

Design and Efficient Controller for Micro Turbine System

G. Saravanan¹, I. Gnanambal²

¹Department of Electrical and Electronics Engineering, Sona College of Technology, Salem, India

²Department of Electrical and Electronics Engineering, Government College of Engineering, Salem, India

Email: gsarangokul@yahoo.com, ignan1960@gmail.com

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Abstract

In this modern era, power generation seems to be a very demanding factor. New models and methods have been proposed to derive from various natural and manmade resources. In such instances, this paper gives a detailed report on the power generation from Micro Turbines. Micro turbine plays a very important role in electric power generation. Especially they are used in the combined cycle process power plants. The parameters of Rowen's model 265-MW single shaft heavy duty gas turbines which are used in dynamic studies are estimated in this paper using the operational and performance data. These data are also used to briefly explain the extraction of parameters of the used model. Micro turbine parameters are approximated using simple thermodynamics assumptions. Micro turbine power generation seems to be an uprising and a promising source and an exact design with a perfect model is capable of producing the highest efficiency. Thus this paper is proposed on the aspects of social awareness to elaborate the control design of Micro Turbine Power Generation System. The parameters of micro turbine models are derived and the results of several simulated tests using Matlab/Simulink are presented.

Keywords

Dynamic Simulation, Micro Turbine, Control Design

1. Introduction

Generally distributed generation technologies can be classified into the following: micro turbine generation, wind generation, photovoltaic generation and diesel engine generation. As micro turbine has the characteristics of low cost, high efficiency, long life and convenient use, it is regarded as one of the best promising ways of distributed generation. Micro turbines are effective and simplistic in their design for small scale power genera-

tion. They also have secure and reliable operating systems. Micro turbine is widely used in distributed power and combined heat and power applications. Micro turbines are small gas turbines which burn gaseous or liquid fuels to create a high energy gas stream that operates an electric generator. Micro turbines are capable of burning number of fuels at high and low pressure levels. The pressure ratio over the compressor is low, around 4, compared to other gas turbines. The compressor and the turbine are 0.15 m in diameter and the entire enclosure is only $2.92 \times 1.90 \times 0.87$ meters. This makes installation easy.

Micro turbine is small combustion turbine, which is approximately the size of a refrigerator, with outputs of 25 kW to 500 kW. It thus provides a variety of opportunities to meet the applications of distributed power systems. Distributed generation provides a wide range of services to consumers and utilities, including standby generation, peak shaving capability, base load generation and co-generation. Our proposed system develops several models with different degrees of simplification for the representation of gas turbines in dynamic studies have introduced, amongst which the IEEE model for combined cycle power plants had deeper sight into internal processes. The paper is organized into existing systems, proposed system, implementation and its performance. Literature related with the proposed systems is discussed in Chapter 2. Chapter 3 deals with the working progress of micro turbine. Chapter 4 discusses the mechanism used for the control systems for a 265-MW Micro Turbine. The performance analysis is detailed in Chapter 5. Chapter 6 concludes with a few points as to the scope for future enhancement.

2. Literature Survey

[1] presents the results of an investigation regarding the electrical performance characteristics of a new, three-phase, 480 V (L-L), 30 kW, micro-turbine generator and its suitability as an electrical power source for applications at the electrical power distribution voltage level. In this work [2] discusses micro-turbine and fuel cell models, and the instantaneous power issue. [3] presents simplified slow dynamic model for micro turbines and fuel cells. Their stand-alone dynamic performances are analyzed and evaluated. It is illustrated that micro turbines and fuel cells are capable of providing load following service, significantly enhancing their economic value. Recently, more attention has been paid to the high-speed generator driven by micro-turbine due to its simple structure and high power density. In this work [4], a method to reduce harmonic current in high-speed generator for a distributed power system is presented. Because no additional hardware is needed, the proposed method can be used for various power systems. The detecting and eliminating method of harmonic current components based on hysteresis control strategy of the active power filter using start-up inverter are discussed in detail. In this work [5] develops the model of a PMSG wind turbine and then simulates short circuits to evaluate the performance of the system during short circuit fault.

