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Analysis of Several Difficult Problems in Assembly Language Programming

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Abstract

In assembly language teaching process, Some problems in assembly language programming are difficult to explain. In order to improve the quality of teaching, the best way is to verify them by experiments. This paper is an experimental verification of several main problems encountered in the teaching process, and gives a detailed explanation. This paper includes the specific allocation of memory in runtime, the calculation of transfer address in transfer instruction, the differences between hard interrupt and soft interrupt. The purpose of this paper is to provide a clear understanding of the difficult problems in assembly language programming.

Keywords

Assembly Language, Teaching, Address Assignment, Interrupt

1. Introduction

Assembly language is a programming language directly oriented to processors. The processor works under the control of instructions. Each instruction that the processor can recognize is called a machine instruction. Each processor has its own set of instructions that can be recognized, called instruction set. When the processor executes instructions, it takes different actions according to different instructions and completes different functions. It can not only change its internal working state, but also control the working state of other peripheral circuits (Wang, 2013).

Because assembly language has the characteristic of "machine dependence", when programmers write programs in assembly language, they can fully arrange various resources within the machine, so that they are always in the best use state. The program written in this way has short execution code and fast execution speed. Assembly, language is one of the most closely related and direct pro-

gramming languages with hardware and the highest efficiency in time and space. It is one of the compulsory courses of computer application technology in Colleges and universities. It plays an important role in training students to master programming technology and familiarize themselves with computer operation and program debugging technology. This paper is the author's teaching of assembly language course. Several difficult problems encountered here are written for your reference.

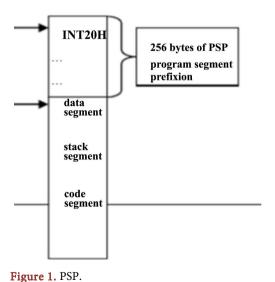
2. Assignment of Program Space in Assembler Runtime

Storage space allocation is needed when assembler runs, which is done by the operating system. When each assembler runs, it first allocates a segment prefix PSP, because DOS uses PSP to communicate with the loaded program.

PSP is 256 bytes, as shown in **Figure 1**. When the executable file is generated to a certain extent, the program is first transferred into memory when it is executed. At this time, the segment address of the program stored in memory is stored in DS. PSP occupies the first 256 bytes of DS:0000H segment. The contents are some instructions of the program, such as how much space the program occupies, etc. Then the real program address is the program address, and CS is pointed here, IP. Setting it to 0000, it is for this reason why CS is 10H larger than DS in general.

The following is a practical program to observe this effect.

The program of Figure 2 runs in DEBUG step by step as shown in Figure 3 and Figure 4. From the execution process of Figure 3, it can be seen that the address space of the program starts from 075A:0000, followed by the program segment prefix PSP of 256 bytes, followed by the data segment. The address space starts from 076A:0000, the data segment size is 16 bytes, then the stack segment of 16 bytes, and the address space starts from 076B:0000. The address space starts at 076C:0000. Through the above experiments, it can be clearly explained to students how the address space of an assembly language program is



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```
assume cs:code,ds:data,ss:stack
                                               mov bx,0₽
                                               mov cx,8₽
data segment«
dw 0123h,0456h
                                               s0: push [bx]₽
                                                  add bx,2₽
data ends₽
                                                  loop s0₽
stack segment₽
dw 0,0,0,0,0₽
                                                  mov bx,0₽
stack endse
                                                  mov cx,8₽
                                                 s1: pop [bx]₽
                                                  add bx,2⊬
code segment∉
start: mov ax, stack₽
                                                  loop s1₽
mov ss,ax
mov sp,08h
                                                  mov ax,4c00h₽
                                                  int 21h
mov ax, data
                                               code ends⊬
mov ds,ax₽
                                               end start⊬
```

Figure 2. Assembly programme 1.

