# Introduction of the Tensor Which Satisfied Binary Law 

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#### Abstract

P: For every coordinate system, there is no immediate reason for preferring certain systems of co-ordinates to others. If we don't recognize that $P$ is establishment, we must recognize to existence of the absolute coordinate system. Therefore, we must recognize that $P$ is establishment. Nevertheless, I got conclusion that $P$ isn't establishment for all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$. If P is establishment, this is the trouble. As against, I got conclusion that if we consider "Binary Law" for all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots, \mathrm{P}$ is establishment for all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$. If we consider Binary Law for all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$, we must consider Binary Law for the coordinate systems using into Tensor, too. So, I decided to report for the Tensor which satisfied Binary Law.


## Keywords

Tensor, Covariant Derivative

## 1. Introduction

Definition 1. For every coordinate system, there is no immediate reason for preferring certain systems of co-ordinates to others.

Definition 2. I named $\overline{x^{\mu}} \neq x^{\mu}, \overline{x^{v}} \neq x^{v}, \overline{x^{\mu}}=x^{v}, \overline{x^{v}}=x^{\mu}$ "Binary Law".
Definition 3. $x^{\mu} \neq x_{\mu}$ is established.
Definition 4. $x^{v} \neq x_{v}$ is established.
Definition 5. $x^{\mu} \neq-x^{\mu}$ is established.
Definition 6. Convariant and contravariant tensor of the first rank $A_{\mu}, A_{\nu}, A^{\mu}, A^{v}$ satisfied $A_{\mu}=\frac{\partial x^{\nu}}{\partial x^{\mu}} A_{\nu}, A^{\mu}=\frac{\partial x^{\mu}}{\partial x^{\nu}} A^{\nu \quad \text { [1]. }}$

Definition 7. Tensor of rank zero $A_{\mu}^{\mu}, A_{v}^{v}$ satisfied $A_{\mu}^{\mu}=A_{v}^{v}$ [1].
Definition 8. If tensor $A_{\nu}^{\mu}$ satisfied $A_{v}^{\mu}=A_{\mu}^{v}$, this tensor $A_{\nu}^{\mu}$ was named symmetric tensor [1].

Definition 9. Convariant differentiation for Convariant Bector $A_{\mu ; \nu}$ satisfied $A_{\mu ; \nu}=\frac{\partial A_{\mu}}{\partial x^{\nu}}-\{\mu \nu, \tau\} A_{\tau}=\frac{\partial A_{\mu}}{\partial x^{v}}-A_{\tau} \frac{1}{2} g^{\tau \sigma}\left(\frac{\partial g_{\mu \sigma}}{\partial x^{\nu}}+\frac{\partial g_{v \sigma}}{\partial x^{\mu}}-\frac{\partial g_{\mu \nu}}{\partial x^{\sigma}}\right) \quad[1]$.

Definition 10. $g_{\mu}^{\mu}=1$ and $g_{v}^{\mu}=0:(\mu \neq v)$ are establishment [2].
Definition 11. Convariant differentiation for contravariant bector $A_{, v}^{\mu}$ satisfied $A_{, v}^{\mu}=\frac{\partial A^{\mu}}{\partial x^{\nu}}+\{\tau \nu, \mu\} A^{\tau}=\frac{\partial A^{\mu}}{\partial x^{\nu}}+A^{\tau} \frac{1}{2} g^{\mu \sigma}\left(\frac{\partial g_{\tau \sigma}}{\partial x^{\nu}}+\frac{\partial g_{v \sigma}}{\partial x^{\tau}}-\frac{\partial g_{\tau v}}{\partial x^{\sigma}}\right)$ [2].

Definition 12. Convariant differentiation for Scalar $S_{; \nu}$ satisfied $S_{; \nu}=\frac{\partial S}{\partial x^{V}} \quad$ [2].

## 2. About Reason to Take Binary Law into Consideration

We will have to receive existence of the absolute coordinate system if Definition 1 is not established. Therefore, we must accept establishment of Definition 1.

Proposition 1. Definition 1 is not established for all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$.

