

Online Maximum Loadability Monitoring Scheme for Smart Grid

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Abstract

This paper presents an algorithm based on Thevenin equivalent network for voltage stability evaluation. The proposed algorithm provides a technique for online predicting the largest possible margin to voltage collapse of an electrical power system. An online maximum loadability determination algorithm is developed by transforming the impedance margin, obtained from the Thevenin equivalent network, into the loading margin at each of the load buses in a power system. Furthermore, the proposed algorithm also takes system load trends into account for practical applications. The effectiveness of the proposed algorithm is tested on the IEEE 14 and 57 bus test systems. Simulation results have shown that the proposed algorithm is useful and practical for online voltage instability monitoring.

Keywords

Maximum Lodability, Online Monitoring, Smart Grid, Thevenin Equivalent, Voltage Stability

1. Introduction

Many power system blackouts throughout the world have been mainly caused by the phenomenon of voltage instability. These voltage collapse problems have threatened power system reliability and security. In recent years, voltage stability is a serious concern in power system operation. Several methods for voltage stability analysis techniques are discussed in [1] [2]. When power systems are operated closer to their maximum loading conditions, there is a necessity to release tension of the transmission network. Nevertheless, maximum loading of a power system is not a fixed quantity. Various factors which can vary with time, such as: transmission network topology, generation status, load patterns, the availability of reactive power reserves, and their locations will all impact such a quantity [3] [4]. As a result, it is critical that system operators use the information of the current operating point to estimate the distance of power system state to the voltage collapse point.

For power system planning and operation, the conventional P-V curves are widely used to determine the loading margin within voltage stability limit. The P-V curve is generated by executing a large number of load-flow analysis. To overcome the uncertainty of the load-flow convergence, the continuation power flow (CPFLOW)

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based methods were proposed in [5] [6]. Owing to the CPFLOW based methods are usually time-consuming for a large-scale power system; they may not be appropriate for online application, so alternative approaches are needed.

The methods proposed in [7]-[10] are called the local methods based on tracking the Thevenin equivalent parameters by local voltage and current phasor measurements. The central principle of the local method is that: when voltage collapse occurs at a load bus, both the Thevenin equivalent impedance and the load impedance have the same value. Thus, tracking the impedance margin, the difference between the Thevenin equivalent impedance and the load impedance, is essential for this kind of method. However, using this approach to determine voltage stability, only the impedance-based margin can be obtained. Instead of the margin in terms of the impedance, the loading margin of a power system is more helpful for system operators and planners.

In order to identify voltage instability and to predict the maximum loadability of a power system, an algorithm which is more efficient and practical is proposed in this paper. The remainder of this paper is organized as follows: Section 2 gives a brief introduction for the local method based on Thevenin equivalent network. Section 3 describes the organization of the proposed algorithm for online power system voltage stability analysis. Simulation results on standard IEEE benchmark systems are illustrated in section 4. Conclusion is provided in Section 5.

2. Basic Concept of the Thevenin Equivalent Network Method

In this section, we review the basic concept of the local method proposed in [7] for voltage security evaluation. Such an approach is based on an estimated Thevenin equivalent network behind a load bus.

Let us begin with a load at the *i*th bus connected to a complex power system, which can be simplified into a two-terminal Thevenin equivalent network as shown in **Figure 1**. The rest of the power system is treated as the Thevenin equivalent network consisting of the Thevenin equivalent voltage behind the Thevenin equivalent impedance. Also, let

$$E_{thi} = |E_{thi}| \angle \beta_i$$

$$Z_{thi} = |Z_{thi}| \angle \alpha_i$$

$$Z_{Li} = |Z_{Li}| \angle \theta_i$$
(1)

Be the symbol of the Thevenin equivalent voltage, the Thevenin equivalent impedance, and the load impedance in phasor representation at bus, respectively.

Applying Kirchoff's voltage law to the electrical circuit in **Figure 1**, then is given by

$$E_{thi} = V_i + Z_{thi}I_i \tag{2}$$

where and correspond to the voltage and current phasors of the load at bus.