```
-r
AX=PFFF BX=0000 CX=004C DX=0000 SP=0000 BP=0000 SI=0000 DI=0000
DS=075A ES=075A SS=0769 CS=076C IP=0000 NU UP EI PL NZ NA PO NC
076C:0000 BB6B07 MOU AX,076B
-t

AX=076B BX=0000 CX=004C DX=0000 SP=0000 BP=0000 SI=0000 DI=0000
DS=075A ES=075A SS=0769 CS=076C IP=0003 NU UP EI PL NZ NA PO NC
076C:0003 BED0 MOU SS,AX
-t

AX=076B BX=0000 CX=004C DX=0000 SP=0008 BP=0000 SI=0000 DI=0000
DS=075A ES=075A SS=076B CS=076C IP=0008 NU UP EI PL NZ NA PO NC
076C:0008 BB6A07 MOU AX,076A
-t

AX=076A BX=0000 CX=004C DX=0000 SP=0008 BP=0000 SI=0000 DI=0000
DS=075A ES=075A SS=076B CS=076C IP=000B NU UP EI PL NZ NA PO NC
076C:000B BEDB MOU DS,AX
-t

AX=076A BX=0000 CX=004C DX=0000 SP=000B BP=0000 SI=0000 DI=0000
DS=075A ES=075A SS=076B CS=076C IP=000B NU UP EI PL NZ NA PO NC
076C:000B BEDB MOU DS,AX
-t

AX=076A BX=0000 CX=004C DX=0000 SP=000B BP=0000 SI=0000 DI=0000
DS=076A ES=075A SS=076B CS=076C IP=000D NU UP EI PL NZ NA PO NC
076C:000D BB00000 MOU BX,00000
```

Figure 3. The running result 1 of assembly programme 1.

```
-r
AX=FFFF BX=0000 CX=004C DX=0000 SP=0000 BP=0000 SI=0000 DI=0000
DS=075A ES=075A
O76C:0000 B86A07
-t

AX=076A BX=0000 CX=004C DX=0000 SP=0000 BP=0000 SI=0000 DI=0000
DS=075A ES=075A
O76C:0003 BEDB
-t

AX=076A BX=0000 CX=004C DX=0000 SP=0000 BP=0000 SI=0000 DI=0000
DS=076A ES=075A
O76C:0005 B86B07
-t

AX=076B BX=0000 CX=004C DX=0000 SP=0000 BP=0000 SI=0000 DI=0000
DS=076A ES=075A
O76C:0005 B86B07
-t

AX=076B BX=0000 CX=004C DX=0000 SP=0000 BP=0000 SI=0000 DI=0000
DS=076A ES=075A
O76C:0008 BED0
-t

AX=076B BX=0000 CX=004C DX=0000 SP=0000 BP=0000 SI=0000 DI=0000
DS=076A ES=075A
O76C:0008 BED0
-t

AX=076B BX=0000 CX=004C DX=0000 SP=0000 BP=0000 SI=0000 DI=0000
DS=076A ES=075A
O76C:000B BB0000 CX=004C DX=0000 SP=000B BP=0000 SI=0000 DI=0000
DS=076A ES=075A
O76C:000B BB0000 CX=004C DX=0000 SP=000B BP=0000 SI=0000 DI=0000
DS=076A ES=075A
O76C:000B BB0000 CX=004C DX=0000 SP=000B BP=0000 SI=0000 DI=0000
DS=076A ES=075A
O76C:000B BB0000 CX=004C DX=0000 SP=000B BP=0000 SI=0000 DI=0000
DS=076A ES=075A
O76C:000B BB0000 CX=004C DX=0000 SP=000B BP=0000 SI=0000 DI=0000
DS=076A ES=075A
O76C:000B BB0000 CX=004C DX=0000 SP=000B BP=0000 SI=0000 DI=0000
DS=076A ES=075A
O76C:000B BB0000 CX=004C DX=0000 SP=000B BP=0000 SI=0000 DI=0000
DS=076A ES=075A
O76C:000B BB0000 CX=004C DX=0000 SP=000B BP=0000 SI=0000 DI=0000
DS=076A ES=075A
O76C:000B BB0000 CX=004C DX=0000 SP=000B BP=0000 SI=0000 DI=0000
DS=076A ES=075A
O76C:000B BB0000 DI=0000 DI=0000 DI=0000
```

Figure 4. The running result 2 of assembly programme 1.

actually allocated in memory. For example, the following information can be obtained from the above run result graph: when a program has just been loaded into memory and has not yet started running, the DS register stores the starting address of the program segment prefix of the program, and this is the beginning address of the program segment prefix. The address is assigned by the DOS operating system. If the definition order of data segment and stack segment in the program is changed, that is to say, the green part of the above code is put in front of the red code segment, and run as shown in **Figure 4**. Compared with **Figure 3** and **Figure 4**, it can be seen that after changing the order, the program runs only to change the allocation order of the address of the data segment and the stack segment, but the address allocated by the data segment and the stack segment has not changed.

3. Address Calculation of Jump Instructions

The program is shown in **Figure 5**. The result of this program is shown in **Figure 6**. As can be seen from **Figure 6**, the instruction mov ax, 4c00h; the function of int 21h is simply to point the IP pointer to their next instruction: start: mov ax, 0.

Using disassembly instructions, **Figure 7** is obtained for the above programs. As can be seen from the figure, the physical address of label S1 is 076A:0018H, the physical address of label S2 is 076A:0020H, and the instruction machine code of instruction s2:jmp short S1 is EBF6, in which the meaning of EB is jmp, and F6 represents the jump distance of the instruction. The distance value is calculated as follows: when the CPU reads in the machine code EBF6, the content of its IP pointer points to the next instruction nop. Its physical address is 076A:0022H, and the distance from the address to the physical address 076A:0018H of the label S1 is 10 (decimal system). Because it is a jump up, its value is negative. The

