# A Design Method of Noncoherent Unitary Space-Time Codes 

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#### Abstract

We generalized an constructing method of noncoherent unitary space time codes (N-USTC) over Rayleigh flat fading channels. A family of N-USTCs with $T$ symbol peroids, $M$ transmit and $N$ receive antennas was constructed by the exponential mapping method based on the tangent subspace of the Grassmann manifold. This exponential mapping method can transform the coherent space time codes (C-STC) into the N-USTC on the Grassmann manifold. We infered an universal framework of constructing a C-STC that is designed by using the algebraic number theory and has full rate and full diversity (FRFD) for $t$ symbol periods and same antennas, where $M, N, T, t$ are general positive integer. We discussed the constraint condition that the exponential mapping has only one solution, from which we presented an approach of searching the optimum adjustive factor $\alpha_{o p t}$ that can generate an optimum noncoherent codeword. For different code parameters $M, N$, $T, t$ and the optimum adjustive factor $\alpha_{o p t}$, we gave the simulation results of the several N -USTCs. ${ }^{1}$


Keywords: Noncoherent Uintary Space-Time Codes (N-USTC), Coherent Space-Time Codes (C-STC), Grassmann Manifold, Degree of Freedom, Exponenatial Map, Full Rate and Full Diversity (FRFD)

## 1. Introduction

The noncoherent unitary space-time code (N-USTC) in [1-4] provided a potential solution for the multiple antennas communication in fading channel that neither transmitter nor receiver knows the channel state imformation (CSI). This paper generalized an constructing method for a family of the N-USTCs based on the Grassmann manifold. The system models on noncoherent and cohenent channel are comparatively built. Starting from the basic theory of the Grassmann manifold [4], a basic thought of designing the Grassmannian unitary space-time matrix was described. That is the exponent mapping method [5,6] from the $M \times t$ C-STC to the $T \times M$ N-USTC for the MIMO system with $M$ transmit and $N$ receive antennas, where $t$ and $T$ are coherent and noncoherent symbol periods, respectively, and $M, N, T, t$ are general positive integer, $T>t \geq M$ and $T=M+t$.

In order to map the $M \times t$ C-STC into the $T \times M$

[^0]N-USTC, firstly, one must consider how to construct the $M \times t \quad$ C-STC. Many literatures [7-11] discussed multifarious methods of constructing the C-STCs. Enlightened by [7-11] and other literatures (omitted in reference as the limitation of length), we discussed a method of constructing the $M \times t$ universal C-STCs with FDFR based on the algebraic number theory. Therefore, we created four kinds of matrices: uncoded symbol matrix $\boldsymbol{S}$, linear combinatorial matrix $\boldsymbol{L}$, rotated matrix $\boldsymbol{R}$ and linear combinatorial symbol matrix $\boldsymbol{Z}$ that is $\boldsymbol{Z}=\boldsymbol{L S R}$ formed by the linear combinatorial technique of the symbols of constellations, such as q-PSK or q-QAM, and then we get the the coded matrix of a C-STC by transforming matrix $Z$.

In the mapping process from the $M \times t \quad \mathrm{C}$-STC into the $T \times M$ N-USTC, we discussed the constraint condition of the only one solution of the the exponent map, from which we discover that the optimum codeword of the Grassmannian N-USTC can be obtained by searching the optimum adjustive factor $\alpha_{o p t}$. Simulation tests show that for BPSK constellation symbols, when $T$ is unchanged and antenna number $M=N$ increases, the
spectral efficiency increases and the performance of the bit error rate (BER) also advances, or when $M=N$ is unchanged and $T$ increases, so do the spectral efficiency and the BER performance; for QPSK constellation symbols, when $M=N=2$ and $T=5$, the spectral efficiency achieves $2.4 \mathrm{bits} / \mathrm{Hz} / \mathrm{s}$ but at the cost of sacrificing the BER performance.