Since PMSG wind turbine systems use a double conversion converter, this paper develops two methods for controlling the converter, a new protection method for capacitor over voltage is also evaluated in this paper [6]. The interconnection of MW scale micro-turbine as a set of small, modular generation system at the LV distribution level has a significant impact on micro-grid performance.

According to the dynamic characteristics of the Micro-turbine system, a complete mathematic model which considers the Micro-turbine and other electrical components as a whole is established in PACAD/EMTDC. In [7], the parameters of rowan's model for heavy duty gas turbines in dynamic studies are estimated by use of available operational and performance data. A 172-MW simple cycle, single shaft heavy duty gas turbine and its available operational data are also presented and studied for deriving the parameters of the model. gas turbine parameters are approximated by using simple thermodynamic assumptions, resulting in good corresponding with typical values. In this work presents modeling [8] and performance analysis of MTG system in grid connected and islanding modes of operation. The modeling of a single-shaft micro-turbine generation system suitable for isolated distributed generation applications has been discussed in [9]. Relative researches have also been done on the modeling of micro turbine system [10].

3. Micro Turbine

Industrial heavy duty gas turbines are specially designed gas turbines for power generation which are specified by their long life and higher availability compared other types of gas turbines. Micro turbines are designed to operate for long periods with less maintenance. There are two major types of operation of micro turbines—one with single shaft and the other with split-shaft design. The basic components of a micro turbine are compressor, turbine generator and recuperator as shown in **Figure 1**. The heart of the Micro turbine is the compressor-turbine

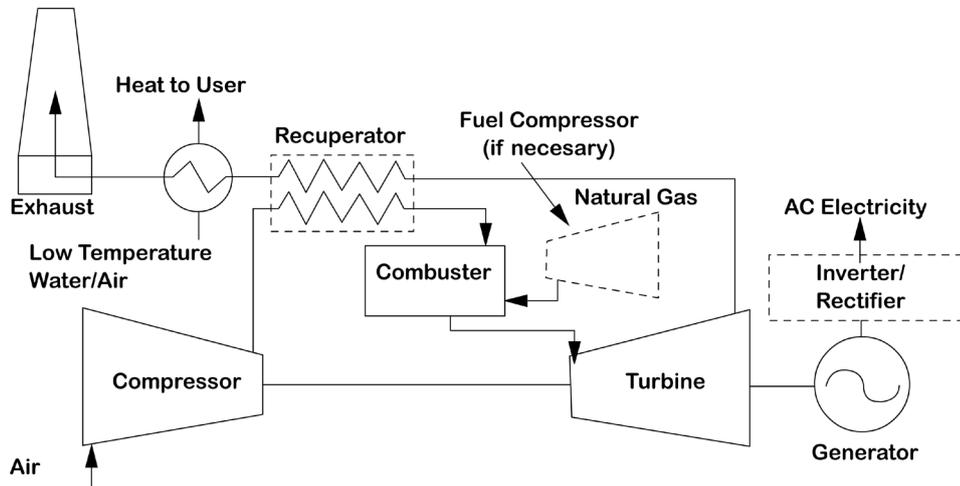


Figure 1. The basic component of micro turbine.

unit, which is commonly mounted on a single shaft along with the electrical generator.

The working progress of the micro turbine can be described as follows: air, at atmosphere pressure, enters the Micro turbine at the compressor inlet. When the air is compressed to achieve the most favourable conditions for combustion, fuel gas is mixed with the compressed air in the combustion chamber. This result in combustion of fuel and the hot exhaust gases are expanded through the turbine to produce the mechanical power.

The system is considered to operate under normal operating conditions and the fast dynamics of the micro turbine (e.g., start-up, shutdown, internal faults and loss of power) are neglected. Speed control is operated on the speed error, which is computed as the difference between a reference speed and the Micro turbine generation rotor speed. It is usually modeled by using a lead-lag transfer function; and is the primary means of control for the Micro turbine under partial load conditions.

