# Nemytskii Operator in the Space of Set-Valued Functions of Bounded $\varphi$-Variation 

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#### Abstract

In this paper we consider the Nemytskii operator, i.e., the composition operator defined by $(N f)(t)=H(t, f(t))$, where $H$ is a given set-valued function. It is shown that if the operator $N$ maps the space of functions bounded $\varphi_{1}$-variation in the sense of Riesz with respect to the weight function $\alpha$ into the space of set-valued functions of bounded $\varphi_{2}$-variation in the sense of Riesz with respect to the weight, if it is globally Lipschitzian, then it has to be of the form $(N f)(t)=A(t) f(t)+B(t)$, where $A(t)$ is a linear continuous set-valued function and $B$ is a set-valued function of bounded $\varphi_{2}$-variation in the sense of Riesz with respect to the weight.


Keywords: Bounded Variation; Function of Bounded Variation in the Sense of Riesz; Variation Space; Weight Function; Banach Space; Algebra Space

## 1. Introduction

In [1], it was proved that every globally Lipschitz Nemytskii operator

$$
(N u)(t)=H(t, u(t))
$$

mapping the space $\operatorname{Lip}([a, b] ; c c(Y))$ into itself admits the following representation:

$$
\begin{aligned}
& (N u)(t)=A(t) u(t)+B(t) \\
& u \in \operatorname{Lip}([a, b] ; c c(Y)), t \in[a, b]
\end{aligned}
$$

where $A(t)$ is a linear continuous set-valued function and $B$ is a set-valued function belonging to the space $\operatorname{Lip}([a, b] ; c c(Y))$. The first such theorem for singlevalued functions was proved in [2] on the space of Lipschitz functions. A similar characterization of the Nemytskii operator has also been obtained in [3] on the space of set-valued functions of bounded variation in the classical Jordan sense. For single-valued functions it was proved in [4]. In [5,6], an analogous theorem in the space of set-valued functions of bounded $p$-variation in the sense of Riesz was obtained. Also, they proved a similar result in the case in which that the Nemytskii operator $N$ maps the space of functions of bounded $p$-variation in the sense of Riesz into the space of set-valued functions
of bounded $q$-variation in the sense of Riesz, where $1 \leq q \leq p<\infty$, and $N$ is globally Lipschitz. In [7], they showed a similar result in the case where the Nemytskii operator $N$ maps the space $R V_{\varphi_{1}}([a, b] ; K)$ of setvalued functions of bounded $\varphi_{1}$-variation in the sense of Riesz into the space $R W_{\varphi_{2}}([a, b] ; c c(Y))$ of set-valued functions of bounded $\varphi_{2}$-variation in the sense of Riesz and $N$ is globally Lipschitz.

While in [8], we generalize article [6] by introducing a weight function. Now, we intend to generalize [7] in a similar form we did in [8], i.e., the propose of this paper is proving an analogous result in which the Nemytskii operator $N$ maps the space $R V_{\varphi_{1}, \alpha}([a, b] ; K)$ of setvalued functions of bounded $\varphi_{1}$-variation in the sense of Riesz with a weight $\alpha$ into the space
$R W_{\varphi_{2}, \alpha}([a, b] ; c c(Y))$ of set-valued functions of bounded $\varphi_{2}$-variation in the sense of Riesz with a weight $\alpha$ and $N$ is globally Lipschitz.

## 2. Preliminary Results

In this section, we introduce some definitions and recall known results concerning the Riesz $\varphi$-variation.

Definition 2.1 By a $\varphi$-function we mean any nondecreasing continuous function $\varphi:[0,+\infty) \rightarrow[0,+\infty)$
such that $\varphi(x)=0$ if and only if $x=0$, and $\varphi(x) \rightarrow \infty$ as $x \rightarrow \infty$.

Let $\mathcal{N}$ be the set of all convex continuous functions that satisfy Definition 2.1.

Definition 2.2 Let $(X,\| \|)$ be a normed space and $\varphi$ be a $\varphi$-function. Given $I \subset \mathbb{R}$ be an arbitrary (i.e., closed, half-closed, open, bounded or unbounded) fixed interval and $\alpha: I \rightarrow \mathbb{R}$ a fixed continuous strictly increasing function called $a$ it is weight. If $\varphi \in \mathcal{N}$, we define the (total) generalized $\varphi$-variation $V_{\varphi}(f) \equiv$ $V_{\varphi}(f, I, \alpha)$ of the function $f: I \rightarrow X$ with respect to the weight function $\alpha$ in two steps as follows (cf. [9]). If $I=[a, b]$ is a closed interval and $\pi$ is a partition $\pi: a=t_{0}<t_{1}<\cdots<t_{n}=b$ of the interval I (i.e., $n \in \mathbb{N}$ ), we set

$$
V_{\varphi}(f, \pi, \alpha):=\sum_{i=1}^{n} \varphi\left(\frac{\left\|f\left(t_{i}\right)-f\left(t_{i-1}\right)\right\|}{\left|\alpha\left(t_{i}\right)-\alpha\left(t_{i-1}\right)\right|}\right)\left|\alpha\left(t_{i}\right)-\alpha\left(t_{i-1}\right)\right| .
$$

Denote by $\Pi$ the set of all partitions of $[a, b]$, we set

$$
V_{\varphi}(f) \equiv V_{\varphi}(f,[a, b], \alpha):=\sup \left\{V_{\phi}(f, \pi, \alpha): \pi \in \Pi\right\} .
$$

If $I$ is any interval in $\mathbb{R}$, we put

$$
V_{\varphi}(f) \equiv V_{\varphi}(f, I, \alpha):=\sup \left\{V_{\varphi}(f,[a, b], \alpha):[a, b] \in I\right\} .
$$

The set of all functions of bounded generalized $\varphi$ variation with weight $\alpha$ will be denoted by
$R V_{\varphi}(I) \equiv R V_{\varphi}(I, \alpha)=\left\{f:[a, b] \rightarrow X \mid V_{\varphi}(f, I, \alpha)<\infty\right\}$.
If $\alpha(t)=i \mathrm{~d}(t)=t, t \in I=[a, b]$, and $\varphi(\rho)=\rho^{q}$, $\rho \geq 0, \quad q>1$, the $\varphi$-variation $V_{\varphi}(f, I, \alpha)$, also written as $V_{q}(f)$, is the classical $q$-variation of $f$ in the sense of Riesz [10], showing that $V_{q}(f)<\infty$ if and only if $f \in A C(I)$ (i.e., $f: I \rightarrow \mathbb{R}$ is absolutely continuous) and its almost everywhere derivative $f^{\prime}$ is Lebesgue $q$-summable on $I$. Recall that, as it is well known, the space $R V_{\varphi}(I)$ with $I, \varphi$ and $\alpha$ as above and endowed with the norm $|f|_{q}=|f(a)|+\left(V_{q}(f)\right)^{1 / q}$ is a Banach algebra for all $q \geq 1$.

Riesz's criterion was extended by Medvedev [11]: if $\varphi \in \mathcal{N}$, then $f \in R V_{\varphi}(I)$ if and only if $f \in A C(I)$ and $\int_{I} \varphi\left(\left|f^{\prime}(t)\right|\right) \mathrm{d} t<\infty$. Functions of bounded generalized $\varphi$-variation with $\varphi \in \mathcal{N}$ and $\alpha=i d$ (also called functions of bounded Riesz-Orlicz $\varphi$-variation) were studied by Cybertowicz and Matuszewska [12]. They showed that if $f \in R V_{\varphi}(I)$, then

$$
V_{\varphi}(f)=\int_{I} \varphi\left(\left|f^{\prime}(t)\right|\right) \mathrm{d} t
$$

and that the space

$$
G V_{\varphi}(I)=\left\{f \in \mathbb{R}^{I} \text { such that } \lim _{\lambda \rightarrow+0} V_{\varphi}(\lambda f)=0\right\}
$$

is a semi-normed linear space with the LuxemburgNakano (cf. [13,14]) seminorm given by

$$
p_{\varphi}(f)=\inf \left\{r>0 \mid V_{\varphi}(f / r) \leq 1\right\} .
$$

Later, Maligranda and Orlicz [15] proved that the space $G V_{\varphi}(I)$ equipped with the norm

$$
\|f\|_{\varphi}=\sup _{t \in I}|f(t)|+p_{\varphi}(f)
$$

is a Banach algebra.