Proof: All coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ thinks about $x^{\mu}$ in a standard and can divide it into two next groups.

$$
\begin{gather*}
x^{\mu}=x^{\mu}, \\
x^{\mu} \neq x^{\nu}, x^{\mu} \neq x^{\sigma}, x^{\mu} \neq x^{\lambda}, \cdots . \tag{1}
\end{gather*}
$$

I think that I change the coordinate systems of the standard $x^{\mu}$ of (1) for all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ sequentially now. By the way, the difference cannot occur between each conclusion to be provided here if Definition 1 is established. This reason is that all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ has a privilege of the equality each other if Definition 1 is established. At first (1) gets an invariable conclusion for $\mu, \mu$ exchange. Therefore, at least (1) must get an invariable conclusion for the next $\mu, \nu$ exchange if Definition 1 is established. Here, I get

$$
\begin{gather*}
x^{\nu}=x^{\nu}, \\
x^{\nu} \neq x^{\mu}, x^{\nu} \neq x^{\sigma}, x^{\nu} \neq x^{\lambda}, \cdots \tag{2}
\end{gather*}
$$

by $\mu, v$ exchange from (1). Therefore, (2) must be equal with (1) if Definition 1 is established. By the way, $x^{\mu}=x^{\mu}, x^{\mu} \neq x^{\nu}$ of (1) is equal with $x^{\nu}=x^{\nu}, x^{\nu} \neq x^{\mu}$ of (2), but $x^{\mu} \neq x^{\sigma}, x^{\mu} \neq x^{\lambda}, \cdots$ of (1) is not equal with $x^{\nu} \neq x^{\sigma}, x^{\nu} \neq x^{\lambda}, \cdots$ of (2). In other words, (2) is not equal with (1). Therefore, Definition 1 is not established for all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$.
-End Proof
Establishment of Proposition 1 is a problem in thinking that Definition 1 must be established. Therefore, I aim at getting establishment of Definition 1 for all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$.
Proposition 2. If all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ satisfies $\overline{x^{\mu}} \neq x^{\mu}, \overline{x^{\nu}} \neq x^{\nu}, \overline{x^{\mu}}=x^{\nu}, \overline{x^{\nu}}=x^{\mu}$, Definition 1 is established for all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$.

Proof: I get

$$
x^{\mu}=x^{\mu},
$$

$$
\begin{align*}
& x^{\mu} \neq x^{\nu},  \tag{3}\\
& x^{\nu}=x^{\nu}, \\
& x^{\nu} \neq x^{\mu} \tag{4}
\end{align*}
$$

from (1), (2) if all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ satisfies

$$
\begin{equation*}
\overline{x^{\mu}} \neq x^{\mu}, \overline{x^{v}} \neq x^{v}, \overline{x^{\mu}}=x^{v}, \overline{x^{v}}=x^{\mu} . \tag{5}
\end{equation*}
$$

(3) is equal with (4) here. In other words, (2) is equal with (1) if all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ satisfies (5). Therefore, Definition 1 is established for all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ if all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ satisfies (5).
-End Proof
Proposition 3. If all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ satisfies $\overline{x^{\mu}} \neq x^{\mu}, \overline{x^{\nu}} \neq x^{\nu}, \overline{x^{\mu}}=x^{\nu}, \overline{x^{\nu}}=x^{\mu}$, all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ shifts to only two of $x^{\mu}, x^{\nu}$.

Proof: If all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ satisfies (5), I get $x^{\mu}, x^{\nu}$ than all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$.
-End Proof
Proposition 4. If $\overline{x^{\mu}} \neq x^{\mu}, \overline{x^{v}} \neq x^{v}, \overline{x^{\mu}}=x^{v}, \overline{x^{v}}=x^{\mu}$ is established, $x^{\mu} \neq x^{v}$ is established.

Proof: I get

$$
\begin{equation*}
\overline{x^{\mu}} \neq x^{\mu}, \overline{x^{v}} \neq x^{v}, \overline{x^{\mu}}=x^{\mu}, \overline{x^{v}}=x^{v} \tag{6}
\end{equation*}
$$

from (5), (7) if I assume establishment of

$$
\begin{equation*}
x^{\mu}=x^{v} \tag{7}
\end{equation*}
$$

when (5) is established. Because (6) includes contradiction,

$$
\begin{equation*}
x^{\mu} \neq x^{v} \tag{8}
\end{equation*}
$$

is established when (5) is established.
-End Proof
Proposition 5. If $\overline{x^{\mu}} \neq x^{\mu}, \overline{x^{v}} \neq x^{\nu}, \overline{x^{\mu}}=x^{v}, \overline{x^{v}}=x^{\mu}$ is established, $x^{\nu}=x_{\mu}, x^{\mu}=x_{\nu}, x^{\nu}=-x^{\mu}, x_{v}=-x_{\mu}$ are established.

