# From Braided Infinitesimal Bialgebras to Braided Lie Bialgebras 

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#### Abstract

The present paper is a continuation of [1], where we considered braided infinitesimal Hopf algebras (i.e., infinitesimal Hopf algebras in the Yetter-Drinfeld category ${ }_{H}^{H} \mathcal{Y D}$ for any Hopf algebra $H$ ), and constructed their Drinfeld double as a generalization of Aguiar's result. In this paper we mainly investigate the necessary and sufficient condition for a braided infinitesimal bialgebra to be a braided Lie bialgebra (i.e., a Lie bialgebra in the category ${ }_{H}^{H} \mathcal{Y D}$ ).


## Keywords

Braided Infinitesimal Bialgebra, Braided Lie Bialgebra, Yetter-Drinfeld Category, Balanceator

## 1. Introduction

An infinitesimal bialgebra is a triple $(A, m, \Delta)$, where $(A, m)$ is an associative algebra (possibly without unit), $(A, \Delta)$ is a coassociative coalgebra (possibly without counit) such that

$$
\Delta(x y)=x y_{1} \otimes y_{2}+x_{1} \otimes x_{2} y, x, y \in A
$$

Infinitesimal bialgebras were introduced by Joni and Rota in [2], called infinitesimal coalgebra there, in the context of the calculus of divided differences [3]. In combinatorics, they were further studied in [4] [5] [6]. Aguiar established the basic theory of infinitesimal bialgebras in [7] [8] by investigating several examples and the notions of antipode, Drinfeld double and the associative YangBaxter equation keeping close to ordinary Hopf algebras. In [9], Yau introduced the notion of Hom-infinitesimal bialgebras and extended Aguiar's main results in [7] [8] to Hom-infinitesimal bialgebras.

One of the motivations of studying infinitesimal bialgebras is that they are
closely related to Drinfeld's Lie bialgebras (see [10]). The cobracket $\Delta$ in a Lie bialgebra is a 1-cocycle in Chevalley-Eilenberg cohomology, which is a 1-cocycle in Hochschild cohomology (i.e., a derivation) in a infinitesimal bialgebra. So the compatible condition in a infinitesimal bialgebra can be seen as an associative analog of the cocycle condition in a Lie bialgebra.

Motivated by [1], in which we considered infinitesimal Hopf algebras in the Yetter-Drinfeld categories, called braided infinitesimal Hopf algebras, the natural idea is whether we can obtain braided Lie bialgebras (called generalized $H$-Lie bialgebras in [11] [12]) from braided infinitesimal Hopf algebras. This becomes our motivation of writing this paper.

To give a positive answer to the question above, we organize this paper as follows.

In Section 1, we recall some basic definitions about Yetter-Drinfeld modules and braided Lie bialgerbas. In Section 2, we introduce the notion of the balanceator of a braided infinitesimal bialgerba and show that a braided infinitesimal bialgerba gives rise to a braided Lie bialgerba if and only if the balanceator is symmetric (see Theorem 2.3).

## 2. Preliminaries

In this paper, $k$ always denotes a fixed field, often omitted from the notation. We use Sweedler's ([13]) notation for the comultiplication: $\Delta(h)=h_{1} \otimes h_{2}$, for all $h \in H$. Let $H$ be a Hopf algebra. We denote the category of left $H$-modules by ${ }_{H} \mathcal{M}$. Similarly, we have the category ${ }^{H} \mathcal{M}$ of left $H$-comodules. For a left $H$ comodules $(M, \rho)$, we also use Sweedler's notation: $\rho(m)=m_{(-1)} \otimes m_{0}$, for all $m \in M$.

A left-left Yetter-Drinfeld module $M$ is both a left $H$-module and a left $H$ comodule satisfying the compatibility condition

$$
\begin{equation*}
h_{1} m_{(-1)} \otimes h_{2} \cdot m_{0}=\left(h_{1} \cdot m\right)_{(-1)} h_{2} \otimes\left(h_{1} \cdot m\right)_{0} \tag{2.1}
\end{equation*}
$$

for all $h \in H$ and $m \in M$. The equation (1.1) is equivalent to

$$
\begin{equation*}
\rho(h \cdot m)=h_{1} m_{(-1)} S\left(h_{3}\right) \otimes\left(h_{2} \cdot m_{0}\right) . \tag{2.2}
\end{equation*}
$$

