

A Lemma on Almost Regular Graphs and an Alternative Proof for Bounds on $\gamma_t(P_k \Box P_m)$

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ABSTRACT

Gravier *et al.* established bounds on the size of a minimal totally dominant subset for graphs $P_k \Box P_m$. This paper offers an alternative calculation, based on the following lemma: Let $k, r \in \mathbb{N}$ so $k \ge 3$ and $r \ge 2$. Let H be an rregular finite graph, and put $G = P_k \Box H$. 1) If a perfect totally dominant subset exists for G, then it is minimal; 2) If $r \ge 2$ and a perfect totally dominant subset exists for G, then every minimal totally dominant subset of G must be perfect. Perfect dominant subsets exist for $P_k \Box C_n$ when k and n satisfy specific modular conditions. Bounds for $\gamma_t (P_k \Box P_m)$, for all k,m follow easily from this lemma. Note: The analogue to this result, in which we replace "totally dominant" by simply "dominant", is also true.

Keywords: Domination; Total Domination; Matrix; Linear Algebra

1. Introduction

Let G = (V(G), E(G)) be a graph. In this paper, each edge of a graph must have two different endpoints; also, two vertices may be linked by at most one edge. A subset Z of vertices is said to *totally dominate* G if every vertex of G has a neighbor in Z. We say Z perfectly totally dominates if every vertex has exactly one neighbor in Z. Next, suppose that G is finite. In this case, we say a totally dominant subset Z is minimal if |Z| is the smallest size possible among all dominant subsets. This minimal size is denoted by $\gamma_t(G)$.

For $r \in \mathbb{N}$, we say that a graph *G* is *r*-regular if every vertex is the endpoint of exactly *r* edges. Suppose *G* is regular. A subset *Z* which perfectly totally dominates is clearly minimal. If a perfect dominant set does not exist, we can search for minimality among dominant subsets *Z* by counting "overlaps". That is, for each $v \in V(G)$, let $ol_t(v,G,Z)$ be the number of neighbors of v which lie in *Z*, minus 1. If Z_1 and Z_2 are two totally dominant subsets, then $|Z_1| < |Z_2|$ happens if and only if the sum of Z_1 -overlaps is strictly less than the sum of Z_2 overlaps.

These elementary links between minimality, perfection and overlaps may fail if G is not regular. For arbitrary graphs, all sorts of behavior is possible. For graph theorists, a challenge is to specific assertions that apply to a broad family of graphs.

The following conventions will be used here.

(1a) For $k \in \mathbb{N}$, $k \ge 2$, let P_k , the *k*-path be the graph whose vertices are the numbers $1, 2, \dots, k$, and whose edges are links from *i* to i+1 for each $1 \le i < k$. There is an infinite member of this family: Interpret \mathbb{Z} as a graph in which edges consist of links from *i* to i+1 for all *i*.

(1b) Let k > 2. The graph consisting of P_k plus an edge between 1 and k called the k-cycle. It is denoted by C_k .

(1c) For G and H graphs, the product graph $G \Box H$ is defined as follows. The set of vertices $V(G \Box H)$ is $V(G) \times V(H)$. Two vertices (x_1, y_1) and (x_2, y_2) are linked by an edge if and only if

• either $x_1 = x_2$ and $y_1 y_2$ is an edge of H, or

• x_1x_2 is an edge of G and $y_1 = y_2$.

For example, for $k, n \in \mathbb{N}$, $P_k \Box P_n$ is the familiar $k \times n$ grid map. A product of a list of paths and circuits by \Box is called a grid graph.

A product of *n* copies of \mathbb{Z} corresponds to the set \mathbb{Z}^n with the "Manhatten metric" notion of the edge: two tuples (x_1, \dots, x_n) and (y_1, \dots, y_n) are linked if and only if there is an index *i* such that $|x_i - y_i| = 1$ and

 $x_i = y_i$ for all $j \neq i$.

Tiling is the route that Gravier [1] takes in computing γ_t for grid graphs. The program begins with the work by herself, Molland and Payan [2] on the tiling question. The solution generates perfectly dominant subsets on \mathbb{Z}^n . Now, finite grid graphs can be interpreted as rectangular subsets, or (for products with C_n factors) as such subsets with some "opposed" sides identified. Domination becomes a problem of refining the patterns at the edges.

Our current work exploits the abundance of perfect dominations on graphs $G = P_k \Box C_n$. A calculation with matrices leads to a lower bound on $\gamma_t(G)$ that can only be attained by a perfectly totally dominant subset. Once we classify which indices k,n admit perfect dominations, an elementary trick provides upper and lower bounds for all graphs $P_k \Box C_n$. The bounds here do not improve on the earlier work, but are almost as narrow.