## 2. System Model and Background Knowledge

### 2.1. System Model

We focus on the block fading channel model on which the fading coefficients are assumed to be constant during $T$ periods of one codeword and to change independently from one codeword to the next. Under the assumption of no inter-symbol interference, the noncoherent channel model with codeword periods $T>M$ is

$$
\begin{equation*}
\boldsymbol{Y}_{T N}=\sqrt{T} \boldsymbol{X}_{T M} \boldsymbol{H}_{M N}+\boldsymbol{W}_{T N} \tag{1}
\end{equation*}
$$

For the convenience of comparison and application later on, we simultaneously give the coherent channel model with codeword periods $t \geq M$ :

$$
\begin{equation*}
\boldsymbol{Y}_{N t}=\boldsymbol{H}_{N M} \boldsymbol{B}_{M t}+\boldsymbol{W}_{N t} \tag{2}
\end{equation*}
$$

where $\boldsymbol{Y}$ is $T \times N$ received signal matrix for noncoherent model or $N \times t$ matrix for coherent model, $\boldsymbol{H}$ is $M \times N$ or $N \times M$ fading coefficients matrix and $\boldsymbol{W}$ is $T \times N$ or $N \times t$ additive noise matrix. Elements of $\boldsymbol{H}$ and $\boldsymbol{W}$ are assumed to be the independent and identically distributed complex Gaussian random variables respectively from distribution $C N(0,1)$ and $C N\left(0, \sigma^{2}\right) . \boldsymbol{X}_{T M}$ and $\boldsymbol{B}_{M t}$ are noncoherent and coherent transmit signal matrices, respectively.

### 2.2. Grassmann Manifolds and Its Tangential Space

Manifold is a topologic space which is locally homeomorphic to the Euclidian space. More formally, Every point on $n$-dimensional manifold has a neighborhood homeomorphic to $n$-dimensional Euclidian space $\boldsymbol{R}^{n}$.

We consider a set of all $M$-dimension linear subspaces in $T$-dimension complex space. This set has the structure of manifold, called Grassmann manifold and denoted by $\boldsymbol{G}_{T, M}^{C}$, and its definition [12] is:

$$
\begin{equation*}
\boldsymbol{G}_{T, M}^{C} \triangleq\left\{\langle\boldsymbol{\Phi}\rangle \mid \boldsymbol{\Phi}^{\dagger} \boldsymbol{\Phi}=\boldsymbol{I}_{M}\right\} \tag{3}
\end{equation*}
$$

where " $\dagger$ " denotes transpose for real number or conjugate transpose for complex number; $\langle\boldsymbol{\Phi}\rangle$ denotes the subspace spanned by $M$ column vectors in an $T \times M$ unitary matrix $\boldsymbol{\Phi} . \boldsymbol{G}_{T, M}^{C}$ can also be represented by the
quotient space of the unitary group $\mathbf{U}(n)$ [12], i.e.

$$
\begin{equation*}
\boldsymbol{G}_{T, M}^{C}=\boldsymbol{U}(T) /(\boldsymbol{U}(M) \times \boldsymbol{U}(T-M)) \tag{4}
\end{equation*}
$$

As the real dimension of the unitary group $\mathbf{U}(n)$ is $\operatorname{dim}_{R} \boldsymbol{U}(n)=n^{2}$, one can obtain the real dimension of $\boldsymbol{G}_{T, M}^{C}: \quad \operatorname{dim}_{R} \boldsymbol{G}_{T, M}^{C}=T^{2}-M^{2}-(T-M)^{2}=2 M(T-M)$ [13] according to (4). So the complex dimension of $\boldsymbol{G}_{T, M}^{C}$ is $\operatorname{dim}_{C} \boldsymbol{G}_{T, M}^{C}=M(T-M)$ which means that the N-USTCs on $\boldsymbol{G}_{T, M}^{C}$ have $M(T-M)$ degrees of freedom, and the maximal symbol rate is $M(1-(M / T))$ [3].

Literature [5,6] introduces that the tangential space of any a point on $\boldsymbol{G}_{T, M}^{C}$ forms a set of matrices as follows:

$$
\boldsymbol{\Delta}_{T M}=\boldsymbol{Q}\left(\begin{array}{cc}
0 & \boldsymbol{B}  \tag{5}\\
-\boldsymbol{B}^{\dagger} & 0
\end{array}\right)
$$