By [14] [15], the left-left Yetter-Drinfeld category ${ }_{H}^{H} \mathcal{Y D}$ is a braided monoidal category whose objects are Yetter-Drinfeld modules, morphisms are both left $H$-linear and $H$-colinear maps, and its braiding $C_{-,-}$is given by

$$
C_{M, N}(m \otimes n)=m_{(-1)} \cdot n \otimes m_{(0)}
$$

for all $m \in M \in{ }_{H}^{H} \mathcal{Y D}$ and $n \in N \in{ }_{H}^{H} \mathcal{Y D}$.
Let $A$ be an object in ${ }_{H}^{H} \mathcal{Y D}$, the braiding $\tau$ is called symmetric on $A$ if the following condition holds:

$$
\begin{equation*}
\left(\left(a_{(-1)} \cdot b\right)_{(-1)} \cdot a_{0}\right) \otimes\left(a_{(-1)} \cdot b\right)_{0}=a \otimes b \tag{2.3}
\end{equation*}
$$

which is equivalent to the following condition:

$$
\begin{equation*}
a_{(-1)} \cdot b \otimes a_{0}=b_{0} \otimes S^{-1}\left(b_{(-1)}\right) \cdot a, \tag{2.4}
\end{equation*}
$$

for any $a, b \in A$.
In the category ${ }_{H}^{H} \mathcal{Y D}$, we call an (co)algebra simply if it is both a left $H$ module (co)algebra and a left $H$-comodule (co)algebra. For more details about (co)module-(co)algebras, the reader can refer to [16] [17].

A braided Lie algebra ([11]) in ${ }_{H}^{H} \mathcal{Y D}$, called generalized $H$-Lie algebra there, is an object $L$ in ${ }_{H}^{H} \mathcal{Y D}$ together with a bracket operation [,]: $L \otimes L \rightarrow L$, which is a morphism in ${ }_{H}^{H} \mathcal{Y D}$ satisfying
(1) $H$-anti-commutativity: $\left[l, l^{\prime}\right]=-\left[l_{(-1)} \cdot l^{\prime}, l_{0}\right], l, l^{\prime} \in L$,
(2) $H$-Jacobi identity:

$$
\left\{l \otimes l^{\prime} \otimes l^{\prime \prime}\right\}+\left\{(\tau \otimes 1)(1 \otimes \tau)\left(l \otimes l^{\prime} \otimes l^{\prime \prime}\right)\right\}+\left\{(1 \otimes \tau)(\tau \otimes 1)\left(l \otimes l^{\prime} \otimes l^{\prime \prime}\right)\right\}=0
$$

for all $l, l^{\prime}, l^{\prime \prime} \in L$, where $\left\{l \otimes l^{\prime} \otimes l^{\prime \prime}\right\}$ denotes $\left[l,\left[l^{\prime}, l^{\prime \prime}\right]\right]$ and $\tau$ the braiding for $L$.

Let $A$ be an associative algebra in ${ }_{H}^{H} \mathcal{Y D}$. Assume that the braiding is symmetric on $A$. Define

$$
[a, b]=a b-\left(a_{(-1)} \cdot b\right) a_{0}, a, b \in A
$$

Then $(A,[]$,$) is a braided Lie algebra (see [11]).$
A braided Lie coalgebra ([12]) $\Gamma$ is an object in ${ }_{H}^{H} \mathcal{Y D}$ together with a linear map $\delta: \Gamma \rightarrow \Gamma \otimes \Gamma$ (called the cobracket), which is also a morphism in ${ }_{H}^{H} \mathcal{Y} \mathcal{D}$ subject to the following conditions:
(1) $H$-anti-cocommutativity: $\delta=-\tau \delta$,
(2) $H$-coJacobi identity:

$$
(i d+(i d \otimes \tau)(\tau \otimes i d)+(\tau \otimes i d)(i d \otimes \tau))(i d \otimes \delta) \delta=0
$$

where $\tau$ denotes the braiding for $L$.
Dually, let $(C, \Delta)$ be a coassociative coalgebra in ${ }_{H}^{H} \mathcal{Y D}$. Assume that the braiding on $C$ is symmetric. Define $\delta: C \rightarrow C \otimes C$, by

$$
c \mapsto c_{1} \otimes c_{2}-c_{1(-1)} \cdot c_{2} \otimes c_{10}, c \in C
$$

Then $(C, \delta)$ is a braided Lie coalgebras in ${ }_{H}^{H} \mathcal{Y} \mathcal{D}$ (see [12]).
A braided Lie bialgebra ([18]) is $(L,[],, \delta)$ in ${ }_{H}^{H} \mathcal{Y D}$, where $(L,[]$,$) is a$ braided Lie algebra, and $(L, \delta)$ is a braided Lie coalgebra, such that the compatibility condition holds:
$\delta[x, y]=(([,] \otimes i d)(i d \otimes \delta)+(i d \otimes[]),(\tau \otimes i d)(i d \otimes \delta))(i d \otimes i d-\tau)(x \otimes y), x, y \in L$,
where $\tau$ denotes the braiding for $L$.

## 3. Main Results

In this section, we will study the relation between braided infinitesimal bialgebras and braided Lie bialgebras as a generalization of Aguiar's result in [8].