## 3. Generalization of Medvedev Lemma

We need the following definition:
Definition 3.1 Let $\varphi$ be a $\varphi$-function. We say $\varphi$ satisfies condition $\infty_{1}$ if

$$
\begin{equation*}
\lim \sup _{t \rightarrow \infty} \frac{\varphi(t)}{t}=\infty \tag{1}
\end{equation*}
$$

For $\varphi$ convex, (1) is just $\lim _{t \rightarrow \infty} \varphi(t) / t=\infty$. Clearly, for $i d=1$ the space $R V_{\alpha}(f,[a, b], i d)$ coincides with the classical space $B V(f,[a, b])$ of functions of bounded variation. In the particular case when $X=\mathbb{R}$ and $1<$ $p<\infty$, we have the space $R V_{p, \alpha}(f,[a, b] ; X)$ of functions of bounded Riesz $p$-variation. Let $\left([a, b], \sum, \mu_{\alpha}\right)$ be a measure space with the Lebesgue-Stieltjes measure defined in $\sigma$-algebra $\sum$ and
$L_{p, \alpha}[a, b]:=$
$\left\{f:[a, b] \rightarrow \mathbb{R} / f\right.$ is $\mu_{\alpha}$ integrable and $\left.\int_{a}^{b}|f|^{p} \mathrm{~d} \alpha<+\infty\right\}$.
Moreover, let $\alpha$ be a function strictly increasing and continuous in $[a, b]$. We say that $E \subset[a, b]$ has $\mu_{\alpha}$ measure 0 , if given $\varepsilon>0$ there is a countable cover $\left\{\left(a_{n}, b_{n}\right) / n \in \mathbb{N}\right\}$ by open intervals of $E$, such that

$$
\sum_{n=1}^{\infty}\left[\alpha\left(b_{n}\right)-\alpha\left(a_{n}\right)\right]<\varepsilon
$$

Since $\alpha$ is strictly increasing, the concept of " $\mu_{\alpha}$ measure 0 " coincides with the concept of "measure 0 " of Lebesgue. [cf. [16], § 25].

Definition 3.2 (Jef) A function $f:[a, b] \rightarrow \mathbb{R}$ is said to be absolutely continuous with respect to $\alpha$, if for every $\varepsilon>0$, there exists $\delta>0$ such that

$$
\sum_{j=1}^{n} \varphi\left(\left|f\left(b_{j}\right)-f\left(a_{j}\right)\right|\right) \leq \varepsilon
$$

for every finite number of nonoverlapping intervals $\left(a_{j}, b_{j}\right), j=1, \cdots, n$ with $\left[a_{j}, b_{j}\right] \subset[a, b]$ and

$$
\sum_{j=1}^{n}\left|\alpha\left(b_{j}\right)-\alpha\left(a_{j}\right)\right| \leq \delta
$$

The space of all absolutely continuous functions $f:[a, b] \rightarrow \mathbb{R}$, with respect to a function $\alpha$ strictly increasing, is denoted by $\alpha-A C$. Also the following
characterization of $[17,18]$ is well-known:
Lemma 3.3 Let $f \in \alpha-A C[a, b]$. Then $f_{\alpha}^{\prime}$ exists and is finite in $[a, b]$, except on a set of $\mu_{\alpha}$-measure 0 .

Lemma 3.4 Let $f \in \alpha-A C[a, b]$. Then $f_{\alpha}^{\prime}$ is integrable in the sense Lebesgue-Stieltjes and

$$
f(x)=f(a)+(L-S) \int_{a}^{x} f_{\alpha}^{\prime}(t) \mathrm{d} \alpha(t), \quad x \in[a, b]
$$

Lemma 3.5 Let $\varphi \in \mathcal{N}$ such that satisfies the $\infty_{1}$ condition. If $f \in R V_{\varphi}(f,[a, b], \alpha)$, then $f$ is $\alpha-a b-$ solutely continuous in $[a, b]$, i.e.,

$$
R V_{\varphi}(f,[a, b], \alpha) \subset \alpha-A C[a, b]
$$

Also the following is a generalization of Medvedev Lemma [11]:

Theorem 3.6 (Generalization a Medvedev Lemma) Let $\varphi \in \mathcal{N}$ such that satisfies the $\infty_{1}$ condition, $f:[a, b] \rightarrow X$. Then

1) If $f$ is $\alpha$-absolutely continuous on $[a, b]$ and

$$
\int_{a}^{b} \varphi\left(\left|f_{\alpha}^{\prime}(x)\right|\right) \mathrm{d} \alpha(x)<+\infty
$$

then

$$
f \in R V_{\varphi}(f,[a, b], \alpha)
$$

and

$$
R V_{\varphi}(f,[a, b], \alpha) \leq \int_{a}^{b} \varphi\left(\left|f_{\alpha}^{\prime}(x)\right|\right) \mathrm{d} \alpha(x)
$$

2) If $f \in R V_{\varphi}(f,[a, b], \alpha)$ (i.e., $\left.R V_{\varphi}(f)<+\infty\right)$, then $f$ is $\alpha$-absolutely continuous on $[a, b]$ and

$$
\int_{a}^{b} \varphi\left(\left|f_{\alpha}^{\prime}(x)\right|\right) \mathrm{d} \alpha(x) \leq R V_{\varphi}(f,[a, b], \alpha)
$$

Proof. 1) Since $f$ is $\alpha$ absolutely continuous, there exists $f_{\alpha^{\prime}}$ a.e. in $[a, b]$ by Lemma 3.3. Let $t_{1}, t_{2} \in[a, b], t_{1}<t_{2}$

$$
\begin{aligned}
& \varphi\left(\frac { | f ( t _ { 2 } ) - f ( t _ { 1 } ) | } { | \alpha ( t _ { 2 } ) - \alpha ( t _ { 1 } ) | } \left|\left|\alpha\left(t_{2}\right)-\alpha\left(t_{1}\right)\right|\right.\right. \\
& =\varphi\left(\left.\frac{\left|\int_{t_{1}}^{t_{2}} f_{\alpha^{\prime}}(t) \mathrm{d} \alpha(t)\right|}{\left|\alpha\left(t_{2}\right)-\alpha\left(t_{1}\right)\right|}| | \alpha\left(t_{2}\right)-\alpha\left(t_{1}\right) \right\rvert\,\right.
\end{aligned}
$$

by Lemma 3.4 and $\varphi$ is strictly increasing

$$
\begin{aligned}
& \leq \varphi\left(\frac{\int_{t_{1}}^{t_{2}}\left|f_{\alpha^{\prime}}(t)\right| \mathrm{d} \alpha(t)}{\left|\alpha\left(t_{2}\right)-\alpha\left(t_{1}\right)\right|}\right)\left|\alpha\left(t_{2}\right)-\alpha\left(t_{1}\right)\right| \\
& =\varphi\left(\frac{\int_{t_{1}}^{t_{2}}\left|f_{\alpha^{\prime}}(t)\right| \mathrm{d} \alpha(t)}{\int_{t_{1}}^{t_{2}}|\mathrm{~d} \alpha(t)|}\right)\left|\alpha\left(t_{2}\right)-\alpha\left(t_{1}\right)\right|
\end{aligned}
$$

using the generalized Jenssen's inequality

$$
\begin{aligned}
& \leq \frac{\int_{t_{1}}^{t_{2}} \varphi\left(\left|f_{\alpha^{\prime}}(t)\right|\right) \mathrm{d} \alpha(t)}{\int_{t_{1}}^{t_{2}} \mathrm{~d} \alpha(t)}\left|\alpha\left(t_{2}\right)-\alpha\left(t_{1}\right)\right| \\
& =\int_{t_{1}}^{t_{2}} \varphi\left(\left|f_{\alpha^{\prime}}(t)\right|\right) \mathrm{d} \alpha(t) .
\end{aligned}
$$

Let $\pi: a=t_{0}<\cdots<t_{n}=b$ be any partition of interval [a,b]; then

$$
\begin{aligned}
& \sum_{i=1}^{n} \varphi\left(\left.\frac{\left|f\left(t_{2}\right)-f\left(t_{1}\right)\right|}{\left|\alpha\left(t_{2}\right)-\alpha\left(t_{1}\right)\right|}| | \alpha\left(t_{2}\right)-\alpha\left(t_{1}\right) \right\rvert\,\right. \\
& \leq \sum_{i=1}^{n} \int_{t_{i-1}}^{t_{j}} \varphi\left(\left|f_{\alpha^{\prime}}(t)\right|\right) \mathrm{d} \alpha(t)=\int_{a}^{b} \varphi\left(\left|f_{\alpha^{\prime}}(t)\right|\right) \mathrm{d} \alpha(t)<\infty
\end{aligned}
$$

and we have

$$
V_{\varphi}(f,[a, b], \alpha) \leq \int_{a}^{b} \varphi\left(\left|f_{\alpha}^{\prime}(x)\right|\right) \mathrm{d} \alpha(x)
$$

Thus $f \in R V_{\varphi}(f,[a, b], \alpha)$.
2) Let $f \in R V_{\varphi}[a, b]$. Then $f$ is $\alpha$-absolutely continuous on $[a, b]$ by Lemma 3.5 and $f_{\alpha}^{\prime}$ exist a.e. on $[a, b]$.