The output of the governor goes to a low value select to produce a value for V_{ce} , the fuel demand signal. If the operating speed of the system is close to its rated speed, the acceleration control could be eliminated in the modeling. The output of low value selector represents the least amount of fuel required for that particular operating point and is denoted as “ V_{ce} ”. The per unit value for “ V_{ce} ” corresponds directly to the per unit value of mechanical power on turbine base in steady state. The output of the low value selector is compared with maximum and minimum limits. The maximum limit acts as back up to temperature control and is not encountered in normal operation and minimum limit is more important dynamically. The output of the “ V_{ce} ” limiter is multiplied by 0.77 and offset by no load fuel flow value to ensure the continuous combustion process. The fuel flow controls are represented by series of blocks including the valve position and flow dynamics.

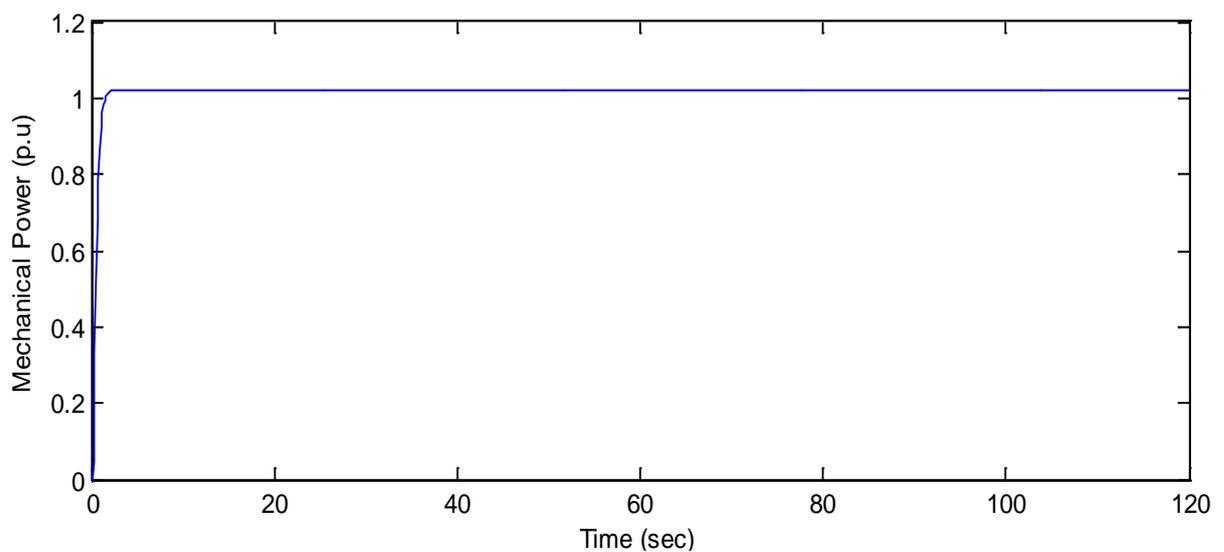
The other signal into the low value select is from the temperature controller. The fuel flow, burned in the combustor results in turbine torque and in exhaust gas temperature measured by a thermocouple. The output from the thermocouple is compared with a reference value, which is usually higher. This enables the temperature control output to remain on the maximum limit, thus resulting in uninhibited governor/speed control. When the thermocouple output exceeds the reference temperature, the temperature control output starts decreasing. When this output becomes lower than the governor output, the former value will pass through the low value select to limit the output, and the unit will operate on temperature control.

4. Controller for Micro Turbine

Turbine is a linear, dynamic device with the exception of the rotor time constant. The rotor time constant is attributed to two transport delays—one is the time lag associated with the compressor discharge volume; and the other is due to the transport of gas from the combustion system through the turbine. Both the torque and exhaust temperature characteristics of the single shaft Micro turbine is linear with respect to fuel flow and turbine speed. The Micro turbine behavior forces its dynamic model to have small delays and lag time constants. The time delays in the Micro turbine are the combustion reaction delay and the delay seen by the exhaust system and turbine to transport the fluid to the measuring point. The combustion reaction delay is between the fuel injection and

Table 1. Parameters values of micro turbine controller.

