

Four-Dimensional Signal Constellations Based on Binary Frequency-Shift Keying and *M*-ary Amplitude-Phase-Shift Keying

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Abstract

In this article, we give the construction of new four-dimensional signal constellations in the Euclidean space, which represent a certain combination of binary frequency-shift keying (BFSK) and *M*-ary amplitude-phase-shift keying (MAPSK). Description of such signals and the formulas for calculating the minimum squared Euclidean distance are presented. We have developed an analytic building method for even and odd values of *M*. Hence, no computer search and no heuristic methods are required. The new optimized BFSK-MAPSK ($M = 5, 6, \dots, 16$) signal constructions are built for the values of modulation indexes $h = 0.1, 0.15, \dots, 0.5$ and their parameters are given. The results of computer simulations are also provided. Based on the obtained results we can conclude, that BFSK-MAPSK systems outperform similar fourdimensional systems both in terms of minimum squared Euclidean distance and simulated symbol error rate.

Keywords

Signal Constellation, Minimum Squared Euclidean Distance, Modulation Index, Signal Phase, Simulation, Symbol Error Rate

1. Introduction

To date, there has been a significant increase in interest in digitally modulated signals, mainly due to the widespread use of multi-input and multi-output (MIMO) systems. Of the well-known effective signal systems, multi-dimensional signals have a better performance of error rate (symbol error rate—SER or bit error rate—BER) compared to conventional two-dimensional signals [1] [2] [3].

It is well known that multidimensional signals can be formed using time or frequency (or both) spaces [2] [3] [4] [5]. Concerning SER characteristics good results are obtained for four-dimensional (4D) signals, which represent certain combinations of binary frequency shift keying (BFSK) and *M*-ary phase-shift keying (MPSK) modulations (BFSK-MPSK signals). Initially, several such signals were presented in combination with channel coding schemes [4] [5], and later, as the components of Spatial Modulation (SM) systems [6]. In both cases, the considered signals gave a remarkable performance.

Numerous new 4D BFSK-MPSK signal characteristics are listed in [7], where their advantage (according to SER) is shown compared to the best *M*-ary amplitude-phase shift keying (MAPSK) signals discussed in [1] [8]. The constellations with usual size ($M = 2^i$, where *i* is a natural number), as well as atypical size ($M \neq 2^i$) are presented in [6], whose use has been particularly convenient and fruitful in MIMO SM systems.

To further improve the signal distance and, accordingly, SER characteristics, in this article we will discuss 4D constructions of hybrid type constellations of size M, which will be built based on a combination of BFSK and MAPSK modulations (the so-called BFSK-MAPSK signals). The main novelty of this paper is the presentation of a general regular method of constructing such 4D constellations that uses an analysis line different from [7] and for particular cases leads to the optimal construction of [7]. In the new scheme, MAPSK modulation uses two-level circular signal constellations with energy levels—high (E_H) and low (E_L). We consider $E_H = k \cdot E_L$, where k > 1 and the signals with the same energy levels are transmitted at the same frequencies. Using the proposed method, for modulation indexes $h \leq 0.5$ and alphabet sizes $5 \leq M \leq 16$, we construct new BFSK-MAPSK signal constellations and present the parameters of the best of them in the form of a table. Furthermore, we illustrate their advantages over systems from [4] [5] [7] concerning the SER performance using computer simulations for the additive white Gaussian noise channel.

MIMO SM techniques appear as competitive candidates for next-generation (5G and beyond) wireless networks due to the attractive advantages they offer in terms of spectral and energy efficiency as well as hardware simplicity. We think that the presented signals can be effectively used in various multiantenna SM realizations developed by us [9] [10]. It should also be noted, that new four-dimensional signals can operate in the similar coded modulation schemes which are described in [2] [3] [4] [5].

The rest of this paper is organized as follows: Section 2 describes BFSK-MAPSK signals, their parameters, and distance characteristics. Section 3 presents signal construction methodology and uses it to calculate the best parameters of the signal system. The results of simulation and comparative analysis are shown in Section 4 whereas the conclusions are figured out in Section 5.

