A Thermal Shock-Chemical Reactive Problem in Flow of Viscoelastic Fluid with Thermal Relaxation

Magdy A. Ezzat^{1*}, Wisam Khatan²

¹Department of Mathematics, Faculty of Sciences and Letters in Al Bukayriyyah, Al-Qassim University, Al-Qassim, KSA ²Department of Mathematics, Faculty of Education, Damanhuur University, Damanhuur, Egypt Email: *maezzat2000@yahoo.com

Received April 20, 2012; revised May 20, 2012; accepted May 27, 2012

ABSTRACT

Effects of thermal and species diffusion with one relaxation time on the boundary layer flow of a viscoelastic fluid bounded by a vertical surface in the presence of transverse magnetic field have been studied. The state space approach developed by Ezzat [1] is adopted for the solution of one-dimensional problem for any set of boundary conditions. The resulting formulation together with the Laplace transform techniques are applied to a thermal shock-chemical reactive problem. The inversion of the Laplace transforms is carried out using a numerical approach. The numerical results of dimensionless temperature, concentration, velocity, and induced magnetic and electric fields distributions are given and illustrated graphically for the problem.

Keywords: MHD; Heat and Mass Transfer; Boundary Layer Theory; Viscoelastic Fluid; State Space Approach; Lord-Shulman Theory; Numerical Results

1. Introduction

Viscoelastic flows are encountered in numerous areas of petrochemical, biomedical and environmental engineering including polypropylene coalescence sintering [2] and geological flows [3]. A wide range of mathematical models have been developed to simulate the nonlinear stress-strain characteristics of such fluids which exhibit both viscous and elastic properties [4].

In nature and many industrial applications, there are plenty of transport processes where simultaneous heat and mass transfer is a common phenomenon. Its application is found in many diverse fields but not limited to cleaning operations, curing of plastics, manufacturing of pulp-insulated cables, many chemical processes such as analysis of polymers in chemical engineering, condensation and frosting of heat exchangers [5]. The study of convection reduces to the determination of convective heat and mass transfer coefficients. Convective heat and mass transfer coefficients are important parameters, which are a measure of the resistance to heat and mass transfer between a surface and the fluid flowing over that surface. The convective coefficients depend on the hydrodynamic, thermal and concentration boundary layers. In many of the internal flows, both forced and natural convection play major roles in the heat and mass transfer processes.

Whereas in the entrance section of a duct, forced convection becomes dominant, as the flow moves towards the downstream section, natural convection could dominate over forced convection and finally in the thermally developed region natural convection becomes negligible. Natural convection may be due to a temperature or concentration gradient or both. If the buoyancy forces are due to temperature and concentration gradients that act in the same direction, both the heat and mass transfer will increase. However, if the temperature and concentration gradients act in the opposite direction, both heat and mass transfer reduce [6].

In recent years, the study of viscoelastic fluid flow is an important type of flow occurring in several engineering processes. Such processes are wire drawing, glass fiber and paper production, crystal growing, drawing of plastic sheets, among which we also cite many applications in petroleum in drilling, manufacturing of foods and slurry transporting. The boundary layer concept of such fluids is of special importance due to its applications to many engineering problems among which we cite the possibility of reducing frictional drag on the hulls of ships and submarines.

A great deal of works has been carried out on various aspects of momentum and heat transfer characteristics in a viscoelastic boundary layer fluid flow over a stretching plastic boundary [7] since the pioneering work of Sa-

Scientific

Research

^{*}Corresponding author.

kiadis [8]. Ezzat and Zakaria [9] studied the effects of free convection currents with one relaxation time on the flow of a viscoelastic fluid through a porous medium. Khan and Sanjayanand [10] studied heat and mass transfer in a viscoelastic boundary layer flow over exponentially stretching sheet.

In this work, we use a more general model of MHD mixed convection flow of conducting viscoelastic fluid which also includes both the relaxation time in the heat and concentration equation and the electric permeability of the electromagnetic field. The unsteady free convection heat and mass transfer flow of electrically conducting incompressible viscoelastic fluid past an infinite vertical plate in the presence of a transverse magnetic field and chemical reaction using the state space approach and Laplace transforms technique. The inversion of the Laplace transform is carried out using a numerical technique [11].

2. Formulation of the Problem

The electro-magnetic quantities satisfy Maxwell's equations [12]:

$$\operatorname{curl} \boldsymbol{h} = \boldsymbol{J} + \varepsilon_o \frac{\partial \boldsymbol{E}}{\partial t} \tag{1}$$

$$\operatorname{curl} \boldsymbol{E} = -\mu_0 \frac{\partial \boldsymbol{h}}{\partial t} \tag{2}$$

$$div \, \boldsymbol{h} = 0 \,, \quad div \, \boldsymbol{E} = 0 \tag{3}$$

$$\boldsymbol{B} = \mu_o \left(\boldsymbol{H}_o + \boldsymbol{h} \right), \quad \boldsymbol{D} = \varepsilon_o \boldsymbol{E}$$
(4)

These equations are supplemented by Ohm's law

$$\boldsymbol{J} = \boldsymbol{\sigma}_o \left[\boldsymbol{E} + \boldsymbol{\mu}_o \boldsymbol{V} \times \boldsymbol{H}_o \right]$$
(5)

Consider an unsteady free convection flow of electrically conducting incompressible, viscoelastic fluid past an infinite vertical plate. The *x*-axis is taken in the vertical direction along the plate and *y*-axis normal to it. Let *u* be the component of the velocity of the fluid in the *x* direction and a constant magnetic field acts in the *y* direction of strength $H_o = (0, H_o, 0)$. This produces an induced magnetic field h = (h, 0, 0) and an induced electric field E = (0, 0, E) as well as a conduction current density J = (0, 0, J). All the considered functions will depend on *y* and the time *t* only.

Equation (5) reduces to

$$J = \sigma_o \left[E + \mu_o H_o u \right]. \tag{6}$$

The vector Equations (1) and (2) reduced to the following scalar equation

$$\frac{\partial h}{\partial y} = -\left(J + \varepsilon_o \frac{\partial E}{\partial t}\right) \tag{7}$$

Copyright © 2012 SciRes.

$$\frac{\partial E}{\partial t} = -\mu_o \frac{\partial h}{\partial y} \tag{8}$$

Eliminating J between Equations (6) and (7) we obtain

$$\frac{\partial h}{\partial y} = -\left(\sigma_o E + \varepsilon_o \frac{\partial E}{\partial t}\right) - \sigma_o \mu_o H_o u \tag{9}$$

Eliminating E between Equations (8) and (9) we obtain

$$\nu_m \frac{\partial^2 h}{\partial y^2} = \frac{\partial h}{\partial t} + \frac{\varepsilon_o}{\sigma_o} \frac{\partial^2 h}{\partial t^2} - H_o \frac{\partial u}{\partial y}$$
(10)

The Lorentz force has a non-vanishing component in the x-direction, given by:

$$F_{x} = \left(\boldsymbol{J} \times \boldsymbol{B}\right)_{x} = \mu_{o} H_{o} \left(\frac{\partial h}{\partial y} + \varepsilon_{o} \frac{\partial E}{\partial t}\right)$$
(11)