Components	Parameters	Rating values
W	Speed governor gain = 1/droop	25
Y	Speed governor lag time constant	0.05
MaxF	Fuel demand signal upper limit	1.5
MinF	Fuel demand signal lower limit	-0.07
K _{NL}	No load fuel consumption	0.16
K _F	Fuel system external feedback loop gain	0
B	Valve system transfer function coefficient	0.04
C	Fuel system transfer function coefficient	1
T _{FS}	Fuel system time constant	0.31
E _{CR}	Combustion reaction time delay	0.05
E _{TD}	Turbine and exhaust delay	0.04
T _{CD}	Compressor discharge volume time constant	0.142
T _R	Turbine rated exhaust temperature	585.6
A	Gas turbine torque block parameter	-0.117
B	Gas turbine torque block parameter	1.1169
C	Gas turbine torque block parameter	0.5
D	Gas turbine exhaust block parameter	492.6
E	Gas turbine exhaust block parameter	351.36
G _{SH}	Radiation shield parameter	0.85
T _{SH}	Radiation shield time constant	12.2
T _{TR}	Thermocouple time constant	1.7
G _{TC}	Temperature controller parameter	3.3
T _T	Temperature controller integration rate	250
N _c	Compressor efficiency	0.895
n _T	Turbine efficiency	0.895

**Figure 3.** Mechanical output power after speed drop by -0.1%.

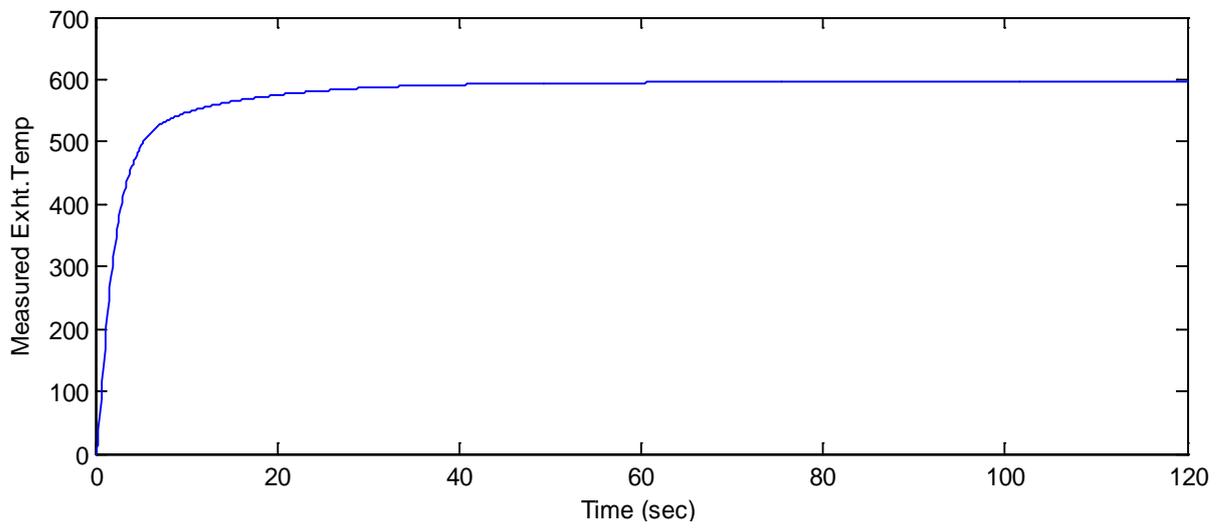


Figure 4. Temperature measurement after turbine speed step of -0.1% .