2. The Description and Parameters of BFSK-MAPSK

In the case of the BFSK-MAPSK signal (or BFSK-MAPSK signal constellation C)

two different frequencies $\omega_c + \pi h/T_s$ rad/s and $\omega_c - \pi h/T_s$ rad/s (T_s is signal duration) are used to transmit *M*1-ary and *M*2-ary PSK signals (namely, M1PSK and M2PSK), respectively. Accordingly, we have two sub-constellations, *C*1 and *C*2, $C = C1 \cup C2$. Besides, *M*-ary (M = M1 + M2) signal configuration is such that M1 = M2 when *M* is even and M2 = M1 - 1 when *M* is odd. The energy of each signal in the *C*1 sub-constellation is E_{H} , and the energy of each signal in *C*2 sub-constellation is E_L . The average signal energy in constellation *C* is

$$(M1 \cdot E_H + M2 \cdot E_L)/M = 1.$$

For the considered cases we have

$$\begin{cases} E_L = 2/(1+k), E_H = 2k/(1+k), & \text{if } M \text{ is even;} \\ E_L = 2/\left(\frac{M+1}{M} \cdot k + \frac{M-1}{M}\right), E_H = 2k/\left(\frac{M+1}{M} \cdot k + \frac{M-1}{M}\right), & \text{if } M \text{ is odd.} \end{cases}$$
(1)

From (1) follows that it is sufficient to know the value of k to determine the energies of the *M*-ary signals in the process of their optimization. As an example, **Figure 1** shows the BFSK-8APSK constellation, where the signal vector norm is $\sqrt{E_H}$ in the *C*1 sub-constellation and $\sqrt{E_L}$ in the *C*2 sub-constellation, respectively.

Analytically, the BFSK-MAPSK signal can be defined as follows:

$$s_{\tau}(t) = \sqrt{\frac{2E_s}{T_s}} \cos\left[\left(\omega_c \pm \frac{\pi h}{T_s}\right)t + \varphi_{\tau}\right], \quad 0 \le t \le T_s,$$
(2)

where E_s is the signal energy, $E_s \in \{E_H, E_L\}$; φ_{τ} is the phase of the signal $s_{\tau}(t)$, $(\tau \in \{1, 2, \dots, M\})$. It is important to note that the following conditions will always be satisfied: $E_s = E_H$, when τ is odd, and $E_s = E_L$ when τ is even.



Figure 1. Presentation of 4D BFSK-8APSK constellation.

In [7] based on the Gram-Schmidt orthonormalization procedure for BFSK-MPSK signals we constructed the basic vectors of 4D space. Similarly, for BFSK-MAPSK signal coordinates we get:

$$s_{\tau} = \begin{cases} \sqrt{E_H} \left(\cos \varphi_{\tau}, \sin \varphi_{\tau}, 0, 0 \right), & \text{for } C1; \\ \sqrt{E_L} \left(K_1 \cos \varphi_{\tau} + K_2 \sin \varphi_{\tau}, K_1 \sin \varphi_{\tau} - K_2 \cos \varphi_{\tau}, \sqrt{D} \cos \varphi_{\tau}, \sqrt{D} \sin \varphi_{\tau} \right), & \text{for } C2, \end{cases}$$
(3)

where $K_1 = (\sin 2\pi h)/(2\pi h)$, $K_2 = (1 - \cos 2\pi h)/(2\pi h)$, $D = 1 - K_1^2 - K_2^2$.

It is obvious, that for C1 sub-constellation τ is odd and for C2 sub-constellation τ is even.

Later on, we will use the general formula for calculation of the squared Euclidean distance between s_i and s_j signals [1]:

$$d^{2}(s_{i}, s_{j}) = \int_{0}^{T_{s}} \left[s_{i}(t) - s_{j}(t) \right]^{2} dt .$$
(4)

Then taking (2) and (4) into account, we obtain the following formulas for the squared Euclidean in sub-constellations *C*1 and *C*2:

$$d^{2}(C1) = 2E_{H}\left[1 - \cos\left(\Delta\varphi(C1)\right)\right],$$
(5)

$$d^{2}(C2) = 2E_{L}\left[1 - \cos\left(\Delta\varphi(C2)\right)\right],$$
(6)

where $\Delta \varphi(C1)$ and $\Delta \varphi(C2)$ are the phase differences between the corresponding signals for each sub-constellation.

