

Derivation the Schemes of Lateral and Vertical Dispersion Parameters: Application in Gaussian Plume Model

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ABSTRACT

The main objective of this paper is to estimate the plume dispersion parameters in lateral direction (σ_y) and vertical direction (σ_z) by using power law wind speed and the scheme of eddy diffusivity in unstable condition. Comparison among our model and algebraic [1] and integral [2] formulations were held. We find that our model and two other models are in agreement with observed data.

Keywords: Dispersion Parameters; Gaussian Plume Model; Eddy Diffusivity

1. Introduction

The study and employment of operational short-range atmospheric dispersion models for environmental impact assessment have demonstrated to be of large use in the evaluation of ecosystems perturbation in many distinct scales [3].

In operational applications, the classical Gaussian diffusion models are largely employed in assessing the impacts of existing and proposed sources of air contaminants on local and urban air quality [4]. Simplicity, associated with the Gaussian analytical model, makes this approach particularly suitable for regulatory usage in mathematical modeling of the air pollution, such models are quite useful in short forecasting. The lateral and vertical dispersion parameters, respectively σ_y and σ_z represent the key turbulent parameterization in this approach. They contain the physical ingredients that describe the dispersion process and, consequently, express the spatial extent of the contaminant plume under the effect of the turbulent motion in the planetary boundary layer (PBL) [5].

In this work, we estimated the schemes of dispersion parameters in the lateral direction (σ_y) and the vertical direction (σ_z) in unstable stability by using wind speed in power law and comparing between our work and da (algebraic and integral formulations) with observed ta of sulfur hexafluoride (SF6) are taken from Copenhagen in Denmark.

2. Model Formulation

The concentration associated from point source of

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strength Q , is expressed as [6]:

$$\frac{C(x, y, z)}{Q} = \frac{A}{\sqrt{2\pi}\sigma_y \bar{U}Z} \exp\left(-\left(\frac{Bz}{\bar{Z}}\right)^s\right) \exp\left(-\frac{y^2}{2\sigma_y^2}\right) \quad (1)$$

C is the average concentration of diffusing point (x, y, z) (kg/m^3).

U is mean wind velocity along the x-axis (m/s).

x is along-winds coordinate measured in wind direction from the source (m).

y is cross-wind coordinate direction (m).

z is vertical coordinate measured from the ground (m).

σ_y is the plume dispersion parameter in the lateral directions.

Where the value of the parameter, s , depends on the stability ($s = 0.75$ and $A = 1.42$) in unstable case [7].

The mean plume height, \bar{Z} , is defined by

$$\bar{Z}(x) = \frac{\int_0^\infty zC(x, y, z) dz}{\int_0^\infty C(x, y, z) dz} \quad (2)$$

And the mean plume velocity, \bar{U} , is defined by

$$\bar{U} = \frac{\int_0^\infty U(z)C(x, y, z) dz}{\int_0^\infty C(x, y, z) dz} \quad (3)$$

We assume that the mean wind speed, $U(z)$, can be described by a power law so that:

$$U(z) = U_r \left(\frac{z}{Z_r}\right)^p \quad (4)$$

U_r is a reference velocity at height Z_r , the value of the

power, p , lies between 0.15 and 0.20 in unstable case [8].

Let, B , be a non-zero constant, then taking:

$$z = \frac{\bar{Z}}{B} X^{\frac{1}{s}} \Rightarrow dz = \frac{\bar{Z}}{Bs} X^{\frac{1}{s}-1} dX \tag{5}$$

Substitution from Equations (1) and (5) in Equation (2) one gets:

$$B = \frac{\Gamma(2/s)}{\Gamma(1/s)} \tag{6}$$

where $\Gamma(p)$ is the gamma function.

Substituting from Equations (4), (1) and (5) in Equation (3), we obtain the mean plume velocity:

$$\bar{U}(z) = U_r \left(\frac{\bar{Z}}{Z_r B} \right)^p \Gamma\left(\frac{p+1}{s}\right) / \Gamma\left(\frac{1}{s}\right) \tag{7}$$

The mean plume height, \bar{Z} , can be calculated according to [9]:

$$\frac{d\bar{Z}}{dx} = \frac{K(q\bar{Z})}{U(q\bar{Z})q\bar{Z}} \tag{8}$$

and

$$q = \left(s \left(\Gamma\left(\frac{2}{s}\right) / \Gamma\left(\frac{1}{s}\right) \right)^s \right)^{1/(1-s)} \tag{9}$$

where $K(z)$ is the eddy diffusivity parameterization that is led to the K -theory assumption.