where $\boldsymbol{B} \in \boldsymbol{C}^{M \times(T-M)}$ and the point $\boldsymbol{Q}$ can be chosen arbitrarily, i.e., for simplified calculation, one can choose $\boldsymbol{B}=\boldsymbol{I}_{T M}=\left[\boldsymbol{I}_{M \times M}, \boldsymbol{0}_{(T-M) \times M}\right]^{\dagger}$ as a reference subspace on $\boldsymbol{G}_{T, M}^{C}$. The dimension of the tangential space defined by (5) is also $M(T-M)$. According to the theory of Liegroup, i.e., the point of the tangential space on $\boldsymbol{G}_{T, M}^{C}$ can be projected into the point of $\boldsymbol{G}_{T, M}^{C}$ by exponent map, the point $\boldsymbol{X}$ of $\boldsymbol{G}_{T, M}^{C}$ can be denoted by the exponent form of the tangential space:

$$
\boldsymbol{X}_{T M}=\left[\exp \left(\begin{array}{cc}
0 & \boldsymbol{B}  \tag{6}\\
-\boldsymbol{B}^{\dagger} & 0
\end{array}\right)\right] \boldsymbol{I}_{T M}
$$

(6) shows a complicated computing task, but it can be simplified by the technique of the singular value decompose (SVD) of matrix. $\boldsymbol{B}$ is disposed by the SVD as follows:

$$
\begin{equation*}
\boldsymbol{B}=\boldsymbol{U}_{M \times M} \boldsymbol{\Lambda}_{M \times(T-M)} \boldsymbol{V}_{(T-M) \times(T-M)}^{\dagger} \tag{7}
\end{equation*}
$$

where $\boldsymbol{U}$ and $\boldsymbol{V}$ are unitary matrices, and the form of $\boldsymbol{\Lambda}$ is:

$$
\boldsymbol{\Lambda}=\left(\begin{array}{cccccc}
\lambda_{1} & 0 & 0 & 0 & \cdots & 0  \tag{8}\\
0 & \ddots & 0 & \vdots & \ddots & \vdots \\
0 & 0 & \lambda_{M} & 0 & \cdots & 0
\end{array}\right)
$$

where $\lambda_{1}, \cdots, \lambda_{M}$ are the singular values of matrix $\boldsymbol{B}$.
Putting (7) into (6), one can obtain the simplified $\boldsymbol{X}_{T M}$ :

$$
\begin{equation*}
\boldsymbol{X}_{T M}=\binom{\boldsymbol{U} \boldsymbol{C} \boldsymbol{U}^{\dagger}}{\boldsymbol{V} \boldsymbol{S} \boldsymbol{U}^{\dagger}}_{T \times M} \tag{9}
\end{equation*}
$$

where

$$
\boldsymbol{C}_{M \times M}=\left(\begin{array}{ccc}
\cos \lambda_{1} & & 0 \\
& \ddots & \\
0 & & \cos \lambda_{M}
\end{array}\right),
$$

$$
\boldsymbol{S}_{(T-M) \times M}=\left(\begin{array}{cccc}
\sin \lambda_{1} & & 0 & \\
& \ddots & & 0 \\
0 & & \sin \lambda_{M} & )^{\dagger} . . . . . . .
\end{array}\right.
$$

## 3. Coherent Space-Time Codes

Most methods of constructing the C-STCs with FRFD are to efficaciously combine all information symbols $s_{i}$ ( $i=1,2, \cdots, t M$ ) to form the coding matrix $\boldsymbol{B}_{M t}$, where all $s_{i}$ belong to one of constellations, such as q -PSK or q-QAM, etc. If we adopt the technique of linear combination to design $\boldsymbol{B}_{M t}$, then the rank and determinant properties of $\boldsymbol{B}_{M t}\left(s_{i}\right)$ is equivalent to them of $\boldsymbol{B}_{M t}\left(s_{i}\right)-\boldsymbol{B}_{M t}\left(s_{j}\right)$, where $i, j \in[1, M t]$ and $i \neq j$. Let $r$ be the minimal rank available of any codeword matrix $\boldsymbol{B}_{M t}\left(s_{i}\right)$. According to the design criterion of determinate in [10], under the linear combination of all $s_{i}$ of forming $\boldsymbol{B}_{M t}$, we can obtain a FRFD matrix and its rank $r=M$, so the maximum coding gain
$\left(\prod_{j=1}^{r} \lambda_{j}\right)^{1 / r}=\left(\prod_{j=1}^{M} \lambda_{j}\right)^{1 / M}$ can be guaranteed. Being enlightened by using the algebraic number theory to construct the C-STCs in [8,10,11], we investigate how to design the universal coherent matrix $\boldsymbol{B}_{M t}$ with FRFD for $M, N, t$ being general positive integer. The applied design step is shown as follows.
a) We first create three kinds of matrices: uncoded symbol matrix $\boldsymbol{S}$, linear combinatorial matrix $\boldsymbol{L}$ (also named left-multiplied matrix) and rotated matrix $\boldsymbol{R}$ (also named right-multiplied matrix), they have next ge-
neral forms:

$$
\begin{aligned}
& \boldsymbol{S}=\left[\begin{array}{cccc}
s_{1} & s_{M+1} & \cdots & s_{(t-1) M+1} \\
s_{2} & s_{M+2} & \cdots & s_{(t-1) M+2} \\
\vdots & \vdots & \ddots & \vdots \\
s_{M} & s_{2 M} & \cdots & s_{M t}
\end{array}\right], \\
& \boldsymbol{L}=\left[\begin{array}{ccccc}
1 & \theta & \theta^{2} & \cdots & \theta^{M-1} \\
1 & j \theta & j^{2} \theta^{2} & \cdots & j^{M-1} \theta^{M-1} \\
\vdots & \vdots & \vdots & \ddots & \vdots \\
1 & j^{M-1} \theta & j \theta^{2} & \cdots & j^{M-2} \theta^{M-1}
\end{array}\right], \\
& \boldsymbol{R}=\left[\begin{array}{cccc}
1 & 0 & \cdots & 0 \\
0 & \phi & \cdots & 0 \\
\vdots & \vdots & \ddots & \vdots \\
0 & 0 & \cdots & \phi^{t-1}
\end{array}\right]
\end{aligned}
$$

where $s_{1}, s_{2}, \cdots, s_{t M}$ take from the constelltions; let $\phi^{t}=\theta$; choosing $j$ makes the determinate of matrix $\boldsymbol{L}$ be unequal to zero. Let $\theta=e^{i \omega}$ which is an algebraic number [10], here $i=\sqrt{-1}$ and $\omega$ is a parameter of needing the optimization design so that $\omega$ is searched in $(0, \pi / 2)$ to maximize the coding gain.
b) For $\boldsymbol{S}$ left-multiplied by $\boldsymbol{L}$ and right-multiplied by $\boldsymbol{R}$, one can get the linear combinatorial symbol matrix $\mathbf{Z}_{M \times t}$ like (10) as follows:
c) In the linear combinatorial symbol matrix $\mathbf{Z}_{M \times t}$, circulant-right-shifting the second row one time, the third row two times,..., the final row (i.e., the $M$ th row) $M-1$ times, respectively, one can get the coded matrix like (11) as follows:

$$
\begin{aligned}
& \boldsymbol{Z}_{M \times t}=\boldsymbol{L} \boldsymbol{S} \boldsymbol{R}=\left[\begin{array}{ccccc}
1 & \theta & \theta^{2} & \cdots & \theta^{M-1} \\
1 & j \theta & j^{2} \theta^{2} & \cdots & j^{M-1} \theta^{M-1} \\
\vdots & \vdots & \vdots & \ddots & \vdots \\
1 & j^{M-1} \theta & j \theta^{2} & \cdots & j^{M-2} \theta^{M-1}
\end{array}\right]\left[\begin{array}{cccc}
s_{1} & s_{1+M} & \cdots & s_{1+M(t-1)} \\
s_{2} & s_{2+M} & \cdots & s_{2+M(t-1)} \\
\vdots & \vdots & \ddots & \vdots \\
s_{M} & s_{2 M} & \cdots & s_{M t}
\end{array}\right]\left[\begin{array}{cccc}
1 & 0 & \cdots & 0 \\
0 & \phi & \cdots & 0 \\
\vdots & \vdots & \ddots & \vdots \\
0 & 0 & \cdots & \phi^{t-1}
\end{array}\right]
\end{aligned}
$$