For a given load power factor, the load power at bus i can be expressed as

$$P_{i} = \frac{\left| Z_{Li} \right| \left| E_{thi} \right|^{2} \cos \theta_{i}}{\left| Z_{thi} \right|^{2} + 2 \left| Z_{Li} \right| \left| Z_{thi} \right| \cos \left(\alpha_{i} - \theta_{i} \right) + \left| Z_{Li} \right|^{2}}$$
(3)

Suppose that the load at bus i is to be increased up to a point at which the maximum power transfer occurs. At this point, the electrical circuit in **Figure 1** satisfies the following conditions:

$$(E_{thi} - V_i)^* = V_i$$

$$|Z_{thi}| = |Z_{Ii}|$$
(4)

In other words, as voltage collapse takes place at bus i, $|Z_{Li}|$ is equivalent to $|Z_{thi}|$. That is, the critical point at voltage collapse is also the point in which the maximum available power can be delivered to the load. Thus, $|Z_{Li}|$ and $|Z_{thi}|$ play important roles in voltage instability monitoring with conditions below:

$$|Z_{Li}| > |Z_{thi}| \Rightarrow \text{Stable}$$
 $|Z_{Li}| \le |Z_{thi}| \Rightarrow \text{Unstable}$ (5)

To illustrate the previous paragraph, Figure 2 diagrams the relationship between $|Z_{Li}|$ and $|Z_{thi}|$ in the

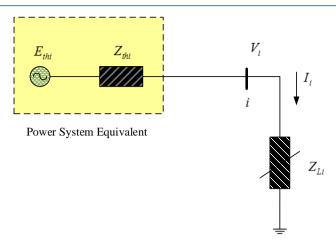


Figure 1. Thevenin equivalent network at bus *i*.

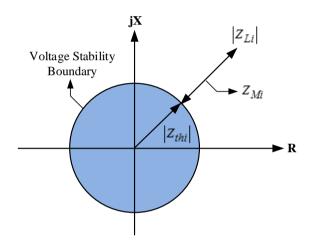


Figure 2. Representation of impedance margin in R-X plane.

impedance plane (R-X plane), in which the impedance margin at bus i, denoted by Z_{Mi} , is defined to be.

$$Z_{thi} = \left| Z_{Li} \right| - \left| Z_{thi} \right| \tag{6}$$

In the context of the preceding discussion, at the voltage-collapse point, $|Z_{Li}|$ equals to $|Z_{thi}|$, which means Z_{Mi} closes to zero when voltage collapses at bus i.

Based on the concepts described above, several impedance-based indices have been proposed in the works of [7]-[10]. Even though these indices can be adopted to identify whether or not the current operating condition of a power system is stable, information about the maximum available power that a system can be delivered to the load cannot be obtained by those impedance-based methods. In fact, the specific value like maximum loadability or loading margin of a power system is more useful to system operators and planners.

3. The Proposed Algorithm

This section presents an algorithm that can estimate the loading margin corresponding to the current operating point. The main idea of the proposed algorithm is to transform the impedance margin, obtained from the Thevenin equivalent network, into the loading margin at each of the load buses. In addition, load changes at the individual buses are considered as well.

Suppose that the voltage phasor V_i and current phasor I_i are available at load bus $i = 1, 2, \dots, n$, the complex load variation at bus i can be measured by

$$\Delta S_{i}(k) = S_{i}(k) - S_{i}(k-1)$$

$$= V_{i}(k) \cdot I_{i}^{*}(k) - V_{i}(k-1) \cdot I_{i}^{*}(k-1)$$
(7)

where the letter *k* represents the *k*th sampling point. Indeed, the complex load variation can have significantly effects on the load impedance and the Thevenin equivalent parameters, which means the impedance margin is involved as well.

Solving for Z_{Mi} requires $|Z_{Li}|$ and $|Z_{thi}|$. To find $|Z_{Li}|$, consider the loads at bus $i = 1, 2, \dots, n$ vary linearly. The changes of complex load powers can be transformed into the changes of load impedances. As a consequence, $|Z_{Li}|$ at the sampling point k can be computed by

$$\left|Z_{Li}\left(k\right)\right| = \frac{\left|V_{i}\left(k\right)\right|^{2}}{\left|S_{i}^{*}\left(k\right)\right|} \tag{8}$$

To compute $|Z_{thi}|$, consider the Thevenin equivalent network in **Figure 1**. Since the local voltage and current phasors are available, the Thevenin equivalent parameters can be computed by the methods proposed in [7]-[10], *i.e.* $|Z_{thi}|$ can be obtained.