Suppose *H* is a finite *r*-regular graph for some natural number *r*, and put $G = P_k \Box H$ for $k \ge 3$. Then the majority of vertices of *G* have a degree r+2. The vertices of the degree r+1 form two connected subgraphs. A crude bound for a minimal totally dominant subset of *G* is k|H|/(r+2). However, this bound is too low by a positive number times |H|.

We find a subtler minimal bound using matrices. The computation also shows that

(2a) A perfect totally dominant subset is minimal, and assumes the bound;

(2b) A minimal subset cannot have fewer members than a perfect subset; and

(2c) Unless r = 2 and n is odd, if a perfect totally dominant subset exists, then every minimal subset is perfect.

The conclusions follow from a formula which, for *Z* a totally dominant subset, determines |Z| is a sum over $v \in V(G)$ of $ol_t(v, Z, G) \cdot \omega_j$, where each ω_j is a non-zero weight associated to row j of v.

Remark. A variation on total domination is (simple) domination. A subset dominates (non-totally) if each vertex v either has a neighbor in Z or belongs to Z. A dominant subset Z is perfect (non-totally) if for each vertex v, either

(3a) $v \in Z$ and v has no neighbors in Z, or

(3b) $v \notin Z$ and v has exactly one neighbor in Z.

Our theory implies that, in this context, if a perfect dominant subset exists, it is minimal and every minimal dominant subset is perfect.

1.1. Sample Perfect Behavior

A proof of minimality has two parts: first, exhibit a subset; then prove no smaller totally dominant subset can exist. The examples here are drawn from Gravier [1].

Assume *n* is even. In this case, $P_k \Box C_n$ is bipartite.

Identify C_n with $\mathbb{Z}/n\mathbb{Z}$ in the standard way. We can "color" the vertices: we say (i, j) (where j is read mod(n)) is *black* if i + j is even and *white* if i + j is odd. Then every edge links a black vertex with a white one. If Z dominates $P_k \Box C_n$, then the set of black members of Z dominates all white vertices, and the white vertices of Z dominate all the black. Consequently, a minimal dominant subset is a disjoint union of two minimal "color" dominates all vertices of the other color. Furthermore, the "shift by 1" automorphism of $P_k \Box C_k$ identifies the sets of different colored vertices.

Figure 1 shows a pattern of vertices of one color. Provided that k is odd, this pattern will totally dominate all vertices of the opposite color.

If k is even, this pattern does not quite work. Instead, as illustrated in **Figure 2** for k = 8, one can build a pattern by taking triangular wedges of the first pattern, and pairing them with a skew reflection. The latter pattern can be repeated throughout $P_k \Box C_n$ provided that 2(k+1) divides n.

The contribution of this paper is an alternate construction of a lower bound. The bound is met for these perfect subsets. Next, using these subsets, one can establish a general upper bound for $P_{k} \Box P_{m}$ for all m.

1.2. A Tie with Perfection

Gravier [1] proves that the set Z consisting of the middle row of $P_3 \Box P_n$, for any n, is a minimal totally dominant subset. Obviously, this choice of minimal

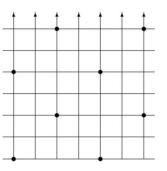


Figure 1. One color dominance, k odd.

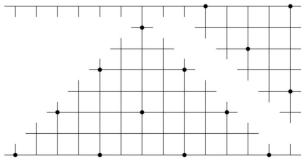


Figure 2. One color dominance, k = 8.

subset produces many overlaps. By rotating 3×3 blocks, we can produce other minimal dominant sets with fewer overlaps, as in **Figure 3**. Furthermore, if *n* is a multiple of 4, there is a variation which is a perfect total domination of $P_3 \Box C_n$, as in **Figure 4**. The flexibility in the number of vertices which are dominated by more than one member of *Z* reflects the presence of vertices of two degrees, namely 3 and 4.

In this example, the size of a minimal, imperfect totally dominant subset "ties" the size of a perfect totally dominant set. Can a minimal subset be smaller than a perfect one? We prove that a tie is rare, and that beating is impossible.

1.3. Weights

We have two sets of theorems based on series.

Definition 1 Let r be a real number. Let $\Xi[r]$ be the set of infinite sequences of real numbers $\{a_i\}_{i=0}^{\infty}$ such that

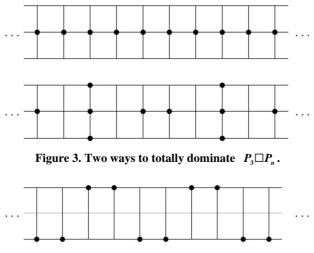
$$\forall i > 1, a_i = ra_{i-1} - a_{i-2}$$
.

Clearly, $\Xi[r]$ is a real vector space, and the function $\{a_i\}_{i=1}^{\infty} \mapsto (a_0, a_1)$ is a linear isomorphism from it onto \mathbb{R}^2 .