$$
\boldsymbol{B}_{M t}=\left[\begin{array}{cccc}
s_{1}+\theta s_{2}+\cdots+\theta^{M-1} s_{M} & \phi\left(s_{1+M}+\theta s_{2+M}+\cdots+\theta^{M-1} s_{2 M}\right) & \cdots & \phi^{t-1}\left(s_{1+M(t-1)}+\theta s_{2+M(t-1)}\right.  \tag{11}\\
\phi^{t-1}\left(s_{1+M(t-1))}+j \theta s_{2+M(t-1)}\right. & s_{1}+j \theta s_{2}+\cdots+j^{M-1} \theta^{M-1} s_{M} & \cdots & \left.+\cdots+\theta^{M-1} s_{M t}\right) \\
\left.+\cdots+j^{M-1} \theta^{M-1} s_{M t}\right) & & & \left.+\cdots+j^{M-1} \theta^{M-1} s_{M(t-1)}\right) \\
\vdots & \vdots & \ddots & \vdots \\
\cdots \phi^{t-1}\left(s_{1+M(t-1)}+j^{M-1} \theta s_{2+M(t-1)}+j \theta s_{2+M(t-2)}\right. \\
\left.+\cdots+j^{M-2} \theta^{M-1} s_{M t}\right) & s_{1}+j^{M-1} \theta s_{2}+\cdots+j^{M-2} \theta^{M-1} s & \phi\left(s_{1+M}+j^{M-1} \theta s_{2+M}\right. \\
& & & \left.+\cdots+j^{M-2} \theta^{M-1} s_{2 M}\right) \cdots
\end{array}\right]
$$

Several examples of the C-STCs are presented as follows. Let $M=t=2$, according to (10), we have:

$$
\begin{aligned}
\boldsymbol{Z}_{2 \times 2} & =\boldsymbol{L} \boldsymbol{S} \boldsymbol{R}=\left[\begin{array}{cc}
1 & \theta \\
1 & j \theta
\end{array}\right]\left[\begin{array}{ll}
s_{1} & s_{3} \\
s_{2} & s_{4}
\end{array}\right]\left[\begin{array}{ll}
1 & 0 \\
0 & \phi
\end{array}\right] \\
& =\left[\begin{array}{cc}
s_{1}+\theta s_{2} & \phi\left(s_{3}+\theta s_{4}\right) \\
s_{1}+j \theta s_{2} & \phi\left(s_{3}+j \theta s_{4}\right)
\end{array}\right]
\end{aligned}
$$

If $j=1$, then $\left|Z_{2 \times 2}\right|=0$ which means the linear
combinatorial form of information symbols is lost. If $j=-1$, the linear combinatorial operation is retained. For $\phi^{2}=\theta=\mathrm{e}^{i(\pi / 4)}$, we can get the $2 \times 2$ C-STC matrix which is same as those in $[5,6]$

$$
\boldsymbol{B}_{2 \times 2}=\left[\begin{array}{cc}
s_{1}+\theta s_{2} & \phi\left(s_{3}+\theta s_{4}\right) \\
\phi\left(s_{3}-\theta s_{4}\right) & s_{1}-\theta s_{2}
\end{array}\right]
$$

Again let $M=3, t=4$, we have

$$
\boldsymbol{Z}_{3 \times 4}=\boldsymbol{L} \boldsymbol{S} \boldsymbol{R}=\left[\begin{array}{ccc}
1 & \theta & \theta^{2} \\
1 & j \theta & j^{2} \theta^{2} \\
1 & j^{2} \theta & j \theta^{2}
\end{array}\right]\left[\begin{array}{cccc}
s_{1} & s_{4} & s_{7} & s_{10} \\
s_{2} & s_{5} & s_{8} & s_{11} \\
s_{3} & s_{6} & s_{9} & s_{12}
\end{array}\right]\left[\begin{array}{cccc}
1 & 0 & 0 & 0 \\
0 & \phi & 0 & 0 \\
0 & 0 & \phi^{2} & 0 \\
0 & 0 & 0 & \phi^{3}
\end{array}\right]
$$

when $\phi^{4}=\theta=\mathrm{e}^{i \frac{\pi}{6}}, j=\mathrm{e}^{i \frac{2 \pi}{3}}, \boldsymbol{Z}_{3 \times 4}$ is full rank. Thus
we can get the $3 \times 4$ C-STC matrix like (12) as follows:

$$
\boldsymbol{B}_{3 \times 4}=\left[\begin{array}{crcr}
s_{1}+\theta s_{2}+\theta^{2} s_{3} & \phi\left(s_{4}+\theta s_{5}+\theta^{2} s_{6}\right) & \phi^{2}\left(s_{7}+\theta s_{8}+\theta^{2} s_{9}\right) & \phi^{3}\left(s_{10}+\theta s_{11}+\theta^{2} s_{12}\right)  \tag{12}\\
\phi^{3}\left(s_{10}+j \theta s_{11}+j^{2} \theta^{2} s_{12}\right) & s_{1}+j \theta s_{2}+j^{2} \theta^{2} s_{3} & \phi\left(s_{4}+j \theta s_{5}+j^{2} \theta^{2} s_{6}\right) & \phi^{2}\left(s_{7}+j \theta s_{8}+j^{2} \theta^{2} s_{9}\right) \\
\phi^{2}\left(s_{7}+j^{2} \theta s_{8}+j \theta^{2} s_{9}\right) & \phi^{3}\left(s_{10}+j^{2} \theta s_{11}+j \theta^{2} s_{12}\right) & s_{1}+j^{2} \theta s_{2}+j \theta^{2} s_{3} & \phi\left(s_{4}+j^{2} \theta s_{5}+j \theta^{2} s_{6}\right)
\end{array}\right]
$$

Similarly, we can get $\boldsymbol{B}_{2 \times 3}, \boldsymbol{B}_{2 \times 4}, \boldsymbol{B}_{2 \times 5}$ and $\boldsymbol{B}_{3 \times 3}$ which and all above will be applied to simulation testing later on.

## 4. Noncoherent Space-Time Codes

Literatures [5,6] introduce the design criterion of the Grassmann N-USTC. Let $\Omega_{i}$ and $\Omega_{j}$ denote the subspaces spanned by the column vectors of $\boldsymbol{X}_{i}$ and $\boldsymbol{X}_{j}$, respectively. Let $\left(\theta_{1}, \theta_{2}, \cdots, \theta_{M}\right)$ denote the principal angles between $\Omega_{i}$ and $\Omega_{j}$, then the chordal product distance between two points $\boldsymbol{X}_{i}$ and $\boldsymbol{X}_{j}$ on $\boldsymbol{G}_{T, M}^{C}$ is:

$$
\begin{equation*}
\Theta_{i, j}=\prod_{m=1}^{M} \sin ^{2} \theta_{m} \tag{13}
\end{equation*}
$$

The design criterion of the Grassmann N-USTC $C$ is
to make the minimal chordal product distance achieve the maximum, i.e. $\max _{C} \min _{X_{i} \neq X_{j} \in C} \Theta_{i, j}$. It is known from the expression (6) that the product $\boldsymbol{\Theta}_{i, 0}$ of the chordal distances between the subspace $\Omega_{i}$ and the reference subspace $\Omega_{0}$ is equal to the product of all singular values in matrix $\boldsymbol{B}_{i}$ whose $M$ column vectors span the subspace $\Omega_{i}$. The design criterion of a C-STC is to maximize its coding gain, which is equal to maximizing the minimum product of singular values of codeword matrix. Therefore we can use the matrix $\boldsymbol{B}_{M t}$ of (11) to design the matrix $\boldsymbol{B}$ in (6).

The exponential map from $\boldsymbol{B}_{M t}$ to $\boldsymbol{X}_{T M}$ must be the monotone and reversible, which requires that the exponential map of (6) is the reversible map, i.e., (9) exists the reversible matrix. So $\cos \lambda_{m}$ and $\sin \lambda_{m}$ in (9) should be the monotone function, then the constraint
condition of $\lambda_{m}$ is:

$$
\begin{equation*}
\max _{m} \lambda_{m}\left(B_{M t}\right) \leq \pi / 2, \quad m=0,1, \cdots, M-1 \tag{14}
\end{equation*}
$$

where $\lambda_{m}\left(B_{M t}\right)$ is the $m$ th singular value of any codeword $B_{M t}$ which is equal to the $m$ th principal angle between any $\Omega$ and $\Omega_{0}$. Therefore, a conceivable skill is that taking a scale $\alpha$, called the adjustive factor which multiplies the codeword matrix $B_{M t}$, can guarantee the map to be monotone and reversible. Thus (6) can be rewritten as follows:

$$
\boldsymbol{X}_{T M}=\left[\exp \left(\begin{array}{cc}
0 & \alpha \boldsymbol{B}  \tag{15}\\
-(\alpha \boldsymbol{B})^{\dagger} & 0
\end{array}\right)\right] \boldsymbol{I}_{T M}
$$

Obviously, $\alpha$ only affects the singular value of the matrix $B_{M t}$. Let $\left(0, \alpha_{\max }\right)$ denote a range of $\alpha$ values, the method of optimum searching $\alpha$ is described as follows.

