

# **Union Resolution Performance of Frequency Modulation Parameter Based on RWT for LFM Signals**

Wenchen Li<sup>1</sup>, Huimin Yang<sup>1</sup>, Hong Li<sup>1</sup>, Mei Dan<sup>2</sup>, Xuesong Wang<sup>2</sup>, Shunping Xiao<sup>2</sup>

<sup>1</sup>National Major Laboratory of Complex Electromagnetic Environmental Effects for Electronic Information System, Luoyang, China; <sup>2</sup>School of Electronic Science and Engineering, National University of Defense Technology, Changsha, China. Email: leewench@yahoo.com.cn

Received July 22<sup>nd</sup>, 2012; revised August 24<sup>th</sup>, 2012; accepted September 7<sup>th</sup>, 2012

#### **ABSTRACT**

Union resolution performance of FM (frequency modulation) parameter based on Radon-Wigner transform (RWT) for multi-component LFM (linear frequency modulation) signals is studied. Firstly, the RWT output expression is offered, and the independent resolution performances of initial frequency and chirp rate are analyzed. Secondly, the RWT output approximate analytic expression is given based on quadratic Taylor's series expansion, and the contour property is analyzed. Contour can be used to picture the union resolution performance of FM parameter, and 2-D resolution performance is studied based on approximate analytic expression, and the union resolution expression of FM parameter and resolution ellipse are offered. The simulation results validate the union resolution expression, and show that the union resolution can improve the resolution performance of multi-component LFM signals, contrasted with absolute resolution performance. The paper can help the study of LFM parameter estimation and resolution performance.

**Keywords:** Multi-Component LFM Signals; Radon-Wigner Transform (RWT); Resolution Ellipse; Union Resolution of FM Parameter; Half-Power Lobe Width

#### 1. Introduction

The LFM signal is widely applied in domains such as radar, correspondence and sound navigation. LFM signal's parameter estimation is an important research subject in the electronic intelligence system, target motive parameter estimation and ISAR image. There are many literatures about LFM signal parameter estimation method, such as estimation performance, the operating speed and the application, for example ML (Maximum Likelihood) method [1], polynomial phase transform (PPT) [2,3], Radon-Wigner transform (RWT) or the Wigner-Hough transform (WHT) [4-6], Radon-Ambiguity transform (RAT) [7,8], Fractional Fourier transform (FrFT) [9]. RWT or WHT are the commonly used LFM signal parameter estimation methods. RWT method searches the straight line in the Wigner-Ville time-frequency distribution plane. The cross term can be suppressed effectively through the line integral in RWT, which is used to estimate the initial frequency and chirp rate of LFM signals, ulteriorly, the amplitude and phase information can be estimated.

The research of RWT resolution for LFM signal is the foundation for multi-component signal separation. And there are quite a few literatures about the RWT resolution. Simulation results in literature [8] show that the RAT

chirp rate resolution is  $1.5/T^2$  and  $1.4/T^2$  for the square-law and enveloping ambiguity respectively. Literature [10] defines the nominal resolution with the main lobe of 3 dB width (half-power width), Literature [11] indicates the range-velocity union resolution with the ambiguity diagram's 3/4 interception area. In summary, the resolution definition is disparate in different literatures, and the nominal resolution can reflect the resolution performance on a certain extent, but not accurately.

The unite resolution of RWT FM parameter (initial frequency and chirp rate) for the multi-component signal is related with SNR (signal to noise ratio), signal form and processing method. Generally the system resolution performance is analyzed under the condition of great SNR and best signal processing, therefore this article analyzes the RWT resolution performance for signal with great SNR. Firstly, the RWT output expression is given, and the independent resolutions of initial frequency and chirp rate are analyzed. Secondly, the RWT output approximate analytic expression is given by Taylor series expansion. The contour line nature is analyzed and the contour line deviation caused by approximation in Taylor expansion is revised. The contour line and two-dimensional resolution have been studied based on the analytic expression. The mathematical expression of FM parame-

ter union resolution and the resolution ellipse area are obtained. Finally, the simulation results indicate that the union resolution of FM parameter is higher than independent resolution.

#### 2. RWT FM Parameter Estimation

#### 2.1. LFM Signal Model

Single LFM signal model is expressed by:

$$x(t) = A \exp \left[ j \left( a_0 + a_1 t + a_2 t^2 \right) \right] + n(t)$$
 (1)

where  $0 \le t \le T$ ,  $A, a_0, a_1, a_2$  are the signal scope, the phase, the initial angular frequency (or initial frequency) and the angle FM rate (or chirp rate) respectively. n(t) is gauss white noise, whose mean is zero and variance is  $\sigma^2$ .