Proof: When (5) is established, (8) is established from Proposition 4. Therefore, I get

$$
\begin{equation*}
x^{\mu} \neq x_{\mu} \text { (False) } \tag{9}
\end{equation*}
$$

from (8), (10) if I assume establishment of $x^{\nu} \neq x_{\mu}$ when (5) is established. I can rewrite $x^{v} \neq x_{\mu}$ as

$$
\begin{equation*}
x^{v}=x_{\mu}(\text { False }) \tag{10}
\end{equation*}
$$

here. When (5) is established, I get

$$
\begin{equation*}
x^{\mu} \neq x_{\mu} \tag{11}
\end{equation*}
$$

from Definition 3. Because (9) includes contradiction for (11),

$$
\begin{equation*}
x^{v}=x_{\mu} \tag{12}
\end{equation*}
$$

is established when (5) is established.
Similary, I get

$$
\begin{equation*}
\left.x^{v} \neq x_{v} \text { (False }\right) \tag{13}
\end{equation*}
$$

from (8), (14) if I assume establishment of $x^{\mu} \neq x_{v}$ when (5) is established. I can rewrite $x^{\mu} \neq x_{v}$ as

$$
\begin{equation*}
x^{\mu}=x_{v}(\text { False }) \tag{14}
\end{equation*}
$$

here. When (5) is established, I get

$$
\begin{equation*}
x^{v} \neq x_{v} \tag{15}
\end{equation*}
$$

from Definition 4. Because (13) includes contradiction for (15),

$$
\begin{equation*}
x^{\mu}=x_{v} \tag{16}
\end{equation*}
$$

is established when (5) is established.
Similary, I get

$$
\begin{equation*}
x^{\mu} \neq-x^{\mu}(\text { False }) \tag{17}
\end{equation*}
$$

from (8), (18) if I assume establishment of $x^{\nu} \neq-x^{\mu}$ when (5) is established. I can rewrite $x^{\nu} \neq-x^{\mu}$ as

$$
\begin{equation*}
x^{\nu}=-x^{\mu}(\text { False }) \tag{18}
\end{equation*}
$$

here. When (5) is established, I get

$$
\begin{equation*}
x^{\mu} \neq-x^{\mu} \tag{19}
\end{equation*}
$$

from Definition 5. Because (17) includes contradiction for (19),

$$
\begin{equation*}
x^{v}=-x^{\mu} \tag{20}
\end{equation*}
$$

is established when (5) is established. And, I get

$$
\begin{equation*}
x_{v}=-x_{\mu} \tag{21}
\end{equation*}
$$

from (12), (16), (20).

## 3. About the Tensor Which Satisfied Binary Law

We will have to think about adaptation of the establishment of Binary Law for the coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ in the tensor if we think about establishment of Binary Law for all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$. Therefore, I decided to report Tensor when all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ satisfied Binary Law.

Proposition 6. If all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ satisfied $\overline{x^{\mu}} \neq x^{\mu}, \overline{x^{\nu}} \neq x^{\nu}, \overline{x^{\mu}}=x^{\nu}, \overline{x^{\nu}}=x^{\mu}$, Convariant and Contravariant Tensor of the first rank does not change the form of the equation.

Proof: I get

$$
\begin{equation*}
A_{\mu}=\frac{\partial x^{v}}{\partial x^{\mu}} A_{\nu}, A^{\mu}=\frac{\partial x^{\mu}}{\partial x^{v}} A^{\nu} \tag{22}
\end{equation*}
$$

from Definition 6 if all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ satisfies (5). Definition 6 and (22) are equal here. Therefore, if all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ satisfied (5), Convariant and Contravariant Tensor of the first rank does not change the form of the equation.
-End Proof
Proposition 7. Tensor of the second rank becomes Symmetric Tensor if all coordinate systems $x^{\mu}, x^{v}, x^{\sigma}, x^{\lambda}, \cdots$ satisfies $\overline{x^{\mu}} \neq x^{\mu}, \overline{x^{\nu}} \neq x^{v}, \overline{x^{\mu}}=x^{\nu}, \overline{x^{v}}=x^{\mu}$.