For r real, let $i \mapsto \lambda(r,i)$ be the unique member of $\Xi[r]$ such that $\lambda(r,0) = 0$ and $\lambda(r,1) = 1$. Observe that $\lambda(r,2) = r$.

In the opening section, we defined the overlap function $ol_t(v,G,Z)$ for totally dominant subsets *Z* of a graph *G*. In addition, for *G* a graph and *Z* a dominant (but possibly not totally) subset, and $v \in V(G)$, let ol(v,G,Z) be $ol_t(v,G,Z)$ if $v \notin Z$ and $ol_t(v,G,Z)+1$ if $v \notin Z$. For k > 3, $G = P_k \Box H$ for some graph *H* and $v \in V(G)$, define row(v) the row of *v* to be the first coordinate of *v*.

Lemma 2 Let $r, k \in \mathbb{N}$ such that $r \ge 2$ and $k \ge 3$.





$$\omega_{j} = \lambda (r, k+1) + (-1)^{j+1} \lambda (r, k+1-j) + (-1)^{k+j} \lambda (r, j).$$

For each $1 \le j \le k$,

(4a) $\omega_i \ge 0$, and

(4b) $\omega_j = 0$ if and only if r = 2, k is odd and j is even.

We refer to $\omega_1, \dots, \omega_k$ as the weight system for parameters r, k.

Definition 3 Let $r, k \in \mathbb{N}$ such that $r \ge 2$ and $k \ge 3$. Let $\omega_1, \dots, \omega_k$ be the weight system for r, k. Also, let v_1, \dots, v_k be the weight system for parameters r+1, k. Define

$$\mu(r,k) = \frac{(rk+2k+2)\lambda(r,k+1)+2\lambda(r,k)+(-1)^{k+1}2}{(r+2)^2\lambda(r,k+1)}.$$

Suppose *H* is an *r*-regular graph, and put n = |H|and $G = P_k \Box H$. Define two functions on $Z \subseteq V(G)$:

$$\operatorname{score}_{t}(Z) = \sum_{v \in V(G)} ol_{t}(v, Z, G) \cdot \omega_{\operatorname{row}(v)}$$
$$\operatorname{score}(Z) = \sum_{v \in V(G)} ol_{t}(v, Z, G) \cdot v_{\operatorname{row}(v)}$$

Theorem 4 Assume the hypothesis and construction of Lemma 2 and Definition 3. Let H be a finite graph, and put n = |H| and $G = P_k \Box H$.

(A) If $Z \subseteq V(G)$ is totally dominant, then

$$Z = n\mu(r,k) + \frac{\operatorname{score}_{r}(Z)}{(r+2)\lambda(r,k+1)}.$$

(B) If $Z \subseteq V(G)$ is dominant, then

$$|Z| = n\mu(r+1,k) + \frac{\operatorname{score}(Z)}{(r+3)\lambda(r+1,k+1)}$$

A trivial consequence of this theorem and the preceding lemma is:

Corollary 5 *Assume the hypothesis of Theorem* 4.

(A) Suppose $r \ge 3$. If Z_1, Z_2 are totally dominant subsets of G, then

$$|Z_1| < |Z_2| \Leftrightarrow \operatorname{score}_t(Z_1) < \operatorname{score}_t(Z_2).$$

(B) If
$$Z_1, Z_2$$
 are dominant subsets of G , then
 $|Z_1| \le |Z_2| \Leftrightarrow \operatorname{score}(Z_1) \le \operatorname{score}(Z_2).$

2. Modeled with Matrices

Our results are based on a simple linear algebra model. For convenience,

(5) For $k \in \mathbb{N}$, let $\operatorname{Ind}(k) = \{1, \dots, k\}$.

Notation 6. Let $k \in \mathbb{N}$. We identify the real vector space \mathbb{R}^k with length k column vectors. We use trans-

pose notation to write these horizontally:

$$(z_1, \cdots, z_k)^{\mathrm{T}}$$
 for $\begin{bmatrix} z_1 \\ \vdots \\ z_k \end{bmatrix}$

For each $1 \le i \le k$, let π_i be the projection function from each vector (z_1, \dots, z_k) to its *i*-coordinate z_i . Also define a linear functional $\mathbb{R}^k \to \mathbb{R}$

k

$$sum(z) = \sum_{i=1}^{n} \pi_i(z).$$

We denote the zero vector by $\hat{0}$.

In what follows, let $k, r \in \mathbb{N}$, and let *H* be a finite, *r*-regular graph. Put $G = P_k \Box H$.

For $Z \subseteq V(G)$, define the row count vector z for Z to be $(z_1, \dots, z_k)^T$ in which z_i is the number of members of Z in the *i*-th row. Obviously, sum(z) = |Z|.