For every $n \in \mathbb{N}$, we consider

$$
\pi_{n}: a=t_{0, n}<t_{1, n}<\cdots<t_{n, n}=b
$$

a partition of the interval $[a, b]$ define by

$$
t_{i, n}=a+i \frac{b-a}{n}, \quad i=0,1, \cdots, n .
$$

Let $\left\{f_{n}\right\}_{n}$ be a sequence of step functions, defined by $f_{n}:[a, b] \rightarrow \mathbb{R}$

$$
t \mapsto f_{n}(t)= \begin{cases}\frac{f\left(t_{i+1, n}\right)-f\left(t_{i, n}\right)}{\alpha\left(t_{i+1, n}\right)-\alpha\left(t_{i, n}\right)}, & t_{i, n} \leq t<t_{i+1, n} \\ 0, & t=b\end{cases}
$$

$\left\{f_{n}\right\}_{n \in \mathbb{N}}$ converge to $f_{\alpha}^{\prime}$ a.e. on $[a, b]$. It is sufficient to prove $\left\{f_{n}\right\} \rightarrow f_{\alpha}^{\prime}$ in those points where $f$ is $\alpha-$ differentiable and different from $t_{i, n}, i=0, \cdots, n$ for $n \in \mathbb{N}$, i.e., in

$$
\begin{aligned}
\mathcal{A}= & \left\{t \in[a, b] / f_{\alpha}^{\prime}(t) \text { exists }\right\} \\
& -\left\{t_{i, n} / n \in \mathbb{N}, i=0,1, \cdots, n\right\}
\end{aligned}
$$

For $t \in \mathcal{A}$, and each $n \in \mathbb{N}$, there exists $k \in\{0, \cdots, n\}$ such that $t_{k, n} \leq t<t_{k+1, n}$, so

$$
\begin{aligned}
f_{n}(t) & =\frac{f\left(t_{k+1, n}\right)-f\left(t_{k, n}\right)}{\alpha\left(t_{k+1, n}\right)-\alpha\left(t_{k, n}\right)} \\
& =\frac{\alpha\left(t_{k+1, n}\right)-\alpha(t)}{\alpha\left(t_{k+1, n}\right)-\alpha\left(t_{k, n}\right)} \frac{f\left(t_{k+1, n}\right)-f(t)}{\alpha\left(t_{k+1, n}\right)-\alpha(t)} \\
& +\frac{\alpha(t)-\alpha\left(t_{k, n}\right)}{\alpha\left(t_{k+1, n}\right)-\alpha\left(t_{k, n}\right)} \frac{f(t)-f\left(t_{k, n}\right)}{\alpha(t)-\alpha\left(t_{k, n}\right)}
\end{aligned}
$$

Therefore, $f_{n}(t)$ is a convex combination of points

$$
\frac{f\left(t_{k+1, n}\right)-f(t)}{\alpha\left(t_{k+1, n}\right)-\alpha(t)} \text { and } \frac{f(t)-f\left(t_{k, n}\right)}{\alpha(t)-\alpha\left(t_{k, n}\right)}
$$

Now if $n \rightarrow \infty$, then $t_{k, n} \rightarrow t$ and $t_{k+1, n} \rightarrow t$ and since $f$ is $\alpha$-differentiable for $t$, the expressions

$$
\frac{f\left(t_{k+1, n}\right)-f(t)}{\alpha\left(t_{k+1, n}\right)-\alpha(t)} \text { and } \frac{f(t)-f\left(t_{k, n}\right)}{\alpha(t)-\alpha\left(t_{k, n}\right)}
$$

tend $f_{\alpha}^{\prime}(t)$ to which is $\alpha$-differentiable from $f$ in $t$. So results

$$
\lim _{n \rightarrow \infty} f_{n}(t)=f_{\alpha}^{\prime}(t)(t \in \mathcal{A} \text { a.e. in }[a, b])
$$

Since $\varphi$ is continuous, we have

$$
\lim _{n \rightarrow \infty} \varphi\left(\left|f_{n}(t)\right|\right)=\varphi\left(\lim _{n \rightarrow \infty}\left|f_{n}(t)\right|\right)=\varphi\left(\left|f_{\alpha}^{\prime}(t)\right|\right) \quad t \in \mathcal{A}
$$

Using the Fatou's Lemma and definition of $f_{n}^{\prime}$ sequence, results that

$$
\begin{aligned}
\int_{a}^{b} \varphi\left(\left|f_{\alpha}^{\prime}(t)\right|\right) \mathrm{d} \alpha(t) & =\int_{a}^{b} \lim _{n \rightarrow \infty} \varphi\left(\left|f_{n}(t)\right|\right) \mathrm{d} \alpha(t) \\
& \leq \liminf _{n \rightarrow \infty} \int_{a}^{b} \varphi\left(\left|f_{n}(t)\right|\right) \mathrm{d} \alpha(t) \\
& =\liminf _{n \rightarrow \infty} \sum_{i=0}^{n-1} \int_{t_{i, n}}^{t_{i+1, n}} \varphi\left(\left|f_{n}(t)\right|\right) \mathrm{d} \alpha(t)
\end{aligned}
$$

By definition from $f_{n}$

$$
\begin{aligned}
& =\liminf _{n \rightarrow \infty} \sum_{i=0}^{n-1} \int_{t_{i, n}}^{t_{i+1, n}} \varphi\left(\frac{\left|f\left(t_{i+1, n}\right)-f\left(t_{i, n}\right)\right|}{\left|\alpha\left(t_{i+1, n}\right)-\alpha\left(t_{i, n}\right)\right|}\left|\alpha\left(t_{i+1, n}\right)-\alpha\left(t_{i, n}\right)\right|\right. \\
& =\liminf _{n \rightarrow \infty} \sum_{i=0}^{n-1} \varphi\left(\frac{\left|f\left(t_{i+1, n}\right)-f\left(t_{i, n}\right)\right|}{\left|\alpha\left(t_{i+1, n}\right)-\alpha\left(t_{i, n}\right)\right|}\right) \int_{t_{i, n}}^{t_{i+1, n}} \mathrm{~d} \alpha(t) \\
& =\liminf _{n \rightarrow \infty} \sum_{i=0}^{n-1} \varphi\left(\frac{\left|f\left(t_{i+1, n}\right)-f\left(t_{i, n}\right)\right|}{\left|\alpha\left(t_{i+1, n}\right)-\alpha\left(t_{i, n}\right)\right|}\right)\left|\alpha\left(t_{i+1, n}\right)-\alpha\left(t_{i, n}\right)\right| \\
& \leq V_{\alpha}(f,[a, b])<+\infty
\end{aligned}
$$

which is what we wished to demonstrate.
Corollary 3.7 Let $\varphi \in \mathcal{N}$ such that satisfies the $\infty_{1}$ condition, then $f \in R V_{\varphi}(I)$ if and only if $f$ is $\alpha$-absolutely continuous on $[a, b]$ and

$$
\int_{a}^{b} \varphi\left(\left|f_{\alpha}^{\prime}(x)\right|\right) \mathrm{d} \alpha(x)<+\infty
$$

Also

$$
\int_{a}^{b} \varphi\left(\left|f_{\alpha}^{\prime}(x)\right|\right) \mathrm{d} \alpha(x)=R V_{\varphi}(f,[a, b], \alpha)
$$

Corollary 3.8 Let $\varphi \in \mathcal{N}$ such that satisfies the $\infty_{1}$ condition. If $f \in R V_{\varphi}(I)$, then $f$ is $\alpha$-absolutely continuous on $[a, b]$ and

$$
\int_{a}^{b} \varphi\left(\left|f_{\alpha}^{\prime}(x)\right|\right) \mathrm{d} \alpha(x)=R V_{\varphi}(f,[a, b], \alpha)
$$

## 4. Set-Valued Function

Let $c c(X)$ be the family of all non-empty convex compact subsets of $X$ and $D$ be the Hausdorff metric in $c c(X)$, i.e.,

$$
D(A, B):=\inf \{t>0: A \subseteq B+t S, B \subseteq A+t S\}
$$

where $S=\{y \in X:\|y\| \leq 1\}$, or equivalently,

$$
D(A, B)=\max \{e(A, B), e(A, B): A, B \in c c(X)\}
$$

where

$$
\left\{\begin{array}{l}
e(A, B)=\sup \{d(x, B): x \in A\}  \tag{2}\\
d(x, B)=\inf \{d(x, y): y \in B\}
\end{array}\right.
$$

Definition 4.1 Let $\varphi \in \mathcal{N}, \alpha$ a fixed continuous strictly increasing function and $F:[a, b] \rightarrow c c(X)$. We say that $F$ has bounded $\varphi$-variation in the sense of Riesz if

$$
\begin{align*}
& W_{\varphi}(F,[a, b], \alpha) \\
& :=\sup _{\pi} \sum_{i=1}^{n} \varphi\left(\frac{D\left(F\left(t_{i}\right), F\left(t_{i-1}\right)\right)}{\left|\alpha\left(t_{i}\right)-\alpha\left(t_{i-1}\right)\right|}\right)\left|\alpha\left(t_{i}\right)-\alpha\left(t_{i-1}\right)\right|<\infty \tag{3}
\end{align*}
$$

where the supremum is taken over all partitions $\pi$ of [a, b].