Let $\boldsymbol{X}_{i}, \boldsymbol{X}_{j} \in \boldsymbol{G}_{T, M}^{C}$ be two distinct N-USTC codewords, the SVD of the matrix $\quad \boldsymbol{X}_{j}^{\dagger} \boldsymbol{X}_{i}$ is $\quad \boldsymbol{X}_{j}^{\dagger} \boldsymbol{X}_{i}=\boldsymbol{U} \boldsymbol{\Sigma} \boldsymbol{V}^{\dagger}$, where $\boldsymbol{\Sigma}$ is a diagonal matrix formed by the singular values $\lambda_{1}, \cdots, \lambda_{M}$. The $M$ principal angles between the subspaces $\Omega_{i}$ and $\Omega_{j}$ spanned respectively by $\boldsymbol{X}_{i}$ and $\boldsymbol{X}_{j}$ are $\theta_{m}=\cos ^{-1} \lambda_{m}, m=0,1, \cdots, M-1$, substituting $\theta_{m}=\cos ^{-1} \lambda_{m}$ for the expression (13), we can get:

$$
\begin{equation*}
\Theta_{i, j}=\prod_{m=1}^{M}\left(1-\lambda_{m}^{2}\right) \tag{16}
\end{equation*}
$$

Under the condition of making $\Theta_{i, j}$ maximize, by searching $\alpha$ in $\left(0, \alpha_{\max }\right)$, we can get the optimum $\alpha_{\text {opt }}$.

Now we design $\boldsymbol{X}_{T M}$ by mapping exponentially $\boldsymbol{B}_{M t}$ to $\boldsymbol{G}_{T, M}^{C}$. The design step is:
(a) For $M$ transmit antennas and $t$ coherent periods, according to (10) and (11), design the C-STC matrix $\boldsymbol{B}_{M t}$ from the information symbol $s_{1}, s_{2}, \cdots, s_{t M}$.
(b) Substitute $\boldsymbol{B}_{M t}$ for $\boldsymbol{B}$ in (15), search the optimum adjustive factor $\alpha$, and construct the exponential mapping matrix $\boldsymbol{E}=\left(\begin{array}{cc}0 & \alpha \boldsymbol{B}_{M t} \\ -\left(\alpha \boldsymbol{B}_{M t}\right)^{\dagger} & 0\end{array}\right)$.
(c) According to (7) and the above $\boldsymbol{E}$ matrix, applying the SVD to $\left(\alpha_{o p t} \boldsymbol{B}_{M t}\right)$, we get the noncoherent codeword $\boldsymbol{X}_{T M}$ like (9), and $T=M+t$. $\square$

## 5. Examples and Numerical Simulation Results

According to the above presented method, this section gives several examples of the N-USTCs whose numerical simulation curves are shown as Figure 1. Let
$D=M(T-M)$ denote the degree of freedom. Suppose
modulation is q -PSK with symbol number $p$. So the spectral efficiency of the N-USTC is
$\eta_{T \times M}=\left(\log _{2} p\right) \cdot D / T$ bits $/ \mathrm{Hz} / \mathrm{s}$.
Example 1: Compare two curves of solid line with black dot and dash line with circle in Figure 1. For system $M=N=2$ and QPSK modulation with $p=4$, let $t=2$, we construct the C-STC $\boldsymbol{B}_{2 \times 2}$, where $\phi^{2}=\theta=\mathrm{e}^{i(\pi / 4)}, j=-1$. When $t=3$, we get $\boldsymbol{B}_{2 \times 3}$, where $\phi^{3}=\theta=\mathrm{e}^{i(\pi / 4)}, j=-1$. As $T=M+t$, having $T=4$ for $t=2$ and $T=5$ for $t=3$, corresponding to $D=4$ and $D=6$, we compute $\eta_{4 \times 2}=2 \mathrm{bits} / \mathrm{Hz} / \mathrm{s}$ and $\eta_{5 \times 2}=2.4$ bits $/ \mathrm{Hz} / \mathrm{s}$, respectively. We map the C-STC $\boldsymbol{B}_{2 \times 2}$ into the N-USTC $\boldsymbol{X}_{4 \times 2}$ on $G_{4,2}^{C}$ and $\boldsymbol{B}_{2 \times 3}$ into $\boldsymbol{X}_{5 \times 2}$ on $G_{5,2}^{C}$ which correspond to the optimum adjustive factor $\alpha_{\text {opt }, Q}^{4 \times 2}=0.29$ and $\alpha_{\text {opt }, Q}^{5 \times 2}=0.25$, respectively. At $10^{-5}$ bit error rate (BER), $\boldsymbol{X}_{5 \times 2}$ outperform $\boldsymbol{X}_{4 \times 2}$ about 3 dB . Obviously, under all parameter being same except $T$ increasing, the N-USTC BER performance and the spectral efficiency are improved.