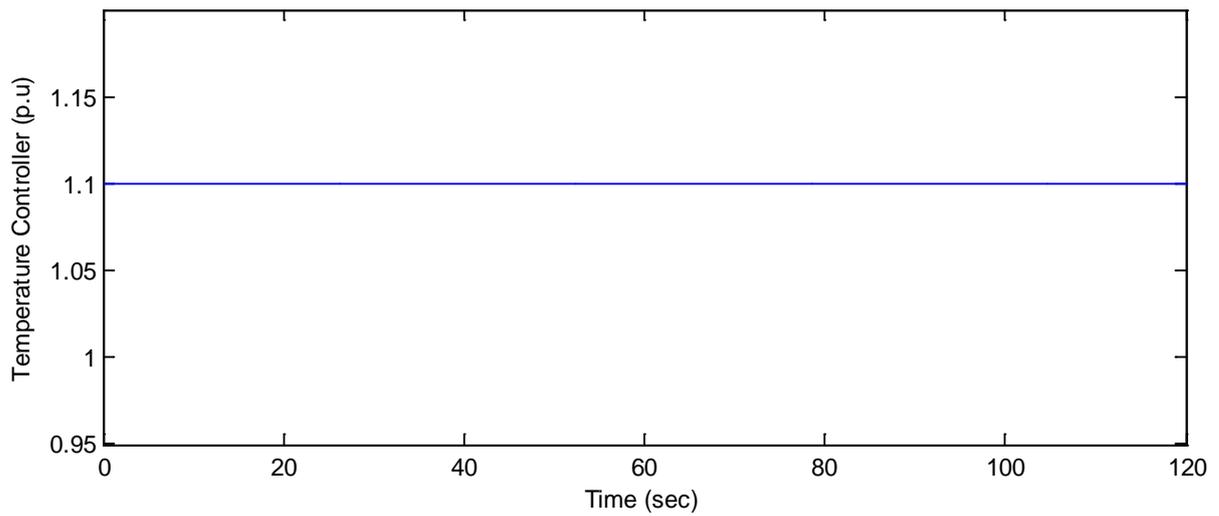


Figure 5. Temperature controller against -0.1% turbine speed deviation.

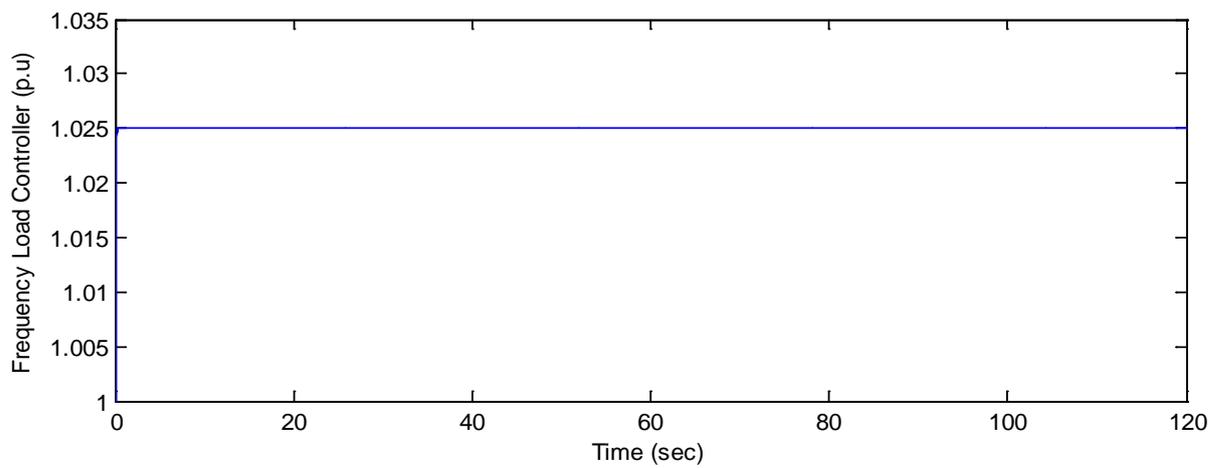


Figure 6. Frequency load controller -0.1% turbine speed deviation.