Let $(A, m, \Delta)$ be a braided $\varepsilon$-bialgebra in ${ }_{H}^{H} \mathcal{Y} \mathcal{D}$. For any $x, y, z \in A$, define an action of $A$ on $A \otimes A$ by

$$
x \rightarrow(y \otimes z)=x y \otimes z-x_{(-1)} \cdot y \otimes\left(x_{0(-1)} \cdot z\right) x_{00}
$$

Then the action $\rightarrow$ is a morphism in ${ }_{H}^{H} \mathcal{Y D}$. In fact, for any $x, y, z \in A$ and $h \in H$, we have

$$
\begin{aligned}
& h_{1} \cdot x \rightarrow h_{2} \cdot(y \otimes z)=h_{1} \cdot x \rightarrow\left(h_{2} \cdot y \otimes h_{3} \cdot z\right) \\
& =\left(h_{1} \cdot x\right)\left(h_{2} \cdot y\right) \otimes\left(h_{3} \cdot z\right)-\left(h_{1} \cdot x\right)_{(-1)} \cdot h_{2} \cdot y \otimes\left(\left(h_{1} \cdot x\right)_{0(-1)} \cdot h_{3} \cdot z\right)\left(h_{1} \cdot x\right)_{00} \\
& =\left(h_{1} \cdot x\right)\left(h_{2} \cdot y\right) \otimes\left(h_{3} \cdot z\right)-h_{11} x_{(-1)} S\left(h_{13}\right) \cdot h_{2} \cdot y \otimes\left(\left(h_{12} \cdot x_{0}\right)_{(-1)} \cdot h_{3} \cdot z\right)\left(h_{12} \cdot x_{0}\right)_{0} \\
& =\left(h_{1} \cdot x\right)\left(h_{2} \cdot y\right) \otimes\left(h_{3} \cdot z\right)-h_{1} x_{(-1)} \cdot y \otimes\left(\left(h_{2} \cdot x_{0}\right)_{(-1)} \cdot h_{3} \cdot z\right)\left(h_{2} \cdot x_{0}\right)_{0} \\
& =\left(h_{1} \cdot x\right)\left(h_{2} \cdot y\right) \otimes\left(h_{3} \cdot z\right)-h_{1} x_{(-1)} \cdot y \otimes\left(h_{21} x_{0(-1)} S\left(h_{23}\right) \cdot h_{3} \cdot z\right)\left(h_{22} \cdot x_{00}\right) \\
& =\left(h_{1} \cdot x\right)\left(h_{2} \cdot y\right) \otimes\left(h_{3} \cdot z\right)-h_{1} x_{(-1)} \cdot y \otimes\left(h_{2} x_{0(-1)} \cdot z\right)\left(h_{3} \cdot x_{00}\right) \\
& =h_{1} \cdot(x y) \otimes\left(h_{2} \cdot z\right)-h_{1} x_{(-1)} \cdot y \otimes h_{2} \cdot\left(\left(x_{0(-1)} \cdot z\right) x_{00}\right) \\
& =h \cdot\left(x y \otimes z-x_{(-1)} \cdot y \otimes\left(x_{0(-1)} \cdot z\right) x_{00}\right) .
\end{aligned}
$$

So $\rightarrow$ is left $H$-linear. To show the left $H$-colinearity of the action $\rightarrow$, we compute

$$
\begin{aligned}
& \rho(x \rightarrow(y \otimes z))=\rho\left(x y \otimes z-x_{(-1)} \cdot y \otimes\left(x_{0(-1)} \cdot z\right) x_{00}\right) \\
& =x_{(-1)} y_{(-1)} z_{(-1)} \otimes x_{0} y_{0} \otimes z_{0}-\left(x_{(-1)} \cdot y\right)_{(-1)}\left(x_{0(-1)} \cdot z\right)_{(-1)} x_{00(-1)} \otimes\left(x_{(-1)} \cdot y\right)_{0} \otimes\left(x_{0(-1)} \cdot z\right)_{0} x_{000} \\
& =x_{(-1)} y_{(-1)} z_{(-1)} \otimes x_{0} y_{0} \otimes z_{0}-x_{(-11)} y_{(-1)} S\left(x_{(-13)}\right) x_{(-1) 4} z_{(-1)} S\left(x_{(-1) 6}\right) x_{(-1) 7} \otimes x_{(-1) 2} \cdot y_{0} \otimes\left(x_{(-1) 5} \cdot z_{0}\right) x_{0} \\
& =x_{(-1)} y_{(-1)} z_{(-1)} \otimes x_{0} y_{0} \otimes z_{0}-x_{(-11)} y_{(-1)} z_{(-1)} \otimes x_{(-1) 2} \cdot y_{0} \otimes\left(x_{(-1) 3} \cdot z_{0}\right) x_{0}
\end{aligned}
$$