The squared Euclidean distance between the *i*-th signal $s_i (i \in \{1, 3, \dots\})$ of *C*1 sub-constellation and *j*-th signal $s_j (j \in \{2, 4, \dots\})$ of *C*2 sub-constellation can be calculated as follows:

$$d^{2}\left(s_{i},s_{j}\right) = E_{H} + E_{L} - 2\operatorname{sinc}\left(\pi h\right) \cdot \sqrt{E_{H}E_{L}} \cdot \cos\left(\varphi_{i} - \varphi_{j}^{s}\right),\tag{7}$$

where $\operatorname{sin}(\pi h) = \operatorname{sin}(\pi h)/(\pi h)$, φ_i is initial phase of s_i signal, $\varphi_j^s = \varphi_j - \pi h$ and φ_j is the initial phase of s_j signal.

3. The Construction of BFSK-MAPSK Signals

First, consider the case when *M* is even. Suppose, that we have the basic constellation C_s with elements s_1, s_2, \dots, s_M with even *M* and the initial phases $\varphi_1, \varphi_2, \dots, \varphi_M$, respectively. Furthermore, for any $m \in \{1, 2, \dots, (M-1)\}$, $\varphi_{m+1} > \varphi_m$ and $\varphi_{m+1} - \varphi_m = \phi_e = 2\pi/M$.

Let us partition C_s into the sub-constellations $C_s 1$ and $C_s 2$ so that $\{s_i\}_{i=1,3,\cdots} \in C_s 1$ and $\{s_j\}_{j=2,4,\cdots} \in C_s 2$. The corresponding values of the signal phases are $\{\varphi_i\}_{i=1,3,\cdots}$ and $\{\varphi_j\}_{j=2,4,\cdots}$. For further use, we denote $\{\varphi_j\}$ by $\{\varphi_j^s\}$. For example, the phase diagrams of the basic constellation C_s as well as the sub-constellations $C_s 1$ and $C_s 2$ for M = 8 are presented in Figure 2:

We say that $C_s 1$ and $C_s 2$ sub-constellations have signal energies E_H and E_L , respectively. As it was noted in the introduction part, we can assume that $E_H > E_L$ and $E_H = k \cdot E_L$, k > 1.

We can define the minimum values of the squared Euclidean distances for signals of $C_s 1$ and $C_s 2$ sub-constellations as follows:



Figure 2. Example of a basic constellation and its two sub-constellations for M = 8.

$$d_{\min}^{2}(C_{s}1) = 2E_{H}(1 - \cos(4\pi/M)), \qquad (8)$$

$$d_{\min}^{2}(C_{s}2) = 2E_{L}(1 - \cos(4\pi/M)).$$
(9)

Taking (7) into account, we define the minimum value of the squared Euclidean distance between the signals from the sub-constellation C_s1 and C_s2 as follows:

$$d_{\min}^{2}(C_{s}1, C_{s}2) = E_{L}(k - 2\operatorname{sinc}(\pi h) \cdot \sqrt{k} \cdot \cos(2\pi/M) + 1).$$
(10)

Given that $d_{\min}^2(C_s 1) > d_{\min}^2(C_s 2)$, the value of minimum squared Euclidean distance for C_s constellation will be:

$$d_{\min}^{2}(C_{s}) = \min \left[d_{\min}^{2}(C_{s}2), d_{\min}^{2}(C_{s}1, C_{s}2) \right].$$
(11)

It is not difficult to see that in (11) $d_{\min}^2(C_s 2)$ is a monotonically decreasing function with respect to k for a given M, while $d_{\min}^2(C_s 1, C_s 2)$ is a monotonically increasing function with respect to a given M and h. The intersection point of these functions determines the optimal value of k. Undoubtedly, this point will exist if the condition is fulfilled:

$$\left[d_{\min}^2\left(C_s\,2\right) \ge d_{\min}^2\left(C_s\,1,C_s\,2\right)\right]_{k=1}.\tag{12}$$