### 2.2. RWT of LFM Signal

The essence of Radon transformation is to transform the straight line to the point in plane through the rotation axis projection integral, and a point coordinate corresponds the straight line slope and the slant range, then the detection and estimation are carried in this parameter spatial domain. RWT method transform the LFM signal from the time domain to the parameter spatial domain including the initial frequency and the FM rate.

The Wigner-Ville distribution [5] of x(t) is

$$W_{x}(t,\omega) = \int_{-\infty}^{\infty} x \left(t + \frac{\tau}{2}\right) x^{*} \left(t - \frac{\tau}{2}\right) \exp(-j\omega\tau) d\tau \qquad (2)$$

LFM signal chirp rate  $K = \tan \phi = 2a_2$ ,  $\omega$  axis intercept  $h = a_1$ , viz. initial frequency of t = 0.

According to the Wigner-Ville distribution characteristic of LFM signal, Radon straight line integral transformation is expressed by the straight line slope K and the axis intercept h, the integral is done along the line  $\omega = Kt + h$ . Then the signal is transformed from time domain to the parameter spatial domain composed by initial frequency h and chirp rate K. The scheme of Radon transformation is shown in **Figure 1**. The RWT formula is expressed by:

$$RW(K,h) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} W(t,\omega) \delta[\omega - (Kt+h)] dt d\omega$$

$$= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x \left(t + \frac{\tau}{2}\right) x^* \left(t - \frac{\tau}{2}\right) \exp[-j(Kt+h)\tau] dt d\tau$$
(3)

Using the integration variable replacement [12], the formula can be transformed into:

$$RW(K,h) = \left| \int_{-\infty}^{\infty} x(t) \exp\left[ -j\left(0.5Kt^2 + ht\right) \right] dt \right|^2$$
 (4)

Namely the two-dimensional integral of RWT modeling can be transformed to the power spectrum estimation

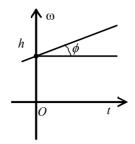


Figure 1. Scheme of radon transform.

of the time domain dechirp signal [13]. And the best estimation of K,h may be determined by the maximum value position of RW(K,h), and obtain the estimation value  $\hat{a}_1,\hat{a}_2$  of  $a_1,a_2$  by the K,h parameter estimation.

# 3. RWT Resolution of Initial Frequency and Chirp Rate

From formula (4), the RWT output of the noise-free LFM signal model x(t) is expressed by:

$$RW(K,h) = A^2 T^2 F_{\text{RWT}}(K,h)$$
 (5)

where

$$F_{\text{RWT}}(K,h) = \begin{cases} \left| \sin c \left( \frac{(a_1 - h)T}{2} \right) \right|^2, & 2a_2 - K = 0 \\ F(\eta, \xi), & 2a_2 - K \neq 0 \end{cases}$$
 (6)

$$F(\eta, \xi) = \frac{\left| F_{\text{exp}}(\eta) - F_{\text{exp}}(\xi) \right|^2}{(\eta - \xi)^2}$$
 (7)

$$F_{\rm exp}(y) = \int_0^y \exp\left\{j\frac{\pi}{2}x^2\right\} dx \tag{8}$$

$$\begin{cases} \eta = \left(T + \frac{a_1 - h}{2a_2 - K}\right) \sqrt{\frac{|2a_2 - K|}{\pi}} \\ \xi = \frac{a_1 - h}{2a_2 - K} \sqrt{\frac{|2a_2 - K|}{\pi}} \end{cases}$$
(9)

where  $F_{\rm exp}(y) = F_{\rm cos}(y) + jF_{\rm sin}(y)$ ,  $F_{\rm cos}(y)$  is Fresnel cosine integral and  $F_{\rm sin}(y)$  is Fresnel sine integral [12].  $\max \left[RW(K,h)\right] = A^2T^2$  when  $h = a_1$ ,  $K = 2a_2$ . The half-power lobe width of the RWT output function, that is  $F_{\rm RWT}(K,h)^2 = 1/2$ , is shown in **Figure 2**.