Definition 4.2 Denote by

$$
\begin{align*}
& R W_{\varphi}^{*}(F,[a, b], \alpha) \\
& :=\left\{F:[a, b] \rightarrow c c(X): W_{\varphi}(F,[a, b], \alpha)<\infty\right\} \tag{4}
\end{align*}
$$

and

$$
\begin{align*}
& R W_{\varphi}(F,[a, b], \alpha):=\{F:[a, b] \\
& \left.\rightarrow c c(X): R W_{\varphi}^{*}(\lambda F)<\infty \text { for some } \lambda>0\right\} \tag{5}
\end{align*}
$$

both equipped with the metric

$$
\begin{align*}
& D_{\varphi}\left(F_{1}, F_{2}\right):=D\left(F_{1}(a), F_{2}(a)\right) \\
& +\inf \left\{\varepsilon>0: W_{\varphi}\left(F_{1} / \varepsilon, F_{2} / \varepsilon\right) \leq 1\right\}, \tag{6}
\end{align*}
$$

where

$$
\begin{aligned}
& W_{\varphi}\left(F_{1}, F_{2}\right) \\
& =\sup _{\pi} \sum_{i=1}^{n} \varphi\left(\frac{D\left(F_{1}\left(t_{i}\right)+F_{2}\left(t_{i-1}\right), F_{1}\left(t_{i-1}\right)+F_{2}\left(t_{i}\right)\right)}{\left|\alpha\left(t_{i}\right)-\alpha\left(t_{i-1}\right)\right|}\right) \\
& \cdot\left|\alpha\left(t_{i}\right)-\alpha\left(t_{i-1}\right)\right| \cdot
\end{aligned}
$$

Now, let $(X,\|\cdot\|),(Y,\|\cdot\|)$ be two normed spaces and $K$ be a convex cone in $X$. Given a set-valued function $H:[a, b] \times K \rightarrow c c(Y)$ we consider the Nemytskii operator $N: K^{[a, b]} \rightarrow Y^{[a, b]}$ generated by $H$, that is
the composition operator defined by:

$$
(N f)(t):=H(t, f(t)), f:[a, b] \rightarrow K ; t \in[a, b]
$$

We denote by $L(K ; c c(Y))$ the space of all setvalued function $A: K \rightarrow c c(Y)$, i.e., additive and positively homogeneous, we say that $A$ is linear if $A \in L(K ; c c(Y))$.
In the proof of the main results of this paper, we will use some facts which we list here as lemmas.

Lemma 4.3 ([19]) Let $(X,\| \| \|)$ be a normed space and let $A, B, C$ be subsets of $X$. If $A, B$ are convex compact and $C$ is non-empty and bounded, then

$$
\begin{equation*}
D(A+C, B+C)=D(A, B) \tag{7}
\end{equation*}
$$

Lemma 4.4 ([20]) Let $(X,\|\cdot\|),(Y,\| \|)$ be normed spaces and $K$ be a convex cone in $X$. A set-valued function $F: K \rightarrow c c(Y)$ satisfies the Jensen equation

$$
\begin{equation*}
F\left(\frac{x+y}{2}\right)=\frac{1}{2}(F(x)+F(y)), x, y \in K \tag{8}
\end{equation*}
$$

if and only if there exists an additive set-valued function $A: K \rightarrow c c(Y)$ and a set $B \in c c(Y)$ such that

$$
F(x)=A(t)+B, \quad x \in K
$$

We will extend the results of Aziz, Guerrero, Merentes and Sánchez given in [8] and [21] to set-valued functions of $\varphi$-bounded variation with respect to the weight function $\alpha$.

## 5. Main Results

Lemma 5.1 If $\varphi \in \mathcal{N}$ such that satisfies the $\infty_{1}$ condition and

$$
F \in R W_{\varphi}([a, b] ; c c(Y), \alpha)
$$

then $F:[a, b] \rightarrow c c(X)$ is continuous.
Proof. Since $F \in R W_{\varphi}([a, b], \alpha)$, exists $\quad M>0$ such that

$$
\begin{equation*}
\sum_{i=1}^{n} \varphi\left(\frac{D\left(F\left(t_{i}\right), F\left(t_{i-1}\right)\right)}{\left|\alpha\left(t_{i}\right)-\alpha\left(t_{i-1}\right)\right|}\right)\left|\alpha\left(t_{i}\right)-\alpha\left(t_{i-1}\right)\right| \leq M \tag{9}
\end{equation*}
$$

for all partitions of $[a, b]$, in particular given $t, t_{0} \in[a, b]$, we have

$$
\begin{equation*}
\varphi\left(\frac{D\left(F(t), F\left(t_{0}\right)\right)}{\left|\alpha(t)-\alpha\left(t_{0}\right)\right|}\right)\left|\alpha(t)-\alpha\left(t_{0}\right)\right| \leq M \tag{10}
\end{equation*}
$$

Since $\varphi$ is convex $\varphi$-function, from the last inequa-
lity, we get

$$
\begin{equation*}
D\left(F(t), F\left(t_{0}\right)\right) \leq \frac{\varphi^{-1}\left(\frac{M}{\left|\alpha(t)-\alpha\left(t_{0}\right)\right|}\right)}{\frac{1}{\left|\alpha(t)-\alpha\left(t_{0}\right)\right|}} \tag{11}
\end{equation*}
$$

By (1),

$$
\begin{align*}
& \lim _{t \rightarrow t_{0}} D\left(F(t), F\left(t_{0}\right)\right) \\
& \leq \lim _{t \rightarrow t_{0}} \frac{\varphi^{-1}\left(\frac{M}{\left|\alpha(t)-\alpha\left(t_{0}\right)\right|}\right)}{\frac{1}{\left|\alpha(t)-\alpha\left(t_{0}\right)\right|}}=\lim _{\rho \rightarrow \infty} \frac{M \rho}{\varphi(\rho)}=0 . \tag{12}
\end{align*}
$$

This proves the continuity of $F$ at $t_{0}$. Thus $F$ is continuous on $[a, b]$.

Now, we are ready to formulate the main result of this work.

Main Theorem 5.2 Let $(X,\| \|),(Y,\| \| \|)$ be normed spaces, $K$ be a convex cone in $X$ and $\varphi_{1}, \varphi_{2}$ be two convex $\varphi$-functions in $X$, strictly increasing, that satisfy $\infty_{1}$ condition and such that there exists constants $c$ and $T_{0}$ with $\varphi_{2}(t) \leq \varphi_{1}(c t)$ for all $t \geq T_{0}$. If the Nemitskii operator $N$ generated by a set-valued function $H:[a, b] \times K \rightarrow c c(Y)$ maps the space $R V_{\varphi_{1}}(f,[a, b], \alpha ; K)$ into the space $R W_{\varphi_{2}}(f,[a, b], \alpha ; c c(Y))$ and if it is globally Lipschitz, then the set-valued function $H$ satisfies the following conditions:

1) For every $t \in[a, b]$ there exists $M(t) \in[0,+\infty)$, such that

$$
\begin{equation*}
D(H(t, x), H(t, y)) \leq M(t)\|x-y\|(x, y \in X) \tag{13}
\end{equation*}
$$

2) There are functions $A:[a, b] \rightarrow L(K, c c(Y))$ and $B \in R W_{\varphi_{2}}(f,[a, b], \alpha ; c c(Y))$ such that

$$
\begin{equation*}
H(t, x)=A(t) x+B(t) \quad(t \in[a, b], x \in K) \tag{14}
\end{equation*}
$$

Proof. 1) Since $N$ is globally Lipschitz, there exists a constant $M \in[0,+\infty)$ such that

$$
\begin{align*}
& D_{\varphi_{2}}\left(N f_{1}, N f_{2}\right) \\
& \leq M\left\|f_{1}-f_{2}\right\|_{\varphi_{1}}\left(f_{1}, f_{2} \in R V_{\varphi_{1}}([a, b], \alpha ; K)\right) \tag{15}
\end{align*}
$$