Let us say, that $d_{\min}^2(C_s 2) = d_{\min}^2(C_s 1, C_s 2)$. Then the following equality is true:

$$k - 2\operatorname{sinc}(\pi h) \cdot \cos(2\pi/M) \cdot \sqrt{k} + 2\cos(4\pi/M) - 1 = 0.$$
 (13)

From (13) we get the solution for $k \ge 1$:

$$k = \left[\operatorname{sinc}(\pi h) \cdot \cos(2\pi/M) \pm \sqrt{\left(\operatorname{sinc}(\pi h) \cdot \cos(2\pi/M)\right)^2 - \left(2\cos(4\pi/M) - 1\right)}\right]^2. (14)$$

If we use the already known values of ϕ_e and k we can fully determine the optimal C_s basic constellation (with respect to the max $d_{\min}^2(C_s)$) and at this time $d_{\min}^2(C_s) = d_{\min}^2(C_s^2)$.

Considering (7), the procedure for obtaining optimized BFSK-MAPSK constellations $C(C = C1 \cup C2)$ will be as follows: sub-constellation C1 must coincide with C_s1 and the sub-constellation C2 is obtained by adding πh (modulo 2π) to the values of the phases of the C_s2 sub-constellation. It is clear that for the constellation C the following equation holds:

$$d_{\min}^{2}(C) = 2E_{L}(1 - \cos(4\pi/M)).$$
(15)

Next, consider the case when M is odd. As in the previous case, we have the basic constellation C_s with an odd number of elements s_1, s_2, \dots, s_M with initial phases values $\varphi_1, \varphi_2, \dots, \varphi_M$, respectively. However, for any

 $m \in \{1, 2, \cdots, (M-1)\}, \varphi_{m+1} > \varphi_m$ and

$$\varphi_{m+1} - \varphi_m = \phi_o = \varphi_M / (M - 1). \tag{16}$$

Just like to **Figure 2**, for M = 7 we have the constellation presented in **Figure 3**.

Similar to the case of even M, for odd M the minimum squared Euclidean distance of the basic constellation C_s is

$$d_{\min}^{2}(C_{s}) = \min\left[d_{\min}^{2}(C_{s}2), d_{\min}^{2}(C_{s}1, C_{s}2), d^{2}(s_{1}, s_{M})\right],$$
(17)

where

$$d_{\min}^{2}(C_{s}2) = 2E_{L}(1 - \cos(2\phi_{o})), \qquad (18)$$

$$d_{\min}^{2}\left(C_{s}1,C_{s}2\right) = E_{L}\left(k-2\operatorname{sinc}\left(\pi h\right)\cdot\sqrt{k}\cdot\cos\left(\phi_{o}\right)+1\right),\tag{19}$$

$$d^{2}(s_{1}, s_{M}) = 2E_{H}\left(1 - \cos\left((M - 1)\phi_{o}\right)\right).$$
(20)

It is easy to show that likewise to the case of even M, the condition of existence of optimal basic C_s constellation is $d_{\min}^2(C_s 2) = d_{\min}^2(C_s 1, C_s 2)$. However, this is a necessary but insufficient condition, as there exists a possibility that the square of the Euclidean distance between the first and last signals of the basic constellation will be $d^2(s_1, s_M) < d_{\min}^2(C_s 2)$ and $d^2(s_1, s_M) < d_{\min}^2(C_s 1, C_s 2)$.