Now suppose $Z \subseteq V(G)$ totally dominates, and let $z = (z_1, \dots, z_k)$ be its row count vector. Let $1 \le i \le k$. The sum of $ol_t(v, Z, G)$ over all v in the *i*-th row, plus |H|, equals

$$rz_{1} + z_{2}, for i = 1, z_{i} + rz_{i+1} + z_{i+1}, for 1 \le i \le k - 1, and (6) z_{k-1} + rz_{k}, for i = k.$$

In particular,

(7a) If Z totally dominates, then each of these expressions must be $\geq |H|$, and

(7b) If Z perfectly totally dominates, then each of these expressions must equal |H|.

If we replace *totally domination* with simple *domination*, the analogous assertions hold after the r terms in (6) are changed to r+1.

These remarks motivate our next definition.

Definition 7 Let r be a real number and let k be a natural number >1. Define L[r,k] to be the $k \times k$ matrix such that

$$\forall i, j \in \operatorname{Ind}(k), L[r,k]_{i,j} = \begin{cases} r & \text{if } i = j, \\ 1 & \text{if } i - j \text{ is } 1 \text{ or } -1, \\ 0 & \text{otherwise.} \end{cases}$$

Note that L[r,k] is symmetric.

Also, for these parameters, define M[r,k] to be the $k \times k$ matrix such that

$$\begin{aligned} \forall i, j \in \mathrm{Ind}(k), \\ M\left[r,k\right]_{i,j} &= \begin{cases} \lambda(-r,i)\lambda(-r,k+1-j) & \text{if } i \leq j, \\ \lambda(-r,j)\lambda(-r,k+1-i) & \text{if } j \leq i. \end{cases} \end{aligned}$$

Note that the case i = j is covered in both parts of this conditional definition.

As we shall see, the matrix M[r,k] is essentially

 $L[r,k]^{-1}$.

3. Relevant Sequences

There is a discrete analogy to *convexity* for functions of a single real variable. We recall some basics.

Definition 8 Let $\{a_i\}_{i=0}^{\infty}$ be a sequence of real numbers, starting at index 0. We say that the sequence is convex if

$$\forall i \in \mathbb{N}, a_{i+1} - a_i \ge a_i - a_{i-1}.$$

We say the sequence is strictly convex if

 $a_{i+1} - a_i > a_i - a_{i-1}$ for each *i*.

Lemma 9 Let $\{a_i\}_{i=0}^{\infty}$ be a convex sequence. For $u, v \in \mathbb{N}$,

$$a_{u+v} \ge a_u + a_v - a_0$$

Moreover, $a_{u+v} = a_u + a_v - a_0$ if and only if there is a number t such that

$$\forall i \in \operatorname{Ind}(u+v), a_i = t + a_{i-1}.$$

Proof. We may interchange u and v without loss of generality. Hence, assume $u \ge v$. For each $i \in \mathbb{N}$, put $b_i = a_i - a_{i-1}$. Then $\{b_i\}_{i=1}^{\infty}$ is a weakly increasing sequence. Then

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$$a_{u+v} - a_{0} - (a_{u} - a_{0}) - (a_{v} - a_{0})$$

$$= \left(\sum_{i=1}^{u+v} b_{i}\right) - \left(\sum_{i=1}^{u} b_{i}\right) - \left(\sum_{i=1}^{v} b_{i}\right)$$

$$\Leftrightarrow a_{u+v} - a_{u} - a_{v} + a_{0} = \left(\sum_{i=1}^{v} b_{u+i}\right) - \left(\sum_{i=1}^{v} b_{i}\right)$$

$$\Leftrightarrow a_{u+v} - a_{u} - a_{v} + a_{0} = \left(\sum_{i=1}^{v} b_{u+v+1-i}\right) - \left(\sum_{i=1}^{v} b_{i}\right)$$

$$\Leftrightarrow a_{u+v} - a_{u} - a_{v} + a_{0} = \left(\sum_{i=1}^{v} (b_{u+v+1-i} - b_{i})\right)$$

$$\Rightarrow a_{u+v} - a_{u} - a_{v} + a_{0} = \left(\sum_{i=1}^{v} (b_{u+v+1-i} - b_{i})\right)$$

Observe that

$$u+v+1-i\geq i \iff (u-v)+2(v-i)+1\geq 0.$$

For each index *i* in the last sum, the term has the format $b_p - b_q$ where p > q. Therefore

$$a_{u+v} - a_u - a_v + a_0 \ge 0.$$

Now suppose $a_{u+v} - a_u - a_v + a_0 = 0$. Then every term in the final sum of (8) must be 0. When i = 1, we get $b_{u+v} - b_1 = 0$. Since b_i is an increasing sequence, it follows that $b_i = b_1$ for every index $i \le u + v$. \Box

We focus on the sequences $\lambda(r,i)$ of Definition 1. The first remark is that the sign can be separated from the magnitude.