Example 2: Compare four curves of solid line with black square, dash line with white square, solid line with black diamond and dash line with white diamond in Figure 1. For system $M=N=2$ and BPSK modulation with $p=2$, let $t=2,3,4,5$, get $T=4,5,6,7$ and $D=4,6,8,10$, so $\eta_{4 \times 2}=1, \eta_{5 \times 2}=1.2, \quad \eta_{6 \times 2}=1.33$ and $\eta_{7 \times 2}=1.43 \mathrm{bits} / \mathrm{Hz} / \mathrm{s}$, respectively. We map $\boldsymbol{B}_{2 \times 2}$, $\boldsymbol{B}_{2 \times 3}, \boldsymbol{B}_{2 \times 4}$ and $\boldsymbol{B}_{2 \times 6}$ into $\boldsymbol{X}_{4 \times 2}, \boldsymbol{X}_{5 \times 2}, \boldsymbol{X}_{6 \times 2}$ and $\boldsymbol{X}_{7 \times 2}$ whose factors are $\alpha_{o p t, B}^{4 \times 2 \times 2}=0.41, \alpha_{\text {opt }, B}^{5 \times 2}=0.36$, $\alpha_{o p t, B}^{6 \times 2}=0.32$ and $\alpha_{o p t, B}^{7 \times 2}=0.29$. At $10^{-5}{ }^{\text {opt, }}$ BER, the performance of the N-USTC improve about $0.5-1.0 \mathrm{~dB}$ and the spectral efficiency increases along with $T$ increasing.

Example 3: Compare two curves with solid line with black triangle and dash line with white triangle in Figure 1. For system $M=N=3$ and BPSK modulation with $p=2$, let $t=3,4$, get $T=6,7$ and $D=9,12$, so $\eta_{6 \times 3}=1.5$ and $\eta_{7 \times 3}=1.71$ bits $/ \mathrm{Hz} / \mathrm{s}$, respectively. We map $\boldsymbol{B}_{3 \times 3}$ and $\boldsymbol{B}_{3 \times 4}$ into $\boldsymbol{X}_{6 \times 3}$ and $\boldsymbol{X}_{7 \times 3}$ whose fac-


Figure 1. Performance comparison of several N-USTCs.
tors are $\alpha_{o p t, B}^{6 \times 3}=0.24$ and $\alpha_{o p t, B}^{7 \times 3}=0.22$. At $10^{-5}$ BER, the performance of the N -USTC improve about 0.8 dB from $T=6$ to $T=7$, and the spectral efficiency also increases 0.2 bits $/ \mathrm{Hz} / \mathrm{s}$.

## 6. Conclusions

A specific step that maps the coherent space-time matrix into the noncoherent space-time matrix by means of the exponent form of the tangential space of Grassmann manifold was summed up for designing the N -USTCs. Especially, our work makes the structural parameters $M, N, T, t$ with regard to both the N-USTC based on the Grassmann manifold and the C-STC based on the algebraic number theory be able to be designed more flexibly. We also discovered that in the discussed family of Grassmannian N-USTC, the optimum codeword can be obtained by searching the optimum adjustive factor $\alpha_{o p t}$. It is noticed that the design of the parameter $j$ in leftmultiplied matrix $L$ is open problem, we will track this problem in the future.

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