• When  $a_2 - 0.5K = 0$ 

 $\Delta x_{3dB} = 2.0038$  is obtained via interpolation method from  $\left|\sin c(x)\right|^4 = 1/2$  in **Figure 2(a)**. The half-power lobe width of h is:

$$\Delta h_{3dB} = 2\frac{2}{T} \frac{\Delta x_{3dB}}{2} = \frac{4.0076}{T} \tag{10}$$

• When  $a_1 - h = 0$ 

Using  $F_{\text{exp}}(0) = 0$ , obtains:

$$RW(K,h) = A^2 T^2 F(\eta,0) = A^2 T^2 |F_{\exp}(\eta)|^2 / \eta^2$$
 (11)

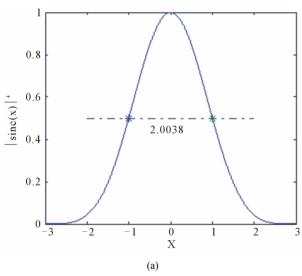
where  $\eta = T\sqrt{|2a_2 - K|/\pi}$ .  $\Delta \eta_{3dB} = 2.2290$  is obtained via interpolation method from  $F(\eta,0)^2 = 1/2$  in **Figure 2(b)**. The half-power lobe width of K is:

$$\Delta K_{3dB} = \frac{2\pi}{T^2} \left(\frac{\Delta \eta_{3dB}}{2}\right)^2 = \frac{7.8047}{T^2}$$
 (12)

# 4. Taylor Formula and Character of the RWT Function

### 4.1. Taylor Formula of the RWT Function

The RWT function's main lobe reflects the RWT union resolution of initial frequency and chirp rate. In order to



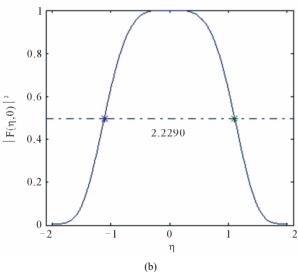


Figure 2. Tangential plane of RWT function. (a)  $\left|\sin c(x)\right|^4 = 1/2$ ; (b)  $F(\eta, 0)^2 = 1/2$ .

obtain the main lobe analytic expression in the different high, the RWT function is indicated with the quadratic Taylor series expansion on the point with maximum value, which is  $h = a_1$  and  $K = 2a_2$ . The Taylor expansion of  $F_{\rm RWT}(K,h)$  is quite complex, so this article directly calculates the quadratic Taylor series of RWT output on the maximum value using the expression of RW(K,h). The quadratic Taylor formula is expressed by [12]:

$$RW(K,h) = RW(K,h) \Big|_{\substack{K=2a_2 \\ h=a_1}}$$

$$+ \frac{\partial RW(K,h)}{\partial K} \Big|_{\substack{K=2a_2 \\ h=a_1}} (K-2a_2)$$

$$+ \frac{\partial RW(K,h)}{\partial h} \Big|_{\substack{K=2a_2 \\ h=a_1}} (h-a_1)$$

$$+ \frac{1}{2} \frac{\partial^2 RW(K,h)}{\partial K^2} \Big|_{\substack{K=2a_2 \\ h=a_1}} (K-2a_2)^2$$

$$+ \frac{1}{2} \frac{\partial^2 RW(K,h)}{\partial h^2} \Big|_{\substack{K=2a_2 \\ h=a_1}} (h-a_1)^2$$

$$+ \frac{\partial^2 RW(K,h)}{\partial K \partial h} \Big|_{\substack{K=2a_2 \\ h=a_1}} (K-2a_2)(h-a_1)$$

From formula (4), when the noise-free input signal model is  $x(t) = A \exp \left[ j \left( a_0 + a_1 t + a_2 t^2 \right) \right]$ ,  $0 \le t \le T$ , the RWT function is:

$$RW(K,h) = A^2 \int_0^T \int_0^T F(h,K) dt d\tau$$
 (14)

where

$$F(h,K) = \exp\left\{j\left[(a_{1}-h)(t-\tau)+\frac{1}{2}(2a_{2}-K)(t^{2}-\tau^{2})\right]\right\}$$

$$Via F(h,K)\Big|_{K=2a_{2}\atop h=a_{1}} = 1,$$

$$\frac{\partial F(h,K)}{\partial K} = -j\frac{1}{2}(t^{2}-\tau^{2})F(h,K),$$

$$\frac{\partial F(h,K)}{\partial h} = -j(t-\tau)F(h,K),$$

$$\frac{\partial^{2}F(K,h)}{\partial h^{2}} = -(t-\tau)^{2}F(h,K),$$

$$\frac{\partial^{2}F(K,h)}{\partial K^{2}} = -\frac{1}{4}(t^{2}-\tau^{2})^{2}F(h,K),$$

$$\frac{\partial^{2}F(K,h)}{\partial K\partial h} = -\frac{1}{2}(t^{2}-\tau^{2})(t-\tau)F(h,K),$$

$$\frac{\partial^{2}F(K,h)}{\partial K\partial h} = -\frac{1}{2}(t^{2}-\tau^{2})(t-\tau)F(h,K),$$