Lemma 10 Let r be a real number. Then

$$\forall i \in \mathbb{N}, \ \left(-1\right)^{i+1} \lambda(r,i) = \lambda(-r,i).$$

Proof. Trivial.

Many of the positive sequences $\lambda(r,i)$ are convex.

Lemma 11 Each member of $\Xi[2]$ is a linear sequence.

Proof. Trivial.

Lemma 12 Let r > 2, and let $\{b_i\} \in \Xi[r]$ such that $b_1 \ge b_0 \ge 0$. If $b_1 > 0$, then $\{b_i\}$ is increasing and strictly convex. Furthermore, $b_i = b_{i-1}$ can occur only if i = 1.

Proof. For $i \ge 2$, we can rewrite the relation $b_i = rb_{i-1} - b_{i-2}$ as

 $(9a) b_i = (r-2)b_{i-1} + b_{i-1} + (b_{i-1} - b_{i-2})$, and

(9b) $(b_i - b_{i-1}) = (r-2)b_{i-1} + (b_{i-1} - b_{i-2})$.

Use the two identities to induct on the double hypothesis that both

$$b_i > b_{i-1} > 0$$
 and $(b_i - b_{i-1}) > (b_{i-1} - b_{i-2}) > 0$.

Corollary 13 Let $r \in \mathbb{R}$ and $k \in \mathbb{N}$ such that $|r| \ge 2$. Then $\lambda(r,k) \ne 0$.

Proof. This is an easy consequence of this lemma and Lemma 10.

The next two propositions play roles in our analysis.

Lemma 14 Let r be a real number other than 2. For $k \ge 1$,

$$\sum_{i=1}^{k} \lambda(r,i) = \frac{\lambda(r,k+1) - \lambda(r,k) - 1}{r-2}.$$
 (10)

Proof. In what follows, a sum from any integer m to m-1 is defined to be 0. For this proof, we abbreviate $\lambda(k)$ for $\lambda(r,k)$.

For each $k \in \mathbb{N} \cup \{0\}$, define

$$s_k = \sum_{i=0}^k \lambda(r,i).$$

Then for $k \ge 2$,

$$\begin{split} s_k &= \lambda(0) + \lambda(1) + \sum_{i=2}^{k} \left[r\lambda(i-1) - \lambda(i-2) \right] \\ &= 1 + r \cdot \left(\sum_{j=1}^{k-1} \lambda(j) \right) - \sum_{j=0}^{k-2} \lambda(j) \\ &= 1 + r \cdot s_{k-1} - s_{k-2} \,. \end{split}$$

Define a new sequence by $t_i = s_i + \frac{1}{r-2}$. Replace

 $s_i = t_i - \frac{1}{r-2}$ into the previous relation to get

$$\forall k \geq 2, \ t_k = r \cdot t_{k-1} - t_k \ .$$

Hence, $\{t_i\}$ belongs to $\Xi[r]$. Now

$$t_0 = s_0 + \frac{1}{r-2} = \frac{1}{r-2}$$

$$t_1 = s_1 + \frac{1}{r-2} = \frac{r-1}{r-2}.$$

In the vector space \mathbb{R}^2 ,

$$\left(\frac{1}{r-2},\frac{r-1}{r-2}\right) = \frac{1}{r-2}(1,r) - \frac{1}{r-2}(0,1)$$

The sequences t_i and

$$i \mapsto \frac{1}{r-2}\lambda(i+1) - \frac{1}{r-2}\lambda(i)$$

both belong to $\Xi[r]$, and agree on the first two indices. Hence, they are the same sequence. This gives the equality of (10).

Lemma 15 Let r be a real number, and let $j,k \in \mathbb{N}$ such that $k \ge j$. Then

$$\lambda(r,k+1) = \lambda(r,j)\lambda(r,k+2-j)$$
$$-\lambda(r,j-1)\lambda(r,k+1-j)$$

Proof. We write $\lambda(i)$ for $\lambda(r,i)$ in this argument. If k = j, then $\lambda(k+2-j) = \lambda(2) = r$,

 $\lambda(k+1-j) = \lambda(1) = 1$, and the result follows from the recursive definition.

The remaining cases follow from a proof is by induction on j. The inductive hypothesis is

$$\forall k > j, \\ \lambda(k+1) = \lambda(j)\lambda(k+2-j) - \lambda(j-1)\lambda(k+1-j).$$

For j = 1, this follows from the fact that $\lambda(1) = 1$ and $\lambda(0) = 0$.