Assume that the viscoelastic fluid contains some chemically reactive diffusive species then the equations describing the flow in the boundary layer reduce to:

$$\frac{\partial u}{\partial t} = v \frac{\partial^2 u}{\partial y^2} + g \beta_T \left(T - T_\infty \right) + g \beta_c \left(c - c_\infty \right) - k_0 \frac{\partial^3 u}{\partial t \partial y^2} + \frac{\alpha^2}{H_0} \left(\frac{\partial h}{\partial y} + \varepsilon_0 \frac{\partial E}{\partial t} \right)$$
(12)

$$\upsilon_m \frac{\partial^2 h}{\partial y^2} = \frac{\partial h}{\partial t} + \frac{\varepsilon_o}{\sigma_o} \frac{\partial^2 h}{\partial t^2} - H_o \frac{\partial u}{\partial y}$$
(13)

$$\left(1 + \tau_o \frac{\partial}{\partial t}\right) \frac{\partial T}{\partial t} = \frac{k}{\rho C_p} \frac{\partial^2 T}{\partial y^2}$$
(14)

$$\frac{\partial h}{\partial y} = -\left(\sigma_o E + \varepsilon_o \frac{\partial E}{\partial t}\right) - \sigma_o \mu_o H_o u \qquad (15)$$

$$\left(1+\tau_o\frac{\partial}{\partial t}\right)\frac{\partial c}{\partial t} = D\frac{\partial^2 c}{\partial y^2} - Kc$$
(16)

Introduce the non-dimensional quantities.

$$y^{*} = \frac{\alpha}{\upsilon} y, t^{*} = \frac{\alpha^{2}}{\upsilon} t, k^{*} = \frac{\alpha^{2}}{\upsilon} k, E^{*} = \frac{1}{\mu H_{o} \alpha} E,$$

$$u^{*} = \frac{u}{\alpha}, k_{o}^{*} = \frac{\alpha^{2}}{\upsilon^{2}} k_{o}, h^{*} = \frac{h}{H_{o}}, x^{*} = \frac{\alpha}{\upsilon} x$$

$$\varepsilon_{o}^{*} = \mu \alpha^{2} \varepsilon_{o}, \sigma_{o}^{*} = \mu_{0} \upsilon \sigma_{o}, P^{*} = \frac{P}{\alpha^{2} \rho}, \tau_{o}^{*} = \frac{\alpha^{2}}{\upsilon} \tau_{o},$$

$$T^{*} = \frac{T - T_{\infty}}{T_{o} - T_{\infty}}, S_{c} = \frac{\upsilon}{D}, c^{*} = \frac{c - c_{\infty}}{c_{o} - c_{\infty}},$$

$$K^{*} = \frac{\upsilon}{\alpha^{2}} K, J^{*} = \frac{\upsilon}{H_{o} \alpha} J, P_{r} = \frac{\upsilon \rho C_{p}}{K},$$

$$G_{T} = \frac{\upsilon \beta_{T} g (T_{o} - T_{\infty})}{\alpha^{3}}, G_{c} = \frac{\upsilon \beta_{C} g (c_{o} - c_{\infty})}{\alpha^{3}}$$
(17)

With the help of the non-dimensional quantities above Equations (12)-(16) reduced to the non-dimensional equations

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial y^2} - k_o \frac{\partial^3 u}{\partial t \partial y^2} + G_T T + G_c c + \frac{\partial h}{\partial y} + \varepsilon_0 \frac{\partial E}{\partial t} \quad (18)$$

$$\frac{\partial^2 h}{\partial y^2} = \varepsilon_1 \frac{\partial^2 h}{\partial t^2} + b \left(\frac{\partial h}{\partial t} - \frac{\partial u}{\partial y} \right)$$
(19)

$$\left(1+\tau_o\frac{\partial}{\partial t}\right)\frac{\partial T}{\partial t} = \frac{1}{P_r}\frac{\partial^2 T}{\partial y^2}$$
(20)

$$\left(1 + \tau_o \frac{\partial}{\partial t}\right) \frac{\partial c}{\partial t} = \frac{1}{S_c} \frac{\partial^2 c}{\partial y^2} - Kc$$
(21)

$$\frac{\partial h}{\partial y} = -\left(\sigma_o E + \varepsilon_o \frac{\partial E}{\partial t}\right) - \sigma_o u \tag{22}$$

where $b = \frac{v}{v_m}$, $\varepsilon_1 = \frac{b\varepsilon_o}{\sigma_o}$.

To simplify the algebra, only problems with zero initial conditions are considered. Taking Laplace transform of Equations (18)-(22) and writing the resulting equations in matrix form results in (23). where

$$m_{1} = P_{r}s(1 + \tau_{o}s),$$

$$m_{2} = S_{c}[s(1 + \tau_{o}s) + K],$$

$$m_{4} = s(b + s\varepsilon_{1}),$$

$$n^{2} = \frac{\left(1 - \frac{\varepsilon_{o}s}{\sigma_{o} + \varepsilon_{o}s}\right)}{1 - sk_{o}}$$

and

$$m_3 = \frac{s\left(1 + \frac{\varepsilon_o \sigma_o}{\sigma_o + \varepsilon_o s}\right)}{1 - sk_o}.$$

In Equation (23) the overbar denotes the Laplace transform and the prime indicates differentiations with respect to y.

Equation (23) can be written in constracted form as

$$\frac{\mathrm{d}V(y,s)}{\mathrm{d}y} = A(s)\overline{V}(y,s) \tag{24}$$

The formal solution can be expressed as:

$$\overline{V}(y,s) = \exp[A(s)y]\overline{V}(0,s)$$
(25)

The characteristic equation of the matrix A(s) is

$$k^{8} - I_{1}k^{6} + I_{2}k^{4} - I_{3}k^{2} + I_{4} = 0$$
 (26)

where

$$I_{1} = m_{1} + m_{2} + m_{3} + m_{4} + bn^{2}$$

$$I_{2} = m_{1}m_{2} + m_{1}m_{3} + m_{1}m_{4} + m_{2}m_{3} + m_{2}m_{4}$$

$$+ m_{3}m_{4} + m_{1}bn^{2} + m_{2}bn^{2}$$

$$I_{3} = m_{1}m_{3}m_{4} + m_{2}m_{3}m_{4} + m_{1}m_{2}m_{3}$$

$$+ m_{1}m_{2}m_{4} + m_{1}m_{2}bn^{2}$$

$$I_{4} = m_{1}m_{2}m_{3}m_{4}$$
(27)

The roots $\pm k_1$, $\pm k_2$, $\pm k_3$ and $\pm k_4$ of Equation (25) satisfy the relations:

$$k_{1}^{2} + k_{2}^{2} + k_{3}^{2} + k_{4}^{2} = I_{1}$$

$$k_{1}^{2}k_{2}^{2} + k_{1}^{2}k_{3}^{2} + k_{1}^{2}k_{4}^{2} + k_{2}^{2}k_{3}^{2} + k_{2}^{2}k_{4}^{2} + k_{3}^{2}k_{4}^{2} = I_{2}$$

$$k_{1}^{2}k_{2}^{2}k_{3}^{2} + k_{1}^{2}k_{2}^{2}k_{4}^{2} + k_{2}^{2}k_{3}^{2}k_{4}^{2} = I_{3}$$

$$k_{1}^{2}k_{2}^{2}k_{3}^{2}k_{4}^{2} = I_{4}$$
(28)

Two of the roots, say $\pm k_1$ and $\pm k_2$ have simple expression given by

$$k_1^2 = m_1,$$

 $k_2^2 = m_2.$ (29a)