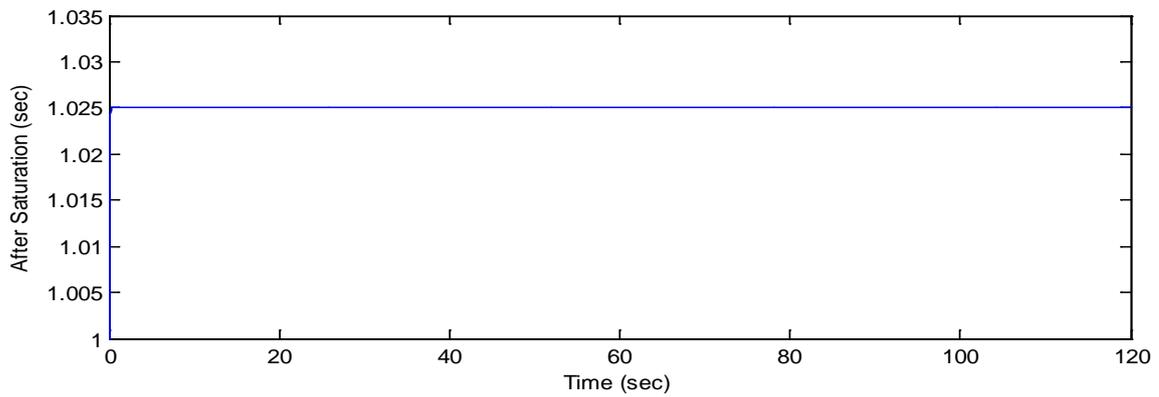


Figure 7. After saturation against -0.1% micro turbine speed deviation.

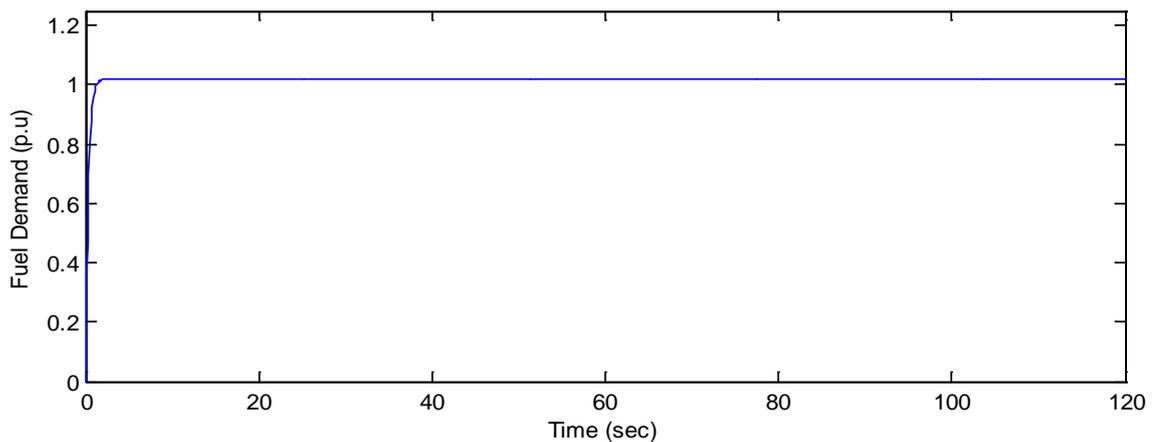


Figure 8. Fuel demand after turbine speed step of -0.1% .

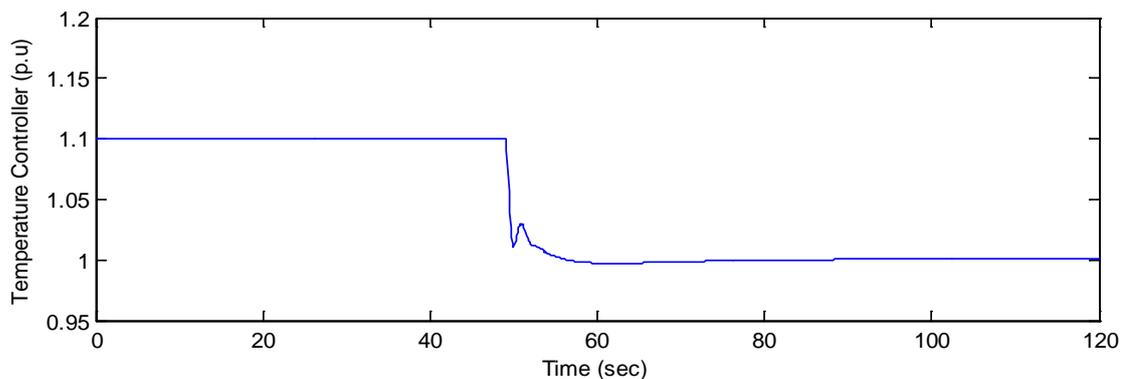


Figure 9. Temperature controller against -0.5% turbine speed deviation.