```
mov cs:[di],ax
assume cs:codesg-
                                                        s0:jmp short se
codesg segmente
   mov ax,4c00h
                                                        s1:mov ax,0₽
   int 21h₽
                                                           int 21h₽
start:mov ax,04
                                                           mov ax,0₽
     s:nop₽
                                                        s2:jmp short s14
                                                           nop⊬
       nop⊎
       mov di,offset s₽
                                                        codesg ends<sub>4</sub>
       mov si,offset s2₽
                                                        end start«
       mov ax,cs:[si]
```

Figure 5. Assembly programme 2.

```
-r
AX=FFFF BX=0000 CX=0023 DX=0000 SP=0000 BP=0000 SI=0000 DI=0000
DS=075A ES=075A SS=0769 CS=076A IP=0005 NV UP EI PL NZ NA PO NC
076A:0005 B80000 MOV AX,0000
```

Figure 6. The running result 1 of assembly programme 2.

–u			
076A:0005	B80000	MOV	AX,0000
076A:0008	90	NOP	
076A:0009	90	NOP	
076A:000A	BF0800	MOV	DI,0008
076A:000D	BE2000	MOV	SI,0020
076A:0010	ZE	cs:	
076A:0011	8B04	MOV	AX,[SI]
076A:0013	ZE	cs:	
076A:0014	8905	MOV	[DI],AX
076A:0016	EBFO	JMP	0008
076A:0018	B80000	MOV	AX,0000
076A:001B	CD21	INT	21
076A:001D	B80000	MOV	AX,0000
076A:0020	EBF6	JMP	0018
076A:0022	90	NOP	
076A:0023	C404	LES	AX,[SI]

Figure 7. The running result 2 of assembly programme 2.

complement of decimal system-10 is F6, and its address calculation is derived from 0022H + F6H = 0018H.

076A:0009 memory cells, and their machine codes are 90H, as shown in Figure 8. Then one-step running of the above program, when running to the instructions mov cs:[di], ax, as shown in Figure 9, the contents stored in the storage units 076A:0008 and 076A:0009 are programmed with EBF6, as shown in Figure 10. Continue to run instruction s0:jmp shorts, then CS and IP become 076A:0008H, then CPU reads machine code EBF6, then IP becomes 0010H. According to the above address jump calculation method, it is concluded that when machine code EBF6 is executed, IP will become 0000H, so the instruction mov ax, 4c00h, int 21h will be executed again, and when the instruction is executed again, the whole program will jump out of the node. Bundle, as shown in Figure 11. It can also be seen from the above process that when the instruction mov ax, 4c00h, int 21h is placed at the beginning of the program, its function is only to point the IP pointer to the next instruction address of this instruction, but when this instruction is executed during the execution of the program, it will cause the IP pointer to jump out of the whole program.

4. The Explanation of Hard Interrupt and Soft Interrupt

Figure 12 is an assembler program that uses keyboard and screen for input and output. The result is that the number is displayed on the screen when the number is input from the keyboard, and the "*" number is displayed when other characters are input. The results are shown in Figure 13.

Internal interruption means that the CPU does not follow the instructions that have just been executed down, but instead moves on to handle this particular information. External interruption refers to the CPU in the computer system, in addition to the ability to execute instructions and operations, but also should be able to control external equipment, receive their input and output to them. Statements in the program Mov ah, 7, int 21h belongs to function call No. 7 in DOS interrupt, which receives keyboard input information and belongs to soft