The other two roots $\pm k_3$ and $\pm k_4$ satisfy the relation

$$\frac{\mathrm{d}}{\mathrm{d}y} \begin{bmatrix} \overline{T} \\ \overline{c} \\ \overline{u} \\ \overline{h} \\ \overline{r}' \\ \overline{c'} \\ \overline{u'} \\ \overline{h'} \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ m_1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & m_2 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & m_2 & 0 & 0 & 0 & 0 & 0 & 0 \\ \frac{-G_T}{1-sk_0} & \frac{-G_c}{1-sk_0} & m_3 & 0 & 0 & 0 & 0 & -n^2 \\ 0 & 0 & 0 & m_4 & 0 & 0 & -b & 0 \end{bmatrix} \begin{bmatrix} \overline{T} \\ \overline{c} \\ \overline{u} \\ \overline{h'} \\ \overline{c'} \\ \overline{u'} \\ \overline{h'} \end{bmatrix}$$
(23)

$$k_3^2 + k_4^2 = bn^2 + m_3 + m_4 k_3^2 k_4^2 = m_3 m_4.$$
 (29b)

The Maclaurin series expansion of $\exp[A(s) \cdot y]$ is given by

$$\exp\left[A(s)y\right] = \sum_{n=0}^{\infty} \frac{\left[A(s) \cdot y\right]^n}{n!}$$

Using the Cayley-Hamilton theorem, the infinite series can be truncated to the following form

$$\exp[A(s) \cdot y] = a_0 I + a_1 A + a_2 A^2 + a_3 A^3 + a_4 A^4 + a_5 A^5 + a_6 A^6 + a_7 A^7,$$
(30)

where I is the unit matrix of order 8 and $a_0 - a_7$ are some parameters depending on s and y.

The characteristic roots $\pm k_1$, $\pm k_2$, $\pm k_3$ and $\pm k_4$ of the matrix A must satisfy the equations.

$$\exp(\pm k_{1}y) = a_{0} \pm a_{1}k_{1} + a_{2}k_{1}^{2} \pm a_{3}k_{1}^{3} + a_{4}k_{1}^{4}$$
$$\pm a_{5}k_{1}^{5} + a_{6}k_{1}^{6} \pm a_{7}k_{1}^{7}$$
$$\exp(\pm k_{2}y) = a_{0} \pm a_{1}k_{2} + a_{2}k_{2}^{2} \pm a_{3}k_{2}^{3} + a_{4}k_{2}^{4}$$
$$\pm a_{5}k_{2}^{5} + a_{6}k_{2}^{6} \pm a_{7}k_{2}^{7}$$
$$\exp(\pm k_{3}y) = a_{0} \pm a_{1}k_{3} + a_{2}k_{3}^{2} \pm a_{3}k_{3}^{3} + a_{4}k_{3}^{4}$$
$$\pm a_{5}k_{3}^{5} + a_{6}k_{3}^{6} \pm a_{7}k_{3}^{7}$$
$$\exp(\pm k_{4}y) = a_{0} \pm a_{1}k_{4} + a_{2}k_{4}^{2} \pm a_{3}k_{4}^{3} + a_{4}k_{4}^{4}$$
$$\pm a_{5}k_{4}^{5} + a_{6}k_{4}^{6} \pm a_{7}k_{4}^{7}$$

The solution of this system of linear equations is given in Appendix A:

Substituting for the parameters $a_0 - a_7$ into Equation (30) and computing A^2 , A^3 , A^4 , A^5 , A^6 and A^7 , we get, the elements $(\ell_{ij}, j = 1, 2, 3, 4, 5, 6, 7, 8)$ of the matrix L(y, s)which listed in Appendix B.

It should be noted here that, we have used Equation (29) in order to write these entries in the simplest possible form. It should also be noted that this is a formal expression for the matrix exponential. In the physical problem $0 \le y < \infty$, we should suppress the positive exponential which are unbounded at infinity. Thus we should replace each $\sinh(ky)$ by $-\frac{1}{2}\exp(-ky)$ and each

 $\cosh(ky)$ by $\frac{1}{2}\exp(-ky)$.

It is now possible to solve broad class problems in the Laplace transform domain.

3. Thermal Shock-Chemical Reactive Problem

Consider the free convection flow of an incompressible

$$T(0,t) = T_oH(t),$$

$$c(0,t) = c_oH(t)$$
(31)

and the mechanical boundary conditions on the plate is taken as

$$u(0,t) = 0,$$

 $h(0,t) = 0$
(32)

where T_o and c_o are constant and H(t) is Heaviside unit step function.

Now we apply the state space approach described above to this problem.

Since the solution is bounded at infinity, then the expressions for $\ell_{ij} = 1, 2, \dots, 8$ can be obtained by suppressing the positive exponential terms in Equation (30) which are not bounded at infinity. Thus for $x \ge 0$, we should replace each $\sinh(ky)$ by $-\exp(-ky)/2$ and each $\cosh(ky)$ by $\exp(-ky)/2$.

The components of the transformed initial state vector V(0,s) are known name

$$\overline{T}(0,s) = \frac{T_o}{s},$$

$$\overline{c}(0,s) = \frac{C_o}{s}$$

$$\overline{u}(0,s) = 0,$$
(34)

In order to obtain the remaining four components $\overline{T}'(0,s), \ \overline{c}'(0,s), \ \overline{u}'(0,s)$ and $\overline{h}'(0,s)$ we substitute y = 0 into Equations (31) and (32) to obtain the following linear system of equations:

 $\overline{h}(0,s) = 0$

$$\overline{T}'(0,s) = \ell_{51} \frac{T_o}{s} + \ell_{55} \overline{T}'(0,s)$$

$$\overline{c}'(0,s) = \ell_{62} \frac{c_o}{s} + \ell_{66} \overline{c}'(0,s)$$

$$\overline{u}'(0,s) = \ell_{71} \frac{T_o}{s} + \ell_{72} \frac{c_o}{s} + \ell_{75} \overline{T}'(0,s)$$

$$+ \ell_{76} \overline{c}'(0,s) + \ell_{77} \overline{u}'(0,s) + \ell_{78} \overline{h}'(0,s)$$
(35)

$$\overline{h}'(0,s) = \ell_{81} \frac{\overline{T_o}}{s} + \ell_{82} \frac{c_o}{s} + \ell_{85} \overline{T}'(0,s) + \ell_{86} \overline{c}'(0,s) + \ell_{87} \overline{u}'(0,s) + \ell_{88} \overline{h}'(0,s)$$

By solving this system, we arrive at

$$\begin{aligned} \overline{T}'(0,s) &= \frac{-k_1}{s} T_o, \overline{c}'(0,s) = \frac{-k_2}{s} c_o \\ \overline{u}'(0,s) &= \sum_{i=1}^2 A_i \left(k_3^2 - k_i^2\right) \left(k_i^2 - k_4^2\right) \left(\frac{k_3 + k_4}{(k_3 + k_4)^2 - bn^2}\right) \left\{ 2k_i \frac{\left[k_i bn^2 + \left(k_i^2 - m_4\right) \left(k_3 + k_4\right)\right]}{\left(k_i^2 - k_3^2\right) \left(k_i^2 - k_4^2\right)} \right. \\ &\left. - \left(k_i + k_3\right) \frac{\left[k_3 bn^2 + \left(k_3^2 - m_4\right) \left(k_3 + k_4\right)\right]}{\left(k_i^2 - k_3^2\right) \left(k_3^2 - k_4^2\right)} + \left(k_i + k_4\right) \frac{\left[k_4 bn^2 + \left(k_4^2 - m_4\right) \left(k_3 + k_4\right)\right]}{\left(k_i^2 - k_4^2\right) \left(k_3^2 - k_4^2\right)} \right] \end{aligned}$$
(36)
$$\overline{h}'(0,s) &= b \sum_{i=1}^2 A_i \left(k_3^2 - k_i^2\right) \left(k_i^2 - k_4^2\right) \left(\frac{k_3 + k_4}{\left(k_3 + k_4\right)^2 - bn^2}\right) \left\{ 2k_i \frac{\left[k_i \left(k_3 + k_4\right) + \left(k_i^2 - m_4\right)\right]}{\left(k_i^2 - k_3^2\right) \left(k_i^2 - k_4^2\right)} \right. \\ &\left. - \left(k_i + k_3\right) \frac{\left[k_3 \left(k_3 + k_4\right) + \left(k_3^2 - m_4\right)\right]}{\left(k_i^2 - k_3^2\right) \left(k_3^2 - k_4^2\right)} + \left(k_i + k_4\right) \frac{\left[k_4 \left(k_3 + k_4\right) + \left(k_4^2 - m_4\right)\right]}{\left(k_i^2 - k_4^2\right) \left(k_3^2 - k_4^2\right)} \right\} \end{aligned}$$