The second scenario with -0.5% step in turbine speed would lead to the activation of the temperature control, as shown in Figure 9. Figure 10 shows the mechanical output power, where a final value close to 1.08 p.u is noted. The power output remains constant until temperature control activation, *i.e.*, until 50 sec. The measured exhaust increases during this period, which is ~ 50 s, until the temperature reaches a value of 625°C . This is shown in Figure 11. The temperature control activation forces the exhaust temperature to decline to its rated value of 585°C at the expense of decrease in the output power, which is illustrated in Figure 10. The behavior of the turbine speed deviation after saturation and that of fuel demand is illustrated in Figure 12 & Figure 13 respectively. Figure 14 ensures this meaning where the output of the frequency-load controller (F_D).

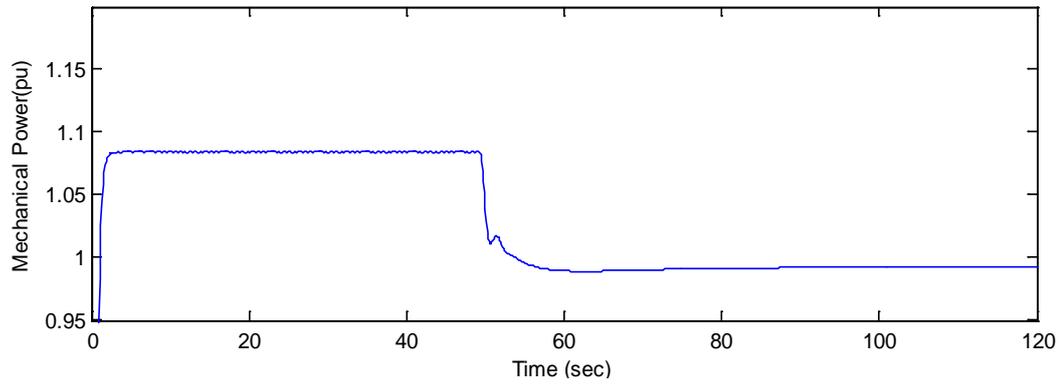


Figure 10. Mechanical output power after speed drop by -0.5% .

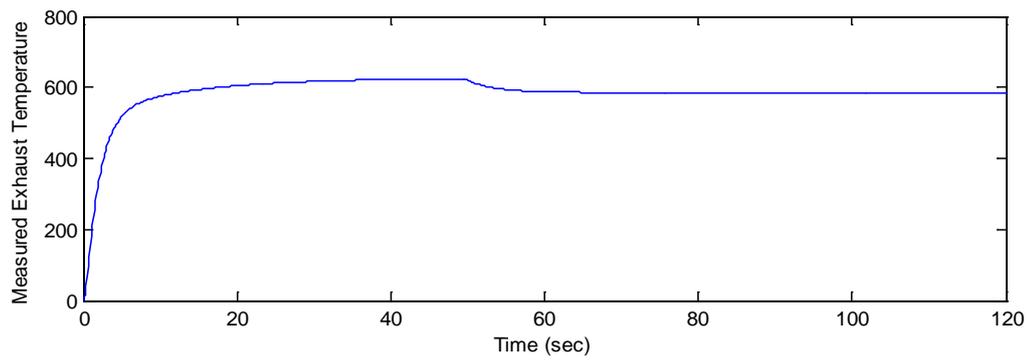


Figure 11. Temperature measurement after turbine speed step of -0.5% .