$$(15)$$

obtains these item in formula (13) as follows:

$$RW(K,h)\Big|_{\substack{K=2a_2\\h=a_1}} = A^2T^2$$
 (16)

$$\left. \frac{\partial RW\left(K,h\right)}{\partial K} \right|_{\substack{K=2a_2\\h=a_1}} = 0 \tag{17}$$

$$\frac{\partial RW(K,h)}{\partial h}\bigg|_{\substack{K=2a_2\\h=a_1}} = 0 \tag{18}$$

$$\frac{\partial^{2} RW(K,h)}{\partial K^{2}} \bigg|_{\substack{K=2a_{2} \\ h=a_{1}}} = -\frac{2A^{2}T^{6}}{45}$$
 (19)

$$\frac{\partial^2 RW(K,h)}{\partial h^2}\bigg|_{\substack{K=2a_2\\h=a_1}} = -\frac{A^2 T^4}{6}$$
 (20)

$$\left. \frac{\partial^2 RW\left(K,h\right)}{\partial K \partial h} \right|_{\substack{K=2a_2\\h=a_1}} = -\frac{A^2 T^5}{12} \tag{21}$$

Taylor formula (13) is transformed into:

$$RW(K,h) = A^{2}T^{2} \left[ 1 - \frac{T^{4}}{45} (K - 2a_{2})^{2} - \frac{T^{2}}{12} (h - a_{1})^{2} - \frac{T^{3}}{12} (K - 2a_{2})(h - a_{1}) \right]$$
(22)

Obviously the RWT output is nonstandard quadratic surface, which can be proved to be nonstandard ellipse paraboloid.

# 4.2. The Contour Line Parameter Analysis of the Quadratic Taylor Formula

The RWT output is two-dimensional function of initial frequency and chirp rate, and the greatest value is  $A^2T^2$ . The lobe characteristic of the RWT output function is reflected by the contour line along  $\rho_{\text{contour}}A^2T^2$  and the cutting coefficient of contour line is  $0 < \rho_{\text{contour}} < 1$ . The output result is not the standard analytic expression, therefore the RWT cutting contour line is indicated by the quadratic Taylor formula, as follows:

$$RW(K,h) = \rho_{\text{contour}}RW(K,h) \bigg|_{\substack{K=2a_2\\h=a_1}}$$
 (23)

Substitutes the quadratic Taylor formula, obtains:

$$a^{2}(h-a_{1})^{2}+b^{2}(K-2a_{2})^{2}+c(h-a_{1})(K-2a_{2})=1$$
 (24) where

$$\begin{cases} a^2 = \frac{T^2}{12 \times (1 - \rho_{\text{contour}})} \\ b^2 = \frac{T^4}{45 \times (1 - \rho_{\text{contour}})} \end{cases}$$

$$c = \frac{T^3}{12 \times (1 - \rho_{\text{contour}})}$$
(25)

Using  $h = a_1, K = 2a_2$  as the center, and prescribing counterclockwise is positive, the coordinate system

$$\begin{bmatrix} h' \\ K' \end{bmatrix} = \begin{bmatrix} h - a_1 \\ K - 2a_2 \end{bmatrix}$$
 is counter-clockwise rotated with

angle  $\theta$ , and the coordinate system  $\begin{bmatrix} x \\ y \end{bmatrix}$  is obtained,

shown in **Figure 3**.

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} h - a_1 \\ K - 2a_2 \end{bmatrix}$$
 (26)

$$\begin{bmatrix} h - a_1 \\ K - 2a_2 \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$
 (27)

In the coordinate system  $\begin{bmatrix} x \\ y \end{bmatrix}$ , Equation (24) trans-

forms into:

$$a^{2} (x\cos\theta - y\sin\theta)^{2} + b^{2} (x\sin\theta + y\cos\theta)^{2} + c(x\cos\theta - y\sin\theta)(x\sin\theta + y\cos\theta) = 1$$
(28)

when the item of xy is zero, the equation is standard ellipse, and obtains

$$\tan 2\theta = \frac{c}{a^2 - b^2} = \frac{T}{1 - \frac{4}{15}T^2}$$
 (29)

And formula (28) is simplified to

$$\left(a^2 \cos^2 \theta + b^2 \sin^2 \theta + \frac{c}{2} \sin 2\theta\right) x^2 + \left(a^2 \sin^2 \theta + b^2 \cos^2 \theta - \frac{c}{2} \sin 2\theta\right) y^2 = 1$$
(30)

It can be proved that the equation coefficient is more than zero, that is

$$\left(a^2\cos^2\theta + b^2\sin^2\theta\right) \pm \frac{c}{2}\sin 2\theta > 0 \tag{31}$$

Therefore, the equation is the elliptic equation, the RWT quadratic surface is nonstandard ellipse paraboloid.

