.10) and the mean value theorem we get $\frac{\partial u}{\partial x_{1}}(\bar{x}) \geq 0$ and this contradicts condition (3.9).

So $\lambda^{*}=\lambda^{\prime}$ is proved.
Now we will prove that $u$ must be symmetric with respect to $T\left(\lambda^{\prime}\right)$. Assume $w \neq 0$ in $\Sigma\left(\lambda^{\prime}\right)$, so as we did for $\lambda=\lambda^{*}$, we infer $w>0$ in $\Sigma\left(\lambda^{\prime}\right)$.

Assume next that condition a) holds, then $\partial \Sigma^{\prime}\left(\lambda^{\prime}\right)$ is internally tangent to $\partial \Omega$ at some point $M^{\lambda^{\prime}}$, where $M \in\left\{\partial \Sigma\left(\lambda^{\prime}\right) \backslash T\left(\lambda^{\prime}\right)\right\} \cap \partial \Omega$. Since $P$ is an interior point of $\Omega, P \neq M^{\lambda^{\prime}}$, so that we can apply the Hopf lemma to $w$ at $M$ and we obtain

$$
\frac{\partial w}{\partial v}\left(M, \lambda^{\prime}\right)>0
$$

where $v$ is the inner normal to $\partial \Omega$ at $M$. For

$$
\frac{\partial w}{\partial v}\left(M, \lambda^{\prime}\right)=\frac{\partial u}{\partial v}\left(M^{\lambda^{\prime}}\right)-\frac{\partial u}{\partial v}(M)=c-c=0
$$

we get the contradiction. Hence condition 2) must be true, i.e. $T\left(\lambda^{\prime}\right)$ is orthogonal to $\partial \Omega$ at some point $B$. From the boundary condition (2.3) and the definition of $w$ it follows that all the first and second derivatives of $w$ vanish at $B$. On the other hand, as $P^{\lambda^{\prime}} \neq B$, Equation (3.6) is uniformly elliptic with bounded coefficents in a neighborhood of $B$, so that the boundary lemma at corner in [1] lemma 2, may be applied to $w$. Let $s$ be a direction which enters $\partial \Sigma\left(\lambda^{\prime}\right)$ nontangentially at $B$, then by the Serrin's lemma

$$
\frac{\partial w}{\partial s}\left(B, \lambda^{\prime}\right)>0 \quad \text { or } \quad \frac{\partial^{2} w}{\partial s^{2}}>0
$$

Then we have again a contradiction with the derivatives of $w$ at $B$, so $w \equiv 0$ in $\Sigma\left(\lambda^{\prime}\right)$. But this last ine-
quality can not be true since otherwise $w$ would be a function symmetric in $T\left(\lambda^{\prime}\right)$ whose only critical point is not on $T\left(\lambda^{\prime}\right)$.

This completes the proof of Theorem 2.1.

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[^0]:    *This work is supported by the Natural Science Foundation of Shandong Province of China (ZR2012AM018).