Finally substituting the above value into (25), we obtain the solution of the problem in the transformed domain as:

$$\overline{T}(y,s) = \frac{T_o}{s} \exp(-k_1 y)$$
(37)

$$\overline{c}(y,s) = \frac{c_o}{s} \exp(-k_2 y)$$
(38)

$$\overline{u}(y,s) = A_1(k_1^2 - m_4)\exp(-k_1y) + A_2(k_2^2 - m_4)\exp(-k_2y) + A_3(k_3^2 - m_4)\exp(-k_3y) + A_4(k_4^2 - m_4)\exp(-k_4y)$$
(39)

$$\overline{h}(y,s) = b \Big[A_1 k_1 \exp(-k_1 y) + A_2 k_2 \exp(-k_2 y) \\ + A_3 k_3 \exp(-k_3 y) + A_4 k_4 \exp(-k_4 y) \Big]$$
(40)

where the constants A_i , i = 1, 2, 3, 4 are listed in Appendix C.

The induced electric field and current density take the following forms

$$\overline{E} = sb\left[A_1 \exp\left(-k_1y\right) + A_2 \exp\left(-k_2y\right) + A_3 \exp\left(-k_3y\right) + A_4 \exp\left(-k_4y\right)\right],$$
(41)

$$\overline{J} = b \Big[A_1 \Big(k_1^2 - \varepsilon_o s^2 \Big) \exp(-k_1 y \Big) + A_2 \Big(k_2^2 - \varepsilon_o s^2 \Big) \exp(-k_2 y \Big) + A_3 \Big(k_3^2 - \varepsilon_o s^2 \Big) \exp(-k_3 y \Big) + A_4 \Big(k_4^2 - \varepsilon_o s^2 \Big) \exp(-k_4 y \Big) \Big].$$
(42)

The shearing stress at the wall is given by

$$\overline{\tau}(s) = \frac{\partial \overline{u}}{\partial y}\Big|_{y=0} = -\left[A_1k_1(k_1^2 - m_4) + A_2k_2(k_2^2 - m_4) + A_3k_3(k_3^2 - m_4) + A_4k_4(k_4^2 - m_4)\right]$$
(43)

4. Inversion of the Laplace Transforms

In order to invert the Laplace transform in the above equations, we adopt a numerical inversion method based on a Fourier series expansion [11]. In this method, the inverse g(t) of the Laplace transform $\overline{g}(s)$ is approximated by the relation

$$g(t) = \frac{e^{ct}}{t_1} \left[\frac{1}{2} \overline{g}(c) + \operatorname{Re}\left(\sum_{k=1}^{\infty} e^{ik\pi t/t_1} \overline{g}(c+ik\pi/t_1)\right) \right], \quad (44)$$
$$0 \le t \le 2t_1,$$

where N is a sufficiently large integer representing the number of terms in the truncated infinite Fourier series. N must chosen such that

$$e^{ct} \operatorname{Re}\left[e^{iN\pi t/t_1}\overline{g}\left(c+iN\pi/t_1\right)\right] \leq \varepsilon_1$$

where ε_1 is a persecuted small positive number that corresponds to the degree of accuracy to be achieved. The parameter c is a positive free parameter that must be greater than the real parts of all singularities of $\overline{g}(s)$. The optimal choice of *c* was obtained according to the criteria described in [11].

5. Numerical Results and Discussion

The problem of free convective flow with heat and mass transfer of a viscous incompressible viscoelastic electrically conducting fluid past a vertical plate in presence of a transverse magnetic field has been considered. The solutions for velocity, temperature and concentration fields as well as the induced magnetic and electric fields are obtained by using the state space approach. The technique is applied to a thermal shock-chemical reactive problem without heat sources. The effects of flow parameters such as Grashof number for heat and mass transfer G_T , G_c , Prandtl number P_r , Schmidt number S_c , chemical reaction parameter K, viscoelastic parameter k_o and relaxation time τ_o have been studied analytically and presented with the help of **Figures 1-8** for the considered problem.

5.1. Velocity Field (*u*)

The velocity of the flow field varies vastly with the variation of the flow parameters such as Grashof number for heat and mass transfer G_T , G_c , viscoelastic parameter k_o , Prandtl number P_r , Schmidt number S_c , chemical reaction parameter K. The effects of these parameters on the velocity fluid of flow field have been presented in **Figures 1-3**.

5.1.1. Effect of Viscoelastic Parameter (k_o)

Figure 1 depicts the effect of viscoelastic parameter k_o on the velocity profiles of the flow field keeping other parameters of the flow field constant. The curve with viscoelastic parameter, $k_o = 0$ corresponds to Newtonian flow and in other two curves the viscoelastic parameter is taken in increasing order. The viscoelastic parameter is found to decelerate the velocity of the flow field. The above parameter is in good agreement with the result obtained in cases of Khan and Sanjayanand [10].

5.1.2. Effect of Grashof Number for Heat (G_T)

The values of Grashof number for heat G_T have been chosen as they are interesting from physical point of view. The free convection of heat is due to the temperature difference $T_o - T_\infty$ and hence $G_T > 0$ when $T_o - T_{\infty} > 0$ which physically corresponds to cooling of the surface by free convection currents. Then $G_T < 0$ correspond to heating of the surface by free convection currents. In **Figure 2**, we observe that the effect of cooling and heating by free convection currents when $G_T > 0$ and $G_T < 0$ are in agreement with physical observations that cooling of the surface by free convection currents occurs for positive values of G_T while heating corresponds to negative values of G_T . It was also noticed that the velocity increase with the increase of G_T .

5.1.3. Effect of Different Parameters (G_c, P_r, S_c, K)

Figure 3 present the effect of Grashof number for mass transfer G_c , Prandtl number P_r , Schmidt number S_c and chemical reaction parameter K on the velocity profiles of the flow fluid. Comparing the curve (1) and (2) of the figure, it is observed that the Grashof number for mass transfer is to enhance the velocity of the flow field at all points. The effect of both Prandtl number P_{μ} and chemical reaction parameter K on the velocity field is shown by the curves (1), (3) and (5). It was found that the increasing of P_r and K lead to decelerate the velocity of the flow field. Curves (1) and (4) describe the effect of Schmidt number S_{a} on the velocity profiles of the flow field which reveal that the presence of heavier diffusing species has a retarding effect on the velocity of the flow field. The effect of the above parameters has the same behavior as in case of Das et al. [13].

5.2. Temperature Field (*T*)

The temperature field is found to change more or less with the variation of the Prandtl number P_r . Figure 4 is plot of non-dimensional temperature and distance for five different values of the Prandtl number. The temperature



Figure 1. Velocity distribution for different values of viscoelastic parameter k_o .











Figure 4. Temperature distribution for different values of *P_r*.











Figure 7. Induced electric field distribution for different values of G_T , P_r , S_c and K.