# 4.3. Contrastive Analysis of Quadratic Taylor Formula and Actual Contour Line

In order to analyze conveniently, the performance of

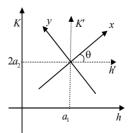


Figure 3. Coordinate system conversion.

RWT resolution is characterized by half-power lobe width in this article. The half-power lobe contour line, which is obtained by quadratic Taylor formula, is the RWT output amplitude  $\rho_{\text{contour}} = \sqrt{2}/2$ . By

 $K - 2a_2 = 0$ , the half-power lobe width of h is:

$$\Delta h'_{3dB} = \frac{2}{a} = \frac{2}{T} \sqrt{12(1 - \rho_{\text{contour}})} = \frac{3.7495}{T}$$
 (32)

By  $h - a_1 = 0$ , the half-power lobe width of K is:

$$\Delta K'_{3dB} = \frac{2}{b} = \frac{2}{T^2} \sqrt{45(1 - \rho_{\text{contour}})} = \frac{7.2609}{T^2}$$
 (33)

The result is close with the half-power lobe width  $\Delta h_{3dB} = 4.0076/T$  and  $\Delta K_{3dB} = 7.8047/T^2$ , which is obtained directly by curve simulation and interpolation. There are two main error sources: The one is abbreviate of higher item, the other is cutting departure from the spot with maximum value. The half-power lobe width of the actual RWT output can be approached by adjustment the parameter  $\rho_{\rm contour}$ , and the best revision interception coefficient  $\rho_{\rm contour}$  is:

$$\rho_{\text{contour}} = \left(\rho_{\text{contour }h} + \rho_{\text{contour }K}\right)/2 = 0.6635 \tag{34}$$

where  $\rho_{\text{contour}_h}$ ,  $\rho_{\text{contour}_K}$  are obtained separately by the half-power lobe width of h, K, the expression is expressed as follows:

$$\Delta h'_{3dB} = \frac{2}{T} \sqrt{12(1 - \rho_{\text{contour}\_h})} = \Delta h_{3dB}$$
 (35)

$$\Delta K'_{3dB} = \frac{2}{T^2} \sqrt{45(1 - \rho_{\text{contour}\_K})} = \Delta K_{3dB}$$
 (36)

Namely, when  $\rho_{\rm contour}=0.6635$ , the lobe width using the quadratic Taylor formula is able to approach the actual RWT output half-power lobe width, which is proved by the simulation result.

# 5. RWT Union Resolution of Initial Frequency and Chirp Rate

The signal resolution is analyzed usually by two signals with equi-signal length, amplitude and initial time. The multi-component signal amplitude is A, the length is T, namely a,b,c are the constants, the signal position is  $0 \le t \le T$ , the i th component signal's initial frequency is  $h_i$  and chirp rate respectively is  $K_i$  (i = 1, 2), its half-power cutting contour line is:

$$a^{2}(h-h_{i})^{2}+b^{2}(K-K_{i})^{2}+c(h-h_{i})(K-K_{i})=1$$
 (37)

This formula can be reduced to:

$$e^{2} \left[ \left( ah + bK \right) - \left( ah_{i} + bK_{i} \right) \right]^{2}$$

$$+ f^{2} \left[ \left( ah - bK \right) - \left( ah_{i} - bK_{i} \right) \right]^{2} = 1$$

$$(38)$$

where

$$\begin{cases} e^2 = \frac{1}{2} \left( 1 + \frac{c}{2ab} \right) \\ f^2 = \frac{1}{2} \left( 1 - \frac{c}{2ab} \right) \end{cases}$$

$$(39)$$

Defines

$$\begin{cases} X = e(ah + bK) \\ Y = f(ah - bK) \end{cases}$$
(40)

Obtains

$$\begin{cases} h = \frac{1}{2a} \left( \frac{X}{e} + \frac{Y}{f} \right) \\ K = \frac{1}{2b} \left( \frac{X}{e} - \frac{Y}{f} \right) \end{cases}$$
 (41)

Therefore X, Y and h, K both have corresponding relationships, formula (37) in coordinate system X, Y is circle equation.

$$\left[X - e\left(ah_i + bK_i\right)\right]^2 + \left[Y - f\left(ah_i - bK_i\right)\right]^2 = 1 \quad (42)$$

where, the circle point of the i th component signal in coordinate system X,Y is  $e(ah_i + bK_i)$ ,  $f(ah_i - bK_i)$ , and the circle track data can be generated by the circle equation, from which, we can get the corresponding contour line data h, K after the coordinate system conversion.