and

$$
\begin{aligned}
& (i d \otimes \rightarrow) \rho(x \otimes y \otimes z)=(i d \otimes \rightarrow)\left(x_{(-1)} y_{(-1)} z_{(-1)} \otimes x_{0} \otimes y_{0} \otimes z_{0}\right) \\
& =x_{(-1)} y_{(-1)} z_{(-1)} \otimes x_{0} y_{0} \otimes z_{0}-x_{(-1)} y_{(-1)} z_{(-1)} \otimes x_{0(-1)} \cdot y_{0} \otimes\left(x_{00(-1)} \cdot z_{0}\right) x_{000} \\
& =x_{(-1)} y_{(-1)} z_{(-1)} \otimes x_{0} y_{0} \otimes z_{0}-x_{(-1) 1} y_{(-1)} z_{(-1)} \otimes x_{(-1) 2} \cdot y_{0} \otimes\left(x_{(-1) 3} \cdot z_{0}\right) x_{0}
\end{aligned}
$$

as desired.
Definition 2.1. Let $(A, m, \Delta)$ be a braided infinitesimal bialgebra and $\tau$ the braiding of $A$. The map $B: A \otimes A \rightarrow A \otimes A$ defined by

$$
\begin{equation*}
B(x, y)=x \rightarrow \tau \Delta(y)+\tau(y \rightarrow \tau \Delta(x)), x, y \in A \tag{3.1}
\end{equation*}
$$

is called the balanceator of $A$. The balanceator $B$ is called symmetric if $B=B \circ \tau$. The braided infinitesimal bialgebra $A$ is called balanced if $B \equiv 0$ on $A$.

Condition (2.1) can be written as follows:

$$
\begin{aligned}
B(x, y) & =x\left(y_{1(-1)} \cdot y_{2}\right) \otimes y_{10}-x_{(-1)} y_{1(-1)} \cdot y_{2} \otimes\left(x_{0(-1)} \cdot y_{10}\right) x_{00} \\
& +\left(x_{(-1)} \cdot y\right)_{(-1)} \cdot x_{01} \otimes\left(x_{(-1)} \cdot y\right)_{0} x_{02}-\left(\left(x_{(-1)} \cdot y\right)_{(-1)} \cdot x_{01}\right)\left(x_{(-1)} \cdot y\right)_{0} \otimes x_{02}
\end{aligned}
$$

Obviously,

$$
\begin{aligned}
B\left(x_{(-1)} \cdot y, x_{0}\right)= & \left(x_{(-1)} \cdot y\right)\left(x_{0(-1)} \cdot x_{02}\right) \otimes x_{010}-\left(x_{(-1)} \cdot y_{1}\right) x_{0} \otimes y_{2}+x_{(-1)} \cdot y_{1} \otimes x_{0} y_{2} \\
& -\left(x_{(-1)} \cdot y\right)_{(-1)} x_{01(-1)} \cdot x_{02} \otimes\left(\left(x_{(-1)} \cdot y\right)_{0(-1)} \cdot x_{010}\right)\left(x_{(-1)} \cdot y\right)_{00}
\end{aligned}
$$

Lemma 2.2. Let $(A, m, \Delta)$ be a braided infinitesimal bialgebra and $x, y \in A$. Assume that the braiding $\tau$ on $A$ is symmetric. Then the following equations hold:
(1) $\left(\left(x_{(-1)} \cdot y\right)_{(-1)} \cdot x_{01}\right) \otimes\left(\left(x_{(-1)} \cdot y\right)_{0(-1)} \cdot x_{02}\right)\left(x_{(-1)} \cdot y\right)_{00}=x_{1} \otimes x_{2} y$,
(2) $\left(\left(x_{(-1)} \cdot y\right)_{(-1)} x_{01(-1)} \cdot x_{02}\right)\left(x_{(-1)} \cdot y\right)_{0} \otimes x_{010}=x_{1(-1)} \cdot\left(x_{2} y\right) \otimes x_{10}$,
(3) $\left(x_{(-1) 1} \cdot y_{1}\right)_{(-1)} \cdot\left(\left(x_{(-1) 2} \cdot y_{2}\right) x_{0}\right) \otimes\left(x_{(-1) 1} \cdot y_{1}\right)_{0}=\left(x_{(-1)} y_{1(-1)} \cdot y_{2}\right) x_{0} \otimes y_{10}$.