Therefore, the necessary and sufficient condition for the optimality of C_s will be:

$$d_{\min}^{2}(C_{s}2) = d_{\min}^{2}(C_{s}1, C_{s}2) = d^{2}(s_{1}, s_{M}).$$
(21)

Given that $d_{\min}^2(C_s 2) = d^2(s_1, s_M)$ we will get the formula

$$k = \frac{\left(\sin\left(\phi_o\right)\right)^2}{\left(\sin\left((M-1)\phi_o/2\right)\right)^2},\tag{22}$$

where ϕ_o is defined by (16). If we take into consideration that $d_{\min}^2(C_s 2) = d_{\min}^2(C_s 1, C_s 2)$ then the following equation is true





$$\left(\sin\left(\varphi_{M}/(M-1)\right) \right)^{2} - \operatorname{sinc}\left(\pi h\right) \cdot \sin\left(2\varphi_{M}/(M-1)\right) \cdot \sin\left(\varphi_{M}/2\right)$$

+
$$\left(\sin\left(\varphi_{M}/2\right) \right)^{2} \cdot \left(1 - 4\left(\sin\left(\varphi_{M}/(M-1)\right) \right)^{2} \right) = 0,$$
 (23)

from which we can determine φ_M .

The Equation (23) can have many solutions and we choose from the $\{\varphi_{Mi}\}_{i>1}$ the maximum real solution less than 2π , which ensures the maximization of the $d_{\min}^2(C_s 2)$ values.

Finally, according to the given k and ϕ_o we get the basic constellation C_s , from which we can obtain the optimized BFSK-MAPSK signal constellation C by a procedure, similar to the case of the even M, that is with the addition (modulo 2π) of the values of πh to the phases to the $C_s 2$ sub-constellation. Finally, it follows from the above discussions, that for odd M we have

$$d_{\min}^{2}(C) = 2E_{L}(1 - \cos(2\phi_{o})).$$
(24)

It should be noted, that without loss of generality, we can assume that $\varphi_1 = 0$ for both even and odd values of *M*.

It follows from [7] that minimum squared Euclidean distance for BFSK-MPSK signals can be calculated as follows:

$$d_{\min(BFSK-MPSK)}^{2} = 2\left(1 - \operatorname{sinc}\left(\pi h\right) \cdot \cos\left(2\pi/M\right)\right).$$
⁽²⁵⁾

Taking into consideration that MAPSK signal systems have better minimum squared Euclidean distance values compared to MPSK, it can be presumed that for certain values of *h* and *M*, BFSK-MAPSK would have better values of d_{\min}^2 compared to BFSK-MPSK, which leads to the suggestion that BFSK-MAPSK should ensure better SER performance compared to BFSK-MPSK. Then the question naturally arises as to what values of *M* and *h* this case could take place. Let us show the principle of solving this problem for even values of *M*.

If for BFSK-MAPSK signals the right-hand side of the condition (25) is valid then the minimum squared Euclidean distance is equal to

$$d_{\min(BFSK-MAPSK)}^2 = 2E_L \left(1 - \cos\left(4\pi/M\right)\right)$$
(26)

and for interesting us case we have

$$2E_L\left(1-\cos\left(4\pi/M\right)\right) > 2\left(1-\sin\left(\pi h\right)\cdot\cos\left(2\pi/M\right)\right). \tag{27}$$

Afterwards, taking into account that $E_L < 1$, we obtain the formula

$$\operatorname{sinc}(\pi h) > \cos(4\pi/M)/\cos(2\pi/M)$$
(28)

and this is a condition under which for given h and M, the inequality

 $d_{\min(BFSK-MAPSK)}^2 > d_{\min(BFSK-MPSK)}^2$ holds.

Clearly, with the same approach, a similar formula can be obtained for odd values of M.

Table 1 lists some of the BFSK-MAPSK system parameters that we have identified and selected using the methods and procedures described above. Here the values of ϕ_o and ϕ_e are given in degrees.