Assume $j \in \mathbb{N}$ for which the inductive hypothesis is true. Let $k \in \mathbb{N}$ so k > j+1. Then

$$\begin{split} \lambda(j+1)\lambda(k+2-(j+1)) &-\lambda(j)\lambda(k+1-(j+1)) \\ &= \left[r\lambda(j) - \lambda(j-1) \right] \lambda(k+1-j) - \lambda(j)\lambda(k-j) \\ &= r\lambda(j)\lambda(k+1-j) - \lambda(j)\lambda(k-j) \\ &-\lambda(j-1)\lambda(k+1-j) \\ &= \lambda(j) \left[r\lambda(k+1-j) - \lambda(k-j) \right] - \lambda(j-1)\lambda(k+1-j) \\ &= \lambda(j)\lambda(k+2-j) - \lambda(j-1)\lambda(k+1-j) \\ &= \lambda(k+1). \end{split}$$

4. The Inverse Matrices

We can now prove

Lemma 16 Let $k \in \mathbb{N}$ and $r \in \mathbb{R}$. The matric product $L[r,k] \cdot M[r,k]$ is $-\lambda(-r,k+1)$ times the identity matrix.

Proof. For this argument, let L = L[r, k] and

M = M[r,k] and, for each $i \in \mathbb{N} \cup \{0\}$, let

 $\lambda(i) = \lambda(-r, i)$. Let $u, v \in \text{Ind}(k)$. We prove the lemma by comparing the u, v entry of $L \cdot M$ and $-\lambda(k+1)$ times the u, v entry of the identity matrix. There are a lot of cases.

Case u = 1. For any $v \in \text{Ind}(k)$,

$$(L \cdot M)_{1v} = 2M_{1v} + M_{2v}$$

Suppose v = 1. Recall that $\lambda(1) = 1$. Therefore

$$rM_{1,1} + M_{2,1} = r\lambda(k) + \lambda(k-1) = -\lambda(k+1).$$

Suppose $v \neq 1$. Recall that $\lambda(2) = -r$. Then $v \ge 2$, and

$$rM_{1,v} + M_{2,v} = r\lambda(k+1-v) + (-r)\lambda(k+1-v) = 0.$$

Case u = k. For any $v \in \text{Ind}(k)$,

$$\left(L\cdot M\right)_{k,\nu}=M_{k-1,\nu}+rM_{k,\nu}.$$

If v = k, this is

$$\lambda(k-1)\lambda(1) + r\lambda(k)\lambda(1)$$

= $\lambda(k-1) + r\lambda(k) = -\lambda(k+1)$.

Now suppose $v \neq k$. Then $v \leq k-1$, and

$$(L \cdot M)_{k,v} = \lambda(v)\lambda(2) + r\lambda(v)\lambda(1)$$
$$= \lambda(v)(-r+r) = 0.$$

Case $1 \le u \le k$. For any $v \in \text{Ind}(k)$,

$$(L \cdot M)_{u,v} = M_{u-1,v} + rM_{r,v} + M_{r+1,v}$$
.

There are three subcases here. First, suppose $v \le u - 1$. Then

$$(L \cdot M)_{u,v}$$

= $\lambda(v)\lambda(k+1-(u-1))+r\lambda(v)\lambda(k+1-u)$
+ $\lambda(v)\lambda(k+1-(u+1))$
= $\lambda(v)(\lambda(k+2-u)+r\lambda(k+1-u)+\lambda(k-u))$

The recursive definition states that

 $\lambda(k+2-u) = -r\lambda(k+1-u) - \lambda(k-u)$. Hence, the expression equals 0.

Next, suppose $v \ge u+1$. Then

$$\begin{split} & \left(L \cdot M\right)_{u,v} \\ &= \lambda \left(u - 1\right) \lambda \left(k + 1 - v\right) + r \lambda \left(u\right) \lambda \left(k + 1 - v\right) \\ &+ \lambda \left(u + 1\right) \lambda \left(k + 1 - v\right) \\ &= \lambda \left(k + 1 - v\right) \left(\lambda \left(u - 1\right) + r \lambda \left(u\right) + \lambda \left(u + 1\right)\right). \end{split}$$

Again, the recursive definition implies that this expression is 0.