Proof. (1) Since the braiding $\tau$ on $A$ is symmetric, for all $x, y \in A$, we have $\left(x_{(-1)} \cdot y\right)_{(-1)} \cdot x_{0} \otimes\left(x_{(-1)} \cdot y\right)_{0}=x \otimes y$, then

$$
(i d \otimes m)(\Delta \otimes i d)\left(\left(x_{(-1)} \cdot y\right)_{(-1)} \cdot x_{0} \otimes\left(x_{(-1)} \cdot y\right)_{0}\right)=(i d \otimes m)(\Delta \otimes i d)(x \otimes y)
$$

that is,

$$
\left(x_{(-1)} \cdot y\right)_{(-1)} \cdot x_{01} \otimes\left(\left(x_{(-1)} \cdot y\right)_{0(-1)} \cdot x_{02}\right)\left(x_{(-1)} \cdot y\right)_{00}=x_{1} \otimes x_{2} y
$$

So (1) holds.
(2) To show the Equation (2.2), we need the following computation:

$$
\begin{aligned}
& \left(\left(x_{(-1)} \cdot y\right)_{(-1)} x_{01(-1)} \cdot x_{02}\right)\left(x_{(-1)} \cdot y\right)_{0} \otimes x_{010} \\
& =\left(\left(x_{1(-1)} x_{2(-1)} \cdot y\right)_{(-1)} x_{10(-1)} \cdot x_{20}\right)\left(x_{1(-1)} x_{2(-1)} \cdot y\right)_{0} \otimes x_{100} \\
& =\left(x_{1(-1) 1} x_{2(-1) 1} y_{(-1)} S\left(x_{2(-1) 3}\right) S\left(x_{12(-1) 3}\right) x_{10(-1)} \cdot x_{20}\right)\left(x_{1(-1) 2} x_{2(-1) 2} \cdot y_{0}\right) \otimes x_{100} \\
& =\left(x_{1(-1) 1} x_{2(-1) 1} y_{(-1)} S\left(x_{2(-1) 3}\right) \cdot x_{20}\right)\left(x_{1(-1) 2} x_{2(-1) 2} \cdot y_{0}\right) \otimes x_{10} \\
& =\left(x_{1(-1) 1}\left(x_{2(-1)} \cdot y\right)_{(-1)} \cdot x_{20}\right)\left(x_{1(-1) 2}\left(x_{2(-1)} \cdot y\right)_{0}\right) \otimes x_{10} \\
& =x_{1(-1)} \cdot\left(\left(\left(x_{2(-1)} \cdot y\right)_{(-1)} \cdot x_{20}\right)\left(x_{2(-1)} \cdot y\right)_{0}\right) \otimes x_{10}=x_{1(-1)} \cdot\left(x_{2} y\right) \otimes x_{10}
\end{aligned}
$$

The last equality holds since $\tau$ is symmetric on $A$. Hence (2) holds.
(3) Finally, we check the Equation (2.3) as follows:

$$
\begin{aligned}
& \left(x_{(-1) 1} \cdot y_{1}\right)_{(-1)}\left(\left(x_{(-1) 2} \cdot y_{2}\right) x_{0}\right) \otimes\left(x_{(-1) 1} \cdot y_{1}\right)_{0} \\
& =\left(x_{(-1) 11} y_{1(-1)} S\left(x_{(-1) 13}\right)\right) \cdot\left(\left(x_{(-1) 2} \cdot y_{2}\right) x_{0}\right) \otimes x_{(-1) 12} \cdot y_{10} \\
& =\left(x_{(-1) 1} y_{1(-1)} S\left(x_{(-1) 3}\right)\right) \cdot\left(\left(x_{(-1) 4} \cdot y_{2}\right) x_{0}\right) \otimes x_{(-1) 2} \cdot y_{10} \\
& =\left(x_{(-1) 11} y_{1(-1) 1} S\left(x_{(-1) 32}\right) x_{(-1) 4} \cdot y_{2}\right)\left(x_{(-1) 12} y_{1(-1) 2} S\left(x_{(-1) 31}\right) \cdot x_{0}\right) \otimes x_{(-1) 2} \cdot y_{10} \\
& =\left(x_{(-1) 11} y_{1(-1) 1} \cdot y_{2}\right)\left(x_{(-1) 12} y_{1(-1) 2} S\left(x_{(-1) 3}\right) \cdot x_{0}\right) \otimes x_{(-1) 2} \cdot y_{10} \\
& =\left(x_{(-1) 1} y_{1(-1)} \cdot y_{2}\right)\left(\left(x_{(-1) 2} \cdot y_{10}\right)_{(-1)} \cdot x_{0}\right) \otimes\left(x_{(-1) 2} \cdot y_{10}\right)_{0} \\
& =\left(x_{(-1)} y_{1(-1)} \cdot y_{2}\right)\left(\left(x_{0(-1)} \cdot y_{10}\right)_{(-1)} \cdot x_{00}\right) \otimes\left(x_{0(-1)} \cdot y_{10}\right)_{0}=\left(x_{(-1)} y_{1(-1)} \cdot y_{2}\right) x_{0} \otimes y_{10} .
\end{aligned}
$$

The last equality holds since $\tau$ is symmetric on $A$. Hence (3) holds as required.