h	<i>M</i> =5		<i>M</i> =6		<i>M</i> =7		<i>M</i> =8		<i>M</i> =9		<i>M</i> =10	
	$\phi_{_o}$	$d_{\scriptscriptstyle{ m min}}^{\scriptscriptstyle{2}}$	ϕ_{e}	$d_{\scriptscriptstyle{ m min}}^{\scriptscriptstyle{2}}$	$\phi_{_o}$	$d_{\scriptscriptstyle{ m min}}^{\scriptscriptstyle{2}}$	ϕ_{e}	$d_{\scriptscriptstyle{ m min}}^{\scriptscriptstyle{2}}$	$\phi_{_o}$	$d_{\scriptscriptstyle{ m min}}^{\scriptscriptstyle{2}}$	ϕ_{e}	$d_{\scriptscriptstyle{ m min}}^{\scriptscriptstyle{2}}$
0.10	74.96	1.4193	60.00	1.2105	52.11	0.9443	45.00	0.8580	39.95	0.6983	36.00	0.6500
0.15	74.92	1.4258	60.00	1.2237	52.04	0.9574	45.00	0.8740	39.88	0.7129	36.00	0.6664
0.20	74.86	1.4348	60.00	1.2420	51.94	0.9757	45.00	0.8966	39.78	0.7338	36.00	0.6899
0.25	74.77	1.4465	60.00	1.2654	51.81	1.0000	45.00	0.9259	39.64	0.7613	36.00	0.7208
0.30	74.68	1.4606	60.00	1.2939	51.65	1.0290	45.00	0.9623	39.48	0.7959	36.00	0.7598
0.35	-	-	60.00	1.3273	51.46	1.0642	45.00	1.0057	39.27	0.8381	36.00	0.8075
0.40	-	-	60.00	1.3654	51.24	1.1053	45.00	1.0563	39.02	0.8886	36.00	0.8645
0.45	-	-	60.00	1.4079	50.98	1.1523	45.00	1.1142	38.72	0.9480	36.00	0.9314
0.50	-	-	60.00	1.4544	50.69	1.2053	45.00	1.1790	38.36	1.0172	36.00	1.0083
h	<i>M</i> =11		<i>M</i> =12		<i>M</i> =13		<i>M</i> =14		<i>M</i> =15		<i>M</i> =16	
	$\phi_{_o}$	$d_{\scriptscriptstyle{ m min}}^{\scriptscriptstyle{2}}$	$\phi_{_e}$	$d_{\scriptscriptstyle{ m min}}^{\scriptscriptstyle{2}}$	$\phi_{_o}$	$d_{\scriptscriptstyle{ m min}}^{\scriptscriptstyle{2}}$	$\phi_{_{e}}$	$d_{\scriptscriptstyle{ m min}}^{\scriptscriptstyle{2}}$	$\phi_{_o}$	$d_{\scriptscriptstyle{ m min}}^{\scriptscriptstyle{2}}$	$\phi_{_{e}}$	$d_{\scriptscriptstyle{ m min}}^{\scriptscriptstyle{2}}$
0.10	32.42	0.5429	30.00	0.5125	27.31	0.4360	25.71	0.4155	23.61	0.3585	22.50	0.3442
0.15	32.36	0.5577	30.00	0.5285	27.25	0.4503	25.71	0.4309	23.55	0.3723	22.50	0.3589
0.20	32.26	0.5790	30.00	0.5517	27.16	0.4714	25.71	0.4535	23.46	0.3929	22.50	0.3808
0.25	32.13	0.6075	30.00	0.5828	27.03	0.5001	25.71	0.4844	23.34	0.4217	22.50	0.4116
0.30	31.97	0.6442	30.00	0.6230	26.86	0.5381	25.71	0.5255	23.16	0.4612	22.50	0.4543
0.35	31.75	0.6902	30.00	0.6734	26.63	0.5875	25.71	0.5793	22.89	0.5166	22.50	0.5140
0.40	31.48	0.7470	30.00	0.7357	26.31	0.6524	25.71	0.6493	-	-	-	-
0.45	31.12	0.8168	30.00	0.8116	-	-	-	-	-	-	-	-
0.50	30.64	0.9026	30.00	0.9026	-	-	-	-	-	-	-	-

Table 1. Parameters of BFSK-MAPSK systems.