According to [10], the form of $K(z)$ in an unstable case is:

$$\frac{d\sigma_y}{dx} = \sigma_v \left/ \left(\frac{h^2 k w_* Z_r^p x}{q^2 (1 - (p/p+1)) U_r q^p} \right)^{p/p+1} \frac{U_r}{(Z_r B)^p} \left(\frac{\Gamma\left(\frac{p+1}{s}\right)}{\Gamma\left(\frac{1}{s}\right)} \right) \right. \tag{13}$$

where

$$\bar{U}(z) = \left(h^2 k w_* Z_r^p x / q^2 \left(1 - \frac{p}{p+1} \right) U_r q^p \right)^{p/p+1} \frac{U_r}{(Z_r B)^p} \left(\Gamma\left(\frac{p+1}{s}\right) / \Gamma\left(\frac{1}{s}\right) \right)$$

where σ_v is the standard deviation of the wind speed in the lateral direction.

By Integrating the Equation (13) with respect to x , we obtain the plume dispersion parameter in the lateral direction (σ_y) as follows:

$$\sigma_y(x) = \frac{\sigma_v x (Z_r B)^p}{\left(h^2 k w_* Z_r^p x / q^2 \left(1 - \frac{p}{p+1} \right) U_r q^p \right)^{p/p+1} U_r \left(\Gamma\left(p + \frac{1}{s}\right) / \Gamma\left(\frac{1}{s}\right) \right)}$$

Also estimating the vertical spread σ_z using hypothesis by [12]:

$$\frac{d\sigma_z}{dx} = \frac{\sigma_w U_r}{\left(h^2 k w_* Z_r^p x / q^2 \left(1 - \frac{p}{p+1} \right) U_r q^p \right)^{p/p+1} (Z_r B)^p \left(\Gamma\left(\frac{p+1}{s}\right) / \Gamma\left(\frac{1}{s}\right) \right)} \tag{15}$$

$$K(z) = k w_* z \left(1 - \frac{z}{h} \right) \tag{10}$$

where k is the Von Karman constant which is set to 0.4, w_* is the convection scaling parameter and h is the effective height of release above the ground estimated from [11]:

$$h = h_s + \Delta h$$

where h_s is physical stack height (115m).

$$\Delta h = 3(W/U_{115})D$$

where, W , is the exit velocity (4 m/s), D is the internal stack diameter (1 m) and

$$U_{115} = U_{10}(h_s/10)^p$$

U_{10} is the wind speed at 10 m height.

Substituting from Equations (4), (10) in Equation (8) and integrating Equation (8), we obtain the mean plume height \bar{Z} :

$$\bar{Z} = \left(h^2 k w_* Z_r^p x / q^2 \left(1 - \frac{p}{p+1} \right) U_r q^p \right)^{1/p+1} \tag{11}$$

Substituting from Equation (11), in Equation (7), we obtain the mean plume velocity \bar{U} :

$$\bar{U}(z) = \left(\frac{h^2 k w_* Z_r^p x}{q^2 \left(1 - \frac{p}{p+1} \right) U_r q^p} \right)^{\frac{p}{p+1}} \frac{U_r}{(Z_r B)^p} \left(\frac{\Gamma\left(\frac{p+1}{s}\right)}{\Gamma\left(\frac{1}{s}\right)} \right) \tag{12}$$

We estimate the horizontal spread σ_y using Eckman's (1994) hypothesis that [12]:

where σ_w is the standard deviation of the wind speed in the vertical direction. Integrating Equation (15) with respect to x , we obtain the plume dispersion parameter in the vertical direction (σ_z) as follows:

$$\sigma_z(x) = \frac{\sigma_w x (Z_r B)^p}{\left(\frac{h^2 k w_* Z_r^p x}{q^2 \left(1 - \frac{p}{p+1}\right) U_r q^p} \right)^{\frac{p}{p+1}} U_r \left(\frac{\Gamma\left(\frac{p+1}{s}\right)}{\Gamma\left(\frac{1}{s}\right)} \right)} \quad (16)$$