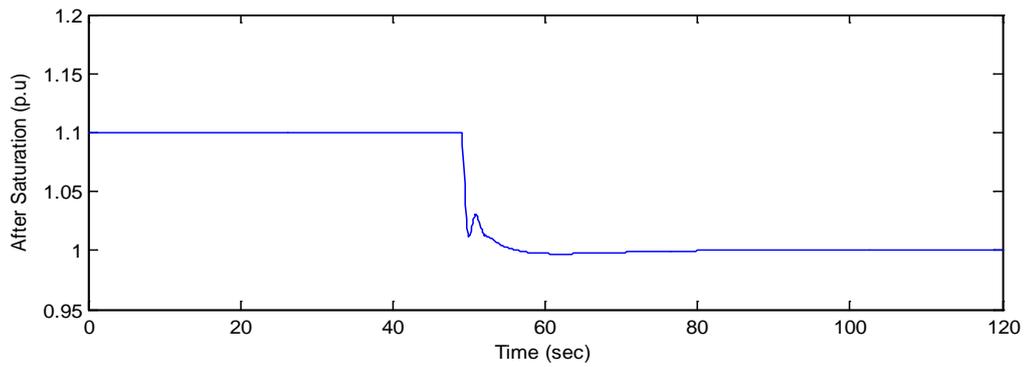


Figure 12. After saturation against -0.5% turbine speed deviation.

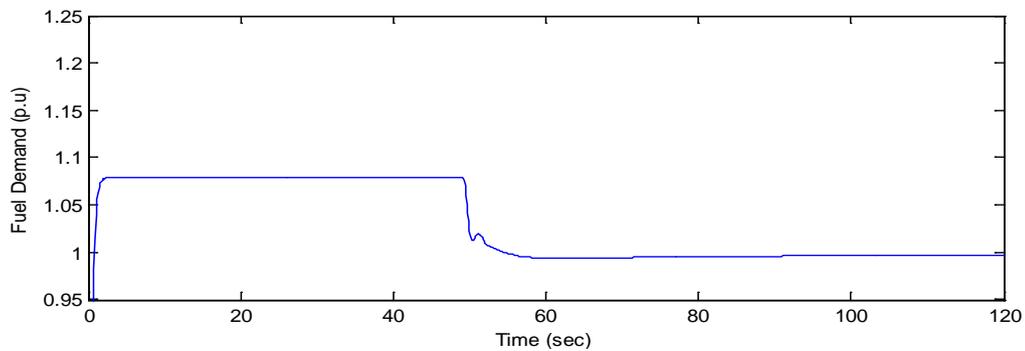


Figure 13. Fuel demand after turbine speed step of -0.5% .

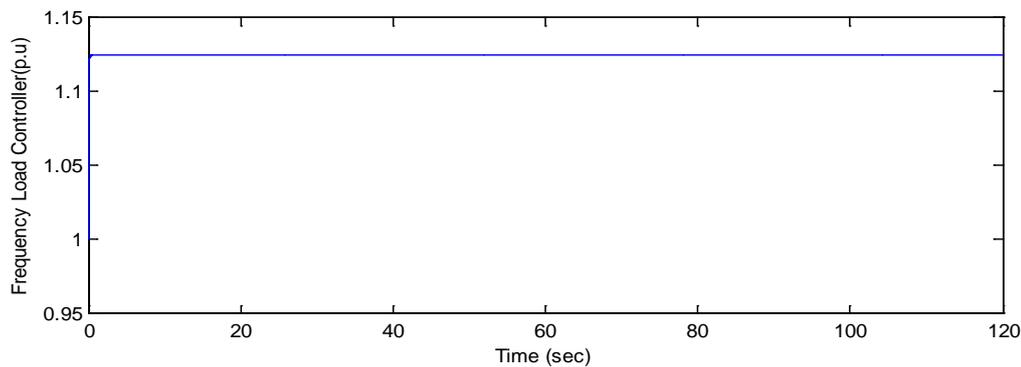


Figure 14. Frequency load controller against -0.5% turbine speed deviation.

6. Conclusion

This paper proposes a control design of micro turbine generation system. A 265-MW micro turbine model is considered and its parameters are extracted successfully after performing several simulation tests. These parameters can be used in dynamic studies for many purposes. Simple physical law and simplifications can be used by trainers to learn the concepts or make simple numerical examples based on the data of existing units. The simulation tests are conducted using Matlab/Simulink and the results obtained are discussed. As an extension of this work the PI controller is to be replaced by Fuzzy logic controller in a Matlab/Simulink operating system.

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