Therem 2.3. Let $(A, m, \Delta)$ be a braided infinitesimal bialgebra. Assume that the braiding $\tau$ on $A$ is symmetric. Then $(A,[]=,m-m \tau, \delta=\Delta-\tau \Delta)$ is a braided Lie bialgebra if and only if $B=B \circ \tau$.

Proof. Since $(A, m)$ is an associative algebra and $(A, \Delta)$ is a coassociative coalgebra in ${ }_{H}^{H} \mathcal{Y D},(A,[]=,m-m \tau)$ is a braided Lie algebra and $(A, \delta=\Delta-\tau \Delta)$ is a braided Lie coalgebra. Therefore it remains to check the compatible condition:

$$
\delta[x, y]=(([,] \otimes i d)(i d \otimes \delta)+(i d \otimes[,])(\tau \otimes i d)(i d \otimes \delta))(i d \otimes i d-\tau)(x \otimes y)
$$

for all $x, y \in A$. In fact, on the one hand, we have

$$
\begin{aligned}
\delta & {[x, y]=\delta\left(x y-\left(x_{(-1)} \cdot y\right) x_{0}\right) } \\
= & (1-\tau) \Delta(x y)-(1-\tau) \Delta\left(\left(x_{(-1)} \cdot y\right) x_{0}\right) \\
= & (1-\tau)\left(x_{1} \otimes x_{2} y+x y_{1} \otimes y_{2}\right) \\
& -(1-\tau)\left(\left(x_{(-1) 1} \cdot y_{1}\right) \otimes\left(x_{(-1) 2} \cdot y_{2}\right) x_{0}+\left(x_{(-1)} \cdot y\right) x_{01} \otimes x_{02}\right) \\
= & x_{1} \otimes x_{2} y+x y_{1} \otimes y_{2}-x_{1(-1)} \cdot\left(x_{2} y\right) \otimes x_{10}-\left(x y_{1}\right)_{(-1)} \cdot y_{2} \otimes\left(x y_{1}\right)_{0} \\
& -\left(x_{(-1)} \cdot y\right) x_{01} \otimes x_{02}-\left(x_{(-1) 1} \cdot y_{1}\right) \otimes\left(x_{(-1) 2} \cdot y_{2}\right) x_{0} \\
& +\left(x_{(-1) 1} \cdot y_{1}\right)_{(-1)} \cdot\left(\left(x_{(-1) 2} \cdot y_{2}\right) x_{0}\right) \otimes\left(x_{(-1)!} \cdot y_{1}\right)_{0} \\
& +\left(\left(x_{(-1)} \cdot y\right) x_{01}\right)_{(-1)} \cdot x_{02} \otimes\left(\left(x_{(-1)} \cdot y\right) x_{01}\right)_{0} .
\end{aligned}
$$

On the other hand, we have

$$
\begin{aligned}
&(([,] \otimes i d)(i d \otimes \delta)+(i d \otimes[,])(\tau \otimes i d)(i d \otimes \delta))(i d \otimes i d-\tau)(x \otimes y) \\
&=(([,] \otimes i d)(i d \otimes \delta)+(i d \otimes[,])(\tau \otimes i d)(i d \otimes \delta))\left(x y-\left(x_{(-1)} \cdot y\right) x_{0}\right) \\
&= x y_{1} \otimes y_{2}-\left(x_{(-1)} \cdot y_{1}\right) x_{0} \otimes y_{2}-x\left(y_{1(-1)} \cdot y_{2}\right) \otimes y_{10} \\
&+\left(x_{(-1)} y_{1(-1)} \cdot y_{2}\right) x_{0} \otimes y_{10}-\left(x_{(-1)} \cdot y\right)_{01} \otimes x_{02} \\
&+\left(\left(x_{(-1)} \cdot y\right)_{(-1)} \cdot x_{01}\right)\left(x_{(-1)} \cdot y\right)_{0} \otimes x_{02}+\left(x_{(-1)} \cdot y\right)\left(x_{01(-1)} \cdot x_{02}\right) \otimes x_{010} \\
&+x_{(-1)} \cdot y_{1} \otimes x_{0} y_{2}-\left(\left(x_{(-1)} \cdot y\right)_{(-1)} x_{01(-1)} \cdot x_{02}\right)\left(x_{(-1)} \cdot y\right)_{0} \otimes x_{010} \\
&-x_{(-1)} \cdot y_{1} \otimes\left(x_{0(-1)} \cdot y_{2}\right) x_{00}-x_{(-1)} y_{1(-1)} \cdot y_{2} \otimes x_{0} y_{10} \\
&+x_{(-1)} y_{1(-1)} \cdot y_{2} \otimes\left(x_{0(-1)} \cdot y_{10}\right) x_{00}-\left(x_{(-1)} \cdot y\right)_{(-1)} \cdot x_{01} \otimes\left(x_{(-1)} \cdot y\right)_{0} x_{02} \\
&+\left(x_{(-1)} \cdot y\right)_{(-1)} \cdot x_{01} \otimes\left(\left(x_{(-1)} \cdot y\right)_{0(-1)} \cdot x_{02}\right)\left(x_{(-1)} \cdot y\right)_{00} \\
&+\left(x_{(-1)} \cdot y\right)_{(-1)} x_{01(-1)} \cdot x_{02} \otimes\left(x_{(-1)} \cdot y\right)_{0} x_{010} \\
&-\left(x_{(-1)} \cdot y\right)_{(-1)} x_{01(-1)} \cdot x_{02} \otimes\left(\left(x_{(-1)} \cdot y\right)_{0(-1)} \cdot x_{010}\right)\left(x_{(-1)} \cdot y\right)_{00} \cdot
\end{aligned}
$$