Then Gaussian expressions for the ground crosswind integrated concentration and the normalized ground level concentration along the plume centerline respectively are given by [4] on the forms:

$$\frac{C_y(x, 0)}{Q} = \sqrt{\frac{2}{\pi}} \frac{1}{U \sigma_z} \exp\left(\frac{-h^2}{2\sigma_z^2}\right) \quad (17)$$

$$\frac{C_y(x, 0, 0)}{Q} = \frac{1}{\pi U \sigma_z \sigma_y \exp(-h^2/2\sigma_z^2)} \quad (18)$$

From the previous works, the plume dispersion parameters in the vertical and lateral directions (σ_z and σ_y) respectively are given by [1] in the form:

$$\frac{\sigma_z^2}{z_i^2} = 0.42 \psi^{\frac{2}{3}} x^2 / 1 + \left(2.9 \psi^{\frac{1}{3}} x \right) \quad (19)$$

and

$$\frac{\sigma_y^2}{z_i^2} = 0.55 \psi^{\frac{2}{3}} x^2 / 1 + \left(2.24 \psi^{\frac{1}{3}} x \right) \quad (20)$$

Also, the plume dispersion parameters in the vertical and lateral directions (σ_z and σ_y) respectively are given by [2] as follows:

$$\frac{\sigma_z^2}{z_i^2} = \left(\frac{0.29}{\pi^2} \right) \int_0^\infty \sin^2 \left(0.98 \pi \Psi^{\frac{1}{3}} x n' \right) / \left(n'^2 (1+n')^{\frac{5}{3}} \right) dn' \quad (21)$$

$$\frac{\sigma_y^2}{z_i^2} = \frac{0.66}{\pi^2} \int_0^\infty \frac{\sin^2 \left(0.75 \pi \Psi^{\frac{1}{3}} x n' \right)}{n'^2 (1+n')^{\frac{5}{3}}} dn' \quad (22)$$

3. Results and Discussion

The used data set was observed from the atmospheric diffusion experiments conducted at the northern part of Copenhagen, Denmark, under unstable conditions [13] and [14]. The tracer sulfur hexafluoride (SF6) was released from a tower at a height of 115 m without buoyancy. There are two Gaussian models. The First is measured at ground surface and the other at the plume centerline. In this work, there are three predicted normalized

concentrations (our model and two previous models) as shown in **Tables 1** and **2**.

Figures 1 and **2** show that the observed and predicted scatter diagram of crosswind integrated concentrations of centerline and ground level respectively using Gaussian model with vertical and lateral dispersion parameters given by (Equations (14) and (16) our model) and (Equations (19) and (20), algebraic formulation), (Equations (21) and (22), integral formulation) respectively. From the two figures one finds that there are some predicted data which are agreement with observed data (one to one) and others lie inside the factor of two.

4. Statistical Method

Now, the statistical method is presented and comparison among analytical, statically and observed results will be offered [Hanna 1989, 15]. The following standard statistical performance measures that characterize the agreement between prediction ($C_p = C_{pred}/Q$) and observations ($C_o = C_{obs}/Q$):

Normalized mean square error (NMSE): It is an esti-

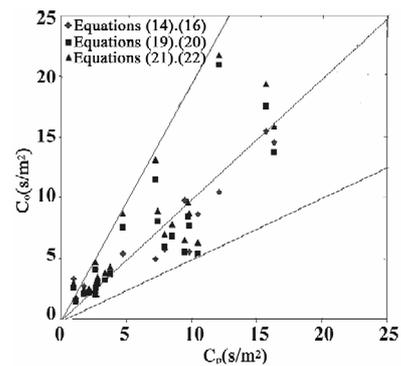


Figure 1. Observed and predicted ground crosswind integrated centerline concentration, normalized with emission $C_y(x, 0, 0)/Q$: scatter diagram for the solution of Equation (18) using Equations (14), (16) and (19)-(22).