Proof: I get

$$
\begin{equation*}
A_{\mu}^{\mu}=A_{\nu}^{\nu} \tag{23}
\end{equation*}
$$

from Definition 7 if all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ satisfies (5). Definition 7 and (23) are equal here. We can use (12), (16), (20), (21) for (23) by considering Proposition 5 here. And we can rewrite (23) by using (12), (16) for

$$
\begin{align*}
& A_{\nu \mu}=A_{v}^{v}, A^{\mu v}=A_{v}^{v},  \tag{24}\\
& A_{\mu}^{\mu}=A_{\mu \nu}, A_{\mu}^{\mu}=A^{v \mu} .
\end{align*}
$$

Then, I get

$$
\begin{equation*}
A_{\nu \mu}=A_{\mu \nu}, A^{\mu \nu}=A^{\nu \mu} \tag{25}
\end{equation*}
$$

from (23),(24). And we can rewrite (23) by using (20), (21) for

$$
\begin{equation*}
-A_{\mu}^{v}=A_{v}^{v},-A_{v}^{\mu}=A_{v}^{v} . \tag{26}
\end{equation*}
$$

Then, I get

$$
\begin{equation*}
A_{\mu}^{v}=A_{\nu}^{\mu} \tag{27}
\end{equation*}
$$

from (26). Therefore, Tensor of the second rank becomes Symmetric Tensor than consideration of Definition 8 when all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ satisfies (5).
-End Proof
Proposition 8. If all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ satisfied $\overline{x^{\mu}} \neq x^{\mu}, \overline{x^{\nu}} \neq x^{\nu}, \overline{x^{\mu}}=x^{\nu}, \overline{x^{\nu}}=x^{\mu}$, The distance of two points be able to change oneself in connection with the metric of space.

Proof: I get

$$
\begin{equation*}
g_{\mu}^{\mu}=1, g_{v}^{\mu}=0:(\mu \neq v) \tag{28}
\end{equation*}
$$

from Definition 10 if all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ satisfies (5). I get

$$
\begin{align*}
A_{\mu ; v}=\frac{\partial A_{\mu}}{\partial x^{v}} & -A_{v} \frac{1}{2} g^{\nu v}\left(\frac{\partial g_{\mu \nu}}{\partial x^{v}}+\frac{\partial g_{\nu v}}{\partial x^{\mu}}-\frac{\partial g_{\mu \nu}}{\partial x^{v}}\right) \\
& =\frac{\partial A_{\mu}}{\partial x^{\nu}}-\frac{1}{2}\left(\frac{\partial g_{v}^{v}}{\partial x^{\mu}}\right) A_{\nu}  \tag{29}\\
& =\frac{\partial A_{\mu}}{\partial x^{v}}-\frac{1}{2}\left(\frac{\partial g_{v}^{\sigma}}{\partial x^{\mu}}\right) A_{\sigma}  \tag{30}\\
& =\frac{\partial A_{\mu}}{\partial x^{v}}-\frac{1}{2}\left(\frac{\partial g_{\sigma}^{\sigma}}{\partial x^{\mu}}\right) A_{\nu} \tag{31}
\end{align*}
$$

from Definition 9 if all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ satisfies (5). By the way, we cannot handle (30), (31) according to Proposition 3. We can use (12), (16), (20), (21) for (29) by considering Proposition 5 here. And we must rewrite (29) by using (16) for

$$
\begin{align*}
A_{\mu ;}^{\mu} & =\frac{\partial A_{\mu}}{\partial x_{\mu}}-\frac{1}{2}\left(\frac{\partial g^{v \mu}}{\partial x^{\mu}}\right) A_{\nu}  \tag{32}\\
& =\frac{\partial A_{\mu}}{\partial x_{\mu}}-\frac{1}{2}\left(\frac{\partial g_{v}^{v}}{\partial x^{\mu}}\right) A^{\mu} . \tag{33}
\end{align*}
$$