Concerning d_{\min}^2 , all signals in **Table 1** are better than the BFSK-MPSK systems presented in [4] [5] [7], especially for small h ($h \le 0.5$) and high M, which is important for better bandwidth and spectral efficiency. The latter is defined as $S_E = \log_2(M)$ and $S_E = 2.322, 2.585, \dots, 4$ in our variants. It is also obvious, that the presented new systems have better d_{\min}^2 values compared with optimal M-ary APSK [8] and M-ary PSK [1] signals.

We observe from the performed calculations that the system is optimal if $k \approx 1$ (or k = 1), which means that we have constructed the optimal BFSK-MPSK constellation, where the parameter k is the signal energy ratio of the two energy levels introduced in Section 1, *i.e.* $k = E_H/E_L$. Therefore, the optimal BFSK-MAPSK system construction method presented in this paper is a general one, which can be used to obtain the optimal signal system of both types—BFSK-MAPSK or BFSK-MPSK [7]. We note that the method used in [7] allows us to build only BFSK-MPSK.

4. Simulation Results

To investigate the effectiveness of the new signals more deeply, the computer



Figure 4. SER characteristics of 4D signals.

simulations of BFSK-MAPSK signals and BFSK-MPSK signals from [7] were conducted in the additive white Gaussian noise channels. The transmission of 50,000,000 *M*-ary symbols was considered. The results are shown in **Figure 4**, where SNR is the average signal-to-noise ratio per transmitted *M*-ary symbol. For all cases, we used h = 0.3. The reception of the signals was carried out in Euclidean space by maximum-likelihood detection. The simulation results show that for SER = 10^{-5} the energy gain of BFSK-MAPSK signals compared to BFSK-MPSK signals are around 0.73 dB, 0.76 dB, and 0.48 dB for M = 8, M = 10 and M = 13, respectively, which once again indicates the advantage of BFSK-MAPSK over BFSK-MPSK systems. During simulation we used the following values of signal energies and phases (in degrees):

1) BFSK-MPSK: $E_s = 1$, $\varphi = [0 \ 9 \ 0 \ 99 \ 180 \ 189 \ 270 \ 279]$ for M = 8; $E_s = 1$, $\varphi = [0 \ 18 \ 72 \ 90 \ 144 \ 162 \ 216 \ 234 \ 288 \ 306]$ for M = 10; $E_s = 1$, $\varphi = [0 \ 80.6741 \ 53.3481 \ 134.0222 \ 106.6962 \ 187.3703 \ 160.0444 \ 240.7184 \ 213.3925 \ 294.0665 \ 266.7406 \ 347.4146 \ 320.0887]$ for M = 13.

2) BFSK-MAPSK: $E_L = 0.48$, $E_H = 1.52$, $\varphi = [0 \ 9 \ 09 \ 91 \ 180 \ 189 \ 270 \ 279]$ for M = 8; $E_L = 0.55$, $E_H = 1.45$, $\varphi = [0 \ 18 \ 72 \ 90 \ 144 \ 162 \ 216 \ 234 \ 288 \ 306]$ for M = 10; $E_L = 0.66$, $E_H = 1.29$, $\varphi = [0 \ 80.8633 \ 53.7265 \ 134.5898 \ 107.4530 \ 188.3163 \ 161.1795 \ 242.0428 \ 214.9060 \ 295.7693 \ 268.6325 \ 349.4958 \ 322.3590]$ for M = 13.

5. Conclusion

In this article, we have introduced a new signal BFSK-MAPSK constellation consisting of sub-constellations with a different energy. We have presented their description and formulas to calculate the distance characteristics. Based on these results we developed the optimized BFSK-MAPSK signaling systems with the help of regular non-computer search and not heuristic methods for both odd and even constellation sizes of M and any modulation index h. We have described the procedure that allows us to build better systems compared to BFSK-MPSK in the case of a given M and h. We have described the procedure that allows to build efficient BFSK-MAPSK systems and presented the new system parameters with the best d_{min}^2 in the form of a table. We also carried out computer simulations. The proposed BFSK-MAPSK systems outperform similar four-dimensional systems in terms of minimum squared Euclidean distance and simulated symbol error rate.

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Conflicts of Interest

The authors declare no conflicts of interest regarding the publication of this paper.

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