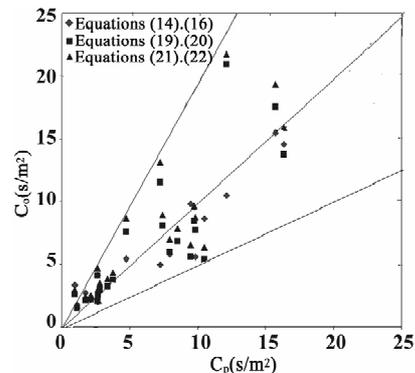


Figure 2. Observed and predicted ground crosswind integrated concentration, normalized with emission $C_y(x, 0)/Q$: scatter diagram for the solution of Equation (17) using Equations (16), (19) and (21).

Table 1. Observed and model ground-level centerline concentration. $C(x, 0, 0)/Q$ at different distances, wind speed and effective height from the source.

Run no.	h (m)	U115	distance (x) (m)	w*	C(x, 0, 0)/Q (s/m ²) Observed	C(x, 0, 0)/Q (s/m ²)		
						Our model Equations (14), (16) and (18)	Previous work Equations (19), (20) and (18)	Previous work Equations (21), (22) and (18)
1	119	3	1900	1.8	10.5	8.61		6.37
1	119	3	3700	1.8	2.14	7.42		2.55
2	117	8	2100	1.8	9.85	5.55	7.67	8.71
2	117	8	4200	1.8	2.83	1.80	5.34	3.48
3	118	4	1900	1.3	16.33	14.56	2.17	15.87
3	118	4	3700	1.3	7.95	5.77	5.95	6.98
3	118	4	5400	1.3	3.76	1.09	3.72	4.32
5	117	5	2100	0.7	15.71	15.49	17.51	19.36
5	117	5	4200	0.7	12.11	10.49	20.94	21.73
5	117	5	6100	0.7	7.24	4.94	11.49	13.14
6	116	11	2000	2	4.75	5.43	7.52	8.69
6	116	11	4200	2	7.44	2.94	8.02	8.91
6	116	11	5900	2	3.37	8.29	3.24	3.8
7	117	7	2000	2.2	1.74	2.74	2.07	2.44
7	117	7	4100	2.2	9.48	9.78	5.55	6.54
7	117	7	5300	2.2	2.62	4.12	2.03	2.41
8	117	7	1900	2.2	1.15	1.74	1.44	1.7
8	117	7	3600	2.2	9.76	3.22	8.43	9.62
8	117	7	5300	2.2	2.64	1.96	4.06	4.69
9	116	8	2100	1.9	0.98	3.34	2.59	2.96
9	116	8	4200	1.9	8.52	1.52	6.86	7.85
9	116	8	6000	1.9	2.66	6.75	2.55	3.04

Table 2. Observed and model ground-level concentration $C_y(x, 0)/Q$ at different distances, wind speed and effective height from the source.

Run no.	h (m)	U115	distance (x) (m)	w*	C(x, 0)/Q (s/m ²) Observed	C(x, 0)/Q (s/m ²)		
						Our model Equations (16) and (17)	Previous work Equations (17) and (19)	Previous work Equations (17) and (21)
1	119	3	1900	1.8	6.48	3.72	6.06	6.58
1	119	3	3700	1.8	2.31	4.61	3.96	4.28
2	117	8	2100	1.8	5.38	4.66	3.64	3.79
2	117	8	4200	1.8	2.95	2.46	2.48	2.68
3	118	4	1900	1.3	8.2	7.92	7.35	7.72
3	118	4	3700	1.3	6.22	1.23	5.22	5.6
3	118	4	5400	1.3	4.3	2.21	4.22	4.52
5	117	5	2100	0.7	6.72	8.24	8.54	8.77
5	117	5	4200	0.7	5.84	2.63	6.04	5.71
5	117	5	6100	0.7	4.97	4.65	5.73	5.96
6	116	11	2000	2	3.96	3.30	4.9	5.19
6	116	11	4200	2	2.22	4.41	3.14	3.18
6	116	11	5900	2	1.83	1.06	2.31	2.47
7	117	7	2000	2.2	6.7	4.63	1.9	2.04
7	117	7	4100	2.2	3.25	1.09	3.69	4.25
7	117	7	5300	2.2	2.23	1.48	2.14	2.73
8	117	7	1900	2.2	4.16	5.16	4.12	2.31
8	117	7	3600	2.2	2.02	2.91	3.12	4.28
8	117	7	5300	2.2	1.52	2.50	2.56	3.31
9	116	8	2100	1.9	4.58	3.04	3.53	2.71
9	116	8	4200	1.9	3.11	2.19	2.34	3.7
9	116	8	6000	1.9	2.59	4.04	1.85	2.54