Figure 8. Current density distribution for different values of G_T , P_r , S_c and K.

of the flow field diminishes as the Prandtl number increases. Higher the Prandtl number, the sharper is the reduction in the temperature of the flow field.

5.3. Concentration Field (*c*)

The variation of the concentration distribution of the flow field with the diffusion of the mass is shown in **Figure 5**. The concentration distribution decreases at all points of the flow field with the increase of the Schmidt number S_c . This shows that the heavier the diffusing species have a greater retarding effect on the concentration distribution of the flow field. The concentration profiles are in good agreement with the results obtained in case of Hsiao [14].

5.4. Induced Magnetic Field (*h*)

Figure 6 concentrate on variations in the induced magnetic field profiles *h* for cooling $G_T > 0$ and heating $G_T < 0$ of the plate due to change in the values of Grashof number for mass transfer G_c . It is observed that for cooling (heating) of the plate the induced magnetic field increases (decreases) rapidly in the vicinity of the plate and decreases (increases) asymptotically for higher values of *y*. It is also observed that an increase in Grashof number for mass transfer G_c increases (decreases) the induced magnetic field.

5.5. Induced Electric Field (*E*) and Current Density (*J*)

The induced electric field and current density of the flow field vary vastly with the variation of the flow parameters such as Grashof number G_T , Prandtl number P_r , Schmidt number S_c and chemical reaction parameter K. The effects of these parameters on the induced electric

field and current density have been presented in **Figures 7** and **8**.

Effect of Different Parameters (G_T, P_r, S_c, K)

Figures 7 and **8** present the effect of Grashof number for heat transfer G_T , Prandtl number P_r , Schmidt number S_c and chemical reaction parameter K on the induced electric field E, and current density J profiles of the flow fluid, respectively. It was found that the increasing of these parameters lead to decelerate the magnitude of both the induced magnetic field and current density but Grashof number for heat transfer is to enhance them.

5.6. Skin Friction (τ)

The numerical values of skin friction coefficient τ for different values of G_T , G_c , P_r , S_c , K and k_o corresponding to cooling of the plate $G_T > 0$ are entered in **Table 1**. It is observed that the skin friction coefficient τ increases due to increase in G_T , G_c while decrease due to increase in P_r , S_c , K and k_o .

6. Concluding Remarks

1) Owing to the complicated nature of the governing equations for the unsteady MHD viscoelastic flow, few attempts have been made to solve problems in this field. These attempts utilized approximate methods valid for only a specific range of some parameters. In this work, the method of direct integration by means of the matrix exponential, which is a standard approach in modern control theory and is developed in detail in many texts such as Ezzat [1], is introduced in the field of MHD and is applied to specific problems in which the temperature, velocity, concentration and magnetic field are coupled. This method gives exact solutions in the Laplace transform

G_T	G_c	P_r	S_c	K	k_o	τ
1	2	0.73	0.22	0.2	0.2	1.2373915
5	2	0.73	0.22	0.2	0.2	1.2373925
1	4	0.73	0.22	0.2	0.2	2.4747825
1	2	1	0.22	0.2	0.2	1.0391526
1	2	0.73	0.62	0.2	0.2	0.2902698
1	2	0.73	0.22	0.5	0.2	1.1652091
1	2	0.73	0.22	0.2	0.4	1.1499502

Table 1. Values of the skin friction τ due to the variation of G_T , G_c , P_r , S_c , K and k_o .

domain without any assumed restrictions on the applied magnetic field or viscoelastic parameters. The same approach was used quite successfully in dealing with problems in generalized thermoelasticity theory by Ezzat *et al.* [15].

2) In this work, we use a more general model of equations, which includes the relaxation time of heat conduction τ_o and the electric permeability of the electromagnetic field ε_o . The inclusion of the relaxation time and electric permeability modifies the governing thermal, concentration and electromagnetic equations, changing them from parabolic to hyperbolic type, and thereby eliminating the unrealistic result that thermal and chemical reactive disturbance is realized instantaneously everywhere within a fluid.

3) The work considered here in reflects the effects of transverse magnetic field and chemical reaction on an unsteady laminar incompressible free convection heat and mass transfer flow of a viscoelastic fluid past an infinite vertical plate. A set of linear differential equations governing the fluid velocity, temperature, species concentration and induced magnetic field is solved by the method of state space approach. The parameters that arise in this analysis are prandtl number P_r (thermal diffusivity), Schmidt number S_c (mass diffusivity), thermal Grashof number G_T (free convection), Solutal Grashof number G_c , chemical reaction parameter K and viscoelastic parameter k_a . A comprehensive set of graphical results for the velocity, temperature, concentration, induced magnetic and electric field and current density is presented and discussed.

4) The flow of fluids over the boundaries has many applications such as boundary-layer control. The study of unsteady boundary layers owes its importance to the fact that all boundary layers that occur in real life are, in a sense, unsteady. In recent years, the requirements of modern technology have stimulated interest in fluid-flow studies, which involve the intersection of several phenomena. One such study is related to the effects of free convection flow through, which play an important role in agriculture, engineering, petroleum industries, and heat transfer.

REFERENCES

- M. A. Ezzat, "State Space Approach to Solids and Fluids," *Canadian Journal of Physics Review*, Vol. 86, No. 11, 2008, pp. 1242-1250. <u>doi:10.1139/P08-069</u>
- [2] E. Scribben, D. Baird and P. Wapperom, "The Role of Transient Rheology in Poly-Meric Sintering," *Rheologica Acta*, Vol. 45, No. 6, 2006, pp. 825-839.
- [3] Z. Wouter, M. Hendriks and M. T. Hart, "A Velocity-Based Approach to Visco-Elastic Flow of Rock," *Mathematical Geology*, Vol. 37, 2005, pp. 141-162.
- [4] B. O. Anwar and O. D. Makinde, "Viscoelastic Flow and Species Transfer in a Darcian High-Permeability Channel," *Journal of Petroleum Science and Engineering*, Vol. 76, No. 3-4, 2011, pp. 93-97. doi:10.1016/j.petrol.2011.01.008
- [5] Y. Xia and A. M. Jacobi, "Air-Side Data Interpretation and Performance Analysis for Heat Exchangers with Simultaneous Heat and Mass Transfer, Wet and Frosted Surfaces," *International Journal of Heat and Mass Transfer*, Vol. 48, No. 25-26, 2005, pp. 5089-5102. doi:10.1016/j.ijheatmasstransfer.2005.08.008
- [6] M. A. Ezzat and M. Zakaria, "Heat Transfer with Thermal Relaxation to a Perfectly Conducting Polar Fluid," *Heat and Mass Transfer*, Vol. 41, No. 3, 2005, pp. 189-198. doi:10.1007/s00231-004-0511-y
- [7] H. I. Andersson, "MHD Flow of a Viscoelastic Fluid past a Stretching Surface," *Acta Mechanica*, Vol. 95, No. 1-4, 1992, pp. 227-230.
- [8] B. C. Sakiadis, "Boundary Layer Behavior on Continuous Solid Surface: Part II. The Boundary Layer on a Continuous Flat Surface," *AIChE Journal*, Vol. 7, No. 2, 1961, pp. 221-225.
- [9] M. A. Ezzat and M. Zakaria, "State Space Approach to Viscoelastic Fluid Flow of Hydromagnetic Fluctuating Boundary-Layer through a Porous Medium," *ZAMM*, Vol. 77, 1997, pp. 197-207.
- [10] S. K. Khan and E. Sanjayanand, "Viscoelastic Boundary Layer Flow and Heat Transfer over an Exponential Stretching Sheet," *International Journal of Heat and*