Using the definitions of the operator $N$ and metric $D_{\varphi_{2}}$ we have

$$
\begin{aligned}
& D\left(N f_{1}(a), N f_{2}(a)\right)+\inf \left\{\varepsilon>0: \sup _{\pi} \sum_{i=1}^{n} \varphi_{2}\left(\frac{D\left(h_{t_{i}, t_{i-1}} N_{f_{1}, f_{2}}, h_{t_{i-1}, t_{i}} N_{f_{1}, f_{2}}\right)}{\varepsilon\left|\alpha\left(t_{i}\right)-\alpha\left(t_{i-1}\right)\right|}\right)\left|\alpha\left(t_{i}\right)-\alpha\left(t_{i-1}\right)\right| \leq 1\right\} \\
& \leq M\left\|f_{1}-f_{2}\right\|_{\varphi_{1}}\left(f_{1}, f_{2} \in R V_{\varphi_{1}}([a, b], \alpha ; K)\right)
\end{aligned}
$$

where $h_{s, t} N_{f_{1}, f_{2}}:=\left(N f_{1}\right)(s)+\left(N F_{2}\right)(t)$. In particular,

$$
\inf \left\{\varepsilon>0: \varphi_{2}\left(\frac{D\left(d_{f_{1}, f_{2}}(H, t, \bar{t}), d_{f_{1}, f_{2}}(H, \bar{t}, t)\right)}{\varepsilon|\alpha(\bar{t})-\alpha(t)|}\right)|\alpha(\bar{t})-\alpha(t)| \leq 1\right\} \leq M\left\|f_{1}-f_{2}\right\|_{\rho_{1}},
$$

for all $f_{1}, f_{2} \in R V_{\varphi_{1}}([a, b], \alpha ; K)$ and $t, \bar{t} \in[a, b]$, $t \neq \bar{t}$, where

$$
d_{f_{1}, f_{2}}(H, s, t)=H\left(s, f_{1}(s)\right)+H\left(t, f_{2}(t)\right) .
$$

Since $\varphi_{1}$ and $\varphi_{2}$ satisfy we obtain

$$
\inf \left\{\varepsilon>0: \varphi_{2}\left(\frac{D\left(d_{f_{1}, f_{2}}(H, t, \bar{t}), d_{f_{1}, f_{2}}(H, \bar{t}, t)\right)}{\varepsilon|\alpha(\bar{t})-\alpha(t)|}\right)|\alpha(\bar{t})-\alpha(t)| \leq 1\right\}=D\left(d_{f_{1}, f_{2}}(H, t, \bar{t}), d_{f_{1}, f_{2}}(H, \bar{t}, t)\right)
$$

Therefore

$$
\begin{equation*}
D\left(d_{f_{1}, f_{2}}(H, t, \bar{t}), d_{f_{1}, f_{2}}(H, \bar{t}, t)\right) \leq M\left\|f_{1}-f_{2}\right\|_{\varphi_{1}}|\alpha(\bar{t})-\alpha(t)| \varphi_{2}\left(\frac{1}{|\alpha(\bar{t})-\alpha(t)|}\right) \tag{17}
\end{equation*}
$$

Define the auxiliary function $\eta:[a, b] \rightarrow[0,1]$ by:

$$
\eta(\tau):= \begin{cases}\frac{\alpha(\tau)-\alpha(a)}{\alpha(t)-\alpha(a)}, & a \leq \tau \leq t  \tag{18}\\ 1, & t \leq \tau \leq b\end{cases}
$$

Then $\eta \in R V_{\varphi_{1}}([a, b], \alpha)$ and

$$
\begin{align*}
& V_{\varphi_{1}}(\eta,[a, b], \alpha)=\varphi_{1}\left(\frac{1}{|\alpha(t)-\alpha(a)|}\right)|\alpha(t)-\alpha(a)| . \quad \begin{array}{c}
\text { Then the functions } f_{i} \in R V_{\varphi_{1}}([a, b] \\
\text { and }
\end{array} \\
&\left\|f_{1}-f_{2}\right\|_{\varphi_{1}}=\left\|f_{1}(a)-f_{2}(a)\right\| \\
&+\inf \left\{\varepsilon>0: \sup _{\pi} \sum_{i=1}^{n} \varphi_{1}\left(\frac{\left\|\left(f_{1}-f_{2}\right)\left(t_{i}\right)-\left(f_{1}-f_{2}\right)\left(t_{i-1}\right)\right\|}{\varepsilon\left|\alpha\left(t_{i}\right)-\alpha\left(t_{i-1}\right)\right|}\right)\left|\alpha\left(t_{i}\right)-\alpha\left(t_{i-1}\right)\right| \leq 1\right\} \tag{20}
\end{align*}
$$

From the definition of $f_{1}$ and $f_{2}$, we have

$$
\begin{equation*}
\left\|f_{1}-f_{2}\right\|_{\varphi_{1}}=\inf \left\{\varepsilon>0: \varphi_{1}\left(\frac{\|x-y\|}{\varepsilon|\alpha(t)-\alpha(a)|}\right)|\alpha(t)-\alpha(a)| \leq 1\right\} . \tag{21}
\end{equation*}
$$

From (16), we get

$$
\begin{equation*}
\inf \left\{\varepsilon>0: \varphi_{1}\left(\frac{\|x-y\|}{\varepsilon|\alpha(t)-\alpha(a)|}\right)|\alpha(t)-\alpha(a)|\right\}=\frac{\|x-y\|}{|\alpha(t)-\alpha(a)| \varphi_{1}^{-1}\left(\frac{1}{|\alpha(t)-\alpha(a)|}\right)} \tag{22}
\end{equation*}
$$

Hence,

$$
\begin{equation*}
D\left(d_{f_{1}, f_{2}}(H, t, \bar{t}), d_{f_{1}, f_{2}}(H, \bar{t}, t)\right) \leq \frac{M|\alpha(\bar{t})-\alpha(t)| \varphi_{2}^{-1}\left(\frac{1}{|\alpha(\bar{t})-\alpha(t)|}\right)\|x-y\|}{|\alpha(t)-\alpha(a)| \varphi_{1}^{-1}\left(\frac{1}{|\alpha(t)-\alpha(a)|}\right)} \tag{23}
\end{equation*}
$$

Hence, substituting in inequality (5) the particular functions $f_{i}(i=1,2)$ defined by (19) and taking $\alpha(\bar{t})=\alpha(a)$ in (23), we obtain

$$
\begin{equation*}
D(H(t, x)+H(a, x), H(a, x)+H(t, y)) \leq M \frac{\varphi_{2}^{-1}\left(\frac{1}{|\alpha(t)-\alpha(a)|}\right)}{\varphi_{1}^{-1}\left(\frac{1}{|\alpha(t)-\alpha(a)|}\right)}\|x-y\| \tag{24}
\end{equation*}
$$

for all $t \in[a, b], x, y \in K$.
By Lemma 4.3 and the inequality (24), we have

$$
D(H(t, x), H(t, y)) \leq M \frac{\varphi_{2}^{-1}\left(\frac{1}{|\alpha(t)-\alpha(a)|}\right)}{\varphi_{1}^{-1}\left(\frac{1}{|\alpha(t)-\alpha(a)|}\right)}\|x-y\|
$$

for all $t \in[a, b], x, y \in K$.

$$
\begin{equation*}
\eta_{1}(\tau):=\frac{\alpha(\tau)-\alpha(a)}{\alpha(b)-\alpha(a)}, \quad \tau \in[a, b] \tag{25}
\end{equation*}
$$

Now, we have to consider the case $\alpha(t)=\alpha(b)$. Define the function $\eta_{1}:[a, b] \rightarrow[0,1]$ by

$$
\begin{aligned}
\left\|f_{1}-f_{2}\right\|_{\varphi_{1}} & =\|x-y\|+\inf \left\{\varepsilon>0: \varphi_{1}\left(\frac{\|x-y\|}{\varepsilon|\alpha(b)-\alpha(a)|}\right)|\alpha(b)-\alpha(a)| \leq 1\right\} \\
& =\|x-y\|+\frac{\|x-y\|}{|\alpha(b)-\alpha(a)| \varphi_{1}^{-1}\left(\frac{1}{|\alpha(b)-\alpha(a)|}\right)} \\
& =\|x-y\|\left(1+\frac{1}{|\alpha(b)-\alpha(a)| \varphi_{1}^{-1}\left(\frac{1}{|\alpha(b)-\alpha(a)|}\right)}\right)
\end{aligned}
$$