mator of the overall deviations between predicted and observed concentrations. Smaller values of NMSE indicate a better model performance. It is defined as:

$$NMSE = \frac{\overline{(C_o - C_p)^2}}{\overline{C_o} \overline{C_p}} \quad (23)$$

Fractional bias (FB): It provides information on the tendency of the model to overestimate or underestimate the observed concentrations. The values of FB lie between -2 and $+2$ and it has a value of zero for an ideal model. It is expressed as:

$$FB = \frac{(\overline{C_o} - \overline{C_p})}{0.5(\overline{C_o} + \overline{C_p})} \quad (24)$$

Correlation coefficient (R): It describes the degree of association between predicted and observed concentrations and is given by:

$$R = \frac{\overline{(C_o - \overline{C_o})(C_p - \overline{C_p})}}{\sigma_o \sigma_p} \quad (25)$$

Fraction within a factor of two (FAC2) is defined as: FAC2 = fraction of the data for which

$$0.5 \leq (C_p / C_o) \leq 2$$

where σ_p and σ_o are the standard deviations of C_p and C_o respectively. Here the over bars indicate the average over all measurements (Nm). A perfect model would have the following idealized performance: NMSE = FB = 0 and COR = FAC2 = 1.0 of the entire journals, and not as an independent document. Please do not revise any of the current designations.

From the statistical method of **Table 3**, we find that the predicted concentrations for all models lie inside factor of 2 with observed data. Regarding to NMSE, we find that two previous works are better than our model. Regarding to FB and correlation coefficient of all models are agreement with observed data.

Table 4 shows that the predicted concentrations for all models lay inside factor of 2 with observed data. Regarding to NMSE, all the predicted concentrations are better to the observed data. Regarding to FB and correlation coefficient of all methods are agreement with observed data.

5. Conclusions

New schemes of dispersion parameters in the lateral direction (σ_y) and the vertical direction (σ_z) are estimated in unstable stability by using power law wind speed and calculating Gaussian plume model at ground and at plume centerline.

One used observed data of the tracer sulfur hexafluoride (SF6) which was released from a tower at a height of 115m without buoyancy at the northern part of Copenhagen, Denmark, under unstable conditions [13,14]. There are two Gaussian models; The First is measured at ground surface and the other at the plume centerline. In this work, there are three predicted normalized concentrations (our model and two previous models).

Table 3. Comparison between different models ground-level centerline concentration $C_y(x, 0, 0)/Q$ and observed concentrations.

Predicted models $C_y(x,0,0)/Q$	NMSE	FB	COR	FAC2
Our model Equations (14), (16) and (18)	0.28	0.12	0.72	1.22
Previous work Equations (19), (18) and (20)	0.18	-0.02	0.83	1.12
Previous work Equations (18), (21) and (22)	0.18	-0.14	0.86	1.28

Table 4. Comparison between different models ground-level centerline concentration $C_y(x, 0)/Q$ and observed concentrations.

Predicted models $C_y(x,0)/Q$	NMSE	FB	COR	FAC2
Our model Equations (16) and (17)	0.13	0.07	0.90	1.09
Previous work Equations (17) and (19)	0.11	0.03	0.72	1.05
Previous work Equations (17) and (21)	0.14	-0.03	0.64	1.15

From the (**Figures 1 and 2**), one finds that there are some predicted data which are agreement with observed data (one to one) and others lie inside the factor of two

From the statistical method, we find that the predicted concentrations for all models lie inside factor of 2 with observed data. Regarding to NMSE, all the predicted concentrations are agreement with the observed data. Regarding to FB and correlation coefficient of all methods agree to observed data.

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