With $|Z_{Li}|$ and $|Z_{thi}|$, Z_{Mi} can be computed by Equation (6). We are now finished with the impedance margin involving the load change, so the next step is to transform the calculated impedance margin into the corresponding loading margin.

In the following, we develop an algorithm that can formulate the transformation between the impedance margin and the load margin at each of the load buses. The technique that we use to derive such an algorithm is called linear fractional transformation with matrix method [11].

To illustrate the algorithm, start by increasing the load at bus i in **Figure 1**. The trajectory of $|Z_{Li}|$ and $|Z_{thi}|$ at bus i is plotted in **Figure 3**. It can be seen that $|Z_{Li}|$ is equal to $|Z_{thi}|$ when the maximum deliverable power is reached

From **Figure 3**, the load margin at bus i, denoted by P_{Mi} , is defined to be

$$P_{Mi} = P_{\text{max}i} - P_{0i} \tag{9}$$

where P_{0i} and $P_{\max i}$ are the current operating value of real power and the maximum deliverable power at bus i, respectively.

Suppose that there exists a transformation T such that $P_{Mi} = T(Z_{Mi})$. In this case, T is called the transformation between Z_{Mi} and P_{Mi} , and such a T can be expressed as the form of linear fractional transformation

$$P_{Mi} = T\left(Z_{Mi}\right) = \frac{a \times Z_{Mi} + b}{c \times Z_{Mi} + d} \tag{10}$$

where a, b, c, and d are all complex numbers. Furthermore, T can be presented by a matrix form as

$$T = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \tag{11}$$

If a, b, c, and d in Equation (11) are known, Z_{Mi} can be transformed into P_{Mi} accordingly.

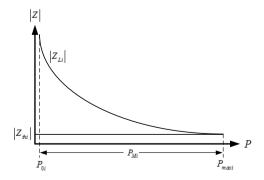


Figure 3. Trajectory of $|Z_{Li}|$ and $|Z_{thi}|$ as load increases.

Figure 4 illustrates the overall transformation diagram between Z_{Mi} and P_{Mi} . Since T cannot be obtained directly, T_1 and T_2 are required to gain T. The relationship between T_1 , T_2 , and T is

$$T = T_2 T_1 \tag{12}$$

As long as T_1 and T_2 are found, T can be solved by Equation (12). In solving T_1 and T_2 , two helpful parameters must be defined in advance.

First, define the voltage stability index at bus i to be

$$VSI_{i} = \frac{P_{Mi}}{P_{0i}}$$
 (13)

Then, define r as the ratio of Z_{Mi} and VSI_i

$$r = \frac{Z_{Mi}}{\text{VSI}}.$$
 (14)

Solving for r by the definitions of Z_{Mi} and VSI, and after some manipulations gives

$$r = \frac{2|Z_{Li}||Z_{thi}|[1 + \cos(\alpha_i - \theta_i)]}{Z_{Mi}}$$

$$(15)$$

Clearly, whenever Z_{Li} and Z_{thi} are known, r is also achieved. Now T_1 , T_2 , and T in **Figure 4** can be derived by means of linear fractional transformation with matrix method.

According to **Figure 4**, $r = T_1(Z_{Mi})$, so T_1 can be expressed as

$$T_{1} = \begin{bmatrix} 0 & 2|Z_{Li}||Z_{thi}|[1+\cos(\alpha_{i}-\theta_{i})]\\ 1 & 0 \end{bmatrix}$$

$$\tag{16}$$

Similarly, T_2 can be found by

$$T_2 = \begin{bmatrix} 0 & P_{0i} \times Z_{Mi} \\ 1 & 0 \end{bmatrix} \tag{17}$$

Since $T = T_2T_1$, this equation gives

$$T = \begin{bmatrix} P_{0i} \times Z_{Mi} & 0\\ 0 & 2|Z_{Li}||Z_{thi}||1 + \cos(\alpha_i - \theta_i) \end{bmatrix}$$
(18)

With this approach to computing T, for $i = 1, 2, \dots, n$, P_{Mi} can be found by taking each of Z_{Mi} into Equation (18). Notice, due to Z_{Mi} with S_i considered, which implies that the actual load increase direction is also contained in the computed P_{Mi} .