Substituting $\alpha(\bar{t})=\alpha(a)$ and $\alpha(t)=\alpha(b)$, and consider $\alpha=\alpha(b)-\alpha(a)$, we obtain

$$
\begin{align*}
& D(H(b, x)+H(a, y), H(a, x)+H(b, x))  \tag{27}\\
& \leq M K\left(a, b, x, y, \varphi_{1}^{-1}, \varphi_{2}^{-1}\right)
\end{align*}
$$

for all $x, y \in K$, where

$$
\begin{aligned}
& K\left(a, b, x, y, \varphi_{1}^{-1}, \varphi_{2}^{-1}\right) \\
& =|\alpha| \varphi_{2}^{-1}\left(\frac{1}{|\alpha|}\right) \| x-y| |\left(1+\frac{1}{|\alpha| \varphi_{1}^{-1}\left(\frac{1}{|\alpha|}\right)}\right)
\end{aligned}
$$

By Lemma 4.3 and the above inequality, we get

$$
\begin{aligned}
& D(H(a, y), H(a, x)) \\
& \leq M|\alpha| \varphi_{2}^{-1}\left(\frac{1}{|\alpha|}\right)\|x-y\|\left(1+\frac{1}{|\alpha| \varphi_{1}^{-1}\left(\frac{1}{|\alpha|}\right)}\right)
\end{aligned}
$$

for all $x, y \in K$. Define the function $M:[a, b] \rightarrow \mathbb{R}$ by

$$
M(t)=\left\{\begin{array}{l}
M \frac{\varphi_{2}^{-1}\left(\frac{1}{|\alpha(t)-\alpha(a)|}\right)}{\varphi_{1}^{-1}\left(\frac{1}{|\alpha(t)-\alpha(a)|}\right)}, a<t \leq b \\
M|\alpha| \varphi_{2}^{-1}\left(\frac{1}{|\alpha|}\right)| | x-y| |\left(1+\frac{1}{|\alpha| \varphi_{1}^{-1}\left(\frac{1}{|\alpha|}\right)}\right), t=a .
\end{array}\right.
$$

Hence

$$
\begin{aligned}
& D(H(t, x), H(t, y)) \\
& \leq M(t)\|x-y\|(x, y \in X, t \in[a, b]),
\end{aligned}
$$

and, consequently, for every $t \in[a, b]$ the function $H:[a, b] \times K \rightarrow c c(Y)$ is continuous.
This completes the proof of part 1).
Now we shall prove that $H$ satisfies equality 2 ).
Let us fix $t, t_{0} \in[a, b]$ such that $t_{0}<t$. Since the Nemytskii operator $N$ is globally Lipschitzian, there exists a constant $M$, such that

$$
\begin{align*}
& D\left(d_{u, v}\left(H, t, t_{0}\right), d_{u, v}\left(H, t_{0}, t\right)\right) \\
& \leq M\|u-v\|_{\varphi_{1}}\left|\alpha\left(t_{0}\right)-\alpha(t)\right| \varphi_{2}\left(\frac{1}{\left|\alpha\left(t_{0}\right)-\alpha(t)\right|}\right), \tag{28}
\end{align*}
$$

where $\quad d_{u, v}(H, s, t)=H(s, u(s))+H(t, v(t))$. Define the function $\eta_{2}:[a, b] \rightarrow[0,1]$ by

$$
\eta_{2}(\tau)= \begin{cases}\frac{\alpha(\tau)-\alpha(a)}{\alpha\left(t_{0}\right)-\alpha(a)}, & a \leq \tau \leq t_{0} \\ \frac{\alpha(t)-\alpha(\tau)}{\alpha(t)-\alpha\left(t_{0}\right)}, & t_{0} \leq \tau \leq t \\ 0, & t \leq \tau \leq b\end{cases}
$$

The function $\eta_{2} \in R V_{\varphi_{1}}([a, b], \alpha)$.
Let us fix $x, y \in K$ and define the functions $f_{i}:[a, b] \rightarrow K$ by
$\begin{cases}f_{1}(\tau):=\frac{1}{2} \eta_{2}(\tau) x+\left(1-\frac{1}{2} \eta_{2}(\tau)\right) y, & \tau \in[a, b] ; \\ f_{2}(\tau):=\frac{1}{2}\left(1+\eta_{2}(\tau)\right) x+\frac{1}{2}\left(1-\eta_{2}(\tau)\right) y, & \tau \in[a, b] .\end{cases}$
The functions $f_{i} \in R V_{\varphi_{1}}([a, b], \alpha ; K) \quad(i=1,2)$ and

$$
\left\|f_{1}-f_{2}\right\|_{\varphi_{1}}=\frac{\|x-y\|}{2} .
$$

Hence, substituting in the inequality (28) the particular functions $f_{i} \quad(i=1,2)$ defined by (29), we obtain

$$
\begin{align*}
& D\left(H\left(t_{0}, x\right)+H(t, y), H\left(t_{0}, \frac{x+y}{2}\right)+H\left(t, \frac{x+y}{2}\right)\right) \\
& \leq \frac{1}{2} M\left|\alpha(t)-\alpha\left(t_{0}\right)\right| \varphi_{2}^{-1}\left(\frac{1}{\left|\alpha(t)-\alpha\left(t_{0}\right)\right|}\right)\|x-y\| . \tag{30}
\end{align*}
$$

Since $N$ maps

$$
R V_{\varphi_{1}}([a, b], \alpha ; K) \text { into } R W_{\varphi_{2}}([a, b], \alpha ; c c(Y))
$$

then $H(\cdot, z)$ is continuous for all $z \in K$. Hence letting $t_{0} \uparrow t$ in the inequality (30), we get

$$
\begin{align*}
& D\left(H(t, x)+H(t, y), H\left(t, \frac{x+y}{2}\right)+H\left(t, \frac{x+y}{2}\right)\right)  \tag{31}\\
& =0
\end{align*}
$$

for all $t \in[a, b]$ and $x, y \in K$.
Thus for all $t \in[a, b], x, y \in K$, we have

$$
\begin{equation*}
H\left(t, \frac{x+y}{2}\right)+H\left(t, \frac{x+y}{2}\right)=H(t, x)+H(t, y) . \tag{32}
\end{equation*}
$$

Since $H$ is convex, we have

$$
\begin{equation*}
H\left(t, \frac{x+y}{2}\right)=\frac{1}{2}[H(t, x)+H(t, y)] \tag{33}
\end{equation*}
$$

for all $t \in[a, b], x, y \in K$. Thus for all $t \in[a, b]$, the set-valued function $H(t, \cdot): K \rightarrow c c(Y)$ satisfies the Jensen Equation (33). Now by Lemma 4.4, there exists an additive set-valued function $A(t): K \rightarrow c c(Y)$ and a set $B(t) \in c c(Y)$, such that

$$
\begin{equation*}
H(t, x)=A(t) x+B(t),(x \in K, t \in[a, b]) . \tag{34}
\end{equation*}
$$

Substituting $H(t, x)=A(t) x+B(t)$ into inequality (13), we deduce that for all $t \in[a, b]$ there exists $M(t) \in[0,+\infty)$, such that

$$
D(A(t) x, A(t) y) \leq M(t)\|x-y\| \quad(x, y \in K)
$$

consequently, for every $t \in[a, b]$ the set-valued function $A(t): K \rightarrow c c(Y)$ is continuous, and

$$
A(t)(\cdot) \in L(K, c c(Y))
$$

Since $A(t)(\cdot)$ is additive and $0 \in K$, then $A(t)=\{0\}$ for all $t \in[a, b]$, thus $H(\cdot, 0)=B(\cdot)$.

The Nemytskii operator $N$ maps the space $R V_{\varphi_{1}}([a, b], \alpha ; K)$ into the space $R W_{\varphi_{2}}([a, b] ; c c(Y))$, then

$$
H(\cdot, 0)=B(\cdot) \in R W_{\varphi_{2}}([a, b], \alpha ; K)
$$

Consequently the set-valued function $H$ has to be of the form

$$
H(t, x)=A(t) x+B(t), \quad t \in[a, b], x \in K
$$

where $A(t) \in L(K, c c(Y))$ and

$$
B \in R W_{\varphi_{2}}([a, b], \alpha ; c c(Y))
$$

Theorem 5.3 Let $(X,\| \|),(Y,\| \|)$ be normed spaces, $K$ a convex cone in $X$ and $\varphi_{1}, \varphi_{2}$ be two convex $\varphi$-functions in $X$, strictly increassing, satisfying $\infty_{1}$ condition and $\lim _{t \rightarrow \infty} \varphi_{2}^{-1}\left(\varphi_{1}(t)\right) / t=\infty$. If the Nemytskii operator $N$ generated by a set-valued function $H:[a, b] \times K \rightarrow c c(Y)$ maps the space $R V_{\varphi_{2}}([a, b] \alpha ; K)$ into the space $R W_{\varphi_{1}}([a, b], \alpha ; c c(Y))$ and if it is globally Lipschizian, then the set-valued function $H$ satisfies the following condition

$$
H(t, x)=H(t, 0)(t \in[a, b], x \in K)
$$

i.e., the Nemytskii operator is constant.