The two component signal's FM parameters are  $h_1, K_1$ ,  $h_2, K_2$  respectively. According to the nominal resolution, two signals can not be distinguished if half-power contour lines have the intersection point in the coordinate system h, K, otherwise two signals are distinguishable. In the coordinate system X, Y, the contour line is circle. So long as the central distances of two circles are more than 2, the two LFM signals can be distinguished. The condition is described by:

$$e^{2} \left[ a(h_{2} - h_{1}) + b(K_{2} - K_{1}) \right]^{2} + f^{2} \left[ a(h_{2} - h_{1}) - b(K_{2} - K_{1}) \right]^{2} > 4$$

$$(43)$$

Inputting  $e^2$ ,  $f^2$ , the formula can be reduced to:

$$a^{2} (h_{2} - h_{1})^{2} + b^{2} (K_{2} - K_{1})^{2} + c (h_{2} - h_{1}) (K_{2} - K_{1}) > 4$$
(44)

Inputting  $a^2, b^2, c$ , the resolution expression based on parameter is

$$\frac{T^{2}}{12} (h_{2} - h_{1})^{2} + \frac{T^{4}}{45} (K_{2} - K_{1})^{2} 
+ \frac{T^{3}}{12} (h_{2} - h_{1}) (K_{2} - K_{1}) > 4 (1 - \rho_{\text{contour}})$$
(45)

where  $\rho_{\rm contour} = 0.6635$ , and multi-component signal is able to be resolved, so long as the position of FM parameter  $h_1, K_1$ ,  $h_2, K_2$  satisfies the above equation. Obviously in order to achieve the high resolution of initial frequency and chirp rate, the time length must be increased.

The union resolution of initial frequency and chirp rate may be indicated by the interception ellipse area.

$$S = \frac{\pi}{\sqrt{a^2b^2 - c^2/4}} = (1 - \rho_{\text{contour}}) \frac{24\sqrt{15}\pi}{T^3}$$
 (46)

Obviously the resolution ellipse's area is in reverse proportion with  $T^3$ , related with the interception coefficient  $\rho_{\text{contour}}$ .

#### 6. Simulation Results

# 6.1. The RWT Output of Single Component LFM Signal

The signal model is:

$$x(t) = \exp \left[ j(1+100t+100t^2) \right]$$
 (47)

The digital simulation result is given in **Figure 4**, where  $0 \le t \le T$ , T = 1, namely a = 0.5334, b = 0.2754, c = 0.2845, and the FM parameter sampling interval is quite small in order to study the fine characteristic of RWT output. **Figure 4(a)** is the contrast of RWT half-power contour line and the Taylor's expansion contour line in  $\rho_{\text{contour}} = 0.6635$ . **Figure 4(b)** is the contour line view. It is indicated that the contour line two-dimensional superposition is very good for the two methods, therefore the RWT output half-power contour line is described well by the contour line equation in  $\rho_{\text{contour}} = 0.6635$ . The results indicate simultaneously that the FM parameter estimation error is very small for a

the FM parameter estimation error is very small for a single component noise-free LFM signal.

#### 6.2. The RWT of Multi Component LFM Signal

The signal model is:

$$x(t) = A \exp \left[ j\left(a_0 + a_1 t + a_2 t^2\right) \right] \tag{48}$$

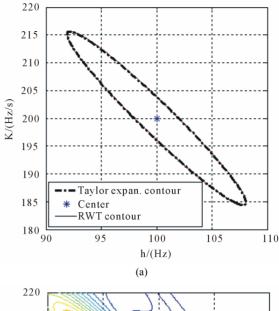
The signal length is 1s, initial frequency independent resolution is  $\Delta h_{3dB} = 4.0076$ , chirp rate independent resolution is  $\Delta K_{3dB} = 7.8047$ . The first component is:

$$x_1(t) = \exp\left[j(1+100t+100t^2)\right]$$
 (49)

The second component is:

$$x_2(t) = \exp\left[j\left(2 + (100 + dh)t + \left(100 + \frac{1}{2}dK\right)t^2\right)\right]$$
 (50)

The RWT resolution performance of two component LFM signals is studied by changing the initial frequency and chirp rate of the second component separately in



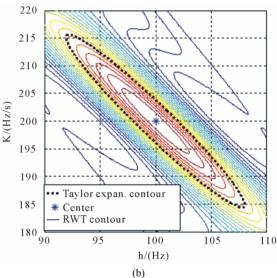


Figure 4. Contrast of Taylor formula and actual contour line of single component LFM signal. (a) Is the contrast of RWT half-power contour line and the Taylor's expansion contour line in  $\rho_{\rm contour} = 0.6635$ ; (b) Is the contour line view.

what follows.