There remains only the subcase u = v.

$$(L \cdot M)_{u,u}$$

= $\lambda (u-1)\lambda (k+1-u) + r\lambda (u)\lambda (k+1-u)$
+ $\lambda (u)\lambda (k-u)$
= $\lambda (u-1)\lambda (k+1-u)$
+ $\lambda (u) [r\lambda (k+1-u) + \lambda (k-u)]$
= $\lambda (u-1)\lambda (k+1-u) - \lambda (u)\lambda (k+2-u).$

By Lemma 15, this equals $-\lambda(k+1)$. **Lemma 17** Let $k \in \mathbb{N}$, $r \in \mathbb{R}$ and $j \in \text{Ind}(k)$. Assume $r \neq -2$. Then

$$\sum_{i=1}^{k} M\left[r,k\right]_{i,j} = \sum_{i=1}^{k} M\left[r,k\right]_{j,i}$$

equals

$$\frac{\lambda(-r,k+1-j)+\lambda(-r,j)-\lambda(-r,k+1)}{r+2}$$

Proof. Put M = M[r,k] and, for each index i, $\lambda(i) = \lambda(-r,i)$. Split the sum from i = 1 to k of $M_{i,j}$ at index j:

$$\sum_{i=1}^{k} M_{i,j} = \sum_{i=1}^{j} \lambda(i) \lambda(k+1-j) + \sum_{i=j+1}^{k} \lambda(j) \lambda(k+1-i)$$
$$= \lambda(k+1-j) \sum_{i=1}^{j} \lambda(i) + \lambda(j) \sum_{i=j+1}^{k} \lambda(k+1-i)$$

In the previous line, the first sum is determined by Lemma 14. Recall the parameter is -r, not r

$$\lambda(k+1-j)\sum_{i=1}^{j}\lambda(i) = \frac{\lambda(k+1-j)}{-r-2} (\lambda(j+1)-\lambda(j)-1)$$
$$= \frac{\lambda(k+1-j)}{r+2} (\lambda(j)-\lambda(j+1)+1)$$

In the second sum, change index to p = k + 1 - i. One can use the same Lemma.

$$\lambda(j) \sum_{i=j+1}^{k} \lambda(k+1-i)$$
$$= \lambda(j) \sum_{p=1}^{k-j} \lambda(p)$$
$$= \frac{\lambda(j)}{r+2} (\lambda(k-j) - \lambda(k+1-j) + 1)$$

Add the two terms to get

$$\begin{split} &\sum_{i=1}^{k} M_{i,j} \\ &= \frac{1}{r+2} \Big(\lambda \big(k+1-j \big) \lambda \big(j \big) - \lambda \big(k+1-j \big) \lambda \big(j+1 \big) \\ &+ \lambda \big(k+1-j \big) + \lambda \big(j \big) \lambda \big(k-j \big) \\ &- \lambda \big(j \big) \lambda \big(k+1-j \big) + \lambda \big(j \big) \Big) \\ &= \frac{1}{r+2} \Big(\lambda \big(j \big) \lambda \big(k-j \big) - \lambda \big(k+1-j \big) \lambda \big(j+1 \big) \big) \\ &+ \lambda \big(k+1-j \big) + \lambda \big(j \big) \end{split}$$

By Lemma 15, this is the stated formula.

At last, we introduce weights. Define ω_j as in the statement of Lemma 2.

Corollary 18 Let $k \in \mathbb{N}$, $r \in \mathbb{R}$. Assume $r \ge 2$, and let $\{\omega_i\}$ be the weight system for r, k.

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(A) If r = 2 and k is odd and j is even, then $\omega_j = 0$.

(B) If r = 2 and either k is even or j is odd, then $\omega_j > 0$.

(C) If r > 2, then $\omega_j > 0$.

(D) Let $x \in \mathbb{R}^n$. Expand $L[r,k] \cdot x$ as $(b_1, \dots, b_n)^T$. Then

$$sum(x) = \frac{1}{(r+2)\lambda(r,k+1)} \sum_{j=1}^{k} \omega_j \cdot b_j.$$
(11)

Proof. We start with Part (D), as that is our motivation. Given

$$x = (x_1, \dots, x_n)$$
 and $b = L[r, k] \cdot x = (b_1, \dots, b_k)$,

it follows that

$$x = L[r,k]^{-1}b$$

By Lemma 16, for each $1 \le i \le k$,

$$x_i = \frac{1}{-\lambda(-r,k+1)} \sum_{j=1}^k M[r,k]_{i,j} b_j.$$

From Lemma 17,

sum(x)

$$= \frac{1}{-\lambda(-r,k+1)} \sum_{i,j} M[r,k] \cdot b_j$$
$$= \sum_{j=1}^k \frac{\lambda(-r,k+1) - \lambda(-r,k+1-j) - \lambda(-r,j)}{(r+2)\lambda(-r,k+1)} \cdot b_j$$

Now replace each $\lambda(-r,i)$ by $(-1)^{i+1}\lambda(r,i)$. The b_j -coefficient becomes $\omega_j/((r+2)\lambda(r,k+1))$.

Recall Lemma 12. Then $\{\lambda(r,i)\}_i$ is a non-negative and convex sequence, and $\lambda(r,0) = 0$. Convexity implies that

$$\lambda(r,k+1)+(-1)^{j+1}\lambda(r,k+1-j)+(-1)^{k+j}\lambda(r,j)$$

is positive unless

(12a) j+1 and k+j are both odd, and

(12b) $\{\lambda(r,i)\}$ is not strictly convex.