Mass Transfer, Vol. 48, No. 8, 2005, pp. 1534-1542. doi:10.1016/j.ijheatmasstransfer.2004.10.032

- [11] G. Honig and U. Hirdes, "A method for the Numerical Inversion of Laplace Transforms," *Computational and Applied Mathematics*, Vol. 10, No. 1, 1984, pp. 113-132.
- [12] M. A. Ezzat, "Free Convection Effects on Perfectly Conducting Fluid," *International Journal of Engineering Science*, Vol. 39, No. 7, 2001, pp. 799-819. doi:10.1016/S0020-7225(00)00059-8
- [13] S. Das, A. Satapathy, J. Das and J. Panda, "Mass Transfer Effects on MHD Flow and Heat Transfer Past a Vertical Porous Plate through a Porous Medium Under Oscillatory Suction and Heat Source," *International Journal of Heat*

and Mass Transfer, Vol. 52, No. 25-26, 2009, pp. 5962-5969. <u>doi:10.1016/j.ijheatmasstransfer.2009.04.038</u>

- [14] K. L. Hsiao, "Heat and Mass Mixed Convection for MHD Visco-Elastic Fluid Past a Stretching Sheet with Ohmic dissipation," *Communications in Nonlinear Science and Numerical Simulation*, Vol. 15, No. 7, 2010, pp. 1803-1812. doi:10.1016/j.cnsns.2009.07.006
- [15] M. A. Ezzat, M. I. Othman and A. A. Smaan, "State Space Approach to Two-Dimensional Electro-Magneto Thermoelastic Problem with Two Relaxation Times," *International Journal of Engineering Science*, Vol. 39, 2001, pp. 1383-1404. doi:10.1016/S0020-7225(00)00095-1.

Appendix A: The Solution of the Linear System

$$\begin{split} a_{0} &= F\left(k_{2}^{2}k_{3}^{2}k_{4}^{2}C_{1} + k_{1}^{2}k_{3}^{2}k_{4}^{2}C_{2} + k_{1}^{2}k_{2}^{2}k_{4}^{2}C_{3} + k_{1}^{2}k_{2}^{2}k_{3}^{2}C_{4}\right), \quad a_{1} = F\left(k_{2}^{2}k_{3}^{2}k_{4}^{2}S_{1} + k_{1}^{2}k_{3}^{2}k_{4}^{2}S_{2} + k_{1}^{2}k_{2}^{2}k_{3}^{2}S_{4} + k_{1}^{2}k_{2}^{2}k_{3}^{2}S_{4}\right) \\ a_{2} &= -F\left\{\left(k_{2}^{2}k_{3}^{2} + k_{2}^{2}k_{4}^{2} + k_{3}^{2}k_{4}^{2}\right)C_{1} + \left(k_{3}^{2}k_{4}^{2} + k_{3}^{2}k_{1}^{2} + k_{1}^{2}k_{4}^{2}\right)C_{2} + \left(k_{4}^{2}k_{1}^{2} + k_{4}^{2}k_{2}^{2} + k_{1}^{2}k_{2}^{2}\right)C_{3} + \left(k_{1}^{2}k_{2}^{2} + k_{1}^{2}k_{3}^{2}\right)C_{4}\right\} \\ a_{3} &= -F\left\{\left(k_{2}^{2}k_{3}^{2} + k_{2}^{2}k_{4}^{2} + k_{3}^{2}k_{4}^{2}\right)S_{1} + \left(k_{3}^{2}k_{4}^{2} + k_{3}^{2}k_{1}^{2} + k_{1}^{2}k_{4}^{2}\right)S_{2} + \left(k_{4}^{2}k_{1}^{2} + k_{4}^{2}k_{2}^{2} + k_{1}^{2}k_{2}^{2}\right)S_{3} + \left(k_{1}^{2}k_{2}^{2} + k_{1}^{2}k_{3}^{2}\right)S_{4}\right\} \\ a_{4} &= F\left\{\left(k_{2}^{2} + k_{3}^{2} + k_{4}^{2}\right)C_{1} + \left(k_{1}^{2} + k_{3}^{2} + k_{4}^{2}\right)C_{2} + \left(k_{1}^{2} + k_{2}^{2} + k_{4}^{2}\right)C_{3} + \left(k_{1}^{2} + k_{2}^{2} + k_{3}^{2}\right)C_{4}\right\} \\ a_{5} &= F\left\{\left(k_{2}^{2} + k_{3}^{2} + k_{4}^{2}\right)S_{1} + \left(k_{1}^{2} + k_{3}^{2} + k_{4}^{2}\right)S_{2} + \left(k_{1}^{2} + k_{2}^{2} + k_{4}^{2}\right)S_{3} + \left(k_{1}^{2} + k_{2}^{2} + k_{3}^{2}\right)S_{4}\right\} \\ a_{6} &= -F\left(C_{1} + C_{2} + C_{3} + C_{4}\right), \quad a_{7} &= -F\left(S_{1} + S_{2} + S_{3} + S_{4}\right) \\ \text{where} \end{split}$$

$$\begin{split} F &= \frac{1}{\left(k_1^2 - k_2^2\right)\left(k_1^2 - k_3^2\right)\left(k_1^2 - k_4^2\right)\left(k_2^2 - k_3^2\right)\left(k_2^2 - k_4^2\right)\left(k_3^2 - k_4^2\right)} \\ C_1 &= \left(k_2^2 - k_3^2\right)\left(k_3^2 - k_4^2\right)\left(k_4^2 - k_2^2\right)\cosh\left(k_1y\right), \quad C_2 &= \left(k_3^2 - k_4^2\right)\left(k_4^2 - k_1^2\right)\left(k_3^2 - k_1^2\right)\cosh\left(k_2y\right) \\ C_3 &= \left(k_4^2 - k_1^2\right)\left(k_1^2 - k_2^2\right)\left(k_2^2 - k_4^2\right)\cosh\left(k_3y\right), \quad C_4 &= \left(k_1^2 - k_2^2\right)\left(k_2^2 - k_3^2\right)\left(k_1^2 - k_3^2\right)\cosh\left(k_4y\right) \\ S_1 &= \frac{1}{k_1}\left(k_2^2 - k_3^2\right)\left(k_3^2 - k_4^2\right)\left(k_4^2 - k_2^2\right)\sinh\left(k_1y\right), \quad S_2 &= \frac{1}{k_2}\left(k_3^2 - k_4^2\right)\left(k_4^2 - k_1^2\right)\left(k_3^2 - k_1^2\right)\sinh\left(k_2y\right) \\ S_3 &= \frac{1}{k_3}\left(k_4^2 - k_1^2\right)\left(k_1^2 - k_2^2\right)\left(k_2^2 - k_4^2\right)\sinh\left(k_3y\right), \quad S_4 &= \frac{1}{k_4}\left(k_1^2 - k_2^2\right)\left(k_2^2 - k_3^2\right)\left(k_1^2 - k_3^2\right)\sinh\left(k_4y\right) \end{split}$$