According to Lemma 2.2, we have

$$
\begin{aligned}
& x y_{1} \otimes y_{2}+\left(x_{(-1)} y_{1(-1)} \cdot y_{2}\right) x_{0} \otimes y_{10}-\left(x_{(-1)} \cdot y\right) x_{01} \otimes x_{02} \\
& -\left(\left(x_{(-1)} \cdot y\right)_{(-1)} x_{01(-1)} \cdot x_{02}\right)\left(x_{(-1)} \cdot y\right)_{0} \otimes x_{010} \\
& -x_{(-1)} \cdot y_{1} \otimes\left(x_{0(-1)} \cdot y_{2}\right) x_{00}-x_{(-1)} y_{1(-1)} \cdot y_{2} \otimes x_{0} y_{10} \\
& +\left(x_{(-1)} \cdot y\right)_{(-1)} \cdot x_{01} \otimes\left(\left(x_{(-1)} \cdot y\right)_{0(-1)} \cdot x_{02}\right)\left(x_{(-1)} \cdot y\right)_{00} \\
& +\left(x_{(-1)} \cdot y\right)_{(-1)} x_{01(-1)} \cdot x_{02} \otimes\left(x_{(-1)} \cdot y\right)_{0} x_{010} \\
& =x y_{1} \otimes y_{2}+\left(x_{(-1) 1} \cdot y_{1}\right)_{(-1)} \cdot\left(\left(x_{(-1) 2} \cdot y_{2}\right) x_{0}\right) \otimes\left(x_{(-1) 1} \cdot y_{1}\right)_{0} \\
& \quad-\left(x_{(-1)} \cdot y\right)_{x_{01} \otimes x_{02}-x_{1(-1)} \cdot\left(x_{2} y\right) \otimes x_{10}}^{\quad-x_{(-1) 1} \cdot y_{1} \otimes\left(x_{(-1) 2} \cdot y_{2}\right) x_{0}-\left(x y_{1}\right)_{(-1)} \cdot y_{2} \otimes\left(x y_{1}\right)_{0}} \\
& \quad+x_{1} \otimes x_{2} y+\left(\left(x_{(-1)} \cdot y\right) x_{01}\right)_{(-1)} \cdot x_{02} \otimes\left(\left(x_{(-1)} \cdot y\right) x_{01}\right)_{0} \\
& =\delta[x, y] .
\end{aligned}
$$

Therefore,

$$
\begin{aligned}
& (([,] \otimes i d)(i d \otimes \delta)+(i d \otimes[,])(\tau \otimes i d)(i d \otimes \delta))(i d \otimes i d-\tau)(x \otimes y) \\
& =\delta[x, y]-x\left(y_{1(-1)} \cdot y_{2}\right) \otimes y_{10}+\left(\left(x_{(-1)} \cdot y\right)_{(-1)} \cdot x_{01}\right)\left(x_{(-1)} \cdot y\right)_{0} \otimes x_{02} \\
& \quad+x_{(-1)} y_{1(-1)} \cdot y_{2} \otimes\left(x_{0(-1)} \cdot y_{10}\right) x_{00}-\left(x_{(-1)} \cdot y\right)_{(-1)} \cdot x_{01} \otimes\left(x_{(-1)} \cdot y\right)_{0} x_{02} \\
& \quad+\left(x_{(-1)} \cdot y\right)\left(x_{01(-1)} \cdot x_{02}\right) \otimes x_{010}-\left(x_{(-1)} \cdot y_{1}\right) x_{0} \otimes y_{2}+x_{(-1)} \cdot y_{1} \otimes x_{0} y_{2} \\
& \quad-\left(x_{(-1)} \cdot y\right)_{(-1)} x_{01(-1)} \cdot x_{02} \otimes\left(\left(x_{(-1)} \cdot y\right)_{0(-1)} \cdot x_{010}\right)\left(x_{(-1)} \cdot y\right)_{00} \\
& = \\
& \delta[x, y]-B(x, y)+B\left(x_{(-1)} \cdot y, x_{0}\right) \\
& = \\
& \delta[x, y]-B(x, y)+B \circ \tau(x, y),
\end{aligned}
$$

as desired. We complete the proof.
Corollary 2.4. Let $(A, m, \Delta)$ be a braided infinitesimal bialgebra. Assume that the braiding $\tau$ on $A$ is symmetric and the balanceator $B=0$. Then $(A,[]=,m-m \tau, \delta=\Delta-\tau \Delta)$ is a braided Lie bialgebra.