## 6.2.1. Independent Resolution of Initial Frequency and Chirp Rate

The simulation results of initial frequency and chirp rate independent resolution are shown in **Figure 5**, including contour map and projection view. Two LFM signals with same chirp rate and different initial frequency  $(dh = \Delta h_{3dB}, dK = 0)$  are shown in **Figure 5(a)**. Two LFM signals with same initial frequency and different chirp rate  $(dh = 0, dK = \Delta K_{3dB})$  are shown in **Figure 5(b)**. Obviously in the RWT output two-dimensional surface of initial frequency and chirp rate, the mutual

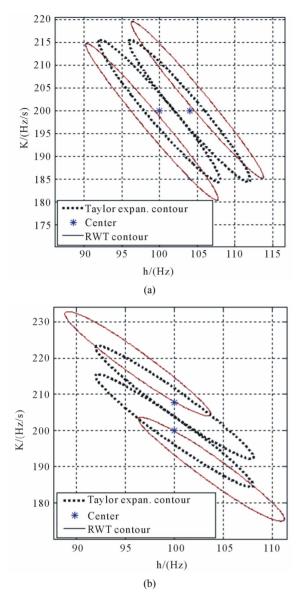


Figure 5. Contrast of Taylor formula and actual contour line of multi component LFM signal. The second component in formula (50) is (a)  $dh = \Delta h_{3dB}$ , dK = 0; (b) dh = 0,  $dK = \Delta K_{3dB}$ .

coupling of the very near two LFM signals cause the RWT output peak position to be away from the primary position, which incurs FM parameter estimation deviation. Simultaneously the further simulation results indicate that the different phase item  $a_0$  in the two LFM signals causes the different peak position errors, and the starting phase items of the two LFM signals affect the parameter estimation errors, but the LFM signals are distinguishable if the distinguishing condition is satisfied. Therefore the nominal resolution reflects the resolution performance to a certain extent. For single component LFM signal or multi-component LFM signal with the great FM parameter space interval in RWT, the RWT

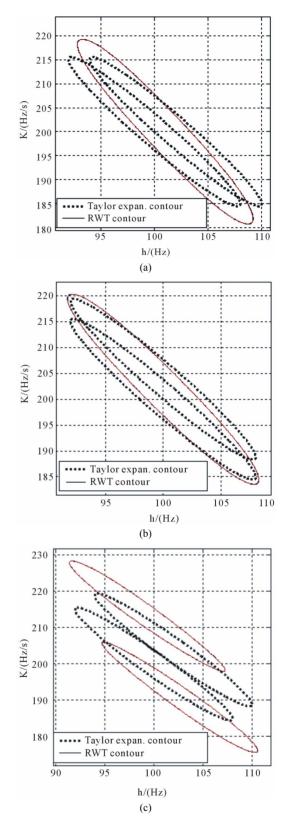


Figure 6. Union resolution of initial frequency and chirp rate of multi component LFM signal. The second component in formula (50) is (a)  $dh = \Delta h_{3dB}/2$ , dK = 0; (b) dh = 0,  $dK = \Delta K_{3dB}/2$ ; (c)  $dh = \Delta h_{3dB}/2$ ,  $dK = \Delta K_{3dB}/2$ .

parameter estimation error is related with SNR input. On the other hand, for the distinguishable multi-component LFM signal with the close FM parameter space interval, FM parameter estimation error is related with both SNR and other component signal's parameter.

# 6.2.2. Union Resolution of Initial Frequency and Chirp Rate

Union resolution of multi-component LFM signal is studied and simulation results are shown in **Figure 6**, including contour map and projection view. (a) The second component  $dh = \Delta h_{3dB}/2$ , dK = 0, and the signals cannot be distinguished by RWT method; (b) The second component dh = 0,  $dK = \Delta K_{3dB}/2$ , and the signals cannot be distinguished by RWT method; (c) The second components with the initial frequency and chirp rate are all half of independent resolution, namely  $dh = \Delta h_{3dB}/2$  and  $dK = \Delta K_{3dB}/2$ . It is obviously the two LFM signals are distinguishable by RWT method. The simulation results confirm the superiority of the FM parameter union resolution.

As to two multi-component signals with close FM parameter space, the estimation error is big when the amplitudes are similar, and the optimum parameter estimation of various components can be obtained by Relax iteration method [14]. On the other hand, if the intensity difference of two signals is distinct, the strong signal suppresses the weak signal, therefore the CLEAN technology must be used to extract the signals [15].