Appendix B: Elements of the Matrix L(s, y)

$$\begin{split} \ell_{11} &= -F\left(k_{1}^{2} - k_{2}^{2}\right)\left(k_{1}^{2} - k_{3}^{2}\right)\left(k_{1}^{2} - k_{4}^{2}\right)C_{1}, \quad \ell_{12} = 0, \quad \ell_{13} = 0, \quad \ell_{14} = 0 \\ \ell_{15} &= -F\left(k_{1}^{2} - k_{2}^{2}\right)\left(k_{1}^{2} - k_{3}^{2}\right)\left(k_{1}^{2} - k_{4}^{2}\right)S_{1}, \quad \ell_{16} = 0, \quad \ell_{17} = 0, \quad \ell_{18} = 0, \quad \ell_{21} = 0 \\ \ell_{22} &= -F\left(k_{2}^{2} - k_{1}^{2}\right)\left(k_{2}^{2} - k_{3}^{2}\right)\left(k_{2}^{2} - k_{4}^{2}\right)C_{2}, \quad \ell_{23} = 0, \quad \ell_{24} = 0, \quad \ell_{25} = 0 \\ \ell_{26} &= -F\left(k_{2}^{2} - k_{1}^{2}\right)\left(k_{2}^{2} - k_{3}^{2}\right)\left(k_{2}^{2} - k_{4}^{2}\right)S_{2}, \quad \ell_{27} = 0, \quad \ell_{28} = 0 \\ \ell_{31} &= \frac{-G_{T}F}{1 - sk_{0}}\left[\left(k_{2}^{2} - k_{1}^{2}\right)\left(k_{1}^{2} - m_{4}\right)C_{1} + \left(k_{2}^{2} - k_{3}^{2}\right)\left(k_{3}^{2} - m_{4}\right)C_{3} + \left(k_{2}^{2} - k_{4}^{2}\right)\left(k_{4}^{2} - m_{4}\right)C_{4}\right] \\ \ell_{32} &= \frac{-G_{c}F}{1 - sk_{0}}\left[\left(k_{1}^{2} - k_{2}^{2}\right)\left(k_{2}^{2} - m_{4}\right)C_{2} + \left(k_{1}^{2} - k_{3}^{2}\right)\left(k_{3}^{2} - m_{4}\right)C_{3} + \left(k_{1}^{2} - k_{4}^{2}\right)\left(k_{4}^{2} - m_{4}\right)C_{4}\right] \\ \ell_{33} &= \frac{F}{m_{4}}\left[k_{4}^{2}\left(k_{2}^{2} - k_{3}^{2}\right)\left(k_{1}^{2} - k_{3}^{2}\right)\left(m_{4} - k_{3}^{2}\right)C_{3} + k_{3}^{2}\left(k_{2}^{2} - k_{4}^{2}\right)\left(k_{1}^{2} - k_{4}^{2}\right)\left(m_{4} - k_{4}^{2}\right)C_{4}\right] \\ \ell_{34} &= -n^{2}m_{4}F\left[\left(k_{1}^{2} - k_{3}^{2}\right)\left(k_{3}^{2} - k_{2}^{2}\right)S_{3} + \left(k_{1}^{2} - k_{4}^{2}\right)\left(k_{4}^{2} - k_{4}^{2}\right)\left(k_{4}^{2} - m_{4}\right)S_{4}\right] \\ \ell_{35} &= \frac{-G_{T}F}{1 - sk_{0}}\left[\left(k_{1}^{2} - k_{1}^{2}\right)\left(k_{1}^{2} - m_{4}\right)S_{1} + \left(k_{2}^{2} - k_{3}^{2}\right)\left(k_{3}^{2} - m_{4}\right)S_{3} + \left(k_{1}^{2} - k_{4}^{2}\right)\left(k_{4}^{2} - m_{4}\right)S_{4}\right] \\ \ell_{36} &= \frac{-G_{c}F}{1 - sk_{0}}\left[\left(k_{1}^{2} - k_{2}^{2}\right)\left(k_{2}^{2} - m_{4}\right)S_{2} + \left(k_{1}^{2} - k_{3}^{2}\right)\left(k_{3}^{2} - m_{4}\right)S_{3} + \left(k_{1}^{2} - k_{4}^{2}\right)\left(k_{4}^{2} - m_{4}\right)S_{4}\right] \\ \ell_{37} &= -F\left[\left(k_{1}^{2} - k_{3}^{2}\right)\left(k_{2}^{2} - k_{3}^{2}\right)\left(k_{3}^{2} - m_{4}\right)S_{3} + \left(k_{1}^{2} - k_{4}^{2}\right)\left(k_{4}^{2} - m_{4}\right)S_{4}\right] \\ \ell_{37} &= -F\left[\left(k_{1}^{2} - k_{3}^{2}\right)\left(k_{2}^{2} - k_{3}^{2}\right)\left(k_{3}^{2} - m_{4}\right)S_{3} + \left(k_{1}^{2} - k_{4}^{2}\right)\left(k_{4}^{2} - m_{4}\right)S_{4}\right] \\ \ell_{37} &= -F\left[\left(k_{1}^{2} - k_{3}^{2}\right)\left$$

Copyright © 2012 SciRes.

$$\begin{split} \epsilon_{18} &= n^2 F \Big[\left(k_1^2 - k_1^2\right) \left(k_1^2 - k_2^2\right) C_3 + \left(k_1^2 - k_1^2\right) \left(k_1^2 - k_2^2\right) C_4 \Big], \\ \epsilon_{41} &= \frac{G_r b F}{1 - s k_0} \Big[k_1^2 \left(k_1^2 - k_2^2\right) S_1 + k_2^2 \left(k_3^2 - k_2^2\right) S_1 + k_4^2 \left(k_4^2 - k_2^2\right) S_4 \Big] \\ \epsilon_{42} &= \frac{G_r b F}{1 - s k_0} \Big[k_2^2 \left(k_2^2 - k_1^2\right) S_2 + k_3^2 \left(k_3^2 - k_1^2\right) S_3 + k_4^2 \left(k_4^2 - k_1^2\right) S_4 \Big] \\ \epsilon_{43} &= b m_3 F \Big[\left(k_3^2 - k_1^2\right) \left(k_3^2 - k_2^2\right) S_3 + \left(k_4^2 - k_1^2\right) \left(k_4^2 - k_2^2\right) S_4 \Big] \\ \epsilon_{44} &= F^2 \Big[\left(k_3^2 - k_1^2\right) \left(k_3^2 - k_2^2\right) S_3 + \left(k_4^2 - k_1^2\right) \left(k_4^2 - k_4^2\right) \left(k_5^2 - k_4^2\right) \left(k_5^2 - m_4\right) C \Big] \\ \epsilon_{45} &= \frac{G_r b F}{1 - s k_0} \Big[\left(k_1^2 - k_1^2\right) C_1 + \left(k_2^2 - k_1^2\right) C_3 + \left(k_2^2 - k_4^2\right) C_4 \Big] \\ \epsilon_{45} &= \frac{G_r b F}{1 - s k_0} \Big[\left(k_1^2 - k_1^2\right) C_1 + \left(k_2^2 - k_4^2\right) C_3 + \left(k_2^2 - k_4^2\right) C_4 \Big] \\ \epsilon_{45} &= \frac{G_r b F}{m_4} \Big[k_3^2 \left(k_2^2 - k_1^2\right) \left(k_2^2 - k_2^2\right) C_3 + \left(k_2^2 - k_4^2\right) C_4 \Big] \\ \epsilon_{45} &= \frac{G_r b F}{m_4} \Big[k_3^2 \left(k_2^2 - k_1^2\right) \left(k_2^2 - k_2^2\right) C_3 + \left(k_2^2 - k_4^2\right) C_4 \Big] \\ \epsilon_{45} &= \frac{G_r F}{m_4} \Big[k_3^2 \left(k_2^2 - k_1^2\right) \left(k_2^2 - k_2^2\right) C_3 + \left(k_2^2 - k_4^2\right) C_4 \Big] \\ \epsilon_{47} &= b F \Big[\left(k_1^2 - k_2^2\right) \left(k_2^2 - k_2^2\right) \left(k_1^2 - k_4^2\right) S_3 + k_4^2 \left(k_2^2 - k_4^2\right) \left(k_2^2 - k_2^2\right) \left(m_4 - k_3^2\right) S_4 \Big] \\ \epsilon_{48} &= \frac{-F}{m_4} \Big[k_3^2 \left(k_2^2 - k_1^2\right) \left(k_2^2 - k_4^2\right) S_1 , \quad \epsilon_{52} = 0, \quad \epsilon_{53} = 0, \quad \epsilon_{64} = 0 \\ \epsilon_{55} &= -F \left(k_1^2 - k_1^2\right) \left(k_2^2 - k_1^2\right) \left(k_2^2 - k_4^2\right) S_2 , \quad \epsilon_{67} = 0, \quad \epsilon_{68} = 0 \\ \epsilon_{66} &= -F \left(k_2^2 - k_1^2\right) \left(k_2^2 - k_1^2\right) \left(k_2^2 - m_4\right) S_2 + k_3^2 \left(k_3^2 - k_1^2\right) \left(k_3^2 - m_4\right) S_4 + k_4^2 \left(k_4^2 - k_2^2\right) \left(k_4^2 - m_4\right) S_4 \Big] \\ \epsilon_{73} &= -m_3 F \Big[\left[k_1^2 - k_1^2 \right) \left(k_2^2 - k_1^2 \right) \left(k_2^2 - k_1^2 \right) \left(k_2^2 - k_1^2 \right) \left(k_4^2 - k_1^2 \right) \left(k_4^2 - m_4 \right) S_4 \Big] \\ \epsilon_{75} &= \frac{G_r F}{1 - s k_0} \Big[\left(k_1^2 - k_1^2 \right) \left(k_2^2 - k_1^2 \right) \left(k_1^2 - k_1^2 \right) \left(k_2^2 - k_1^2 \right) \left(k_4^2 - k_1^2 \right) \left(k_4^2 - m_4 \right) S_4 \Big] \\ \epsilon_{75} &= \frac{G_r F}{1 - s k_0} \Big[\left(k_1^2 - k_1^2 \right) \left(k_2^2 - k_1^2 \right$$