This remark establishes all our conclusions except in the case when r = 2, k is odd and j is even. Assume these parameters, and we know $\lambda(2,i) = i$ for all i, and (A) follows.

This corollary proves Lemma 2.

Corollary 19 Let $k \in \mathbb{N}$, $r \in \mathbb{R}$. Assume $r \ge 2$, and let $\{\omega_j\}$ be the overlap weights for (k,r). Let $\hat{1}$ be the vector in which every entry is 1, that is $(1,1,\dots,1)$. Then

$$sum(L[r,k]^{-1}\cdot\hat{1}) = \mu(r,k),$$

where $\mu(r,k)$ is defined in Definition 3.

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Proof. The easiest way is to get this formula is

(13a) Start with the formulas in Lemma 17;

(13b) Sum the terms over j using Lemma 14; and

(13c) Convert all $\lambda(-r,i)$ to $(-1)^{i+1}\lambda(r,i)$.

The observation of (6) completes the proof of all the propositions in Section 1.3.

5. When *r* = 2

The numerical calculations allow us to add some secondary comments on the examples of Sections and 1.1 and 1.2. Fix r = 2, and put L = L[2,k]. Then $\lambda(2,i) = i$ for all indices i. If Z is a perfect totally dominant subset of $P_k \Box C_n$ and z is its row-count vector, then $L \cdot z = n\hat{1}$.

If
$$k$$
 is odd,

$$L^{-1}(n\hat{1}) = (n/2, 0, n/2, 0, \dots, n/2).$$

Consequently, a perfect totally dominant subset cannot exist if *n* is odd. However, since $\omega_j = 0$ for *j* even, there may be totally dominant subsets whose size "ties" the estimate for a perfect subset. In the case k = 3, the set consisting of the middle row has row-count (0,n,0). Its image under *L* is (n,3n,n).

If k is even, the *i*-th coordiante of $L^{-1} \cdot (n\hat{1})$ is

$$\frac{n}{2(k+1)} \quad \text{times} \begin{cases} k+1-i & \text{if } i \text{ is odd,} \\ i & \text{if } i \text{ is even.} \end{cases}$$

The entries are integral if and only if k+1 divides *n*. Unlike the case when *k* is odd, $sum(L^{-1}(n\hat{1}))$ cannot be matched by the size of an imperfect dominant subset.

Near Perfect

Now

$$\mu(2,k) = \begin{cases} \frac{2k^2 + 4k}{8(k+1)} & \text{if } k \text{ is even,} \\ \frac{k+1}{4} & \text{if } k \text{ is odd.} \end{cases}$$

Proposition 20 For $k, n \ge 4$,

- $\mu(2,k)n \le \gamma_t \left(P_k \Box P_n\right) \le \mu(2,k)(n+2).$ **Proof.** There is $d \in \mathbb{N}$ and $Z \subseteq P_k \Box C_d$ such that
 - (14a) n+2 divides d,
 - (14b) Z is a totally dominant subset of $P_k \Box C_d$,
- (14c) $|Z| = \mu(2,k)d$.

Partition $P_k \Box C_m$ into subsets Y_1, \dots, Y_m where each Y_i consists of n+2 successive columns. For at least one index i, $|Y_i \cap Z| \le \mu(2,k)(n+2)$. Choose such an index. Identify $P_k \Box P_n$ with Y', the subgraph of columns 2 through n+1 of Y_i . Let $Z_1 = Z \cap Y'$. Any member of Y' which is not dominated by Z_1 is dominated by exactly one member of Z in either the 1st or

n+2 column; furthermore, each member of either column dominates just one member of Y'. Consequently, we can expand Z_1 to a totally dominant Z_2 for Y' of size $\leq |Y_i \cap Z|$.

6. Extended Functigraphs

Our lower bound uses only a few aspects of the graphs $P_k \Box H$. Consequently, the calculation applies to a slightly larger family of graphs.

Fix $k, r, n \in \mathbb{N}$ with n, k, r > 2. Let H_1, \dots, H_k be a list of *r*-regular graphs, each with *n* vertices. For each $1 \le i < k$, let $h_i : V(H_i) \to V(H_{i+1})$ be a bijection. Define the *extended functigraph* on this data to be *G* in which

(15a) V(G) is the (disjoint) union $\bigcup_{i=1}^{k} V(H_i)$, and

(15b)
$$E(G)$$
 is union of $\bigcup_{i=1}^{k} E(H_i)$ with
 $\{vh_i(v): 1 \le i \le k \land v \in V(H_i)\}.$

Then the assertions of Theorem 4, and its Corollary, apply to G.

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