```
076A:0000
                             B8 00 00-90 90 BF 08 00 BE 20 00
076A:0010
            2E 8B 04 2E 89 05 EB F0-B8 00 00 CD 21 B8 00 00
076A:0020
            EB F6 90 C4 04 50 E8 9F-0E 83 C4 04 3D FF FF
            03 E9 11 01 B8 2F 00 50-8B 46 FC 8B 56 FE 05 0C
076A:0030
076A:0040
            00 52 50 E8 EA 48 83 C4-04 50 E8 7B 0E 83 C4 04
            3D FF FF 74 03 E9 ED 00-C4 5E FC 26 8A 47 0C 2A
076A:0050
           E4 40 50 8B C3 8C C2 05-0C 00 52 50 E8 C1 48 83 C4 04 50 8D 86 FA FE 50-E8 17 73 83 C4 06 8B B6
076A:0060
076A:0070
076A:0080
               FE 81 E6 FF
            FA
```

Figure 8. The running result 3 of assembly programme 2.

```
SS=0769 CS=076A IP=000A NU UP EI PL NZ NA PO NC
076A:000A BF0800
                           MNU
                                    DI,0008
                   CX=0023 DX=0000 SP=0000
                                                   BP=0000 SI=0000 DI=0008
AX=0000 BX=0000
DS=075A ES=075A
                    SS=0769 CS=076A IP=000D
                                                    NU UP EI PL NZ NA PO NC
                                    SI,0020
                           MOV
976A:000D BE2000
                   CX=0023 DX=0000 SP=0000 BP=0000 SI=0020 DI=0008 SS=0769 CS=076A IP=0010 NU UP EI PL NZ NA PO NC
AX=0000 RX=0000
DS=075A ES=075A
976A:0010 ZE
                           CS:
976A:0011 8B04
                           MOV
                                    AX,[SI]
                                                                            CS:0020=F6EB
AX=F6EB BX=0000 CX=0023 DX=0000 SP=0000 BP=0000 SI=0020 DI=0008
DS=075A ES=075A SS=0769 CS=076A IP=0013 N∪UP EI PL NZ NA PO NC
076A:0013 ZE
076A:0014 8905
                           CS:
                           MOV
                                    [DII.AX
                                                                            CS:0008=9090
AX=F6EB BX=0000 CX=0023 DX=0000 SP=0000 BP=0000 SI=0020 DI=0008
         ES=075A
                   SS=0769
                             CS=076A
                                         IP=0016
                                                    NU UP EI PL NZ NA PO NC
                           .TMP
                                    0008
076A:0016 EBF0
```

Figure 9. The running result 4 of assembly programme 2.

```
076A:0000
                                   EB F6 BF 08 00 BE 20 00
           2E 8B 04 2E 89 05 EB F0-B8 00 00 CD 21 B8 00 00
076A:0010
           EB F6 90 C4 04 50 E8 9F-0E 83 C4 04 3D FF FF
076A:0020
           03 E9 11 01 B8 2F
                             00 50-8B 46 FC 8B 56 FE
076A:0030
                                                     05
           00 52 50 E8 EA 48 83 C4-04 50 E8 7B 0E 83 C4 04
076A:0040
           3D FF FF 74 03 E9 ED 00-C4 5E FC 26 8A 47 0C 2A
076A:0050
076A:0060
           E4 40 50 8B C3 8C C2 05-0C 00 52 50 E8 C1 48 83
           C4 04 50 8D 86 FA FE 50-E8 17 73 83 C4 06 8B B6
076A:0070
          FA FE 81 E6 FF 00 C6 82
076A:0080
```

Figure 10. The running result 5 of assembly programme 2.