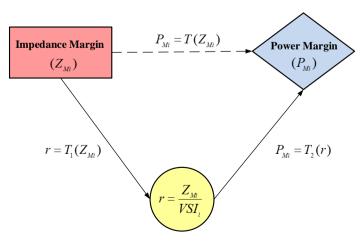


Figure 4. Transformation diagram between Z_{Mi} and P_{Mi} .

As stressed earlier, a load increase direction has a lot to do with a load margin estimation. Consequently, for the system load margin, denoted by P_{SM} , can be expressed as the sum of P_{Mi} estimated at each of the load buses.

$$P_{SM} = \sum_{i=1}^{n} P_{Mi} \tag{19}$$

4. Simulation Results

The proposed method is applied to two sample power systems: IEEE 14-bus and IEEE 57-bus power systems. The programs are coded in MATLAB and implemented on a PC which has a CPU with Intel® CoreTM i5 1.8 GHz and a memory with 8 GB.

To demonstrate the robustness of the proposed method, the simulations are conducted in different cases, including various system and load conditions. Moreover, in this paper the simulation results obtained are all compared with those found by the conventional CPFLOW method which results are considered as the exact values. More details are presented and discussed as follows.

4.1. IEEE 14-Bus System

The first test system is concerned with the IEEE 14-bus test system which is composed of 20 branches, 5 generators, and 9 loads [12]. Two kinds of load patterns, the single load bus variation and multiple load bus variation, are considered. In addition, bar charts are employed to demonstrate the simulation results.

In this study, a lot of test cases on the IEEE 14-bus system have been studied. The selected simulation results are illustrated in **Figure 5**. The maximum loadability value λ_{max} of the selected cases are plotted on the Y-axis of the figure; the bars in left-slanted lines represent the results obtained by the proposed method and the bars with criss-cross lines denote the exact values. As **Figure 5** shows, the proposed method is able to provide the results with acceptable accuracy.

4.2. IEEE 57-Bus System

The IEEE 57-bus system is also used as a test model to demonstrate the applicability of the proposed method to bulk power systems. This simulated system consists of 80 branches, 7 generators, and 42 loads [12]. In order to evaluate the performance of the proposed method, we have studied a lot of test cases. These include different load levels and load patterns. The selected simulation results among those cases are shown in **Figure 6**. From the shown figure, it is clearly seen that the errors of the proposed method are within a relatively small range.

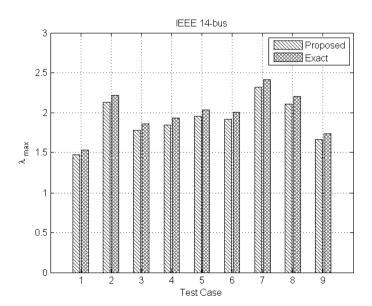


Figure 5. Performance evaluation of the proposed method under the test cases for the IEEE 14-bus system.

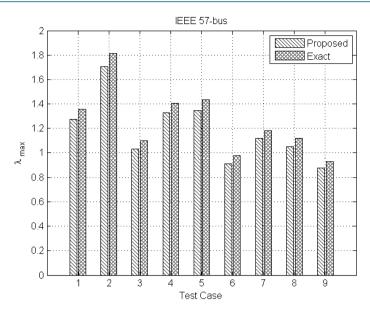


Figure 6. Performance evaluation of the proposed method under the test cases for the IEEE 57-bus system.

5. Conclusion

In this paper, a new approach to monitor and identify voltage instability of a power system is presented. Specifically, an online loading margin estimation algorithm with load changes considered is developed. Moreover, the proposed algorithm is a simple, fast, and stable technique that can be applied in the field of online applications. Due to the advent of the method, the proposed algorithm can achieve an excellent performance for the determination of maximum lodability of the transmission network. In this study, we have run a great deal of simulations on two standard IEEE benchmark systems, and satisfaction is within the results.

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