I decide not to handle (33) by consideration of (28) here. Well, I get conclution from (32) that if all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ satisfied (5), Scalar quantity be able to change oneself in connection with the metric of space. Here, This Scalar quantity expressed the all of quantity expressed as Scalar. Therefore, I get conclution that the distance of two points be able to change oneself in connection with the metric of space.
-End Proof
Proposition 9. If all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ satisfied $\overline{x^{\mu}} \neq x^{\mu}, \overline{x^{\nu}} \neq x^{\nu}, \overline{x^{\mu}}=x^{\nu}, \overline{x^{\nu}}=x^{\mu}$, convariant differentiation for Contravariant Bector $A_{, v}^{\mu}$ behave like a convariant differentiation for Scalar $S_{; v}$.
Proof: I get

$$
\begin{align*}
A_{, v}^{\mu}=\frac{\partial A^{\mu}}{\partial x^{v}} & +A^{\nu} \frac{1}{2} g^{\mu \nu}\left(\frac{\partial g_{v v}}{\partial x^{\nu}}+\frac{\partial g_{v v}}{\partial x^{\nu}}-\frac{\partial g_{v v}}{\partial x^{v}}\right) \\
& =\frac{\partial A^{\mu}}{\partial x^{v}}+\frac{1}{2}\left(\frac{\partial g_{v}^{\mu}}{\partial x^{v}}\right) A^{\nu}  \tag{34}\\
& =\frac{\partial A^{\mu}}{\partial x^{v}}+\frac{1}{2}\left(\frac{\partial g_{\sigma}^{\mu}}{\partial x^{v}}\right) A^{\sigma}  \tag{35}\\
& =\frac{\partial A^{\mu}}{\partial x^{v}}+\frac{1}{2}\left(\frac{\partial g_{v}^{\mu}}{\partial x^{\sigma}}\right) A^{\sigma} \tag{36}
\end{align*}
$$

from Definition 11 if all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ satisfies (5). By the way, we cannot handle (35), (36) according to Proposition 3. We can use (12), (16), (20), (21) for (34) by considering Proposition 5 here. And we must rewrite (34) by using (21) for

$$
\begin{align*}
-A_{, \mu}^{\mu} & =-\frac{\partial A^{\mu}}{\partial x^{\mu}}-\frac{1}{2}\left(\frac{\partial g_{v}^{\mu}}{\partial x^{\mu}}\right) A^{v} \\
& =-\frac{\partial A^{\mu}}{\partial x^{\mu}}-\frac{1}{2}\left(\frac{\partial g_{\mu}^{\mu}}{\partial x^{v}}\right) A^{v} . \tag{37}
\end{align*}
$$

And, I can get

$$
\begin{equation*}
-A_{, \mu}^{\mu}=-\frac{\partial A^{\mu}}{\partial x^{\mu}} \tag{38}
\end{equation*}
$$

from (37) for consideration of (28). And we can rewrite (38) by using (21) for

$$
\begin{equation*}
A_{, v}^{\mu}=\frac{\partial A^{\mu}}{\partial x^{v}} \tag{39}
\end{equation*}
$$

Because the second term of the right side of (38) does not exist here, we may adopt (38) and (39) description form of which. Well, I get conclution from (39), Definition 12 that if all coordinate systems $x^{\mu}, x^{\nu}, x^{\sigma}, x^{\lambda}, \cdots$ satisfied (5), Convariant differentiation for Contravariant Bector $A_{, v}^{\mu}$ behave like a Convariant differentiation for Scalar $S_{; v}$.

## 4. Discussion

## About Definition 2:

I named (5) "Binary Law" by Proposition 3.
About Proposition 6:
Convariant and contravariant tensor of the first rank don't change the formula whether it's satisfied (5) or not.

About Proposition 8:
In (32), we can think that $\frac{\partial A_{\mu}}{\partial x_{\mu}}$ expressed the distance of two points in $\frac{\partial g^{\nu \mu}}{\partial x^{\mu}}=0$ is establishment and this is constant. And, $A_{\mu ;}^{\mu}$ expresses the distance of two points in general and this is not constant.

About Proposition 9:
In (39), we can handle $\frac{\partial A^{\mu}}{\partial x^{\nu}}$ as tensor similarly $A_{, v}^{\mu}$.

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