Proof. Since the Nemytskii operator $N$ is globally Lipschizian between $R V_{\varphi_{1}}([a, b], \alpha ; K)$ and the space $R W_{\varphi_{1}}([a, b], \alpha ; c c(Y))$, then there exists a constant $M$, such that

$$
\begin{align*}
& D_{\varphi_{1}}\left(N f_{1}, N f_{2}\right) \\
& \leq M\left\|f_{1}-f\right\|_{2 \varphi_{2}}\left(f_{1}, f_{2} \in R V_{\varphi_{2}}([a, b], \alpha ; K)\right) \tag{35}
\end{align*}
$$

Let us fix $t, t_{0} \in[a, b]$ such that $t_{0}<t$. Using the definitions of the operator $N$ and of the metric $D_{\varphi_{1}}$, we have

$$
\begin{aligned}
& D\left(H\left(t, f_{1}(t)\right)+H\left(t_{0}, f_{2}\left(t_{0}\right)\right)\right. \\
& \left.H\left(t_{0}, f_{1}\left(t_{0}\right)\right)+H\left(t, f_{2}(t)\right)\right) \\
& \leq M\left|\alpha(t)-\alpha\left(t_{0}\right)\right|\left\|f_{1}-f_{2}\right\|_{\varphi_{2}} \varphi_{1}^{-1}\left(\frac{1}{\left|\alpha(t)-\alpha\left(t_{0}\right)\right|}\right) \\
& \left(f_{1}, f_{2} \in R V_{\varphi_{2}}([a, b], \alpha ; K)\right)
\end{aligned}
$$

Define the auxiliary function $\eta_{3}:[a, b] \rightarrow[0,1]$. by

$$
\eta_{3}(\tau):= \begin{cases}1, & a \leq \tau \leq t_{0} \\ -\frac{\alpha(\tau)-\alpha(t)}{\alpha(t)-\alpha\left(t_{0}\right)}, & t_{0} \leq \tau \leq t \\ 0, & t \leq \tau \leq b\end{cases}
$$

The function $\eta_{3} \in R V_{\varphi_{2}}([a, b], \alpha)$ and

$$
V_{\varphi_{2}}\left(\eta_{3} ;[a, b]\right)=\left|\alpha(t)-\alpha\left(t_{0}\right)\right| \varphi_{2}^{-1}\left(\frac{1}{\left|\alpha(t)-\alpha\left(t_{0}\right)\right|}\right)
$$

Let us fix $x \in K$ and define the functions $f_{i}:[a, b] \rightarrow K \quad(i=1,2) \quad$ by

$$
\begin{equation*}
f_{1}(\tau):=x, \quad f_{2}(\tau):=\eta_{3}(\tau) x, \quad \tau \in[a, b] \tag{37}
\end{equation*}
$$

The functions $f_{i} \in R V_{\varphi_{2}}([a, b], \alpha ; K) \quad(i=1,2)$ and

$$
\begin{aligned}
\left\|f_{1}-f_{2}\right\|_{\varphi_{2}} & =\left\|f_{1}(a)-f_{2}(a)\right\|+\inf \left\{\varepsilon>0: \sup _{\pi} \sum_{i=1}^{n} \varphi_{2}\left(\frac{\left\|\left(f_{1}-f_{2}\right)\left(t_{i}\right)-\left(f_{1}-f_{2}\right)\left(t_{i-1}\right)\right\|}{\varepsilon\left|\alpha\left(t_{i}\right)-\alpha\left(t_{i-1}\right)\right|}\right)\left|\alpha\left(t_{i}\right)-\alpha\left(t_{i-1}\right)\right| \leq 1\right\} \\
& =\inf \left\{\varepsilon>0: \varphi_{2}\left(\frac{\|x\|}{\varepsilon\left|\alpha(t)-\alpha\left(t_{0}\right)\right|}\right)\left|\alpha(t)-\alpha\left(t_{0}\right)\right| \leq 1\right\} \\
& =\frac{\|x\|}{\left|\alpha(t)-\alpha\left(t_{0}\right)\right| \varphi_{2}^{-1}\left(\frac{1}{\left|\alpha(t)-\alpha\left(t_{0}\right)\right|}\right)} .
\end{aligned}
$$

Hence, substituting in the inequality (36) the auxiliary functions $f_{i}(i=1,2)$ defined by (37), we obtain

$$
D\left(H(t, x)+H\left(t_{0}, x\right), H\left(t_{0}, x\right)+H(t, 0)\right) \leq M\left|\alpha(t)-\alpha\left(t_{0}\right)\right| \frac{\varphi_{1}^{-1}\left(\frac{1}{\left|\alpha(t)-\alpha\left(t_{0}\right)\right|}\right)}{\left|\alpha(t)-\alpha\left(t_{0}\right)\right| \varphi_{2}^{-1}\left(\frac{1}{\left|\alpha(t)-\alpha\left(t_{0}\right)\right|}\right)}\|x\| .
$$

By Lemma 4.3 and the above inequality, we get

$$
D(H(t, x), H(t, 0)) \leq M\left|\alpha(t)-\alpha\left(t_{0}\right)\right| \frac{\varphi_{1}^{-1}\left(\frac{1}{\left|\alpha(t)-\alpha\left(t_{0}\right)\right|}\right)}{\left|\alpha(t)-\alpha\left(t_{0}\right)\right| \varphi_{2}^{-1}\left(\frac{1}{\left|\alpha(t)-\alpha\left(t_{0}\right)\right|}\right)}\|x\|
$$

Since $\lim _{t \rightarrow \infty} \varphi_{2}^{-1}\left(\varphi_{1}(t)\right) / t=\infty$, letting $t_{0} \uparrow t$ in the above inequality, we have

$$
D(H(t, x), H(t, 0))=0
$$

Thus for all $t \in[a, b]$ and for all $x \in K$, we get

$$
H(t, x)=H(t, 0)
$$

Theorem 5.4 Let $(X,\| \|),(Y,\| \|)$ be normed spaces, $K$ a convex cone in $X$ and $\varphi$ be a convex $\varphi$ function in $X$ satisfying the $\infty_{1}$ condition. If the Nemytskii operator $N$ generated by a set-valued function $H:[a, b] \times K \rightarrow c c(Y)$ maps the space
$R V_{\varphi}([a, b], \alpha ; K)$ into the space $B W([a, b] ; c c(Y))$ and if it is globally Lipschizian, then the left regularization $H^{*}:[a, b] \times K \rightarrow c c(Y)$ of the function $H$ defined by

$$
H^{*}(t, x):= \begin{cases}H(t, x), & t \in(a, b], x \in K \\ \lim _{s \downarrow a} H(s, x), & t=a, x \in K\end{cases}
$$

satisfies the following conditions:

- for all $t \in[a, b]$ there exists $M(t)$, such that

$$
D\left(H^{*}(t, x), H^{*}(t, y)\right) \leq M(t)\|x-y\| \quad(x, y \in K)
$$

- $H^{*}(t, x)=A(t) x+B(t) \quad(t \in[a, b] x \in K)$, where $A(t)$ is a linear continuous set-valued function, and $B \in B W([a, b] ; c c(Y))$.
Proof. We take $t \in[a, b]$, and define the auxiliary function $\eta_{4}:[a, b] \rightarrow[0,1]$ by:

$$
\eta_{4}(\tau):= \begin{cases}1, & a \leq \tau \leq t \\ \frac{\alpha(\tau)-\alpha(b)}{\alpha(t)-\alpha(b)}, & t \leq \tau \leq b\end{cases}
$$

The function $\eta_{4} \in R V_{\varphi}([a, b], \alpha ; K)$ and

$$
V_{\varphi}\left(\eta_{4},[a, b]\right)=\varphi\left(\frac{1}{|\alpha(b)-\alpha(t)|}\right)|\alpha(b)-\alpha(t)|
$$

Let us fix $x, y \in K$ and define the functions $f_{i}:[a, b] \rightarrow K \quad(i=1,2) \quad$ by

$$
\begin{equation*}
f_{1}(\tau):=x, f_{2}(\tau):=\eta_{4}(\tau)(y-x)+x, \quad \tau \in[a, b] \tag{38}
\end{equation*}
$$