#### 7. Conclusion

Union resolution performance of FM parameter based on RWT for multi-component LFM signals is studied in this paper. Firstly, the RWT output expression is given, and the independent resolutions of initial frequency and chirp rate are analyzed. Secondly, the RWT output approximate analytic expression is given by Taylor series expansion. The contour line property is analyzed and the contour line is deviation, which caused by approximation in Taylor expansion, is revised. Contour can be used to picture the union resolution performance of FM parameter of RWT, and 2-D resolution performance is studied based on approximate analytic expression. The union resolution expression of FM parameter and resolution ellipse area is offered. Finally the simulation results indicate that the union resolution of FM parameter is higher than independent resolution. The research in this paper can help the study of LFM parameter estimation and resolution performance.

#### REFERENCES

T. J. Abatzoglou, "Fast Maximum Likelihood Joint Estimation of Frequency and Frequency Rate," IEEE Trans-

- actions on Aerospace and Electronic Systems, Vol. 22, No. 6, 1986, pp. 708-715.
- [2] S. Peleg and B. Porat, "Linear FM Signal Parameter Estimation from Discrete-Time Observations," *IEEE Transactions on Aerospace and Electronic Systems*, Vol. 27, No. 4, 1991, pp. 607-615. doi:10.1109/7.85033
- [3] S. Peleg and B. Porat, "Estimation and Classification of Polynomial Phase Signals," *IEEE Transactions on Information Theory*, Vol. 37, No. 2, 1991, pp. 423-430. doi:10.1109/18.75269
- [4] J. C. Wood and D. T. Barry, "Radon Transformation of Time-Frequency Distributions for Analysis of Multi-Component Signals," *IEEE Transactions on Signal Processing*, Vol. 42, No. 11, 1994, pp. 3166-3177. doi:10.1109/78.330375
- [5] J. C. Wood and D. T. Barry, "Linear Signal Synthesis Using the Radon-Wigner Transform," *IEEE Transactions* on Signal Processing, Vol. 42, No. 8, 1994, pp. 2105-2111. doi:10.1109/78.301845
- [6] S. Barbarossa, "Analysis of Multi-Component LFM Signals by a Combined Wigner-Hough Transform," *IEEE Transactions on Signal Processing*, Vol. 43, No. 6, 1995, pp. 1511-1515. doi:10.1109/78.388866
- [7] M. S. Wang, A. K. Chan and C. K. Chui, "Linear Frequency-Modulated Signal Detection Using Radon-Ambiguity Transform," *IEEE Transactions on Signal Processing*, Vol. 46, No. 3, 1998, pp. 571-586. doi:10.1109/78.661326
- [8] W. C. Li, M. Dan, X. S. Wang, D. Li and G. Y. Wang, "Fast Estimation Method and Performance Analysis of Frequency Modulation Rate via RAT," *International Conference on Information and Automation*, Changsha, China, 20-23 June 2008, pp. 144-147. doi:10.1109/ICINFA.2008.4607984
- [9] L. B. Almeida, "The Fractional Fourier Transforms and Time-Frequency Representations," *IEEE Transactions on Signal Processing*, Vol. 42, No. 11, 1994, pp. 3084-3091. doi:10.1109/78.330368
- [10] M. I. Skolnik, "Radar Handbook," 2nd Edition, McGraw-Hill Publishing Company, New York, 1990.
- [11] A. W. Rihaczek, "Principles of High-Resolution Radar," McGraw-Hill Publishing Company, New York, 1969.
- [12] L. X. Wang, D. Z. Fang, M. Y. Zhang, et al., "Mathematics Handbook," Higher Education Publishing Company, Beijing, 2004.
- [13] W. P. Li, "Wigner Distribution Method Equivalent to Dechirp Method for Detecting a Chirp Signal," *IEEE Transactions on Acoustics, Speech, Signal Processing*, Vol. 35, No. 8, 1987, pp. 1210-1211.
- [14] Y. M. Zheng and Z. Bao, "Autofocusing of SAR Images Based on Relax," *IEEE International Radar Conference*, Alexandria, 7-12 May 2000, pp. 533-538. doi:10.1109/RADAR.2000.851890
- [15] J. Tsao and B. D. Steinberg, "Reduction of Side Lobe and Speckle Artifacts in Microwave Imaging: The CLEAN Technique," *IEEE Transactions on Antennas and Propagation*, Vol. 36, No. 4, 1988, pp. 543-556. doi:10.1109/8.1144