Copyright © 2012 SciRes.

 C_P

$$\begin{split} \ell_{83} &= m_3 b F \Big[\Big(k_3^2 - k_1^2 \Big) \Big(k_3^2 - k_2^2 \Big) C_3 + \Big(k_4^2 - k_1^2 \Big) \Big(k_4^2 - k_2^2 \Big) C_4 \Big] \\ \ell_{84} &= F \Big[k_3^2 \Big(k_3^2 - k_1^2 \Big) \Big(k_3^2 - k_2^2 \Big) \Big(k_4^2 - m_4 \Big) S_3 + k_4^2 \Big(k_4^2 - k_1^2 \Big) \Big(k_4^2 - k_2^2 \Big) \Big(k_3^2 - m_4 \Big) S_4 \Big] \\ \ell_{85} &= \frac{-G_T b F}{1 - s k_0} \Big[k_1^2 \Big(k_1^2 - k_2^2 \Big) S_1 + k_3^2 \Big(k_3^2 - k_2^2 \Big) S_3 + k_4^2 \Big(k_4^2 - k_2^2 \Big) S_4 \Big] \\ \ell_{86} &= \frac{-G_c b F}{1 - s k_0} \Big[k_2^2 \Big(k_2^2 - k_1^2 \Big) S_2 + k_3^2 \Big(k_3^2 - k_1^2 \Big) S_3 + k_4^2 \Big(k_4^2 - k_1^2 \Big) S_4 \Big] \\ \ell_{87} &= b F \Big[k_3^2 \Big(k_3^2 - k_1^2 \Big) \Big(k_3^2 - k_2^2 \Big) S_3 + k_4^2 \Big(k_4^2 - k_1^2 \Big) \Big(k_4^2 - k_2^2 \Big) S_4 \Big] \\ \ell_{88} &= \frac{F}{m_4} \Big[k_3^2 \Big(k_3^2 - k_1^2 \Big) \Big(k_3^2 - k_2^2 \Big) \Big(k_4^2 - m_4 \Big) C_3 + k_4^2 \Big(k_4^2 - k_1^2 \Big) \Big(k_4^2 - k_2^2 \Big) \Big(k_3^2 - m_4 \Big) C_4 \Big] \end{split}$$

Appendix C: The Constants for the Problem

$$\begin{split} A_{1} &= \frac{G_{T}T_{o}}{s\left(1-sk_{o}\right)\left(k_{3}^{2}-k_{1}^{2}\right)\left(k_{1}^{2}-k_{4}^{2}\right)}, \quad A_{2} &= \frac{G_{c}c_{o}}{s\left(1-sk_{o}\right)\left(k_{3}^{2}-k_{2}^{2}\right)\left(k_{2}^{2}-k_{4}^{2}\right)} \\ A_{3} &= \frac{\left(k_{3}k_{4}+m_{4}\right)}{m_{4}\left[\left(k_{3}+k_{4}\right)^{2}-bn^{2}\right]\left(k_{3}-k_{4}\right)}\sum_{i=1}^{2}A_{i}\left[k_{i}\left(k_{4}^{2}-m_{4}\right)-k_{4}\left(k_{i}^{2}-m_{4}\right)\right] \\ A_{4} &= \frac{\left(k_{3}k_{4}+m_{4}\right)}{m_{4}\left[\left(k_{3}+k_{4}\right)^{2}-bn^{2}\right]\left(k_{3}-k_{4}\right)}\sum_{i=1}^{2}A_{i}\left[k_{3}\left(k_{i}^{2}-m_{4}\right)-k_{i}\left(k_{3}^{2}-m_{4}\right)\right]. \end{split}$$

Nomenclature

	donaite	k_o	viscoelasti
ρ	density	G_{τ}	thermal Gr
t	time	Ġ	solute Gras
(x, y, z)	space coordinates	P	Prandtl nur
V	velocity vector	r S	S along i dt mu
H	magnetic field intensity vector	S_c	Senmial nu
В	magnetic induction vector	H_{o}	constant co
D	electric induction vector	$\sigma_{_o}$	electrical c
F	induced electric field vector	μ_o	magnetic p
	induced memoria field vector	K	thermal con
n		μ	dynamic vi
J	conduction electric density vector	ı D	$= \mu/\rho$. ki
и	velocity of the fluid along the x-direction	-	1
Т	temperature	\mathcal{U}_m	$= \frac{1}{1}$, n
С	concentration		$\mu_{_o}\sigma_{_o}$
D	mass diffusivity of chemically reactive species	$ au_{\circ}$	thermal rel
Κ	chemical reaction parameter	0	II^2
σ	acceleration	α	$= \int \frac{\mu_o H_o}{\mu_o H_o}$
8 T	temperature of the fluid away from the surface		$\sqrt{\rho}$
I [∞]	temperature of the fluid away from the surface	H(t)	Heaviside
\mathcal{C}_{∞}	concentration of the fluid away from the sur-		1100 i bide i
	tace		

$$f_{a}$$
 viscoelastic parameter
 G_{T} thermal Grashof number
 G_{c} solute Grashof number
 P_{r} Prandtl number
 F_{c} Schmidt number
 H_{o} constant component of magnetic field
 σ_{o} electrical conductivity
 μ_{o} magnetic permeability
 t thermal conductivity
 μ_{o} dynamic viscosity
 $\rho_{m} = \frac{1}{\mu_{o}\sigma_{o}}$, magnetic diffusivity
 τ_{o} thermal relaxation time
 $\mu_{o} = \sqrt{\frac{\mu_{o}H_{o}^{2}}{r_{o}}}$, Alfven velocity

specific heat at constant pressure

$$H(t)$$
 Heaviside unit step function