The functions $f_{i} \in R V_{\varphi}([a, b], \alpha ; K)(i=1,2)$ and

$$
\begin{equation*}
\left\|f_{1}-f_{2}\right\|_{\varphi}=\left\|f_{1}(a)-f_{2}(a)\right\|+\inf \left\{\varepsilon>0: \sup _{\pi} \sum_{i=1}^{n} \varphi\left(\frac{\left\|\left(f_{1}-f_{2}\right)\left(t_{i}\right)-\left(f_{1}-f_{2}\right)\left(t_{i-1}\right)\right\|}{\varepsilon\left|\alpha\left(t_{i}\right)-\alpha\left(t_{i-1}\right)\right|}\right)\left|\alpha\left(t_{i}\right)-\alpha\left(t_{i-1}\right)\right| \leq 1\right\} \tag{39}
\end{equation*}
$$

From the definition of $f_{1}$ and $f_{2}$, we obtain

$$
\begin{equation*}
\left\|f_{1}-f_{2}\right\|_{\varphi}=\|x-y\|\left(1+\frac{1}{|\alpha(b)-\alpha(t)| \varphi^{-1}\left(\frac{1}{|\alpha(b)-\alpha(t)|}\right)}\right) \tag{40}
\end{equation*}
$$

Since the Nemytskii operator $N$ is globally Lipschitzian between
$R V_{\varphi}([a, b], \alpha ; K)$ and $B W([a, b] ; c c(Y))$, then there exists a constant $M$, such that

$$
D\left(H\left(b, f_{1}(b)\right)+H\left(t, f_{2}(t)\right), H\left(t, f_{1}(t)\right)+H\left(b, f_{2}(b)\right)\right) \leq M\left\|f_{1}-f_{2}\right\|_{\varphi}
$$

for $f_{1}, f_{2} \in R V_{\varphi}([a, b], \alpha ; K)$. By Lemma 4.3, substituting the particular functions $f_{i} \quad(i=1,2)$ defined by (38) in the above inequality, we obtain

$$
\begin{equation*}
D\left(H\left(b, f_{1}(b)\right)+H\left(t, f_{2}(t)\right), H\left(t, f_{1}(t)\right)+H\left(b, f_{2}(b)\right)\right) \leq M(t)\|x-y\|_{\varphi} \tag{41}
\end{equation*}
$$

for all $x, y \in K, t \in[a, b]$. By Lemma 4.3, we get

$$
\begin{equation*}
D(H(t, x), H(t, y)) \leq M(t)\|x-y\|_{\varphi} \tag{42}
\end{equation*}
$$

for all $t \in[a, b)$ and $x, y \in K$.
In the case where $t=b$, by a similar reasoning as
above, we obtain that there exists a constant $M(b)$, such that

$$
\begin{equation*}
D(H(b, x), H(b, y)) \leq M(b)\|x-y\|_{\varphi}(x, y \in K) \tag{43}
\end{equation*}
$$

Define the function $M:[a, b] \rightarrow \mathbb{R}$ by

$$
M(t)= \begin{cases}M\left(1+\frac{1}{|\alpha(b)-\alpha(t)| \varphi^{-1}\left(\frac{1}{|\alpha(b)-\alpha(t)|}\right)}\right) & , a \leq t<b  \tag{44}\\ M(b), & t=b\end{cases}
$$

Hence,

$$
\begin{aligned}
& D(H(t, x), H(t, y)) \leq M(t)\|x-y\|_{\varphi} \\
& t \in[a, b], x, y \in K
\end{aligned}
$$

By passing to the limit in the inequality (41) by the inequality (43) and the definition of $H^{*}$ we have for all $t \in[a, b]$ that there exists $M(t)$, such that

$$
\begin{aligned}
& D\left(H^{*}(t, x), H^{*}(t, y)\right) \leq M(t)\|x-y\|_{\varphi} \\
& (t \in[a, b] x, y \in K)
\end{aligned}
$$

Now we shall prove that $H^{*}$ satisfies the following equality

$$
H^{*}(t, x)=A(t) x+B(t) \quad(t \in[a, b], x \in K)
$$

where $A(t)$ is a linear continuous set-valued functions, and

$$
B \in B W([a, b] ; c c(Y)) .
$$

Let us fix $t, t_{0} \in[a, b], n \in \mathbb{N}$ such that $t_{0}<t$. De-

$$
\eta_{5}(\tau):= \begin{cases}0, & a \leq \tau \leq t_{0} \\ \frac{\alpha(\tau)-\alpha\left(t_{i-1}\right)}{\alpha\left(t_{i}\right)-\alpha\left(t_{i-1}\right)}, & t_{i-1} \leq \tau \leq t_{i}, i=1,3, \cdots, 2 n-1 \\ -\frac{\alpha(\tau)-\alpha\left(t_{i}\right)}{\alpha\left(t_{i}\right)-\alpha\left(t_{i-1}\right)}, & t_{i-1} \leq \tau \leq t_{i}, i=2,4, \cdots, 2 n \\ 0, & t \leq \tau \leq b\end{cases}
$$

The function $\eta_{5} \in R V_{\varphi}([a, b], \alpha ; K)$ and

$$
V_{\varphi}\left(\eta_{5}, \alpha ;[a, b]\right)=\left|\alpha(t)-\alpha\left(t_{0}\right)\right| \varphi\left(\frac{2 n}{\mid \alpha(t)-\alpha\left(\left(t_{0}\right) \mid\right.}\right)
$$

Let us fix $x, y \in K$ and define the functions $f_{i}:[a, b] \rightarrow K$ by:

$$
\begin{cases}f_{1}(\tau):=\frac{1}{2} \eta_{5}(\tau) x+\left[1-\frac{1}{2} \eta_{5}(\tau)\right] y, & \tau \in[a, b]  \tag{46}\\ f_{2}(\tau):=\frac{1}{2}\left[1+\eta_{5}(\tau)\right] x+\frac{1}{2}\left[1-\eta_{5}(\tau)\right] y, & \tau \in[a, b]\end{cases}
$$

The functions $f_{i} \in R V_{\varphi}([a, b], \alpha ; K)(i=1,2)$ and

$$
\left\|f_{1}-f_{2}\right\|_{\varphi}=\frac{\|x-y\|}{2}
$$

Substituting in the inequality (45) the particular functions $f_{i}(i=1,2)$ defined in (46), we obtain

$$
\begin{equation*}
\sum_{i=1}^{n} D\left(H\left(t_{2 i-1}, x\right)+H\left(t_{2 i}, y\right), H\left(t_{2 i-1}, \frac{x+y}{2}\right)+H\left(t_{2 i}, \frac{x+y}{2}\right)\right) \leq \frac{1}{2} M\|x-y\|_{\varphi} \quad x, y \in K . \tag{47}
\end{equation*}
$$

Since the Nemytskii operator $N$ maps the spaces $R V_{\varphi}([a, b], \alpha ; K)$ into $B W([a, b] ; c c(Y))$, then for all $z \in K$, the function $H(\cdot, z) \in B W([a, b] ; c c(Y))$. Letting $t_{0} \uparrow t$ in the inequality (47), we get

$$
\begin{aligned}
& D\left(H^{*}(t, x)+H^{*}(t, y), H^{*}\left(t, \frac{x+y}{2}\right)+H^{*}\left(t, \frac{x+y}{2}\right)\right) \\
& \leq \frac{M}{2 n}\|x-y\|_{\varphi} .
\end{aligned}
$$

for all $x, y \in K$ and $n \in \mathbb{N}$. By passing to the limit when $n \rightarrow \infty$, we get

$$
\begin{aligned}
& H^{*}\left(t, \frac{x+y}{2}\right)+H^{*}\left(t, \frac{x+y}{2}\right)=H^{*}(t, x)+H^{*}(t, y) \\
& t \in[a, b], x, y \in K
\end{aligned}
$$

Since $H^{*}(t, x)$ is a convex function, then

$$
\begin{aligned}
& H^{*}\left(t, \frac{x+y}{2}\right)=\frac{1}{2}\left[H^{*}(t, x)+H^{*}(t, y)\right] \\
& (t \in[a, b], x, y \in K) .
\end{aligned}
$$

Thus for every $t \in[a, b]$, the set-valued function $H^{*}(t, \cdot): K \rightarrow c c(Y)$ satisfies the Jensen equation. By Lemma 4.4 and by the property (a) previously established, we get that for all $t \in[a, b]$ there exist an additive set-valued function $A(\cdot): K \rightarrow c c(Y)$ and a set $B(t) \in c c(Y)$, such that

$$
H^{*}(t, x)=A(t) x+B(t) \quad(t \in[a, b], x \in K)
$$

By the same reasoning as in the proof of Theorem 5.2, we obtain that

$$
A(t)(\cdot) \in L(K, c c(Y)) \text { and } B \in B W([a, b] ; c c(Y))
$$

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