```
AX=F6EB BX=0000
          ES=025A
 76A:0016 EBF0
                     CX=0023 DX=0000 SP=0000
SS=0769 CS=076A IP=0008
JMP 0000
AX=F6EB BX=0000
DS=075A ES=075A
                                                         BP=0000 SI=0020 DI=0000
NU UP EI PL NZ NA PO NC
                                                                                 DI=0008
                     CX=0023 DX=0000 SP=0000
SS=0769 CS=076A IP=0000
MOU AX,4C00
AX=F6EB BX=0000
                                                          BP=0000 SI=0020 DI=0008
0S=075A ES=075A
076A:0000 B8004C
                                                            NU UP EI PL NZ NA PO NC
                     CX=0023 DX=0000
SS=0769 CS=076A
INT 21
AX=4C00 BX=0000
                                              SP=0000
                                                          BP=0000 SI=0020 DI=0000
NU UP EI PL NZ NA PO NC
DS=075A ES=075A
076A:0003 CD21
                                               IP=0003
                                                          BP=0000 SI=0020 DI=0008
NV UP DI PL NZ NA PO NC
AX=4C00 BX=0000 CX=0023 DX=0000
                                              SP=FFFA
DS=075A ES=075A
F000:14A0 FB
                      SS=0769 CS=F000
STI
                                               IP=14A0
```

Figure 11. The running result 6 of assembly programme 2.

```
assume cs:cc,ds:qwer-
                                     getkey: mov ah,7₽
                                                                          cmp dl,'a'₽
                                     int 21h₽
qwer segment₽
                                                                          jb getkey₽
tip1 db 10,13, please input
                                     :in al.60h₽
                                                                          cmp dl, 'z'₊
char.cr then end:'₽
                                     cmp al.13₽
                                                                          ia getkev√
db 10,13,36₽
                                     je exit₽
                                                                          dispx:mov dl,1*14
gwer ends₽
                                     mov dl,al₽
                                                                          disp:mov ah,24
                                     cmp dl,'0'₽
                                                                          int 21h⊌
cc segment<sub>€</sub>
                                     jb getkey⊬
                                                                          jmp getkey⊌
beg:⊬
                                     cmp dl, '9'₽
                                                                          exit:mov ah,4ch
mov ax,qwer
mov ds,ax₽
                                     jbe disp₽
                                                                          int 21h₽
                                     cmp dl, 'a'√
mov dx,offset tip1₽
                                                                          cc ends⊌
mov ah.9₽
                                                                          end beg<sub>4</sub>
                                     jb getkey₽
int 21h₽
                                     cmp dl,'z'₽
                                     jbe dispx₽
```

Figure 12. Assembly programme 3.

```
please input char,cr then end:
7----345262039-----3948348---384388347583-----63763653673378-7337----
```

Figure 13. The running result of assembly programme 3.

interrupt. Its process is to find the entry address of interrupt program according to int 21h instruction. This interrupt program is used to read keyboard input characters, and the interrupt is triggered by int 21h instruction; instruction in al, 60H is the information read directly into port 60h, and the information of port 60H is the same as that of port 60h. Sample from the keyboard input, the reading process is still to use the same int 21h instruction pointed to the interrupt service program, but this call process is triggered by the keyboard keys caused by the changes in the keyboard internal circuit switch state, belongs to hard interrupt. The substitution of these three instructions well explains the difference and relationship between soft interrupt and hard interrupt (Wu, Wang, & Liu, 2009; Qian, 2004).

Summary: For beginners, assembly language, because of its close combination with hardware, if their hardware knowledge is not enough, then the course will be more difficult to grasp; For teachers, some of the concepts are particularly difficult to explain clearly, This paper makes a preliminary discussion on some difficult problems in assembly language through examination, including assignment of program space, address calculation of jump instructions and explanation of hard interrupt and soft interrupt, hoping that through a few practical examples, it can be helpful to teachers and students engaged in this teaching work.

Conflicts of Interest

The author declares no conflicts of interest regarding the publication of this paper.

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