Proof. Straightforward from Theorem 2.3.
Example 2.5. Let $q$ be an 2th root of unit of $k$ and $G$ the cyclic group of order 2 generated by $g, H=k G$ be the group algebra in the usual way. We consider the algebra $A_{4}=k[x] /\left(x^{4}\right)$. By [8], $A_{4}$ is a infinitesimal bialgebra equipped with the comultiplication:

$$
\Delta(1)=0, \Delta(x)=x \otimes x^{2}-1 \otimes x^{3}, \Delta\left(x^{2}\right)=x^{2} \otimes x^{2}, \Delta\left(x^{3}\right)=x^{3} \otimes x^{2}
$$

Define the left- $H$-module action and the left- $H$-comodule coaction of $A$ by

$$
g^{i} \cdot x^{j}=q^{i j} x^{j}, \rho\left(x^{j}\right)=g^{j} \otimes x^{j}, i=0,1, \quad j=0,1,2,3 .
$$

It is not hard to check that the multiplication and the comultiplicaition are
both $H$-linear and $H$-colinear, therefore $A_{4}$ is a braided infinitesimal bialgebra. Since $B(x, x)=2 x^{2} \otimes x^{2}-q x \otimes x^{2}-q x^{2} \otimes x-q x^{3} \otimes x-x \otimes x^{3}$ and $\tau(x \otimes x)=\left(x_{(-1)} \cdot x\right) x_{0}=(g \cdot x) x=q x \otimes x$, it is clear that $B(x, x)=B \tau(x, x)$ if and only if $q=1$. If $q=1$, it is not hard to check that the balanceator is symmetric on $A_{4}$. By Theorem 2.3, ( $\left.A_{4},[]=,m-m \tau, \delta=\Delta-\tau \Delta\right)$ is a braided Lie bialgebra.

Example 2.6. Let $q$ be a 4th root of unit of $k$. Consider the Hopf algebra $H=k G$, where $G$ is a cyclic group of order 4 generated by $g$. Recall from [1] that $A=M_{2}(k)$ is a braided infinitesimal bialgebra in ${ }_{H}^{H} \mathcal{Y D}$ equipped with the comultiplication:

$$
\Delta\left(\begin{array}{ll}
a & b \\
c & d
\end{array}\right)=\left(\begin{array}{ll}
0 & a \\
0 & c
\end{array}\right) \otimes\left(\begin{array}{ll}
0 & 1 \\
0 & 0
\end{array}\right)-\left(\begin{array}{ll}
0 & 1 \\
0 & 0
\end{array}\right) \otimes\left(\begin{array}{ll}
c & d \\
0 & 0
\end{array}\right)
$$

and the $H$-module action, the $H$-comodule coaction:

$$
g^{k} \cdot E_{i j}=q^{2 k(i+j)} E_{i j}, \rho\left(E_{i j}\right)=g^{2(i+j)} \otimes E_{i j}, k=0,1,2,3, i, j=1,2
$$

Since

$$
\begin{gathered}
B\left(E_{11}, E_{21}\right)=2\left(E_{12} \otimes E_{22}-E_{11} \otimes E_{12}\right), \\
B\left(E_{11_{(-1)}} \cdot E_{21}, E_{11_{0}}\right)=B\left(E_{21}, E_{11}\right)=2\left(E_{22} \otimes E_{12}-E_{11} \otimes E_{11}\right),
\end{gathered}
$$

we claim that the balanceator is not symmetric. By Theorem 2.3, $\left(M_{2}(k),[]=,m-m \tau, \delta=\Delta-\tau \Delta\right)$ is not a braided Lie bialgebra, where $m$ is the multiplication of $A$.

Let $A_{1}=\left\{\left.\left(\begin{array}{ll}a & b \\ 0 & a\end{array}\right) \right\rvert\, a, b \in k\right\} \subset M_{2}(k)$. It is clear that $A_{1}$ is both $H$-stable and $H$-costable, hence $A_{1}$ is also a braided infinitesimal bialgebra contained in $A$. One can check easily that the balanceator $B=0$ on $A_{1}$. By Corollary 2.4, $\left(A_{1},[]=,m-m \tau, \delta=\Delta-\tau \Delta\right)$ is a braided Lie bialgebra.

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